

Mass properties of link-knee

Configuration: Default

Coordinate system: Coordinate System1

Density = 0.00 grams per cubic millimeter

Mass = 20.73 grams

Volume = 20726.50 cubic millimeters

Surface area = 10627.50 square millimeters

Center of mass: (millimeters)

X = 0.00

Y = 0.00

Z = 0.00

Principal axes of inertia and principal moments of inertia: (grams * square millimeters)

taken at the center of mass.

Ix = (-0.08, 1.00, 0.00) Px = 6902.83

Iy = (-1.00, -0.08, 0.00) Py = 8976.42

Iz = (0.00, 0.00, 1.00) Pz = 10135.24

Moments of inertia: (grams * square millimeters)

taken at the center of mass and aligned with the output coordinate system.

Lxx = 8962.80 Lxy = -167.48 Lxz = 0.00

Lyx = -167.48 Lyy = 6916.45 Lyz = 0.00

Lzx = 0.00 Lzy = 0.00 Lzz = 10135.24

Moments of inertia: (grams * square millimeters)

taken at the output coordinate system.

Ixx = 8962.80 Ixy = -167.48 Ixz = 0.00

Iyx = -167.48 Iyy = 6916.45 Iyz = 0.00

Izx = 0.00 Izy = 0.00 Izz = 10135.24