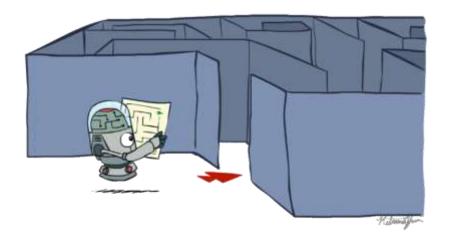
Problem Solving Using Search

Lec-02 Introduction to State Space Search



Slide credits: AI BERKELEY

Introduction

- Suppose an agent can execute several actions immediately in a given state
- It doesn't know the utility of these actions
- Then, for each action, it can execute a sequence of actions until it reaches the goal
- The immediate action which has the best sequence (according to the performance measure) is then the solution
- Finding this sequence of actions is called search, and the agent which does this is called the problem-solver.
- Note: Its possible that some sequence might fail, e.g., getting stuck in an infinite loop, or unable to find the goal at all.

Problem-Solving Agent

 Problem solving agent is a goal-based agent that decides what to do by systematically finding sequences of actions that lead to desirable states (goal)

 Many problems can be represented as a set of states and a set of rules of how one state is transformed to another.

Example Problems

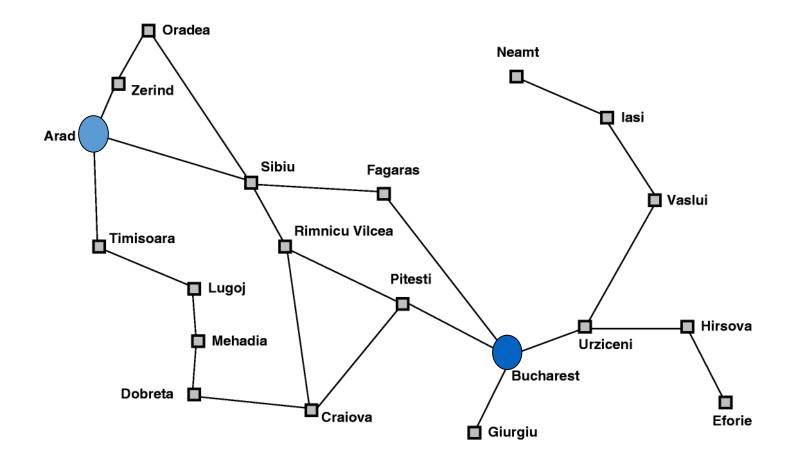
Toy Problems

- 8-puzzle
- 8-queens
- Tic-Tac-Toe
- missionaries and cannibals

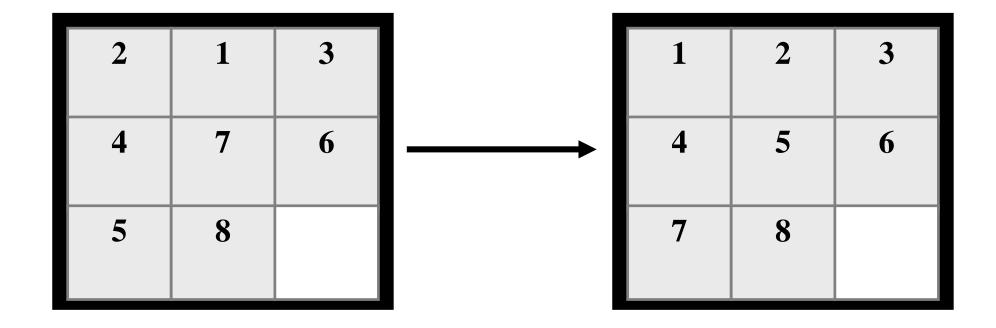
Real-world Problems

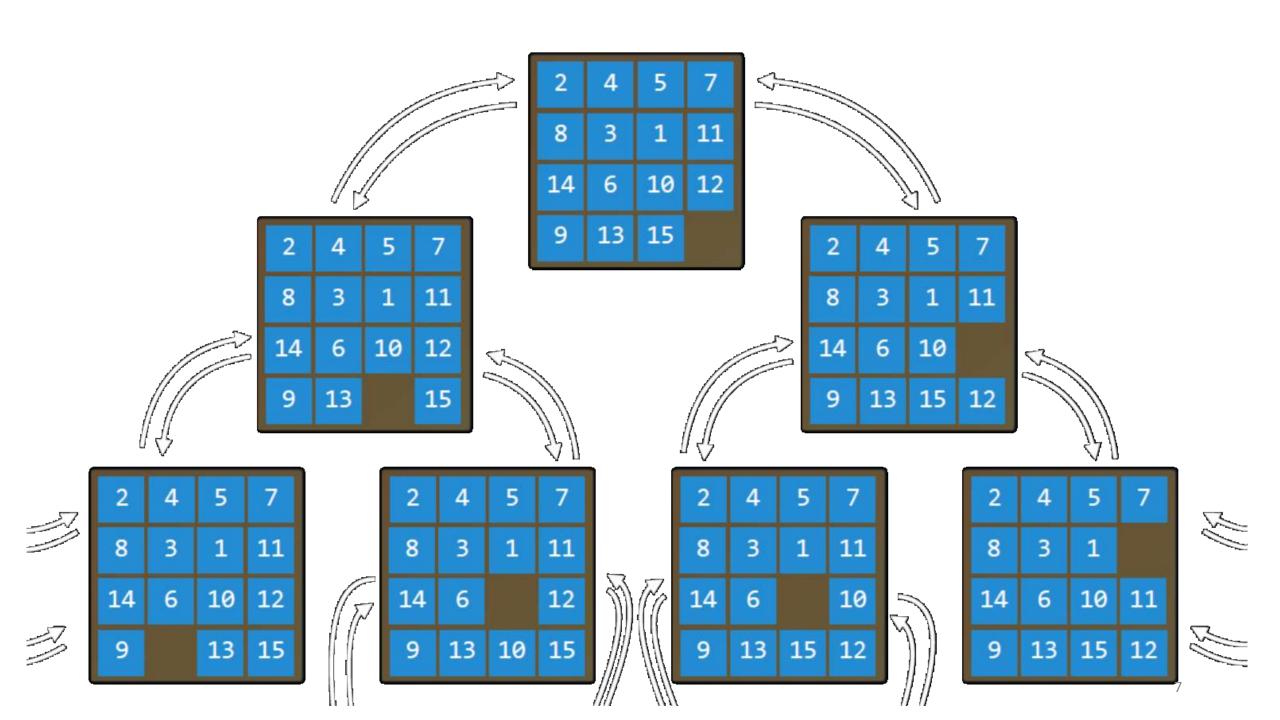
- route finding
- touring problems
 - traveling salesperson
- VLSI chip design layout
- robot navigation
- Web search

