

Practical work 2

```
In [1]: #Requirements
!pip install pythonds
```

Requirement already satisfied: pythonds in c:\users\jehanne\anaconda3\lib\site-packages (1.2.1)

WARNING: Ignoring invalid distribution -umpy (c:\users\jehanne\anaconda3\lib\site-packages)

WARNING: Ignoring invalid distribution -umpy (c:\users\jehanne\anaconda3\lib\site-packages)

```
In [2]: from pythonds import *
```

Task 1 : Decimal to hexadecimal with Stack

```
In [3]: #First function
s=Stack()

def fun(decimal): #Converts decimal values to hexadecimal ones using stacks
    if decimal==0 : return "0"

    L = ["A", "B", "C", "D", "E", "F"]
    result = Stack()
    remainder = 0
    newdec = 0

    while True:
        newdec = decimal//16
        remainder = decimal%16
        if remainder ==0 and decimal<16: #we've reached the end of the loop
            break

        if remainder>9 : #above 9, we use number
            remainder = L[remainder-10]

        result.push(remainder)
        decimal = newdec

    strres = ""
    while not result.isEmpty(): #at the end of the loop, we pop out the results
        strres = strres + str(result.pop())
    return strres
```

```
In [4]: #Test of the function
for k in range(0,64):
    print(str(k) + " : " +fun(k))
```

0 : 0
1 : 1
2 : 2
3 : 3
4 : 4
5 : 5
6 : 6
7 : 7
8 : 8
9 : 9
10 : A
11 : B
12 : C
13 : D
14 : E
15 : F
16 : 10
17 : 11
18 : 12
19 : 13
20 : 14
21 : 15
22 : 16
23 : 17
24 : 18
25 : 19
26 : 1A
27 : 1B
28 : 1C
29 : 1D
30 : 1E
31 : 1F
32 : 20
33 : 21
34 : 22
35 : 23
36 : 24
37 : 25
38 : 26
39 : 27
40 : 28
41 : 29
42 : 2A
43 : 2B
44 : 2C
45 : 2D
46 : 2E
47 : 2F
48 : 30
49 : 31
50 : 32
51 : 33
52 : 34
53 : 35
54 : 36
55 : 37

```
56 : 38
57 : 39
58 : 3A
59 : 3B
60 : 3C
61 : 3D
62 : 3E
63 : 3F
```

Task 2 : Brackets match with Stacks

```
In [5]: def bracketsCheck(input): #Functions that takes a string in input and uses Stacks
        #to verifies if all brackets are complete
        firstBrackets = Stack()
        brackets = "<({[>])]"

        for k in input:
            if k in brackets :

                if not firstBrackets.isEmpty():
                    last = firstBrackets.peek() #verifies the last brackets seen before
                    if match1(last, k):
                        firstBrackets.pop() #if it's a match, we move on
                    else:
                        firstBrackets.push(k) #if it's not, we had it to the stack
                else :
                    firstBrackets.push(k)
        return firstBrackets.isEmpty()

def match1(one, two): #For two brackets in input, match1 verifies whether they
    #match or not
    brackets1 = "<({["
    brackets2 = ">)]}"
    for k in range(len(brackets1)):
        if (brackets1[k]==one and brackets2[k]==two) or (brackets2[k]==one and \
            brackets1[k]==two):
            return True
    return False
```

```
In [6]: test_cases = [
        "(input[<>])",
        "((()))",
        "{[()]}",
        "[{(<)}]",
        "{[<>]}",
        "([[]])",
        "(([])]",
        "{<[()]>}",
        "([]]",
        "abc",
    ]
```

```

for test_case in test_cases:
    result = bracketsCheck(test_case)
    print(f"bracketsCheck('{test_case}') = {result}")

```

```

bracketsCheck('(input[<>])') = True
bracketsCheck('(((( )))') = True
bracketsCheck('{[()]}' ) = True
bracketsCheck('{(< >)}') = False
bracketsCheck('{[<>]}') = True
bracketsCheck('([[]])') = True
bracketsCheck('((()))') = False
bracketsCheck('{<[()]>') = False
bracketsCheck('([])') = False
bracketsCheck('abc') = True

