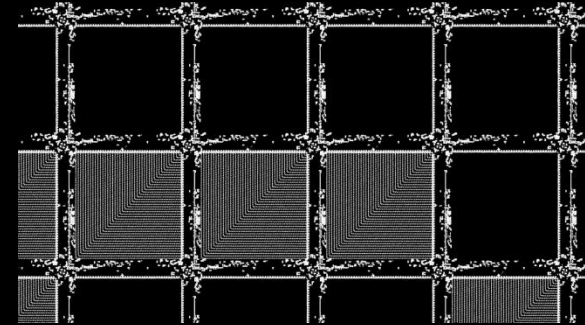
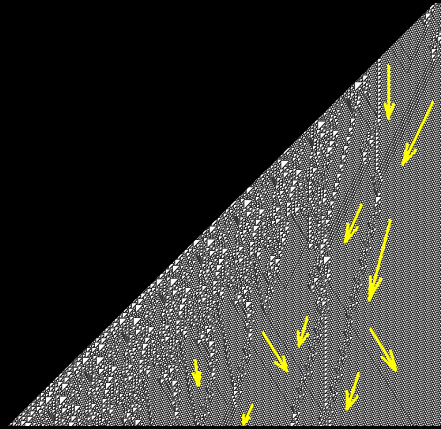


# Computer modeling of physical phenomena



Lecture VIII: LBM

# Cellular automata



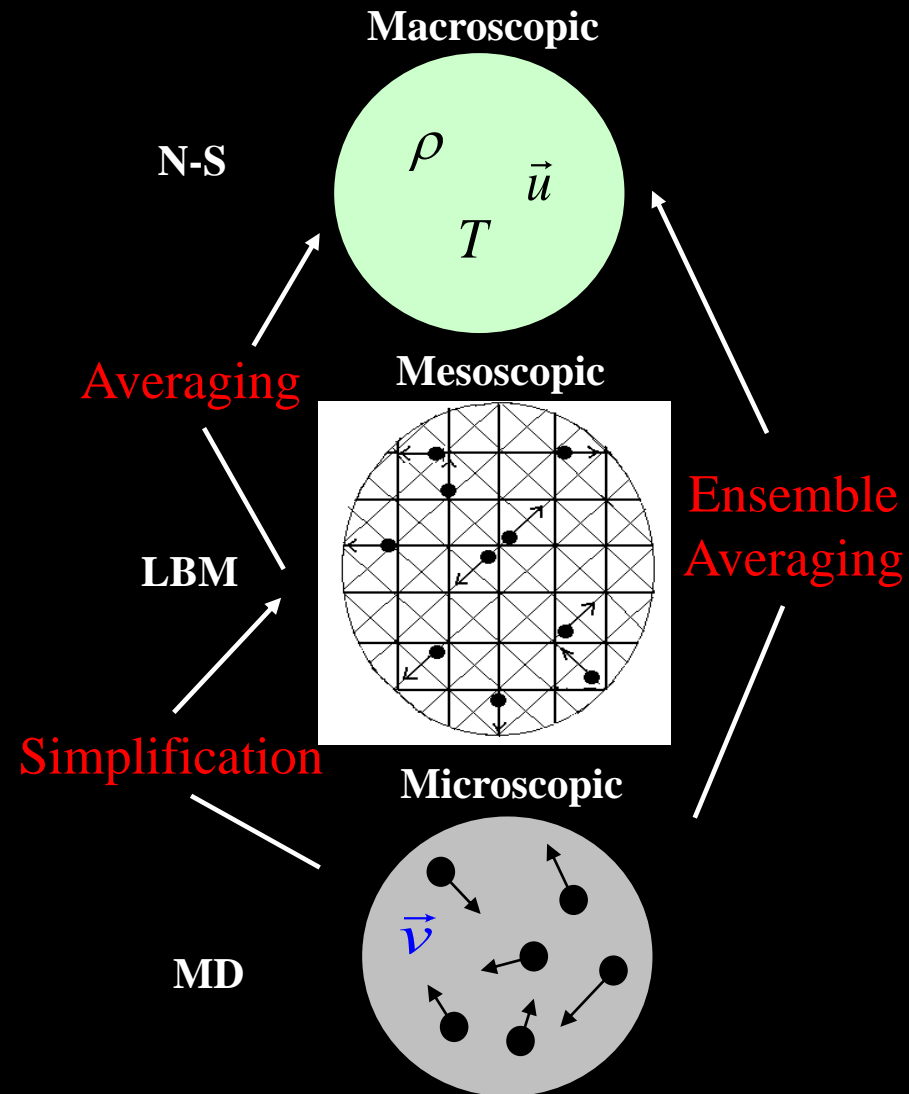
It's all very nice but....

What it has to do with physics?





# Mesosopic approach



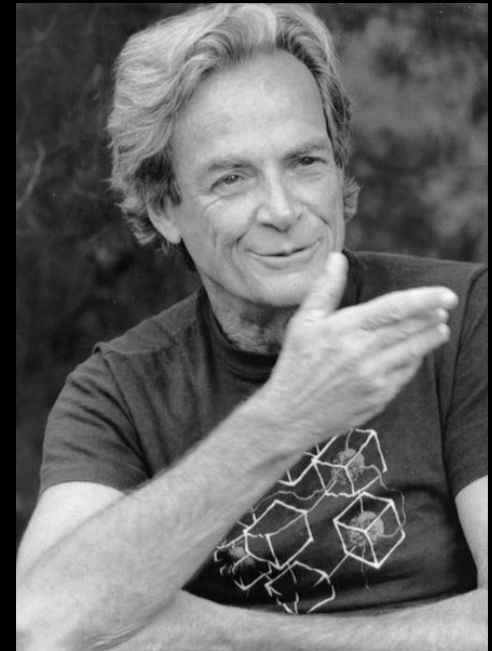
# Lattice-particle methods

**Idea:** Solve fluid equations using fictitious particle dynamics.

**Universality:** Molecular details do not count as long as correct dynamics is recovered in the macroscopic limit.

# Feynman on lattice automata

„We have noticed in nature that the behavior of a fluid depends very little on the nature of the individual particles in that fluid. For example, that flow of sand is very similar to the flow of water...”





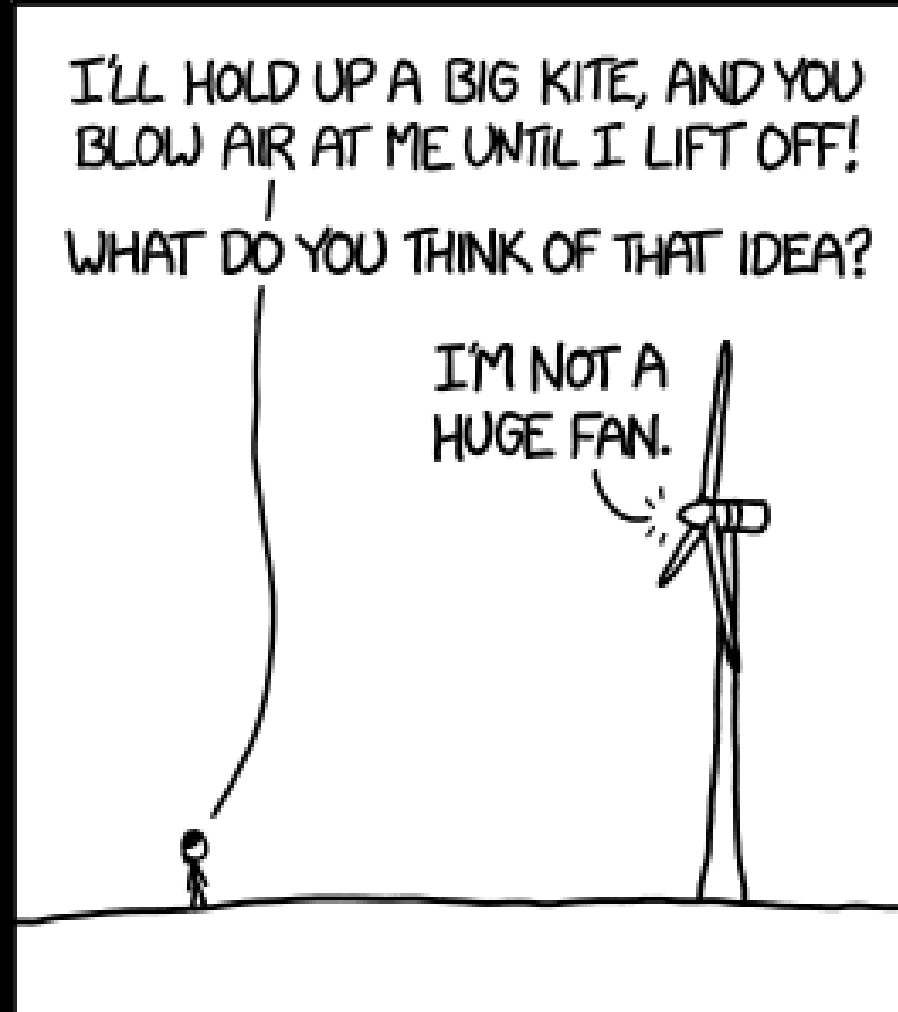
...or the flow of sheep!