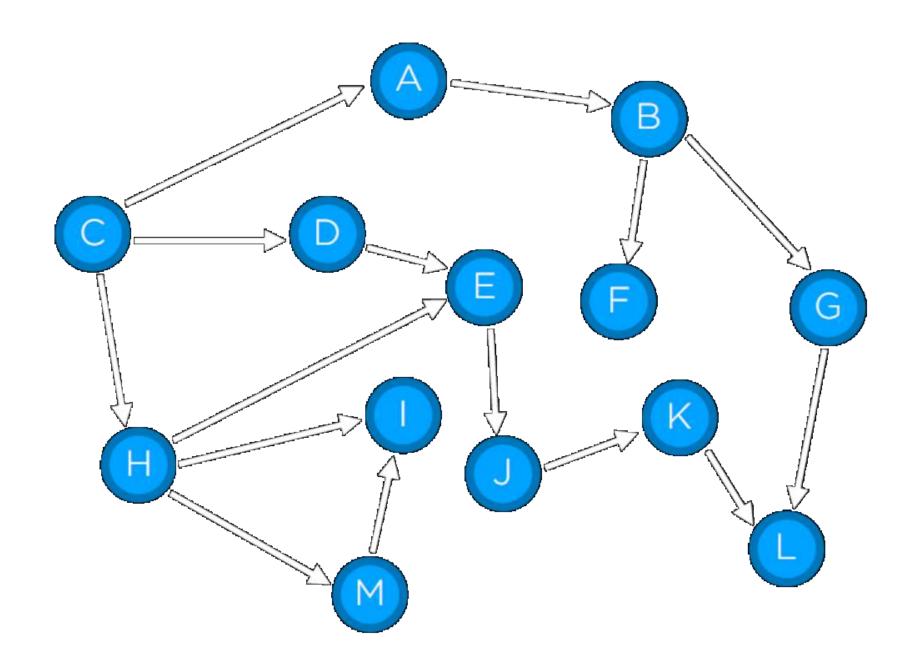
Touring Agent Problem (Map Search / Navigation)