```

Task 3 : Dijkstra's algorithm

```

In [7]: #We're going to read it like :
#Graph :
#[[distance from node 1 to node 1 = 0, from 1 to 2 = 3, from 1 to
#3 = 0 (=no links between 1 and 3), from 1 to 4 : 7],
#[from 2 to 1 = 3, from 2 to 2 = 0, from 2 to 3 = 1, from 2 to 4 =0],
#[3 to 1 =0, 3 to 2 = 1, 3 to 3 = 0, 3 to 4 = 2],
#[4 to 1 = 7, 4 to 2 = 0, 4 to 3=2,, 4 to 4 = 0]]
# so :
# [[0, 3, 0, 7],
#  [3, 0, 1, 0],
#  [0, 1, 0, 2],
#  [7, 0, 2, 0]]

#Requirements
import networkx as nx #to draw the graphs
import numpy as np

class Graph: #As defined in the comment above
    def __init__(self, vertex):
        self.nbVertex = vertex
        self.vertex = [[0 for column in range(vertex)] for row in range(vertex)]
        self.distanceFromSource = [np.inf for column in range(vertex)]
            #calculated distance from the source
        self.visited = [False for column in range(vertex)]
            #whether a node has been visited yet or not

    def listNeighbour(self, node): #list all nodes neighbour to the one of entry
        res = []
        n=0
        for others in self.vertex[node]:
            if others!=0:
                res.append(n)
            n=n+1
        return res

    def resetVisited(self):#self-explanatory

```

```

for u in range(self.nbVertex):
    self.visited[u]=False

def updateDistanceTable(self, node): #update the distance from the source
    #of all nodes neighbour to the one of entry
    for otherNodes in self.listNeighbour(node):
        if self.distanceFromSource[otherNodes]>self.distanceFromSource[node]\
        +self.vertex[node][otherNodes]:
            self.distanceFromSource[otherNodes]=self.distanceFromSource[node]\
            +self.vertex[node][otherNodes]

def nextNodeToVisit(self): #looks for unvisited node with the smallest
    #distance from the source. Also marks it as visited.
    minDist = np.inf
    res = None
    for nodes in range(self.nbVertex):
        if self.visited[nodes]==False and self.distanceFromSource[nodes]<minDist:
            minDist = self.distanceFromSource[nodes]
            res = nodes
    if res!=None :
        self.visited[res]=True
        return res
    return False

```

```

def dijkstra(self, source): #the algorithm

    self.distanceFromSource[source]=0 #we start at the source
    self.visited[source]=True
    self.updateDistanceTable(source) #input all distances from the source
    nextNode = self.nextNodeToVisit() #find the next node to use
    #(smallest distance from the source)
    while nextNode!=False: #while there are other nodes to visit
        self.updateDistanceTable(nextNode) #we update the distance
        #from the source if we find better
        nextNode = self.nextNodeToVisit() #then look for another node to visit
    return self.distanceFromSource #returns all the distances from the source
    #to the n^th node

```

#Let's test it quickly with an example :

```

G = Graph(9)
G.vertex = [
    [0, 5, 0, 0, 0, 0, 0, 18, 0],
    [5, 0, 4, 0, 0, 0, 0, 6, 0],
    [0, 4, 0, 12, 0, 5, 0, 0, 1],
    [0, 0, 12, 0, 7, 4, 0, 0, 0],
    [0, 0, 0, 7, 0, 10, 0, 0, 0],
    [0, 0, 5, 4, 10, 0, 3, 0, 0],
    [0, 0, 0, 0, 0, 3, 0, 11, 16],
    [18, 6, 0, 0, 0, 0, 11, 0, 2],
    [0, 0, 1, 0, 0, 0, 16, 2, 0]]

