# COSC 3360/6310 Wednesday, February 24



#### **Announcements**



- First assignment is now due on March 3 anywhere on earth
- Second quiz will be on Monday, March 1
  - □ Will cover chapter 2 of class notes
    - Three video lectures
      - □ F. Wednesday February 10
      - □ G. Monday February 22
      - H. Wednesday February 24





#### More announcements

- Some people have not yet accepted the invitations I sent to their UH Mail accounts in January
  - Please check your UH mail account (jsbach@uh.edu)
- Videos of last two lectures are now online
  - □ Had problems with MS Teams default permissions

# Chapter II Processes

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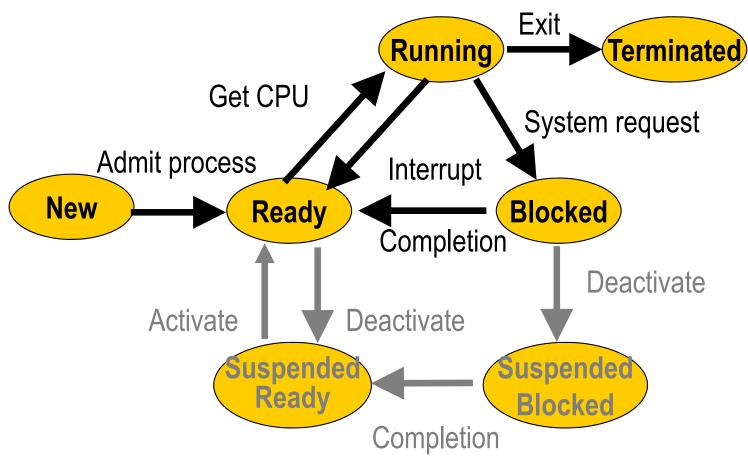
#### **Chapter Overview**



- Processes
- States of a process
- Operations on processes
  - fork(), exec(), kill(), signal()
- Threads and lightweight processes











# Operations on processes

Process creation, deletion, ...



#### Operations on processes



- Process creation
  - □ fork()
  - □ exec()
  - □ The argument vector
- Process deletion
  - □ kill()
  - □ signal()





## What will this program print out?

```
#include <iostream>
using namespace std;
main() {
    if ((pid = fork()) == 0) {
        //child
        cout << "Hello" << endl;
    }
    // parent
    cout << "Goodbye" << endl;
} // main</pre>
```



#### **Answer**



Hello Goodbye Hello

or

Goodbye Hello Goodbye



# Lightweight processes/threads

Kernel supported threads, user-level threads, POSIX threads (pthreads)



#### Limitations of processes

- Single threaded server:
  - □ Processes one request at a time

```
for (;;) {
    receive(&client, request);
    process_request(...);
    send(client, reply);
} // for
```



# A basic question



What does a server do when it does not process client requests?



## Three good answers



- Nothing
- □ It waits for client requests
- □ It "sleeps"
  - Blocked state is sometimes called the sleep state



# The problem



- Most client requests involve disk accesses
  - ☐ File servers
  - Authentications servers
- When this happens, the server remains in the BLOCKED state
  - Cannot handle other customers' requests
- Could end doing nothing most of the time
- Poor throughput





#### An analogy

- In most fast-food restaurants, counter employees process customer orders one order at a time.
- Not be possible in a traditional restaurant
  - □ A server that would only be able to wait on one table at a time would be idle most of the time.





#### A first solution

```
int pid;
for (;;) {
    receive(&client, request);
    if ((pid = fork()) == 0) {
        process_request(...);
        send(client, reply);
        _exit(0); // done
    } // if
} // for
```



# The good and the bad news



- The good news:
  - □ Server can now handle several user requests in parallel
- The bad news:
  - fork() is a very expensive system call
    - Has to create a new address space



#### A better solution



- Provide a faster mechanism for creating cheaper processes:
  - □ Lightweight processes
  - □ Threads



#### How?

- Lightweight processes and threads share the address space of their parent
  - □ No need to create a new address space
    - Most expensive step of fork() system call



### Is it not dangerous?



#### To some extent because

- □ No memory protection inside an address space
- □ Lightweight processes can now interfere with each other

#### But

□ All lightweight process code is written by the same team



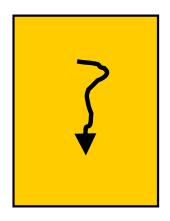
### General Concept (I)

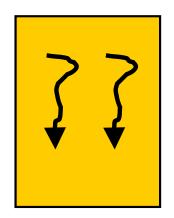
- A thread or lightweight process
  - □ Does *not* have its *own address space*
  - □ Shares it with its parent and other peer threads in the same address space (*task*)
- Each thread has a program counter, a set of registers and its own stack.
  - Everything else is shared



## General Concept (II)







- A regular process (single-threaded)
- A process containing several threads



#### **Implementation**



- Threads and LWPs can either be
  - □ Kernel supported:
    - Mach, Linux, Windows NT and after
  - □ User-level:
    - Original pthread library, ...