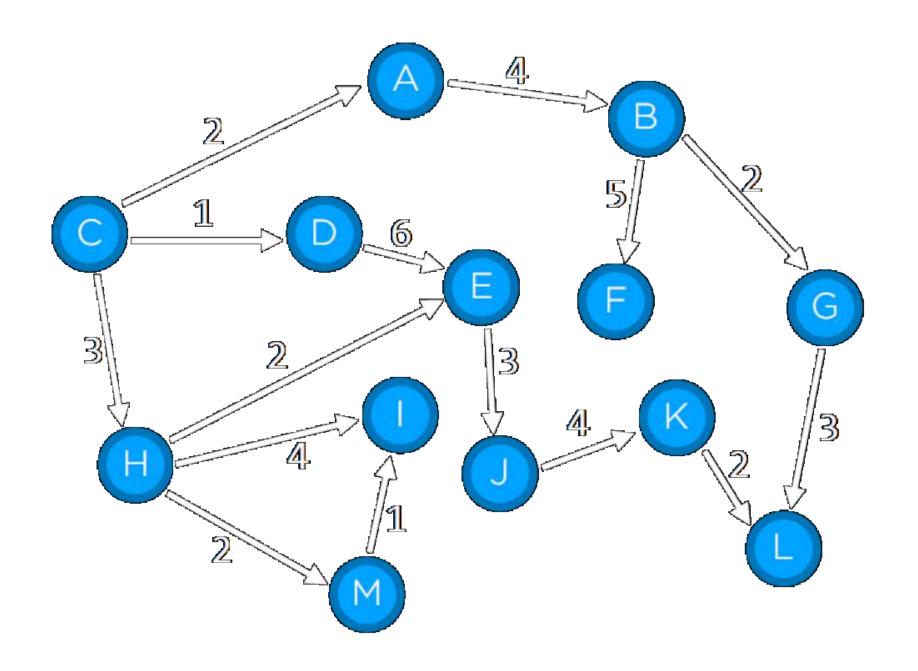


• 8-Puzzle

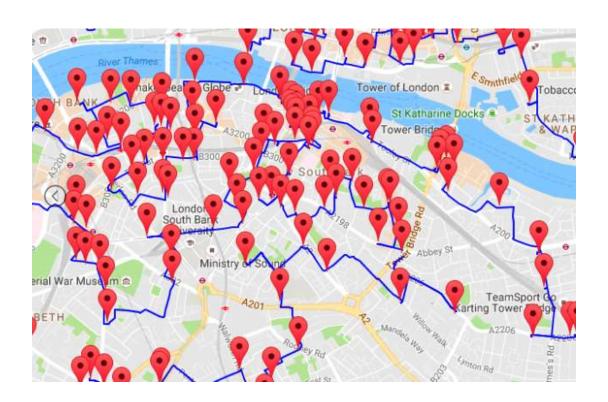




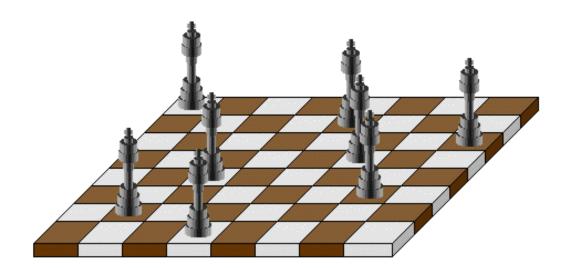


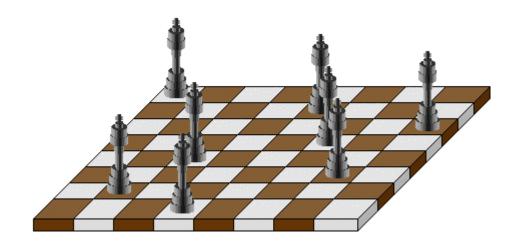


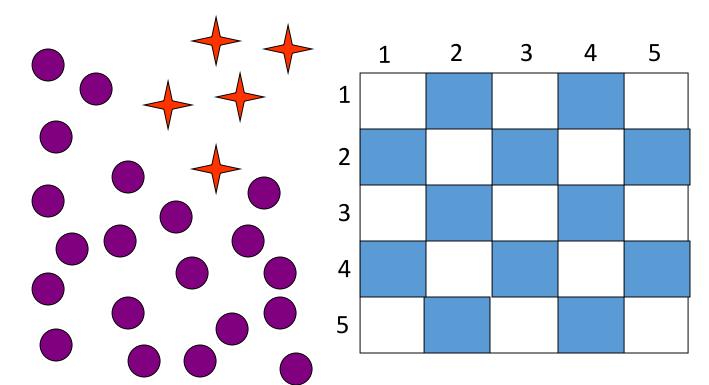
- Travelling Salesperson Problem (TSP)
 - Suppose a salesman has five cities to visit and then must return home.
 - The goal of the problem is to find the shortest path for salesman to travel, visiting each city, and then returning to the starting city.

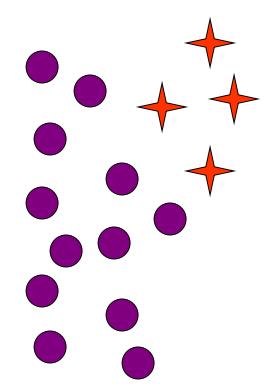


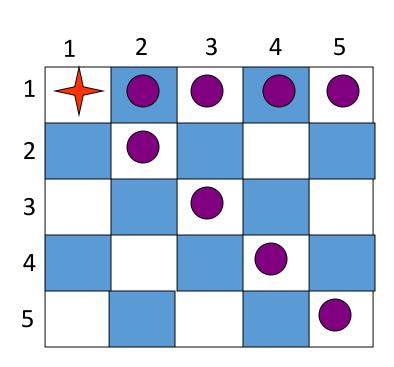
- N-Queens
 - Problem of placing n chess queens on an n×n chessboard so that no two queens attack each other
 - A solution requires that no two queens share the same row, column, or diagonal