```

```
print(G.dijkstra(0))
```

```
[0, 5, 9, 18, 24, 14, 17, 11, 10]
```

```
In [8]: #plotting :
import matplotlib.pyplot as plt
import networkx as nx

def generateNodeName(nbNodes, node): #generate the name of a node
    #based on the total nb of nodes and which node is being named
    alphabet="abcdefghijklmnopqrstuvwxyz" #it goes a,b,c,d etc if the nb
    #of node is <=26, it goes a1, b1...a2, b2 etc if not.
    if nbNodes<=26:
        return alphabet[node]
    return alphabet[node%26]+str(node//26)

def generateGraph(graph, title):#generate a visual graph based
    #on the format of my class Graph
    G1 = nx.Graph() #building the graph
    for i in range(graph.nbVertex):
        for j in range(graph.nbVertex):
            if graph.vertex[i][j]!=0:
                G1.add_edge(generateNodeName(graph.nbVertex, i),\
                    generateNodeName(graph.nbVertex, j), weight=graph.vertex[i][j])

    pos = nx.planar_layout(G1) # positions for all nodes, seed for reproducibility

    # nodes
    nx.draw_networkx_nodes(G1, pos, node_size=700)

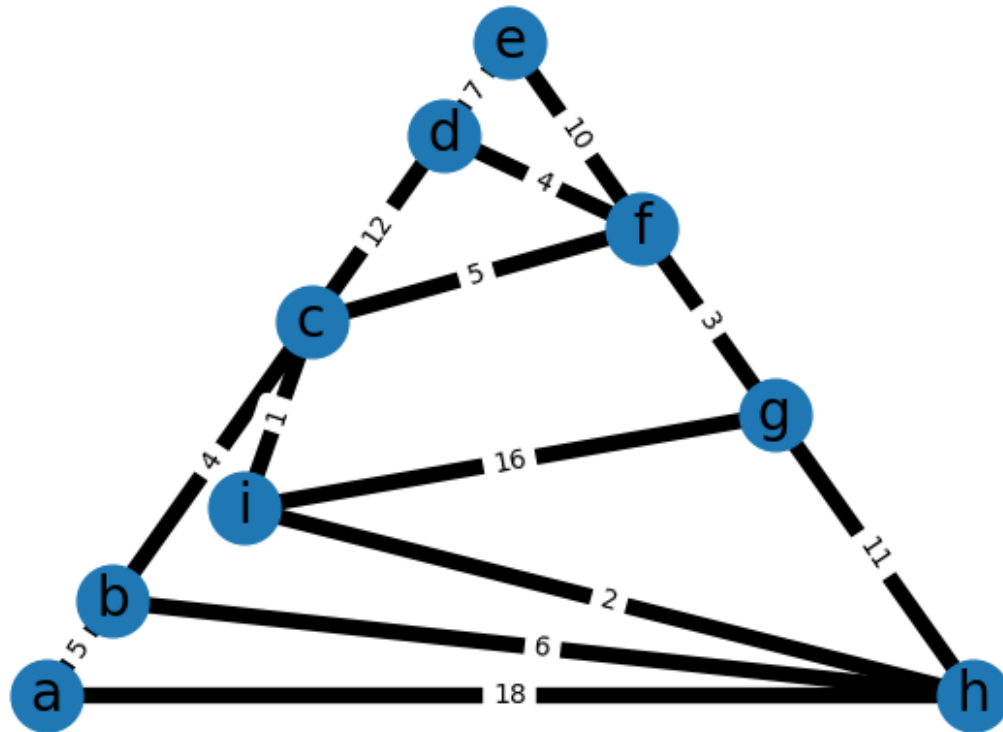
    # edges
    nx.draw_networkx_edges(G1, pos, width=6)

    # node labels
    nx.draw_networkx_labels(G1, pos, font_size=20, font_family="sans-serif")
    # edge weight labels
    edge_labels = nx.get_edge_attributes(G1, "weight")
    nx.draw_networkx_edge_labels(G1, pos, edge_labels)

    ax = plt.gca()
    ax.margins(0.08)
    plt.axis("off")
    plt.title(title)
    plt.tight_layout()
    plt.show()

#using the previous example :
generateGraph(G, "Example")
```