## Kernel-Supported Threads (I)

- Managed by the kernel through system calls
- One process table entry per thread
- This is the best solution for multiprocessor architectures
  - □ Kernel can allocate several processors to a single multithreaded task





### Kernel-Supported Threads (II)

- Supported by Mach, Linux, Windows NT and more recent systems
- Performance Issue:
  - Switching between two threads in the same task involves a system call
  - Results in two context switches



#### **Linux Threads**

- clone(fn, stack, flags)
  where
  - ☐ **fn** specifies function to be executed by new thread or process
  - □ stack points to the stack it will use
  - ☐ **flags** is a set of flags specifying various options
    - CLONE\_VM for threads
    - Regular process if CLONE\_VM is missing





### User-Level Threads (I)

- User-level threads are managed by procedures within the task address space
  - ☐ The *thread library*
- One process table entry per task/address space
  - Kernel is not even aware that process is multithreaded



#### User-Level Threads (II)



- Can be retrofitted into an OS lacking thread support
  - Portable thread libraries

#### No performance penalty:

- Switching between two threads of the same task is done cheaply within the task
- □ Same cost as a procedure call



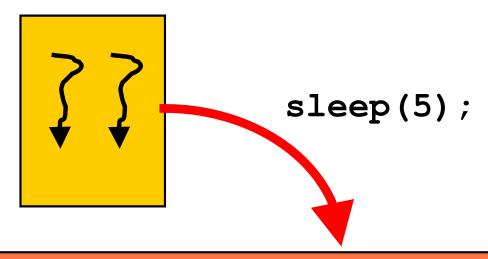
# User-Level Threads (III)



- Programming issue:
  - □ Each time a thread does a blocking system call, kernel will move the whole process to the blocked state
    - It does not know better
  - Must then use non-blocking system calls
    - Complicates programmer's task







#### **Kernel**

Process wants to sleep for 5 seconds: Should be moved it to the blocked state



#### **POSIX Threads**

- POSIX threads, or *pthreads*, started as pure user-level threads managed by the POSIX thread library
  - ☐ Gained later *some kernel support*
- Ported to various Unix and Windows systems (*Pthreads-win32*).
- Function names start with pthread\_
- Calls tend to have a complex syntax





```
#include <pthread.h>
static int count[2];
```

Static variables are shared by all threads

Other variables are stored on the private stack of each thread.







```
void *child(void *arg) {
    int index;
    index = (int) arg; // required
    for(;;) {
        printf("Child count: %d\n",
             ++count[index]);
      sleep(1); // one second delay
     } // for loop
} // child
```

### An Example (III)



**NULL stack address specifies** a new stack "anywhere"





```
i++; // now i == 1
  while (count[i] < 12) {
     printf("Parent count: %d\n", ++count[i]);
     sleep(1); // one second delay
  } // while loop
  return 0;
} // main</pre>
```



- pthread\_create() has four arguments
  - □ &tid
    - Placeholder for thread\_id
  - NULL
    - Stack address of new stack
    - NULL means "anywhere"
  - □ start\_function
    - Void pointer to a function
  - □ (void \*) arg
    - Sole argument passed to start\_function







Feature	Kernel threads	User-level threads
Portability		
Multiprocessing		
Performance		
Ease of use		





Feature	Kernel threads	User-level threads
Portability		
Multiprocessing		
Overhead		
Ease of use		





Feature	Kernel threads	User-level threads
Portability		
Multiprocessing	V	
Overhead		
Ease of use		





Feature	Kernel threads	User-level threads
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Feature	Kernel threads	User-level threads
Portability		
Multiprocessing	V	
Overhead		$\overline{\mathbf{V}}$
Ease of use	$\overline{\mathbf{A}}$	





#### Conclusion

- No clear winner between kernel-supported and user-level threads
- Solaris (from Sun, now taken over by Oracle)
  - ☐ Supports both *user-level threads* and *kernel threads*
  - □ Lets programmers combine them as they need