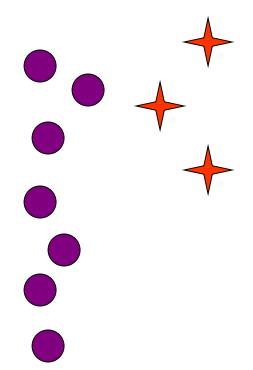


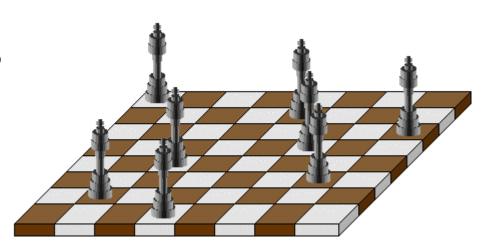


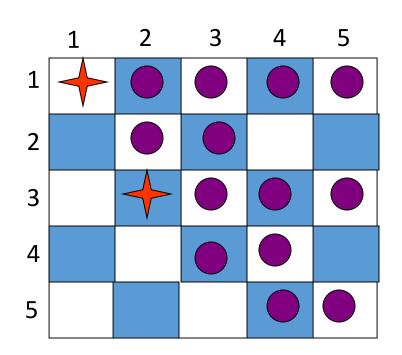


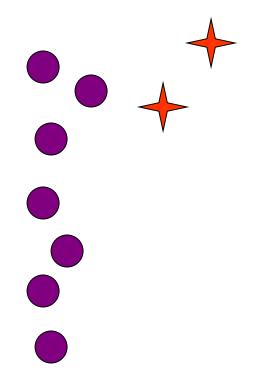


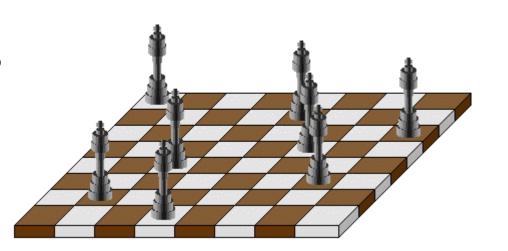


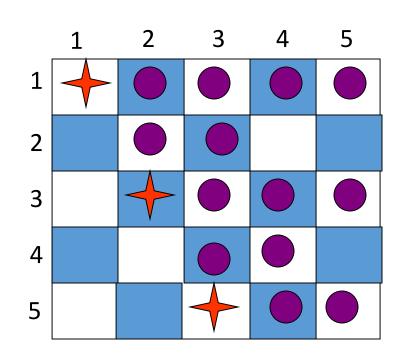


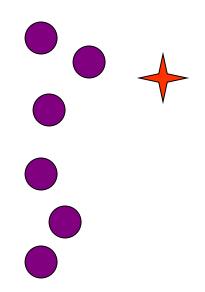


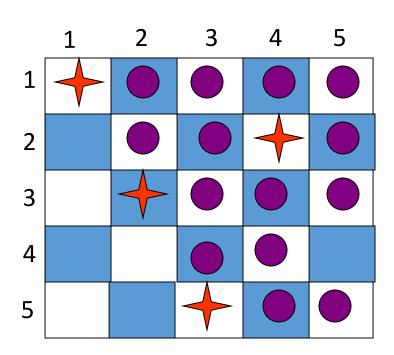


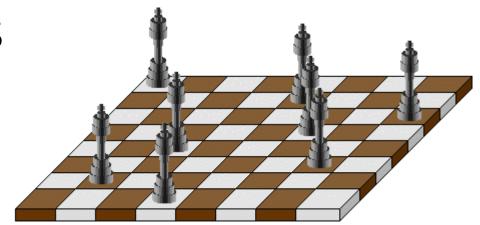


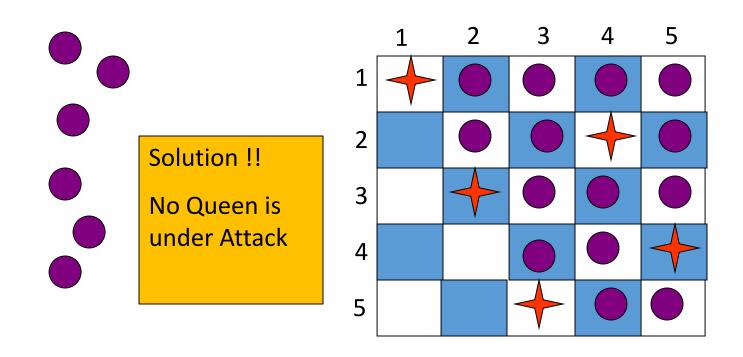








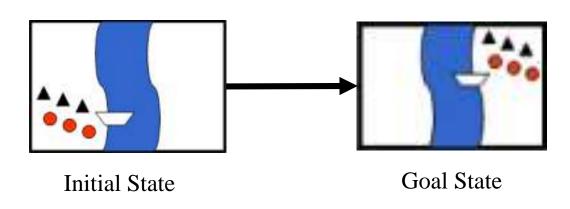




Missionaries and cannibals

- Three missionaries and three cannibals are on the left bank of a river.
- There is one boat which can hold one or two people.
- Find a way to get everyone to the right bank, without ever leaving a group of missionaries in one place outnumbered by cannibals in that place.





River Crossing Problem

- A farmer wishes to carry a wolf, a duck and corn across a river, from the south to the north shore.
 - The farmer has a small rowing boat.
 - The boat can only carry at most the farmer and one other item.
 - If left unattended the wolf will eat the duck and the duck will eat the corn.
- How can the farmer safely transport the wolf, the duck and the corn to the opposite shore?



Search in Al

Search in Data Structures

- You're given an existent tree.
- You search it in different orders.
- It resides in memory.

Search in Artificial Intelligence

- The tree does not exist.
- You have to generate it as you go.
- For realistic problems, it does not fit in memory.

Problem Formulation

A **Problem Space** consists of

- The current state of the world (<u>initial state</u>)
- A description of the actions we can take to transform one state of the world into another (<u>operators or successor function</u>).
- A description of the desired state of the world (goal state), this could be implicit or explicit.
- A **solution** consists of the goal state, or a path to the goal state.

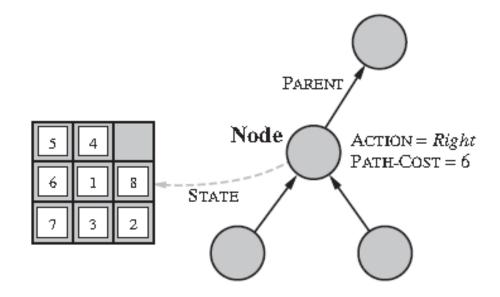
Problem Formulation

- Initial state
- Actions (operators, successor functions)
- State space
- Path
- Goal test
- Solution
- Path cost
- Total cost

Representation of a Search/State Space

 A convenient way of representing search spaces is as a graph

- States are nodes
- Actions are edges
- Initial state is root
- Solution is path from root to goal node
- Edges sometimes have associated costs
- States resulting from operator are children



State Space Representation (Pac man)

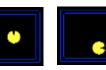
- A search problem consists of:
 - A state space





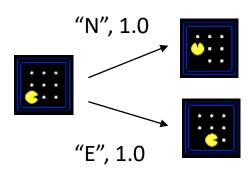








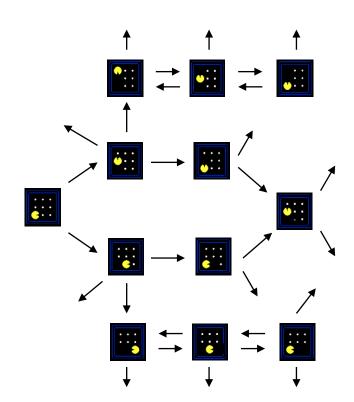
 A successor function (with actions, costs)

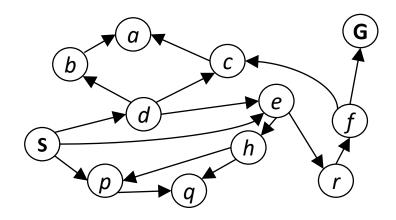


- A start state and a goal test
- A solution is a sequence of actions (a plan) which transforms the start state to a goal state

