

Displacement Current

$$I_d = \epsilon_0 \frac{d\phi_E}{dt}$$

→ Faraday's Law of Electromagnetic Induction

First Law: Emf_L is induced due to change in magnetic flux.

$$\Rightarrow e = - \frac{d\phi_B}{dt}$$

Second Law (Lenz's Law): Induced emf opposes the change in magnetic flux.

→ Vector form of Faraday's Law (Differential and Integral).

1. Integral form:

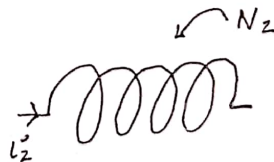
$$\oint \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{S}$$

2. Differential form:

$$\text{curl } \vec{E} = - \frac{d\vec{B}}{dt}$$

$$\vec{\nabla} \times \vec{E} = - \frac{d\vec{B}}{dt}$$

→ Mutual Inductance



$$\therefore N_2 \phi_2 \propto i_1$$

$$N_2 \phi_2 = M i_1$$

$$M = \frac{N_2 \phi_2}{i_1}$$

$$\therefore e_1 = -M \frac{di_2}{dt}$$

Mutual Inductance of a solenoid

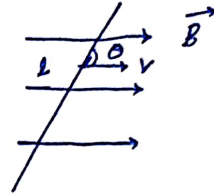
$$M = \mu_0 n_1 n_2 \pi r^2 l$$

\swarrow Length of solenoid
 \searrow radius of solenoid

→ EMF due to movement of a conducting rod

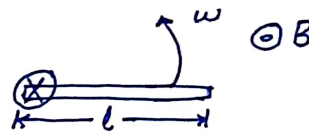
$$\mathcal{E} = B(\vec{v} \times \vec{L})$$

$$\mathcal{E} = B v L \sin \theta$$



→ EMF due to rotation of a conducting rod.

$$\therefore \mathcal{E} = \frac{1}{2} B \omega l^2$$



→ Maxwell's Equation

The divergence and curl relation of electromagnetic fields are called Maxwell Equations.

$$v = l\omega$$

$$\therefore \omega = \frac{v}{l}$$

→ Integral Form

$$1. \oint \vec{E} \cdot d\vec{S} = \frac{q}{\epsilon_0} \quad [\text{Gauss's Law in Electrostatics}]$$

$$2. \oint \vec{B} \cdot d\vec{S} = 0 \quad [\text{Gauss's Law in Magnetostatics}]$$

$$3. \oint \vec{E} \cdot d\vec{l} = - \frac{d\phi_B}{dt} \quad [\text{Faraday's Law of EMI}]$$

$$4. \oint \vec{B} \cdot d\vec{l} = \mu_0 \left(\underbrace{i}_{\text{traditional current}} + \epsilon_0 \frac{d\phi_E}{dt} \right) \quad [\text{Modified Ampere circuital law}]$$

\searrow displacement current

→ Differential Form

$$1. \text{div } \vec{E} = \frac{\rho}{\epsilon_0} \quad \text{or} \quad \text{Div } \vec{D} = \rho$$

$$2. \text{div } \vec{B} = 0$$

$$3. \text{curl } \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$4. \text{curl } \vec{B} = \mu_0 \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) = \mu_0 \left(\vec{J} + \epsilon_0 \frac{d\vec{E}}{dt} \right)$$

Maxwell's equation for free space

1. $\vec{\nabla} \cdot \vec{E} = 0$
2. $\vec{\nabla} \cdot \vec{B} = 0$
3. $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$
4. $\vec{\nabla} \times \vec{B} = \mu_0 \epsilon \frac{\partial \vec{E}}{\partial t}$

→ Electromagnetic Wave Equation in medium

$$\nabla^2 \vec{E} - \sigma \mu \frac{\partial \vec{E}}{\partial t} - \epsilon \mu \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

$$\nabla^2 \vec{H} - \sigma \mu \frac{\partial \vec{H}}{\partial t} - \epsilon \mu \frac{\partial^2 \vec{H}}{\partial t^2} = 0$$

