## COSC 3360/6310 Monday, January 25



#### Announcements

- The first assignment is online
  - Folder First assignment of Assignments Channel on Teams
  - Sub-folder Files of Resources folder on Prulu
- **Explanations** will come on Wednesday
- Watch for sample inputs and outputs all by next Monday

# The four missions (continued)



#### Functions of an OS

- Four basic functions
  - ☐ To provide a better user interface
  - □ To manage the system resources
  - To protect users' programs and data
  - To let programs exchange information



#### Managing system resources

- Focus of the remainder of the course
- Not an easy task
  - □ Enormous gap between CPU speeds and disk access times

## The memory hierarchy (I)

Level	Device	Access Time
1	Fastest registers (2 GHz)	0.5 ns
2	Main memory	10-70 ns
3	Secondary storage (flash)	35-100 μs
4	Secondary storage (disk)	3-12 ms
5	Mass storage (off line)	a few s



## The memory hierarchy (II)

■ To make sense of these numbers, let us consider an analogy



Level	Resource	Access Time
1	Open book on desk	1 s
2	Book on desk	
3	Book in UH library	
4	Book in another library	
5	Book very far away	



Level	Resource	Access Time
1	Open book on desk	1s
2	Book on desk	20-140 s
3	Book in UH library	
4	Book in another library	
5	Book very far away	

## Writing a paper (II)

Level	Resource	Access Time
1	Open book on desk	1s
2	Book on desk	20-140s
3	Book in UH library	20-55h
4	Book in another library	
5	Book very far away	

## Writing a paper (III)

Level	Resource	Access Time
1	Open book on desk	1 s
2	Book on desk	20-140 s
3	Book in UH library	20-55 h
4	Book in another library	70-277 days
5	Book very far away	

## Writing a paper (V)

Level	Resource	Access Time
1	Open book on desk	1 s
2	Book on desk	20s-140 s
3	Book in UH library	20-55 h
4	Book in another library	70-277 days
5	Book very far away	> 63 years



#### Will the problem go away?

- New storage technologies
  - □ Cheaper than main memory
  - ☐ Faster than disk drives
- Flash drives
- Optane memory



#### Flash drives

- Offspring of EEPROM memories
- Fast reads
  - □ Block-level
- Slower writes
  - Whole page of data must be erased then rewritten
- Can only go through a finite number of program /erase cycles



#### Optane memory (I)

- Byte-addressable non-volatile memory (BNVM)
- Simpler design
  - ☐ Bits are stored as resistivity levels of a secret alloy
  - No transistors (≠ SRAM and DRAM)
- Faster than flash
  - □ 100-300 ns



#### Optane memory (II)

- Now
  - Non-volatile RAM
  - □ Disk cache
- In a few years
  - □ Could replace flash (phones, laptops, ...)
  - ☐ Flash could replace disks (disk farms)
  - □ Disks could replace slower devices
  - □Will require a *redesign* of file system



#### Optimizing disk accesses

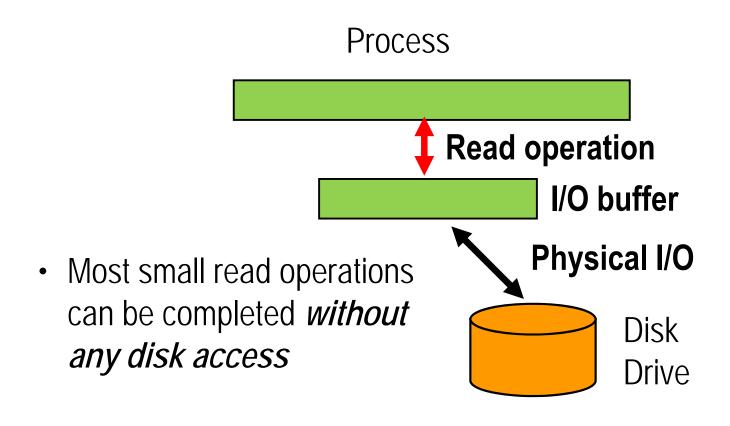
- Two main techniques
  - Making disk accesses more efficient
  - □ Doing something else while waiting for an I/O operation
- Not very different from what we are doing in our every day's lives



## Optimizing read accesses (I)

- When we shop in a market that's far away from our home, we plan ahead and buy food for several days
- The OS will read as many bytes as it can during each disk access
  - In practice, entire blocks (4KB or more)
  - Blocks are stored in the I/O buffer

## Optimizing read accesses (II)





#### Optimizing read accesses (III)

- Buffered reads work quite well
  - ☐ Most systems use it
- Major limitation
  - □ Cannot read *too much ahead* of the program
    - Could end bringing into main memory data that would never be used