State Space Graphs

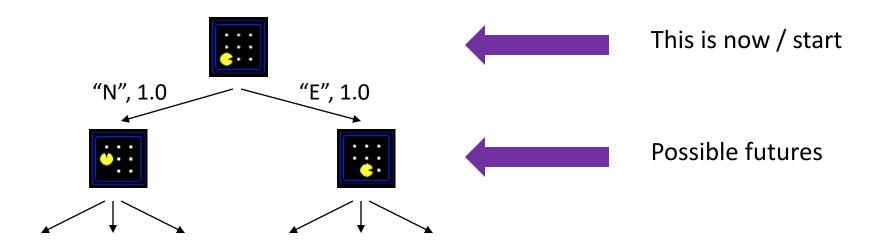
- State space graph: A mathematical representation of a search problem
 - Nodes are (abstracted) world configurations
 - Arcs represent successors (action results)
 - The goal test is a set of goal nodes (maybe only one)
- In a state space graph, each state occurs only once!
- We can rarely build this full graph in memory (it's too big), but it's a useful idea





Tiny search graph for a tiny search problem

Search Trees



A search tree:

- A "what if" tree of plans and their outcomes
- The start state is the root node
- Children correspond to successors
- Nodes show states, but correspond to PLANS that achieve those states
- For most problems, we can never actually build the whole tree

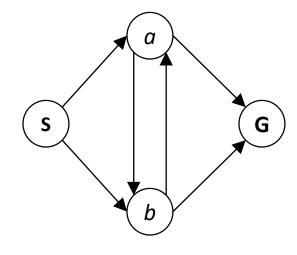
Approach

- Start with a frontier that contains the initial state.
- Repeat:
 - If the frontier is empty, then no solution.
 - Remove a node from the frontier.
 - If node contains goal state, return the solution.
 - Expand node, add resulting nodes to the frontier.

Quiz: State Space Graphs vs. Search Trees

Consider this 4-state graph:

How big is its search tree (from S)?



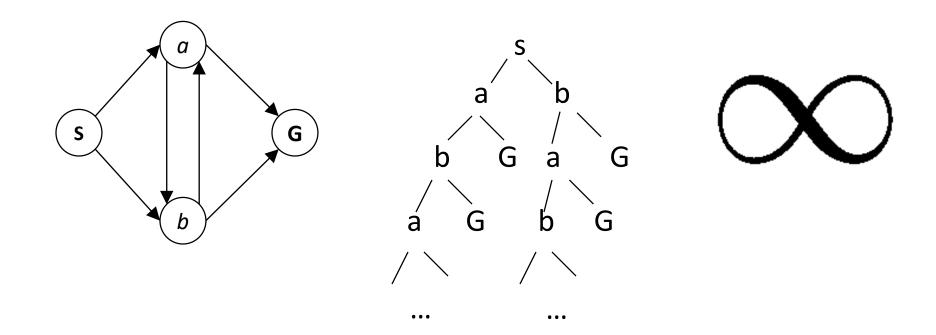


Important: Lots of repeated structure in the search tree!

State Space Graphs vs. Search Trees

Consider this 4-state graph:

How big is its search tree (from S)?



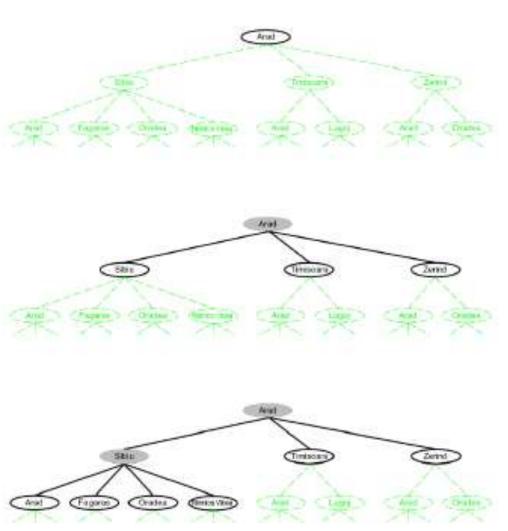
Important: Lots of repeated structure in the search tree!

Revised Approach

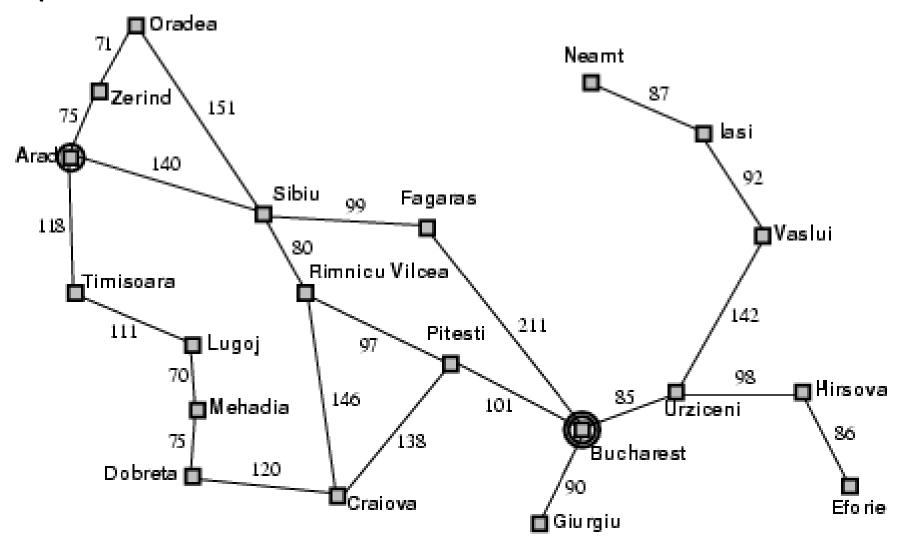
- Start with a frontier that contains the initial state.
- Start with an empty explored set.
- Repeat:
 - If the frontier is empty, then no solution.
 - Remove a node from the frontier.
 - If node contains goal state, return the solution.
 - Add the node to the explored set.
 - **Expand** node, add resulting nodes to the frontier if they aren't already in the frontier or the explored set.