→ EMW equation in vacuum

$$\left. \begin{array}{l} \sigma = 0 \\ \epsilon = \epsilon_0 \\ \mu = \mu_0 \end{array} \right\} \text{For vacuum}$$

$$\nabla^2 \vec{E} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

$$\nabla^2 \vec{H} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{H}}{\partial t^2} = 0$$

Above equation can be written as

$$\nabla^2 U - \frac{1}{v^2} \frac{\partial^2 U}{\partial t^2} = 0$$

$$\Rightarrow v = \frac{1}{\sqrt{\epsilon_0 \mu_0}} = 3 \times 10^8 = c$$

and EMW equation will be given as; (for v)

$$\nabla^2 \vec{E} - \frac{1}{c^2} \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

$$\nabla^2 \vec{H} - \frac{1}{c^2} \frac{\partial^2 \vec{H}}{\partial t^2} = 0$$

$$\nabla^2 U - \frac{1}{c^2} \frac{\partial^2 U}{\partial t^2} = 0$$

Poynting Vector

$$\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B})$$

→ Growth of current in LR circuit

$$i = i_0 (1 - e^{-R/Lt})$$

$$\frac{L}{R} = \lambda$$

$$i = i_0 (1 - e^{-t/\lambda})$$

Inductive time constant

$\lambda \rightarrow$ time that current takes to grow from 0 to 63%

→ Decay of current

$$i = i_0 e^{-R/Lt}$$

$$\frac{L}{R} = \lambda$$

$$i = i_0 e^{-t/\lambda}$$

$\lambda \rightarrow$ time that current takes to decay from 0 to 37%

→ Relation between B_0 and E_0

$$E = Bc$$

$$\therefore E = Bv \rightarrow \text{velocity of wave}$$

$$E = E_0 \sin(\omega t - \beta x)$$

→ Wave propagating in +x direction.

$$V = \frac{1}{\sqrt{\mu_r \epsilon_r}}$$

$$\rightarrow \text{Instantaneous Energy density} = \epsilon_0 \vec{E}^2 = \frac{B^2}{\mu_0}$$

$$\rightarrow \text{Average energy density} = \frac{1}{2} \epsilon_0 \vec{E}^2 = \frac{B^2}{2\mu_0}$$

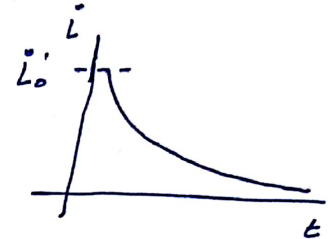
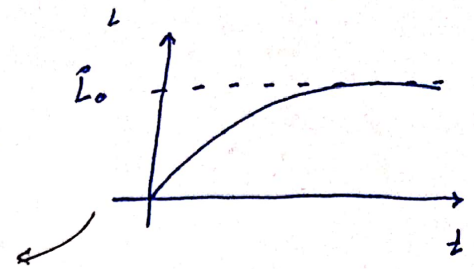
$$\rightarrow \text{Wavelength} : \lambda = \frac{V}{f} \begin{matrix} \text{velocity} \\ \text{(frequency)} \end{matrix} = \frac{2\pi}{\beta} \begin{matrix} \\ \text{(phase constant)} \end{matrix}$$

$$\rightarrow \text{Phase constant } (\beta) = \frac{2\pi}{\lambda}$$

$$\rightarrow \text{Intrinsic Impedance } (\eta) = \eta = \eta_0 \sqrt{\frac{\mu_r}{\epsilon_r}}$$

$$\eta_0 = 333 \Omega \text{ for vacuum}$$

$$\rightarrow \text{Electric Field Intensity } E_0 = \eta H_0$$



These handwritten notes are of PHY-S102 taught to us by Prof. Prabal Pratap Singh, compiled and organized chapter-wise to help our juniors. We hope they make your prep a bit easier.

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