Example



In [9]: *#Now Let's do it for the figure seen in class :*

#Implementation :

```
fig1 = [[0, 2, 5, 1, 0, 0],
        [2, 0, 3, 2, 0, 0],
        [5, 3, 0, 3, 1, 5],
        [1, 2, 3, 0, 1, 0],
        [0, 0, 1, 1, 0, 1],
        [0, 0, 5, 0, 1, 0]]
```

```
G1 = Graph(len(fig1))
```

```
G1.vertex = fig1
```

```
fig2 = [[0, 3, 0, 0, 1, 6],
        [3, 0, 4, 0, 1, 0],
        [0, 4, 0, 9, 0, 0],
        [0, 0, 9, 0, 1, 0],
        [1, 1, 0, 1, 0, 2],
        [6, 0, 0, 0, 2, 0]]
```

```
G2 = Graph(len(fig2))
```

```
G2.vertex = fig2
```

```
fig3 = [[0, 3, 0, 0, 0, 0, 0, 0, 0],
        [3, 0, 0, 0, 0, 0, 0, 0, 0],
        [0, 0, 0, 3, 2, 0, 0, 0, 0],
        [0, 0, 0, 0, 0, 1, 2, 0, 0],
        [4, 0, 0, 0, 0, 0, 1, 0, 0],
        [0, 5, 0, 1, 0, 0, 0, 0, 4],
        [0, 0, 0, 0, 0, 0, 0, 0, 1],
```

```

        [0, 0, 0, 0, 0, 4, 0, 0]]
G3 = Graph(len(fig3))
G3.vertex = fig3

fig4 = [[0, 2, 3, 0, 0, 0, 0],
        [2, 0, 1, 1, 4, 0, 0],
        [3, 1, 0, 0, 0, 5, 0],
        [0, 1, 0, 0, 1, 0, 0],
        [0, 4, 0, 1, 0, 1, 0],
        [0, 0, 5, 0, 1, 0, 1],
        [0, 0, 0, 0, 0, 1, 0]]
G4 = Graph(len(fig4))
G4.vertex = fig4

fig5 = [[0, 5, 10, 0],
        [5, 0, 3, 11],
        [10, 3, 0, 2],
        [0, 11, 2, 0]]
G5 = Graph(len(fig5))
G5.vertex = fig5

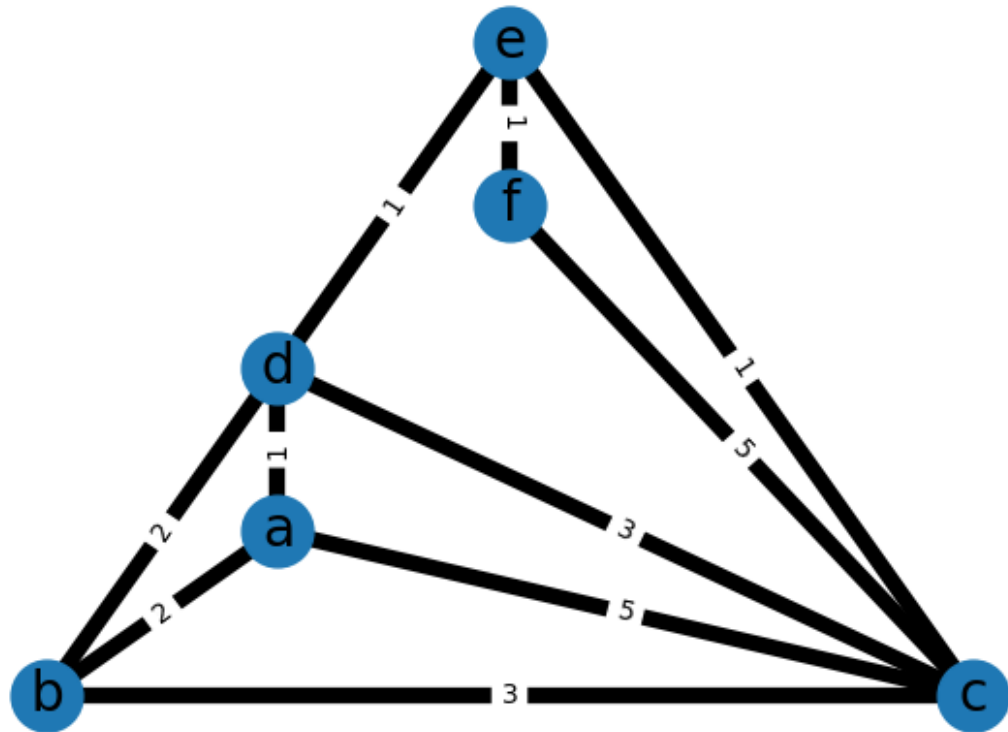
def representation(graph, source, titre):
    print("\n"+ titre + " : ")
    generateGraph(graph, titre)
    print("\nSolution : ")
    print(graph.dijkstra(source))

representation(G1, 0, "Fig1")
representation(G2, 0, "Fig2")
representation(G3, 0, "Fig3")
representation(G4, 0, "Fig4")
representation(G5, 0, "Fig5")

