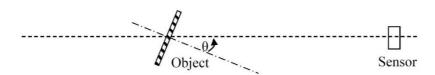
## **EN2532 Robot Design and Competition Laboratory Sheet-Practical No: 4**

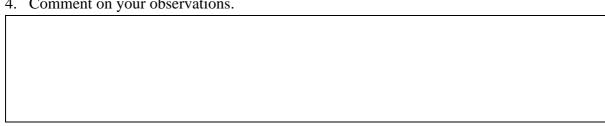
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Name:	 Group No:	

1.	Comment on your observations of the sensor readings and how you can obtain the distance value according to the particular reading.

- 2. Place objects of different size at the same distance from the sensor and identify the minimum dimensions of the object that is detected by the sensor.
- 3. Place a cardboard sheet at a fixed distance with different ultrasound wave incident angles ( $\theta$ ) with the sensor and observe the measurement. Vary  $\theta$  from  $0^0$  to  $70^0$  at steps of  $10^0$ .



4. Comment on your observations.



5. Place an object with minimum detectable dimensions. Then vary the angle from  $60^{\circ}$  to  $0^{\circ}$ in steps of 10<sup>0</sup> and obtain the maximum object detectable distance of the sensor for each angle and plot them in the given graph below,