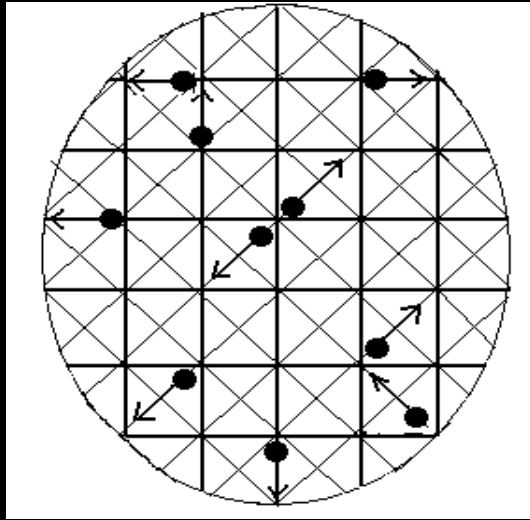




Solving full NS equations may not be a great idea...

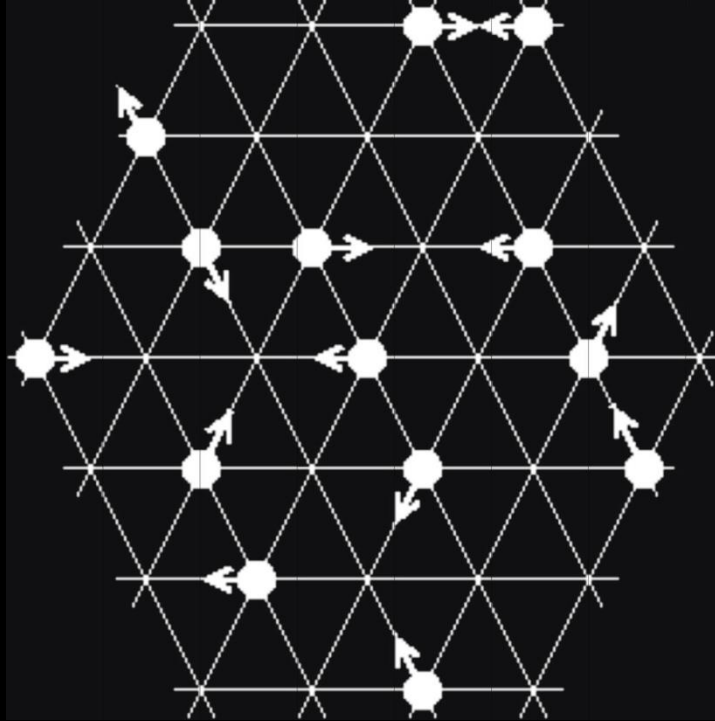


# Be wise, discretize!



Marek Kac, 1914-1984

# Lattice gas automata



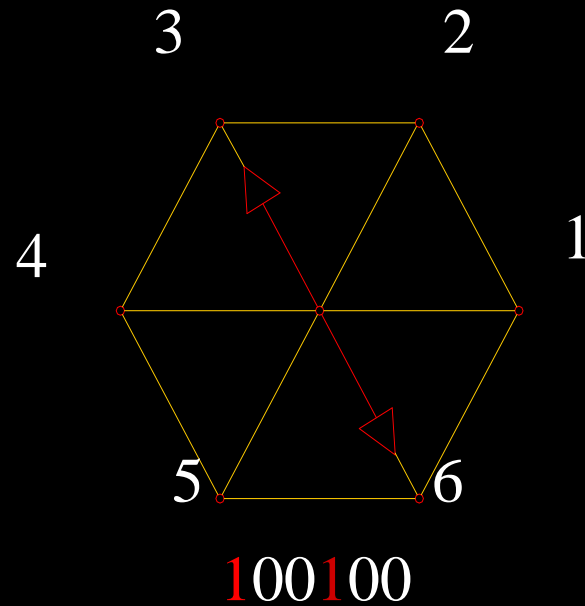
➤ streaming

➤ collisions

- positions restricted to lattice sites
- discrete velocities
- no two particles with the same velocity allowed at one site