```

Fig1 :

Fig1

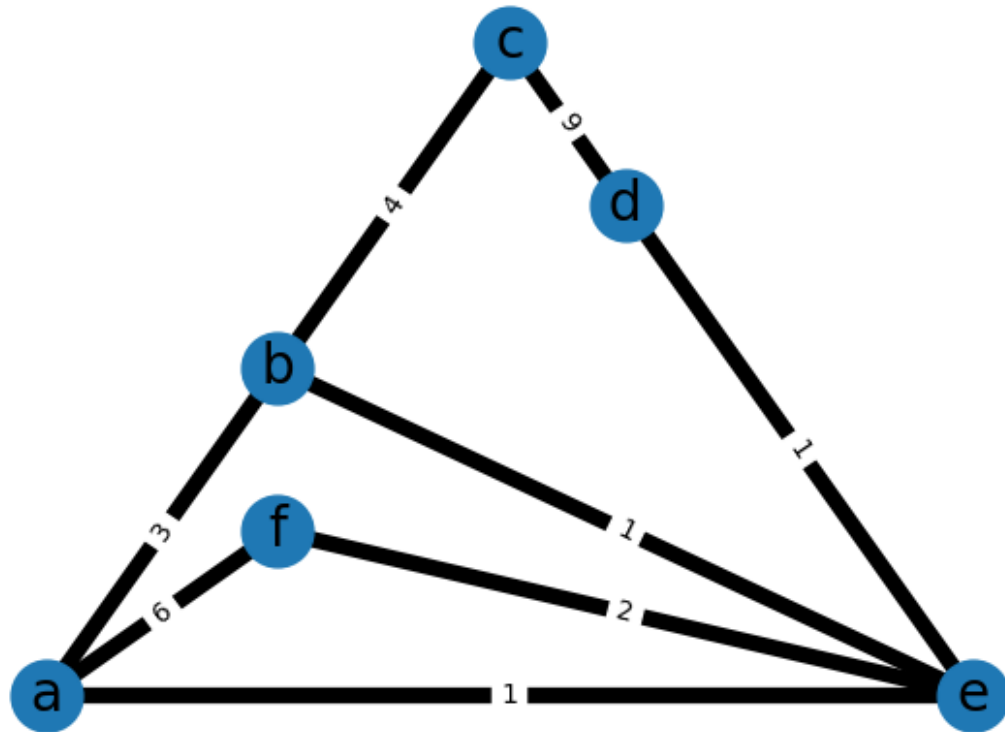


Solution :

[0, 2, 3, 1, 2, 3]

Fig2 :

