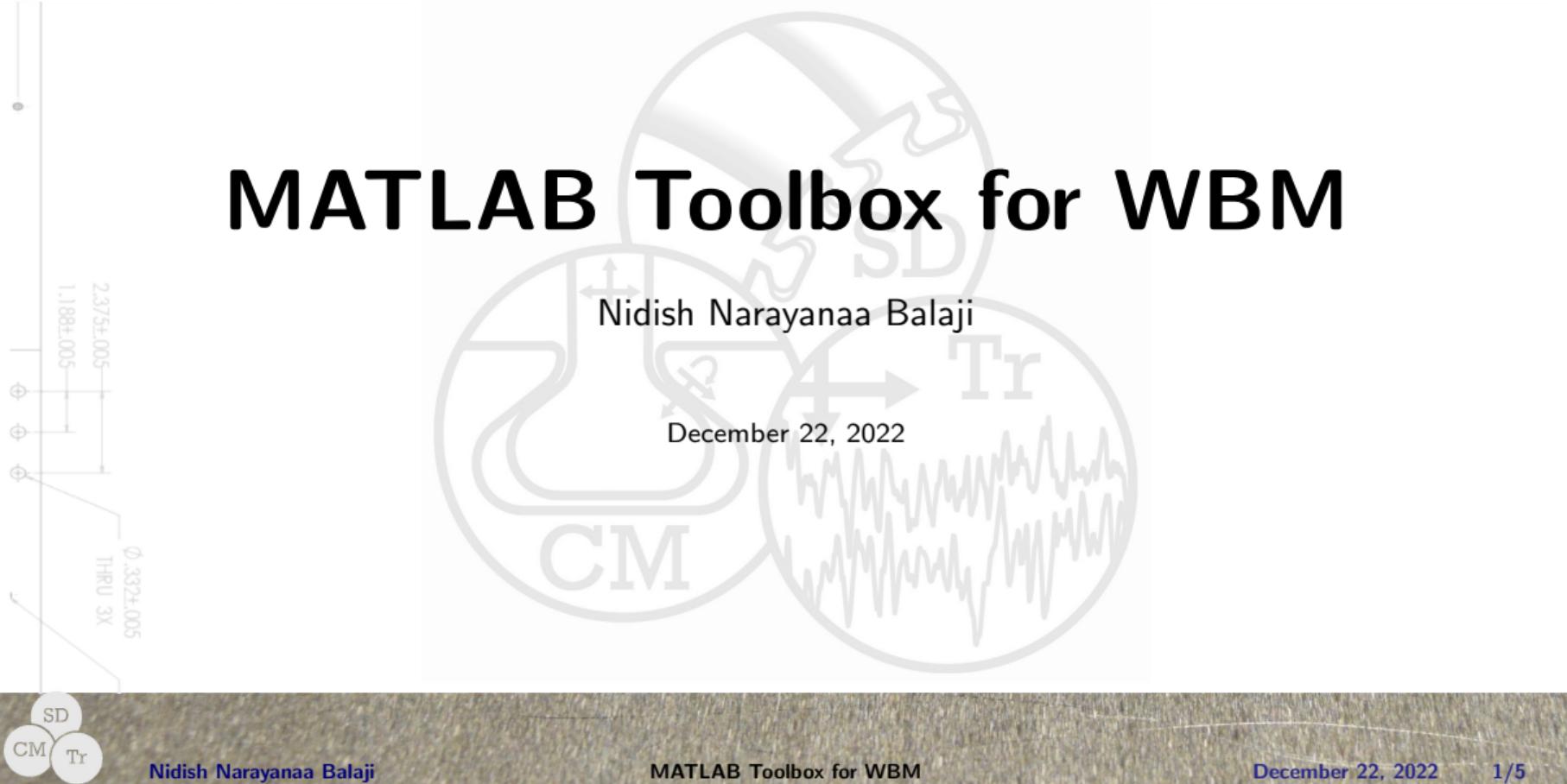


MATLAB Toolbox for WBM

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Example: Jointed EB-Beam

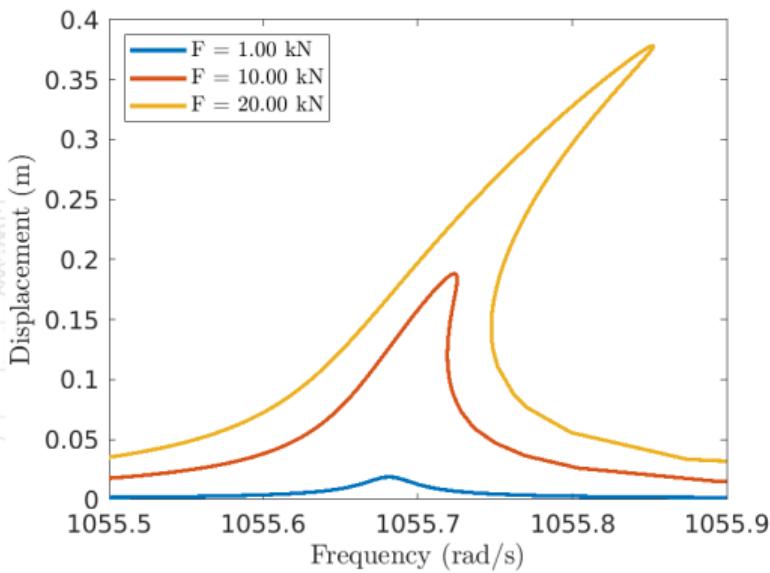


Figure: Forced Response

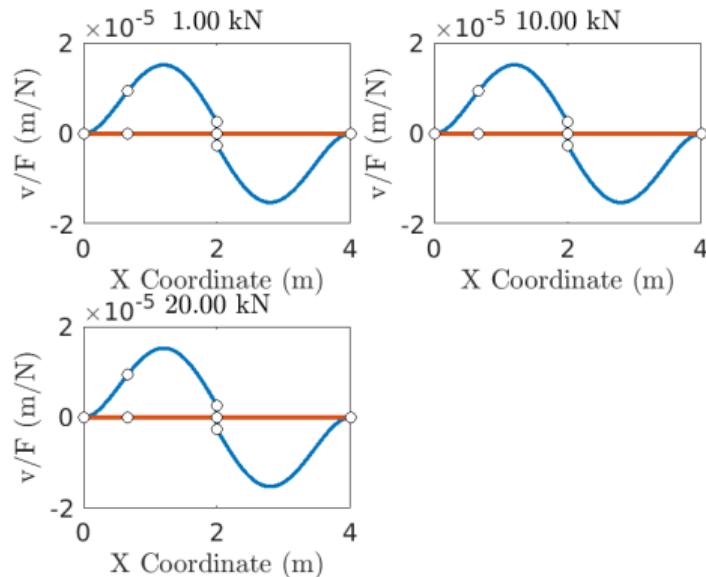


Figure: Deflection Shape

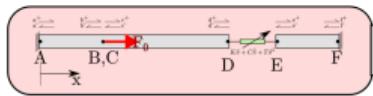
Toolbox Plan I

Dispersion Relationships

$$\begin{aligned}k_1^+ &= k_1^+(\omega) \\k_1^- &= k_1^-(\omega) \\k_2^+ &= k_2^+(\omega) \\k_2^- &= k_2^-(\omega) \\&\vdots\end{aligned}$$

Propagation Relationships

$$\begin{bmatrix} b_1^+ \\ b_1^- \\ b_2^+ \\ b_2^- \\ \vdots \end{bmatrix} = \begin{bmatrix} e^{k_1^+ x_B} & 0 & 0 & 0 & \dots \\ 0 & e^{k_1^- x_B} & 0 & 0 & \dots \\ 0 & 0 & e^{k_2^+ x_B} & 0 & \dots \\ 0 & 0 & 0 & e^{k_2^- x_B} & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} a_1^+ \\ a_1^- \\ a_2^+ \\ a_2^- \\ \vdots \end{bmatrix}$$



Vector of Points
 $X = \{0, 0.1, 0.2, \dots\}$

Excitation Properties

Point Nonlinearities

Residue Vector

Toolbox Plan II

- ▶ Allows user to input arbitrary dispersion relationships for the different “pieces” in the model.
- ▶ Have implemented an **efficient symbolic differentiation** for all the expressions, making the Jacobian evaluations reliably fast, while ensuring the user doesn’t need to type these in.
- ▶ Have validated the code for the bar examples in our paper as well as a jointed Euler-Bernoulli Beam example.
- ▶ **Multi-Harmonic**, allows for PWE-type harmonic balance (& stability), EPMC, etc.



Toolbox Plan III

Need to do:

- ▶ Only binary joints are implemented. Higher order joints can be implemented, but has to be done.
- ▶ Schur complement based decomposition to make the nonlinear solves much more efficient.
- ▶ Implementing constitutive relationships for 3D frame joints (direction cosines are available for each “piece”).
- ▶ Curved members?