#### Optimizing read accesses (IV)

- Can also keep in a buffer recently accessed blocks hoping they will be accessed again
  - Caching
- Works very well because we keep accessing again and again the data we are working with
- Caching is a fundamental technique of OS and database design



## Optimizing write accesses (I)

- If we live far away from a library, we wait until we have several books to return before making the trip
- The OS will delay writes for a few seconds then write an entire block
  - □ Since most writes are sequential, most small writes will not require any disk access



## Optimizing write accesses (II)

- Delayed writes work quite well
  - Most systems use it
- Major drawback
  - □ We will *lose data* if the system or the program crashes
    - After the program issued a write but
    - Before the data were saved to disk
  - □ Unless we use NVRAM



#### Doing something else

- When we order something on the web, we do not remain idle until the goods are delivered
- The OS can implement multiprogramming and let the CPU run another program while a program waits for an I/O



## Advantages (I)

- Multiprogramming is very important in business applications
  - Many of these applications use the peripherals much more than the CPU
  - □ For a long time the CPU was the most expensive component of a computer
  - □ *Multiprogramming* was invented to keep the CPU busy



## Advantages (II)

- Multiprogramming made time-sharing possible
- Multiprogramming lets your PC run several applications at the same time
  - MS Word and MS Outlook



## Multiprogramming (I)

- Multiprogramming lets the CPU divide its time among different tasks:
  - One tenth of a second on a program, then another tenth of a second on another one and so forth
- Each core of your CPU will still be working on one single task at any given time



## Multiprogramming (II)

- The CPU does not waste any time waiting for the completion of I/O operations
- From time to time, the OS will need to regain control of the CPU
  - Because a task has exhausted its fair share of the CPU time
  - □ Because something else needs to be done.
- This is done through *interrupts*.



#### Interrupts (I)

- Request to interrupt the flow of execution the CPU
- Detected by the CPU hardware
  - □ *After* it has executed the current instruction
  - □ **Before** it starts the next instruction.



#### A very schematic view (I)

A very basic CPU would execute the following loop:

```
forever {
    fetch_instruction();
    decode_instruction();
    execute_instruction();
}
```

- Pipelining makes things more complicated
  - And CPU much faster!

#### A very schematic view (II)

We add an extra step:

```
forever {
   check_for_interrupts();
   fetch_instruction();
   decode_instruction();
   execute_instruction();
}
```



#### Interrupts (II)

- When an interrupt occurs:
  - a. The current state of the CPU (program counter, program status word, contents of registers, and so forth) is saved, normally on the top of a stack
  - b. A *new CPU state* is fetched



#### Interrupts (III)

- New state includes a new hardware-defined value for the program counter
  - Cannot "hijack" interrupts
- Process is totally transparent to the task being interrupted
  - □ A process *never* knows whether it has been interrupted or not



#### Types of interrupts (I)

#### I/O completion interrupts

□ Notify the OS that an I/O operation has completed,

#### Timer interrupts

Notify the OS that a task has exceeded its quantum of core time



#### Types of interrupts (II)

#### Traps

□ Notify the OS of a *program error* (division by zero, illegal opcode, illegal operand address, ...) or a *hardware failure* 

#### System calls

Notify OS that the running task wants to submit a request to the OS



## A surprising discovery

Programs do interrupt themselves!



#### Context switches

- Each interrupt will result into two context switches:
  - □ One when the running task is interrupted
  - Another when it regains the CPU
- Context switches are not cheap
- The overhead of any simple system call is two context switches

Remember that!



## Prioritizing interrupts (I)

- Interrupt requests may occur while the system is processing another interrupt
- All interrupts are not equally urgent (as it is also in real life)
  - □ Some are more urgent than other
  - □ Also true in real life



## Prioritizing interrupts (II)

- The best solution is to prioritize interrupts and assign to each source of interrupts a priority level
  - New interrupt requests will be allowed to interrupt lower-priority interrupts but will have to wait for the completion of all other interrupts
- Solution is known as vectorized interrupts.



#### Example from real life

- Let us try to prioritize
  - □ Phone is ringing
  - Washer signals end of cycle
  - □ Dark smoke is coming out of the kitchen
  - ...
- With vectorized interrupts, a phone call will never interrupt another phone call



#### The solution

Smoke in the kitchen

Phone is ringing

End of washer cycle

More low-priority stuff



#### Disabling Interrupts

- We can *disable* interrupts
- OS does it before performing short critical tasks that cannot be interrupted
  - Works only for single-threaded kernels
- User tasks *must* be prevented from doing it
  - □ Too dangerous



#### **DMA**

- Disk I/O poses a special problem
  - □ CPU will have to transfer large quantities of data between the disk controller's buffer and the main memory
- Direct memory access (DMA) allows the disk controller to read data from and write data to main memory without any CPU intervention
  - Controller "steals" memory cycles from CPU