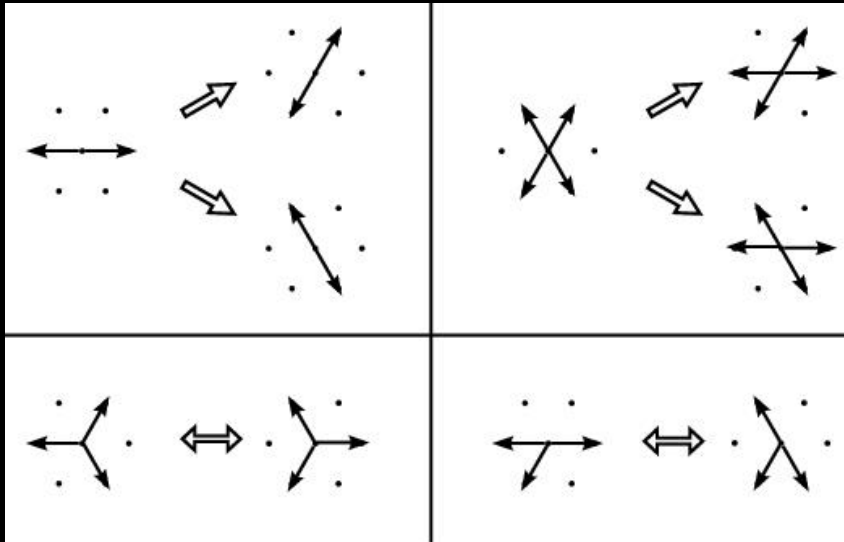
# Boolean representation

$n_i = 0, 1$       particle absence/presence



# Collisions

Collision rules



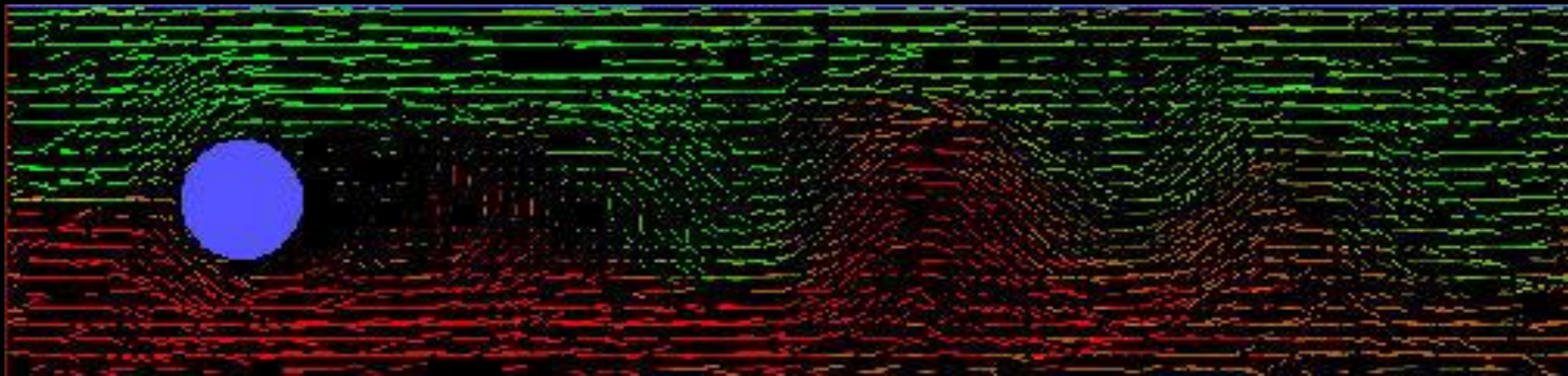
Binary representation

INPUT STATE	OUTPUT STATE
001001	010010 100100
010101	101010
001011	100110
011011	110110 101101

Very simple to implement numerically – **no floating point operations!**



# Von Karman street



(Sauro Succi)

# Pros and cons

## Pros:

- extremely simple to program,
- fast,
- exact, no round-off errors,
- inherently stable.

## Cons:

- noisy,
- viscosity set by collision table (cannot be tuned).

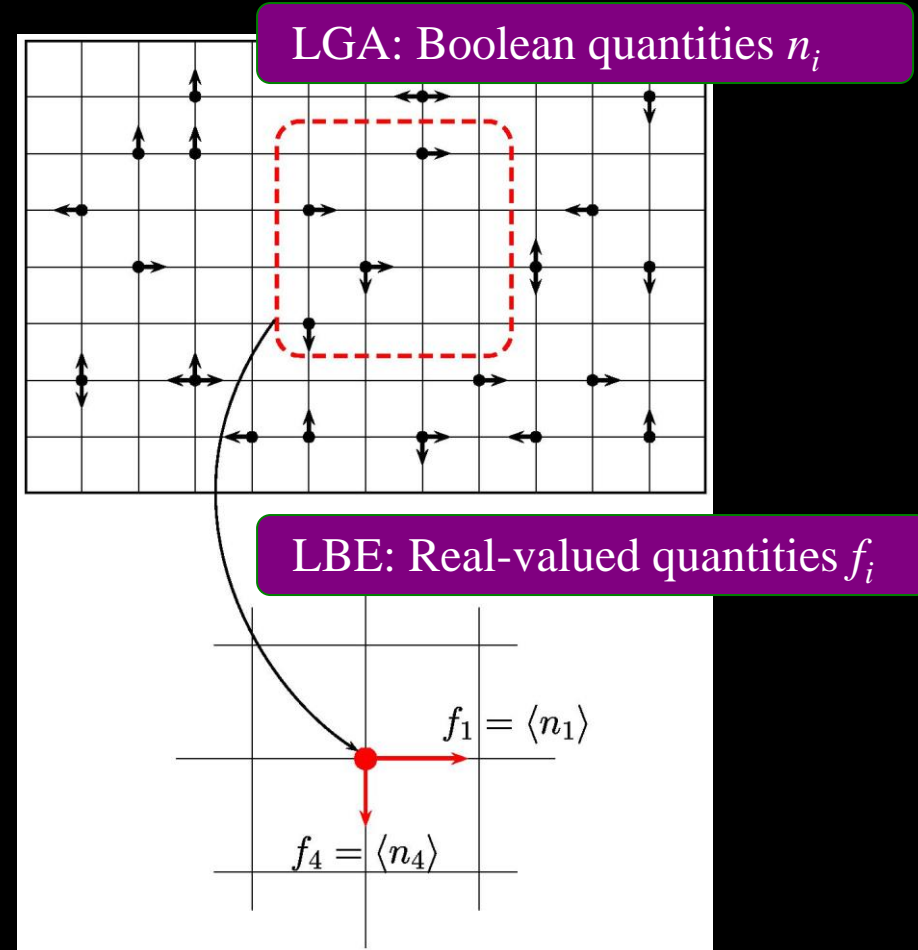
# From LGA to LBE

One lattice node represents particle *densities*: discrete dynamics are replaced by a smooth flow.

Less averaging needed, increased performance.

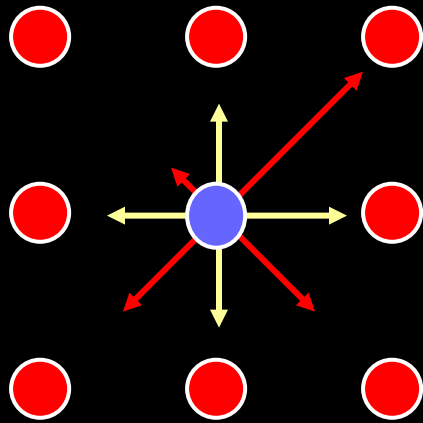
$$n_i \rightarrow f_i = \langle n_i \rangle$$

continuous population density,  $f_i$

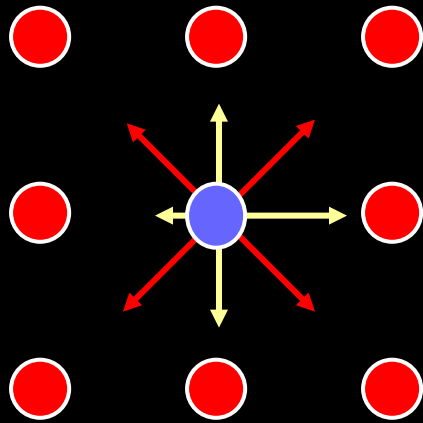


# Lattice-Boltzmann model:

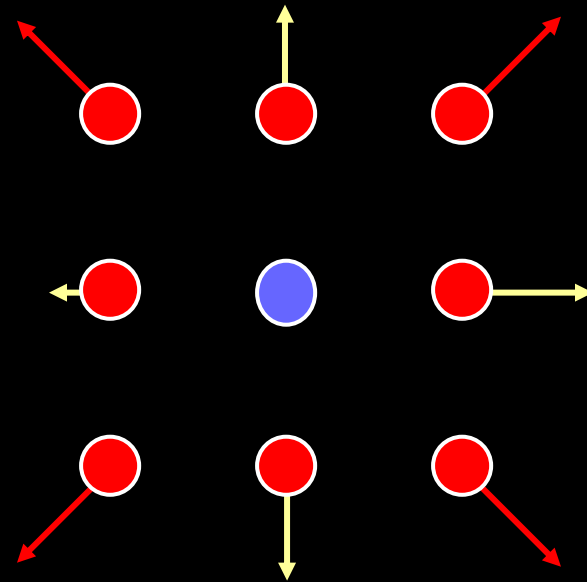
Initial State:



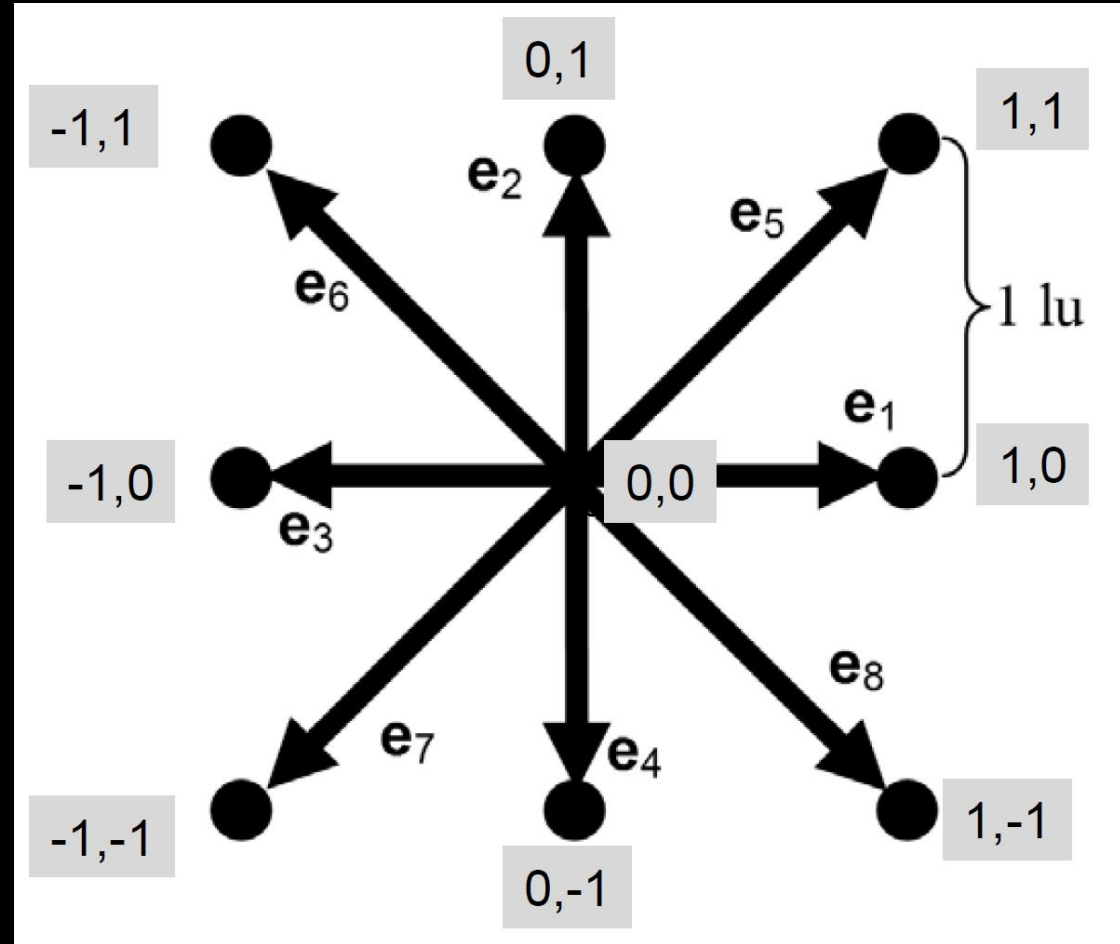
Post-Collision:



Propagation



# Discrete set of velocities



$$e = [[0, 0], [1, 0], [0, 1], [-1, 0], [0, -1], [1, 1], [-1, 1], [-1, -1], [1, -1]]$$

Hydrodynamic fields are moments  
of the distribution function  $f(\mathbf{r},t)$ :

$$\rho(\mathbf{r},t) = \sum_i f_i(\mathbf{r},t) \quad \text{Mass}$$

$$\rho(\mathbf{r},t)\mathbf{u}(\mathbf{r},t) = \sum_i f_i(\mathbf{r},t) \mathbf{e}_i \quad \text{Momentum}$$

where  $\mathbf{e}_i$  are the discrete velocities in the model



# Evolution equation

$$f_i(\mathbf{r} + \mathbf{c}_i \Delta t, t + \Delta t) = f_i(\mathbf{r}, t) - [f_i(\mathbf{r}, t) - f_i^{eq}(\mathbf{r}, t)]/\tau$$

relaxation-time form of the collision operator

$f_i^{eq}(\mathbf{r}, t)$  - equilibrium distribution

Equilibrium distribution is an expansion of the local Maxwell distribution.

# Equilibrium distribution

- start from the Maxwell distribution  $f^{eq} = \frac{\rho}{2\pi RT} \exp\left(\frac{-(\mathbf{e} - \mathbf{u})^2}{2RT}\right)$
- normalize the velocities by  $\sqrt{3RT}$  :  $f^{eq} = \frac{\rho}{2\pi/3} \exp\left(-\frac{3}{2}(\mathbf{e} - \mathbf{u})^2\right)$
- expand in  $\mathbf{u}$  up to  $O(u^2)$ :

$$f^{eq} = \frac{\rho}{2\pi/3} \exp\left(-\frac{3}{2}e^2\right) \left[1 + 3(\mathbf{e} \cdot \mathbf{u}) + \frac{9}{2}(\mathbf{e} \cdot \mathbf{u})^2 - \frac{3}{2}u^2\right]$$

- for discrete set of velocities  $\mathbf{e}_i$  the corresponding distribution functions read

$$f_i^{eq} = W_i \rho \left[1 + 3(\mathbf{e}_i \cdot \mathbf{u}) + \frac{9}{2}(\mathbf{e}_i \cdot \mathbf{u})^2 - \frac{3}{2}u^2\right]$$

# Equilibrium distribution (2)

The weights  $W_i$  are then determined from the isotropy conditions and the moment conditions:

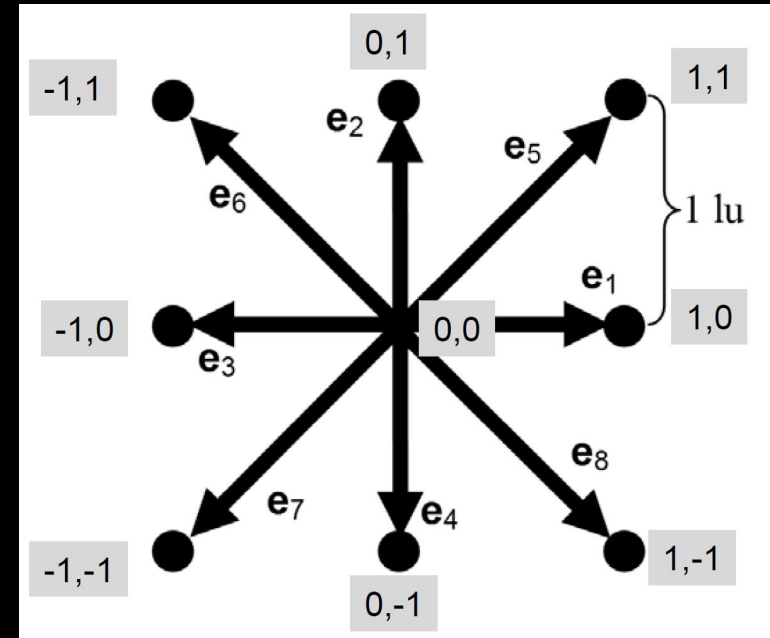
$$\rho = \sum_i f_i^{eq}, \quad \rho \mathbf{u} = \sum_i f_i^{eq} \mathbf{e}_i$$