Fig2

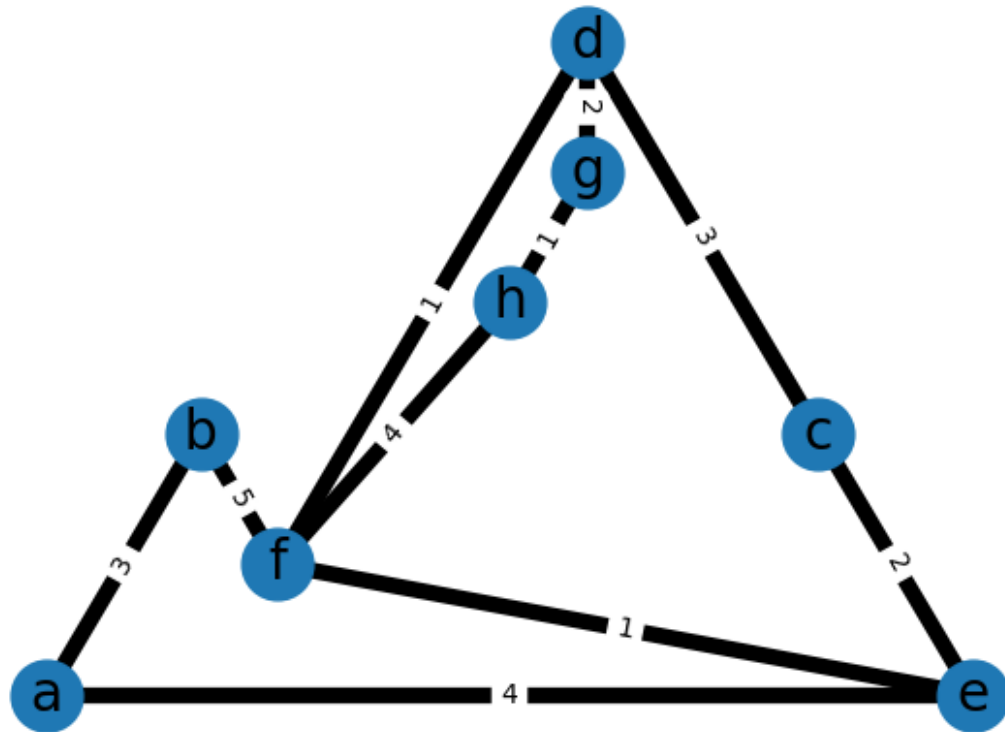


Solution :

[0, 2, 6, 2, 1, 3]

Fig3 :

Fig3

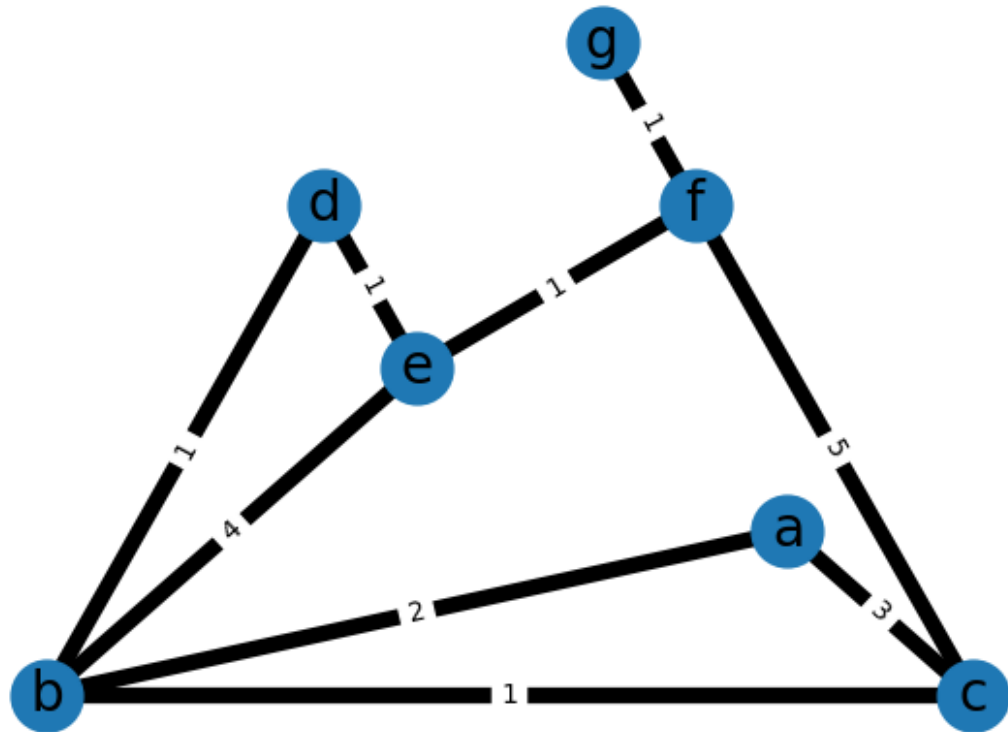


Solution :