Searching with a Search Tree

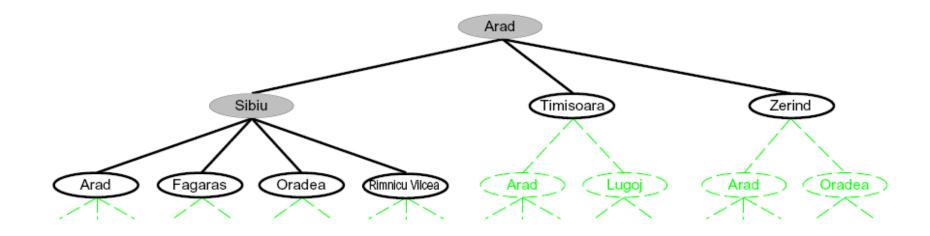
- Search:
- (1) Expand out potential plans (tree nodes)
- (2) Maintain a fringe of partial plans under consideration.
- (3) Try to expand as few tree nodes as possible



Example: Romania



Searching with a Search Tree



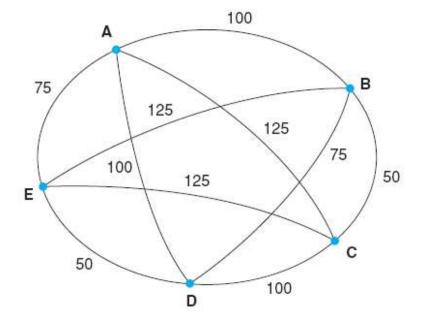
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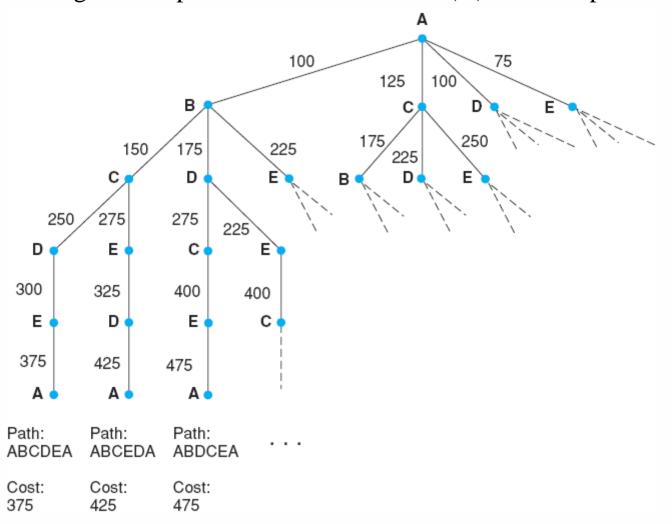
Problem Formulation: TSP

Travelling Salesperson Problem (TSP)

- Suppose a salesman has five cities to visit and then must return home.
- The goal of the problem is to find the shortest path for salesman to travel, visiting each city, and then returning to the starting city.



Search for the travelling salesperson problem. Each arc is marked with the total weight of all paths from the start node (A) to its endpoint.



Problem Formulation: 8-Puzzle Problem

Initi	al St	tate	Operators	Goal State		
2	1	3	Slide blank square left.	1	2	3
4	7	6	Slide blank square right.	4	5	6
5	8		••••	7	8	

Representing states:

- For the 8-puzzle
- 3 by 3 array
 - 5, 6, 7
 - 8, 4, BLANK
 - 3, 1, 2
- A vector of length nine
 - 5, 6, 7, 8, 4, BLANK, 3, 1, 2
- A list of facts
 - Upper_left = 5
 - Upper_middle = 6
 - Upper_right = 7
 - Middle_left = 8

5	6	7
8	4	
3	1	2

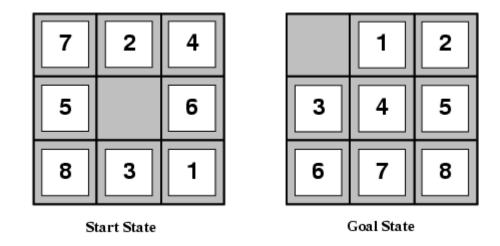
- Specifying operators
 - There are often many ways to specify the operators, some will be much easier to implement...
 - Move 1 left
 - Move 1 right
 - Move 1 up
 - Move 1 down
 - Move 2 left
 - Move 2 right
 - Move 2 up
 - Move 2 down
 - Move 3 left
 - Move 3 right
 - Move 3 up
 - Move 3 down
 - Move 4 left

•	Move	Blank	left
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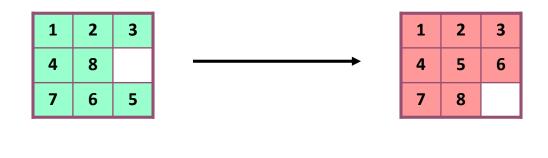
- Move Blank right
- Move Blank up
- Move Blank down

5	6	7
8	4	
3	1	2

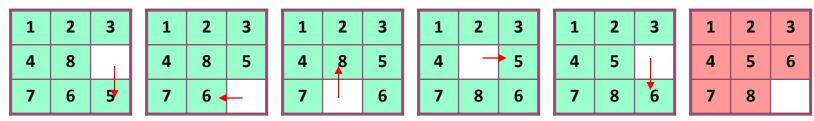
• ..



