



# Astro-Alliance(StarLab)



## RADIO TELESCOPE

### Task for Radio Telescope Team

**Make presentation for objectives**

**Main objectives of our project is :-**

#### 1. Mapping the Night Sky:

- **Planning and Resources:**
  - Use online star charts like Stellarium Web [Stellarium Web Online Star Map] or Sky & Telescope's Interactive Sky Chart [Interactive Sky Chart | Map Your Night Sky - Sky & Telescope] to identify interesting celestial objects (stars, planets, nebulae, etc.) visible from your location based on date and time. These tools will help you plan your observations.
  - Consider getting a good astronomy book or app for further information about objects and their locations.

#### 2. Telescope Control System:

- **Mechanics:**
  - Design a sturdy mount for the telescope dish using metal or strong wood. Ensure it has smooth bearings (e.g., ball bearings) for low-friction movement.
  - Choose gears with appropriate gear ratios to balance between speed and precision of movement. Consider factors like telescope weight, desired pointing accuracy, and motor torque.
  - Select stepper motors for precise positioning control. They offer good holding torque when powered.
- **Motor Selection:**
  - **Torque Calculation:**
    - Measure the total weight (W) of the telescope dish and mount.
    - Determine the maximum distance (D) from the motor shaft's center to the point where the dish connects to the mount (moment arm).
    - Calculate the torque (T) required using the formula:  $T = W * D$
  - **Motor Selection:**
    - Choose stepper motors with a torque rating exceeding the calculated torque to handle the dish's weight and potential wind resistance.
    - Consider factors like motor speed, size, and voltage requirements when selecting.
- **Microcontroller:**

- Use a microcontroller like Arduino or Raspberry Pi to control the stepper motors. These offer good programmability for telescope movement and interfacing with a computer.
- **Joystick Control:**
  - Connect a joystick or gamepad to the microcontroller for user-friendly telescope control.
  - Program the microcontroller to translate joystick movements into motor control signals for smooth pointing adjustments.

### 3. Stand Design:

- Build a sturdy tripod or pier-like stand using metal or strong wood.
- Ensure the stand can handle the weight of the telescope and dish assembly without wobbling.
- Consider adding weights to the base for additional stability, especially in windy conditions.

### 4. Interfacing with PC:

- Connect the microcontroller to your computer using a USB cable.
- Install software libraries that allow your computer to communicate with the microcontroller.
- Develop custom software (or use existing astronomy software) to send movement commands to the telescope control system based on your desired sky map coordinates.

- **Amplifiers:**
  - You might need an amplifier to boost the weak signal from faint celestial objects before capturing an image with your camera.
  - The need for an amplifier depends on the telescope's optics, camera sensitivity, and the specific objects you're observing. Consult your camera and telescope manuals for guidance.
- **Filters:**
  - Light pollution filters can help reduce the impact of streetlights and other light sources, improving the visibility of faint objects.
  - Consider narrowband filters that selectively allow light from specific wavelengths, which can be useful for observing nebulae or emission lines from stars.

**Your task is to read up on radio telescopes to gain a better understanding of the components required for the project.**

**Deadline for the task 21 June 2024**