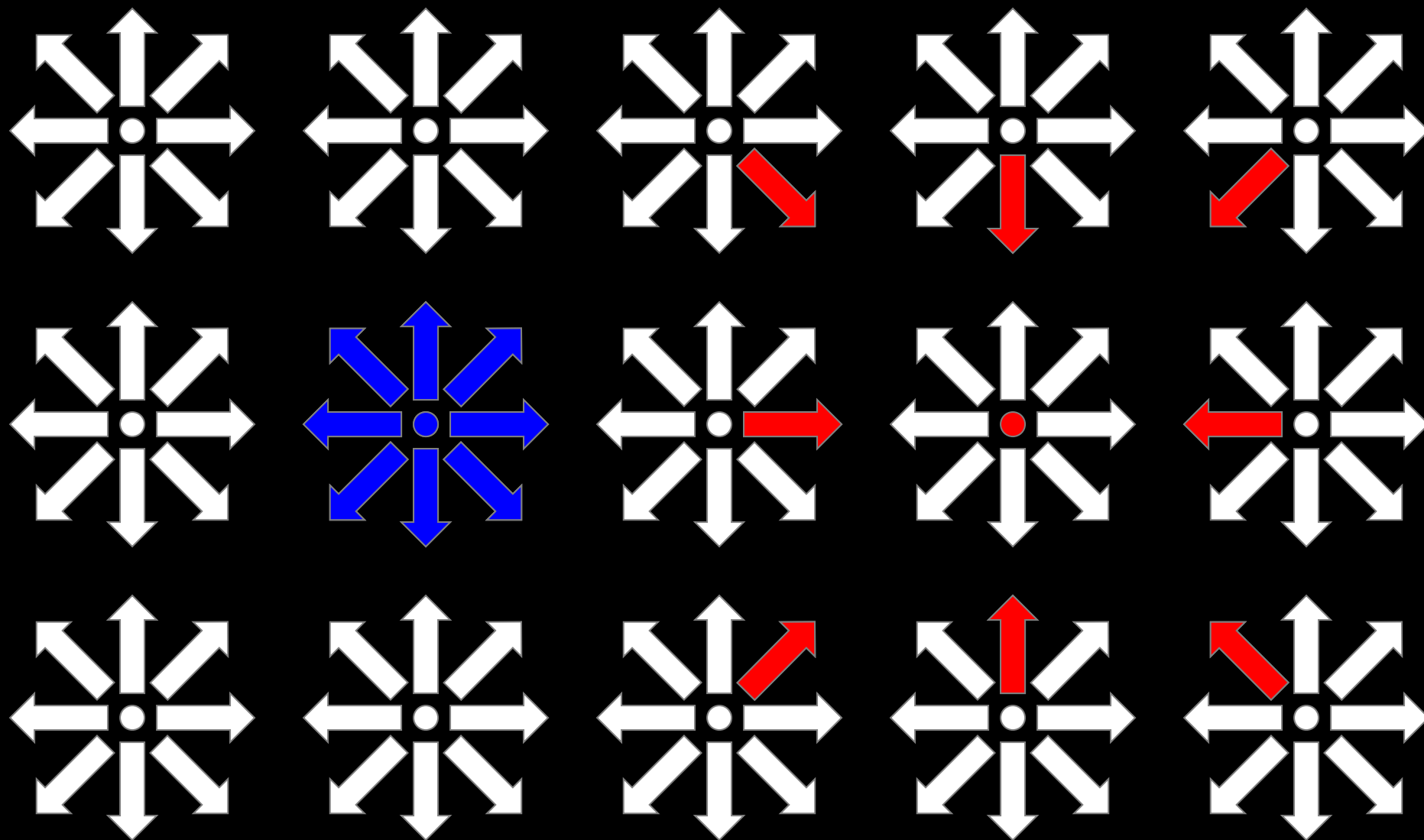
For the 2D square lattice with nine velocities one gets:

$$W_0 = 4/9$$

$$W_1 = W_2 = W_3 = W_4 = 1/9$$

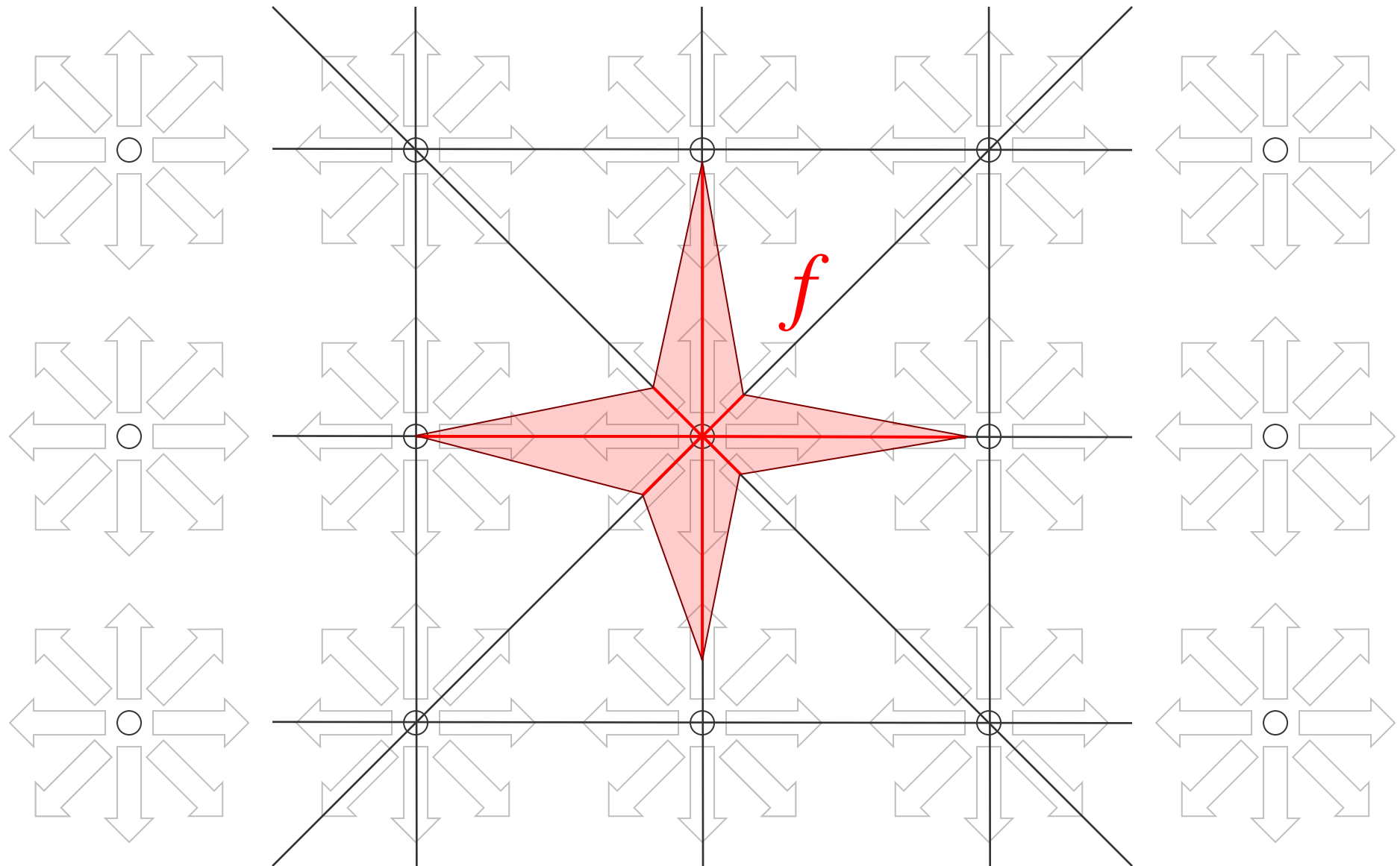
$$W_5 = W_6 = W_7 = W_8 = 1/36$$





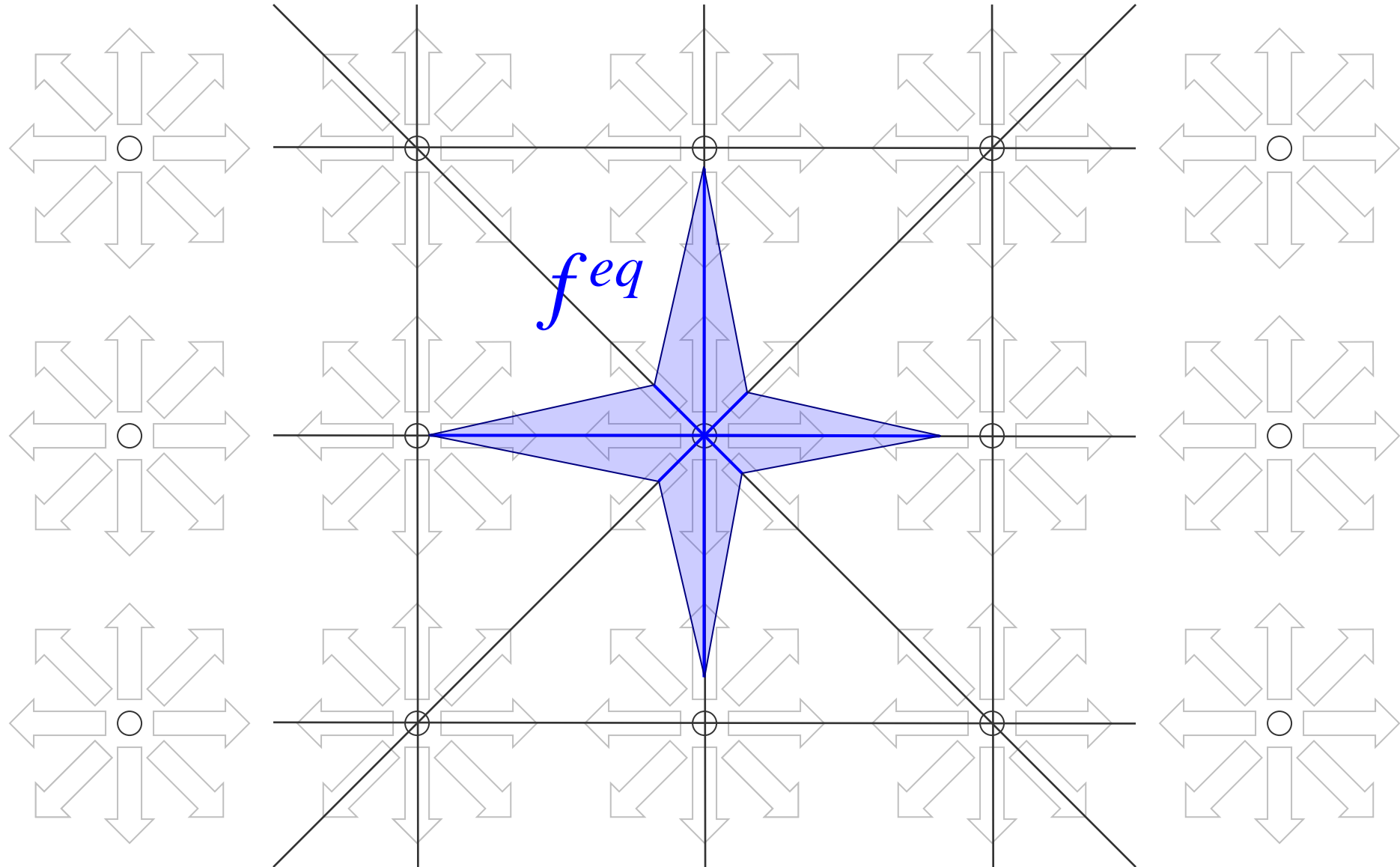
animation by D.Thorne and M.Sukop  
(FIU, Miami)

streaming step



animation by D.Thorne and M.Sukop  
(FIU, Miami)

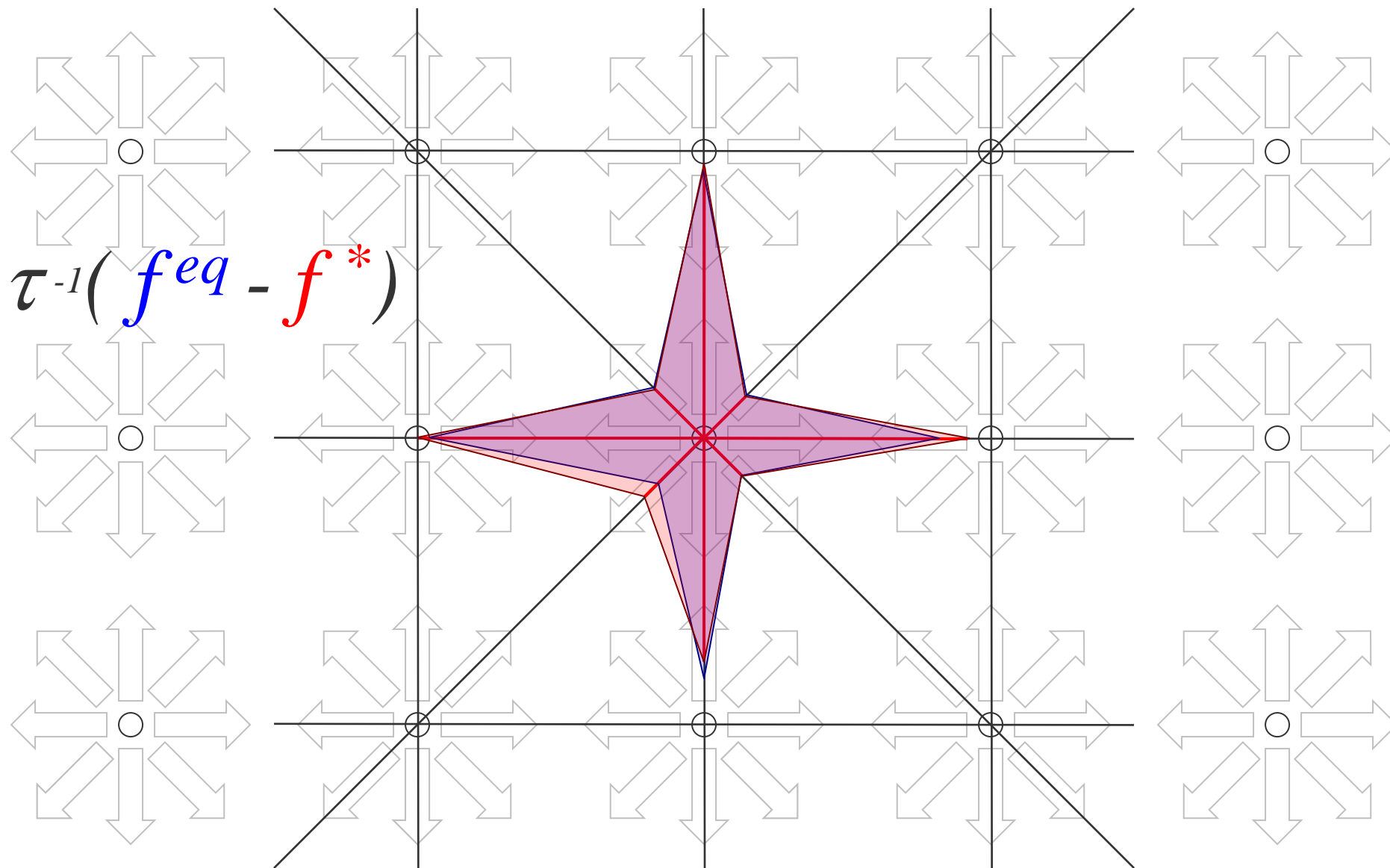
collision step



animation by D.Thorne and M.Sukop  
(FIU, Miami)