- states locations of tiles
- actions move blank left, right, up, down
- goal test goal state (given)
- path cost 1 per move



 Operators: slide blank up, slide blank down, slide blank left, slide blank right



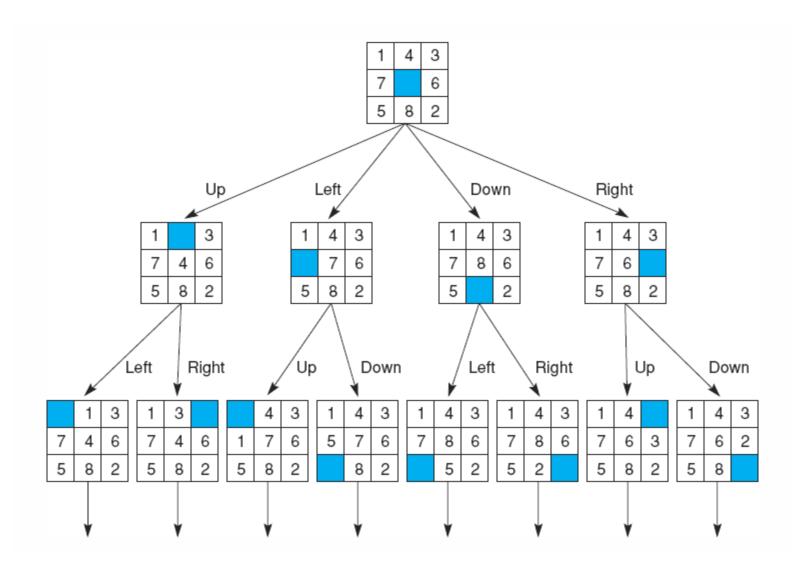
Goal state

• Solution: *sb-down, sb-left, sb-up, sb-right, sb-down*

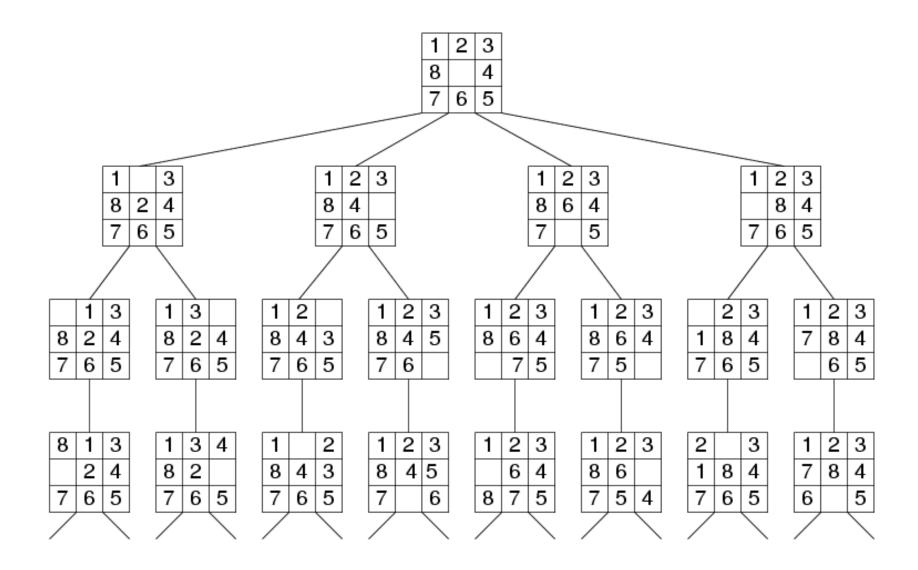
Initial state

• Path cost: **5** steps to reach the goal

State space of the 8-puzzle generated by "move blank" operations



Fragment of 8-Puzzle Problem Space



Problem Formulation: Missionaries and Cannibals

Three missionaries and three cannibals are on the left bank of a river.

There is one boat which can hold one or two people.

• Find a way to get everyone to the right bank, without ever leaving a group of missionaries in one place outnumbered by cannibals in that place.

Missionaries and cannibals

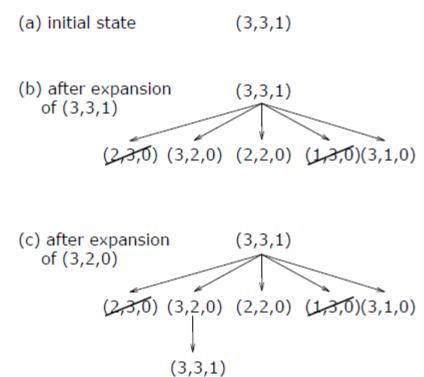
- <u>States</u>: three numbers (i, j, k) representing the number of missionaries, cannibals, and boats on the left bank of the river.
- <u>Initial state</u>: (3, 3, 1)
- Operators: take one missionary, one cannibal, two missionaries, two cannibals, one missionary and one cannibal across the river in a given direction
- Goal Test: reached state (0, 0, 0)?
- Path Cost: Number of crossings.

Formalization of the M&C Problem

- State space: triple (x,y,z), where x,y, and z represent the number of missionaries, cannibals and boats currently on the original bank.
- Initial State: (3,3,1)
- Successor function: From each state, either bring one missionary, one cannibal, two missionaries, two cannibals, or one of each type to the other bank.
- Note: Not all states are attainable (e.g., (0,0,1)), and some are illegal.
- Goal State: (0,0,0)
- Path Costs: 1 unit per crossing

