

# Supervisor meeting

Wednesday, 21st of September 2016

## Modeling

- The model looks fine for now, however we might discover some signerrors when we start doing control.
- Drag force:  $D = \frac{1}{2}\rho AV^2 C_D$ , look it up on Wiki.
- The drag is easy to model, just put it in with a negative sign in the velocity direction.

## Communication

- We can use an acknowledge-based communication, reason: Educational.
- We will send position and angle information through the network.

## Miscellaneous

- Write down details on the scope of the project.
- Get a blue box to keep stuff in the Vicon room.

## Next Supervisor Meeting

Wednesdays, 28th of September at 10.00