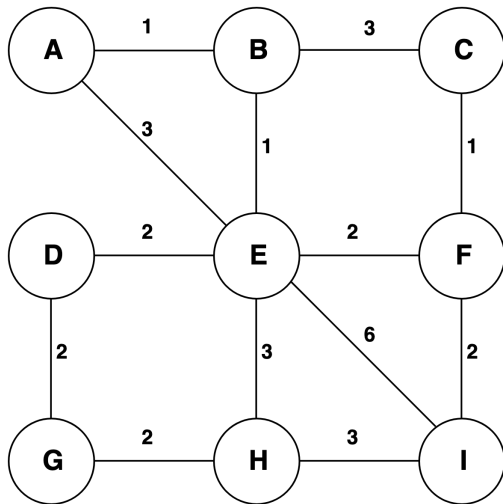


# INTRODUCTION TO ARTIFICIAL INTELLIGENCE

## Lab 7 – A star

- 1) **A star algorithm:** Find the shortest path between nodes A (source) and I (target) in the non-directed graph. The distance (cost) between two nodes is written next to the edge connecting these nodes. For each iteration, complete the table containing the G and F values for nodes. Then write the current list of visited nodes (closed set) and unvisited (open set) nodes.



	A	B	C	D	E	F	G	H	I
H	8	7	6	5	4	3	2	1	0

### I iteration:

Current node: A

Previous node: -

Closed set:

Open set:

Node				
G				
F				

### II iteration:

Current node:

Previous node:

Closed set:

Open set:

Node	A	B	E				
G	0	1	3				
F	8	8	7				

### III iteration:

Current node:

Previous node:

Closed set:

Open set:

Node	A	B	D	E	F	H		
G	0	1	5	3	5	6		
F	8	8	10	7	8	7		

### IV iteration:

Current node:

Previous node:

Closed set:

Open set:

Node	A	B	D	F	G	H	I		
G	0	1	5	5	8	6	9		
F	8	8	10	8	10	7	9		

### V iteration:

Current node:

Previous node:

Closed set:

Open set:

Node	A	B	C	E	G				
G	0	1	4	2	8				
F	8	8	10	6	10				

### VI iteration:

Current node:

Previous node:

Closed set:

Open set:

Node	A	B	C	D	E	F	H		
G	0	1	4	4	2	4	5		
F	8	8	10	9	6	7	6		

### VII iteration:

Current node:

Previous node:

Closed set:

Open set:

Node	A	B	D	E	F	G	H		
G	0	1	4	2	4	7	5		
F	8	8	9	6	7	9	6		

### VII iteration:

Current node:

Previous node:

Closed set:

Open set:

**Shortest path A-I:**