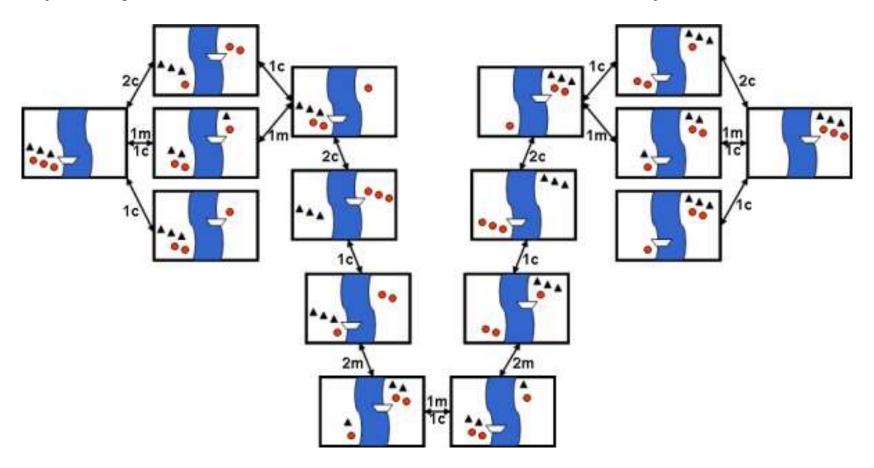
Missionaries and Cannibals

• From the initial state, produce all successive states step by step in search tree.

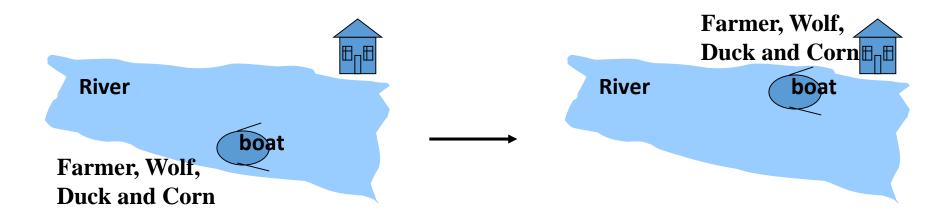


Missionaries and Cannibals

Search-space for the Missionaries and Cannibals problem

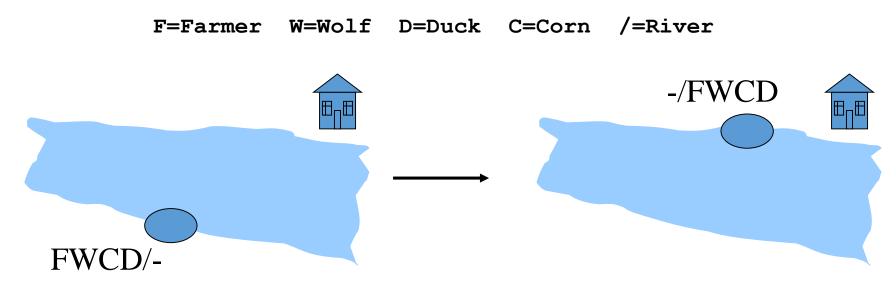


- A farmer wishes to carry a wolf, a duck and corn across a river, from the south to the north shore. The farmer has a small rowing boat. The boat can only carry at most the farmer and one other item.
- If left unattended the wolf will eat the duck and the duck will eat the corn.



How can the farmer safely transport the wolf, the duck and the corn to the opposite shore?

• The River Problem:



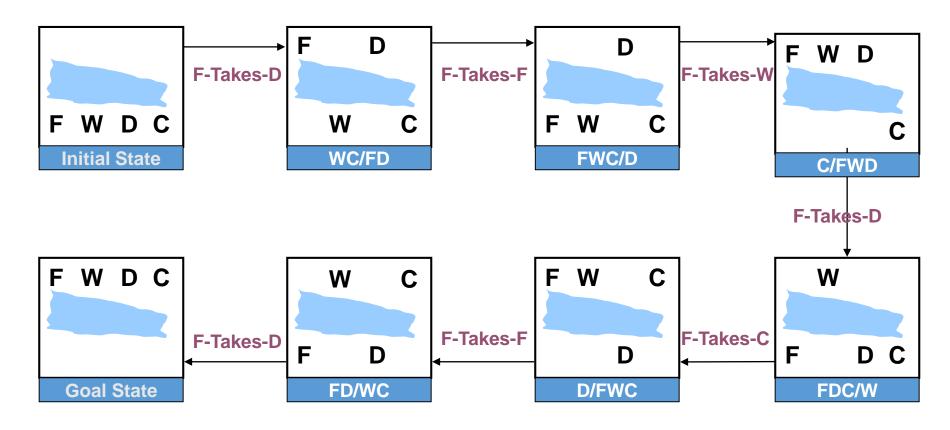
How can the farmer safely transport the wolf, the duck and the corn to the opposite shore?

- Problem formulation:
 - State representation: location of farmer and items in both sides of river [items in South shore / items in North shore] : (FWDC/-, FD/WC, C/FWD ...)
 - Initial State: farmer, wolf, duck and corn in the south shore FWDC/-
 - Goal State: farmer, duck and corn in the north shore -/FWDC
 - Operators: the farmer takes in the boat at most one item from one side to the other side

```
(F-Takes-W, F-Takes-D, F-Takes-C, F-Takes-Self [himself only])
```

Path cost: the number of crossings

- **Problem solution:** (path Cost = 7)
 - While there are other possibilities here is one **7** step solution to the river problem



Summary

- **Search**: process of constructing sequences of actions that achieve a goal given a problem.
- **Goal formulation** is the first step in solving problems by searching. It facilitates problem formulation.
- Formulating a problem requires specifying five components:
 - State representation,
 - Initial state,
 - Goal state,
 - Operators (actions), and
 - Path cost function.

Search Strategies (Next Lecture)

• Several general-purpose search algorithms that can be used to solve these problems.

1. Uninformed search algorithms

- algorithms that are given no information about the problem other than its definition
- Although some of these algorithms can solve any solvable problem, none of them can do so efficiently

2. Informed search algorithms

can do quite well given some guidance on where to look for solutions