[0, 3, inf, inf, inf, inf, inf, inf]

Fig4 :

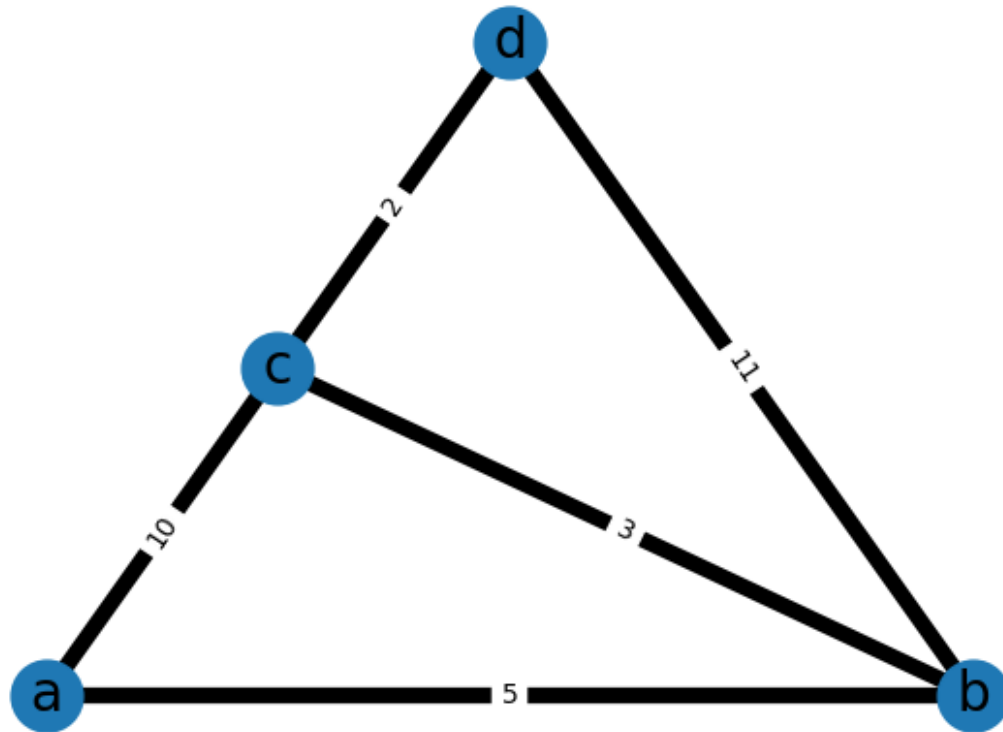
Fig4



Solution :
[0, 2, 3, 3, 4, 5, 6]

Fig5 :

Fig5



Solution :
[0, 5, 8, 10]

Task 4 : Prim's Algorithm

```

In [10]: #NOW for Prim algorithm
import random as rd

#we'll just use the same class Graph as input
def prim(graph, source=None):

    if source==None : #in the algorithm, the start can be chosen randomly.
        #I let the user choose as we are comparing it to Dijkstra.
        source = rd.randint(0, graph.nbVertex)
    graph.visited[source]=True
    origin = source #im not the brightest so i changed the source later

    #initialiation of variables
    table2 = [[np.inf for column in range(graph.nbVertex)] for \
               row in range(graph.nbVertex)]
    seen = []
    mini = np.inf
    n = None

    #finiding the next node
    for node in range(graph.nbVertex):
        table2[source][node] = graph.vertex[source][node]
        if graph.vertex[source][node]<mini and graph.vertex[source][node]!=0:

```

```

        mini = graph.vertex[source][node]
        n = node

#first path taken
seen.append([source, n, mini])
nextNode = n
graph.visited[n] = True

#filling in the table of reference of what's left to explore
for u in range(graph.nbVertex):
    table2[nextNode][u] = graph.vertex[nextNode][u]

while nextNode !=None:

    mini = np.inf
    nextNode = None

    for i in range(graph.nbVertex):
        for j in range(graph.nbVertex):

            if graph.visited[i] and graph.visited[j] and table2[i][j]!=np.inf:
                table2[i][j] = np.inf
            if table2[i][j]!=np.inf and table2[i][j]!=0 and table2[i][j]<mini:

                if not graph.visited[j] :
                    source = i
                    nextNode = j
                    mini = table2[i][j]
                    break
    if nextNode!=None :
        seen.append([source, nextNode, mini])
        graph.visited[nextNode] = True
        for u in range(graph.nbVertex):
            table2[nextNode][u] = graph.vertex[nextNode][u]

#print(seen) #seen is the output : it's a list of the path taken
#in the form of [from node1, to node2, distance node1<->node2]

#now that we have the "shortest" tree we want to calculate
#all distance from the source to the n^th node
#so as to format the answer in the same way as Dijkstra's algorithm :

res = [0 for i in range (graph.nbVertex)] #0 the distance, false whether
#the node as been fully linked to the origin or not yet
node = 0
for step in seen:
    res[step[1]]=res[step[1]]+step[2]+res[step[0]]
    node = node +1

for node in range(graph.nbVertex):
    if res[node]==0 and node!=origin:
        res[node]=np.inf #removing the values that can't be reached
#print(res)
return res

```

```

#first test
G = Graph(9)
G.vertex = [
    [0, 5, 0, 0, 0, 0, 0, 18, 0],
    [5, 0, 4, 0, 0, 0, 0, 6, 0],
    [0, 4, 0, 12, 0, 5, 0, 0, 1],
    [0, 0, 12, 0, 7, 4, 0, 0, 0],
    [0, 0, 0, 7, 0, 10, 0, 0, 0],
    [0, 0, 5, 4, 10, 0, 3, 0, 0],
    [0, 0, 0, 0, 0, 3, 0, 11, 16],
    [18, 6, 0, 0, 0, 0, 11, 0, 2],
    [0, 0, 1, 0, 0, 0, 16, 2, 0]]
prim(G,0)

```

Out[10]: [0, 5, 9, 18, 25, 14, 17, 12, 10]

In [11]: *#Now with the 5 graph we've seen :*

```

G1.resetVisited()
print(prim(G1,0))

G2.resetVisited()
print(prim(G2,0))

G3.resetVisited()
print(prim(G3,0))

G4.resetVisited()
print(prim(G4,0))

G5.resetVisited()
print(prim(G5,0))

```

```

[0, 2, 3, 1, 2, 3]
[0, 2, 6, 2, 1, 3]
[0, 3, inf, inf, inf, inf, inf, inf]
[0, 2, 3, 3, 4, 5, 6]
[0, 5, 8, 10]

```

Comparison of Prim's and Dijkstra's algorithm

In [17]: *#We will now compare Dijkstra's algorithm and Prim alorithm :*

```

import timeit

#Based on their results :
def bestDistance(graphList):
    resDji = 0
    resPri = 0

    for graph in graphList :
        graph.resetVisited()
        resDji = resDji+sum(graph.dijkstra(0))
        graph.resetVisited()
        resPri = resPri+sum(prim(graph,0))

```

```

return "Dijkstra total weight : "+str(resDji)\
      +" - Prim total weight: "+str(resPri)

#Based on their time :
def bestTime(graphList):
    for graph in graphList:
        graph.resetVisited()

    dij_time = timeit.timeit(lambda: [graph.dijkstra(0) for graph in graphList], nu

    for graph in graphList:
        graph.resetVisited()

    pri_time = timeit.timeit(lambda: [prim(graph, 0) for graph in graphList], numbe

    return f"Dijkstra total time: {dij_time:.6f} seconds - Prim total time: {pri_ti

graphList = [G1, G2, G4, G5] #removed G3 bc starting at 0 raise
#infinity and I dont want to make longer functions to handle it
print(bestDistance(graphList))
print(bestTime(graphList))

#When we run, we can see that both Djikstra and Prim have the
#same weight in distance, but Djikstra is slightly faster than Prim

```

Dijkstra total weight : 71 - Prim total weight: 71

Dijkstra total time: 0.000077 seconds - Prim total time: 0.000372 seconds

When we run, we can see that both Djikstra and Prim have the same weight in distance, but
Djikstra is slightly faster than Prim