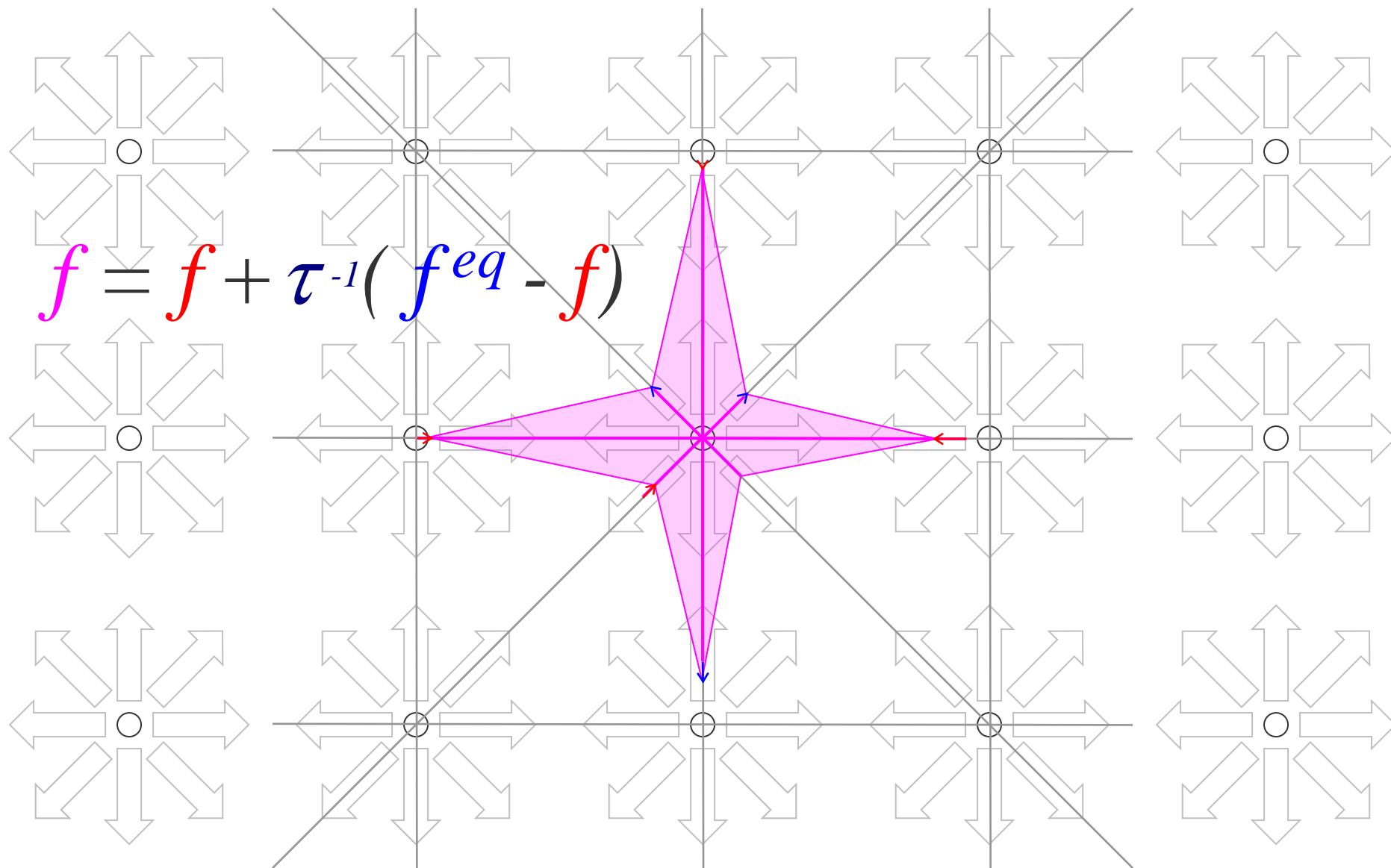
collision step





animation by D.Thorne and M.Sukop  
(FIU, Miami)

collision step



animation by D.Thorne and M.Sukop  
(FIU, Miami)

collision step

# LBM to Navier-Stokes

- start from **lattice Boltzmann equation**

$$f_i(\mathbf{r} + \mathbf{c}_i \Delta t, t + \Delta t) - f_i(\mathbf{r}, t) = -[f_i(\mathbf{r}, t) - f_i^{eq}(\mathbf{r}, t)] / \tau$$

- Taylor expand  $f_i(\mathbf{r} + \mathbf{c}_i \Delta t, t + \Delta t)$  about  $(\mathbf{r}, t)$  to 2nd order in  $\Delta t$

- write  $f_i = f_i^{eq} + f_i^{neq}$  and note that  $\rho = \sum_i f_i^{eq}$  and  $\rho \mathbf{u} = \sum_i f_i^{eq} \mathbf{c}_i$

- in the incompressible (small  $\text{Ma} = u/c_s$ ) limit you get the

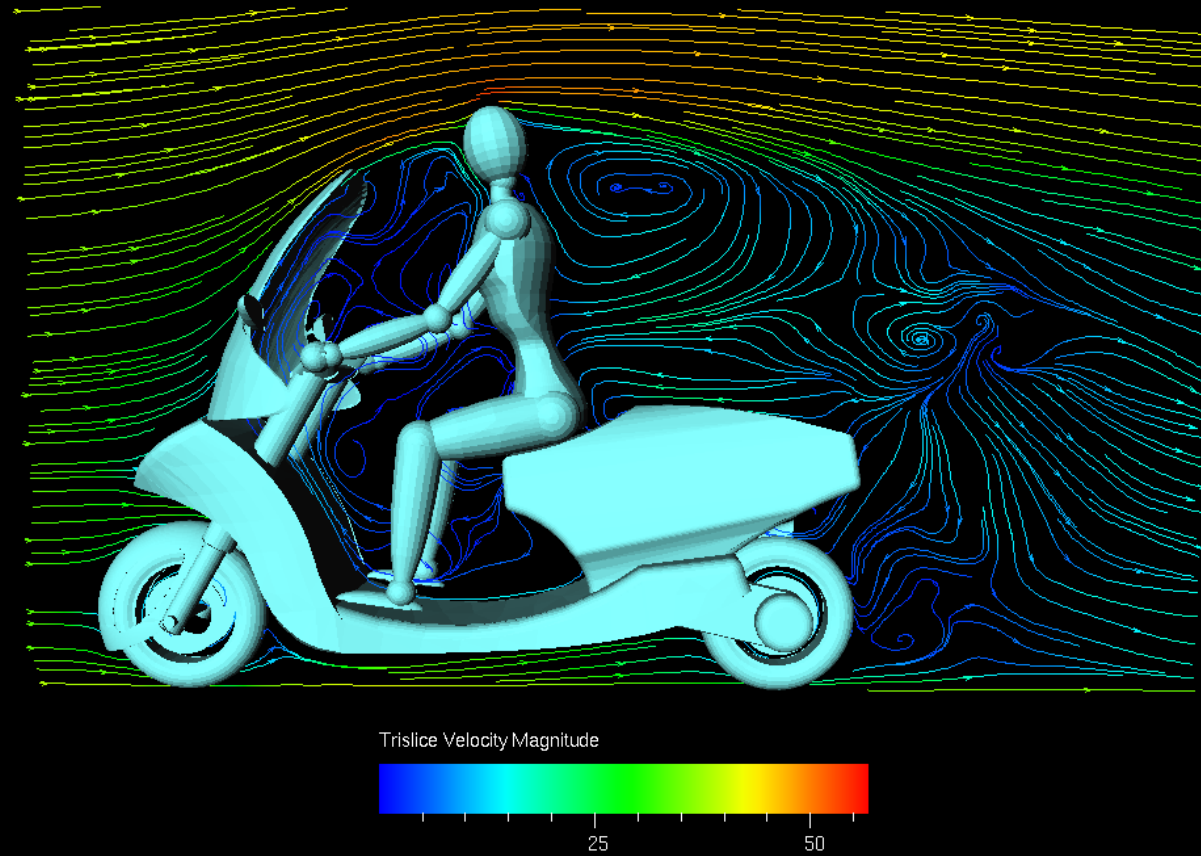
## **Navier Stokes equation**

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{u}$$

with

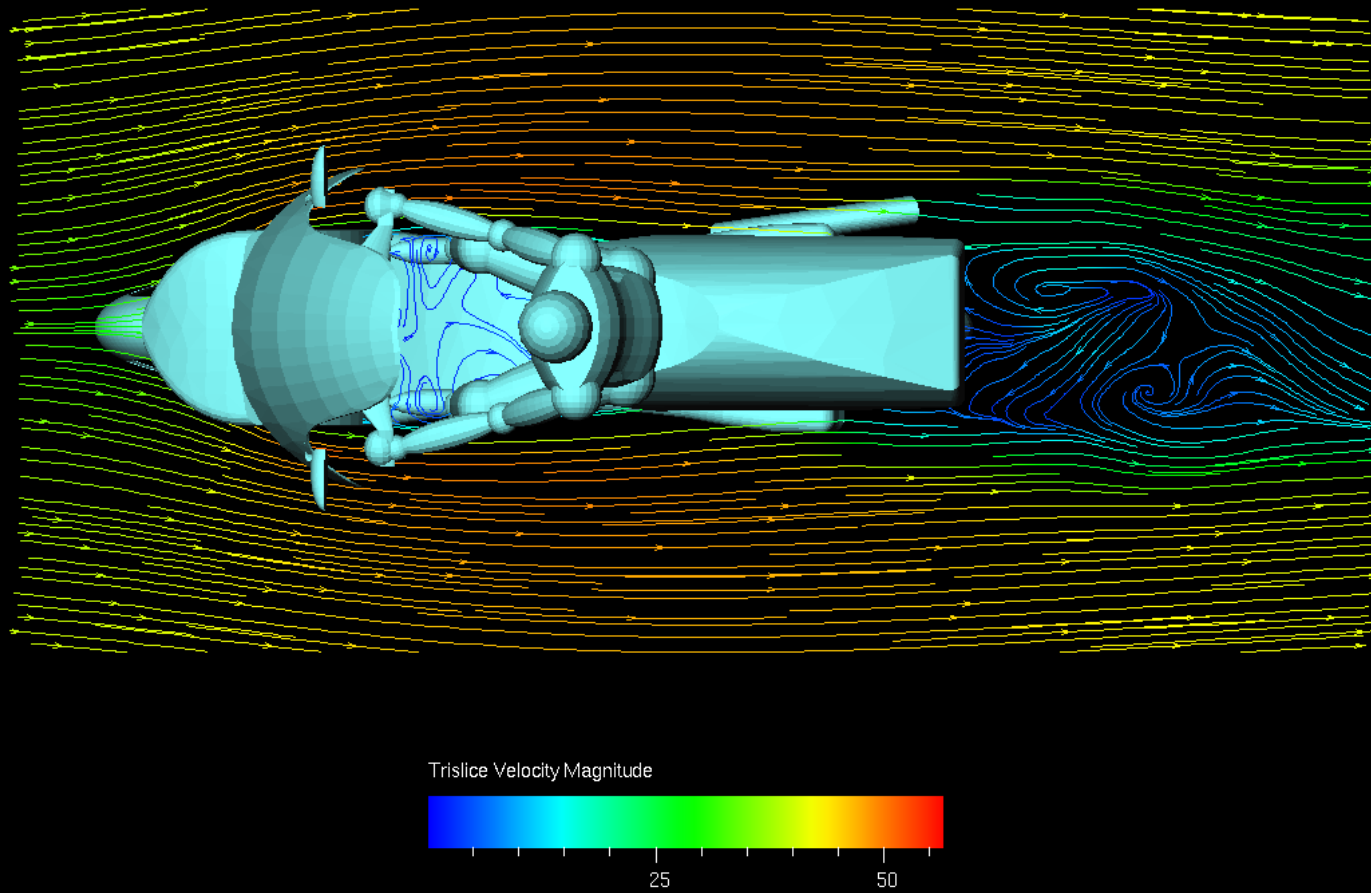
$$\nu = \left(1 - \frac{1}{2\tau}\right) \frac{\Delta t}{3}$$

# Examples (1)



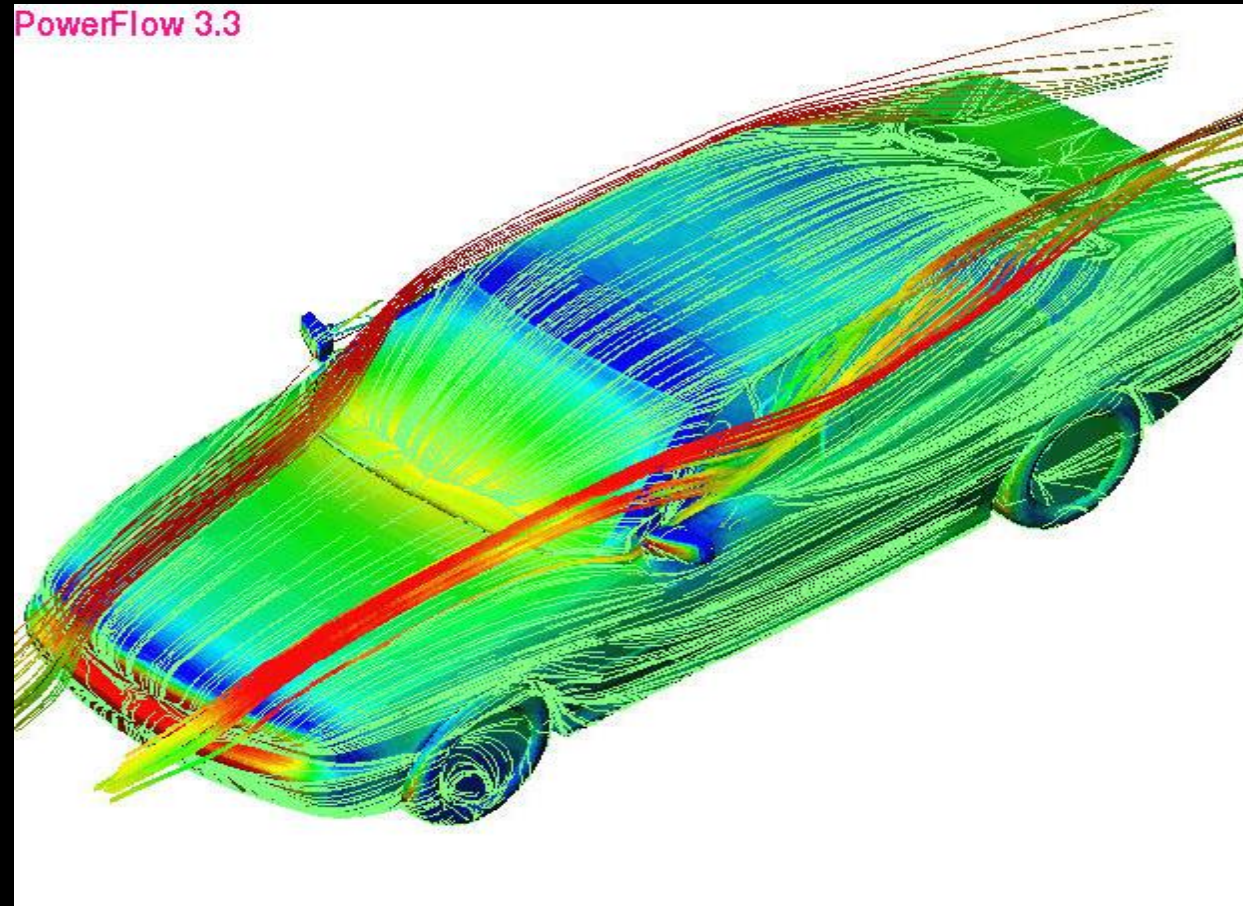
Bella, Ubertini, Succi 2001

# Examples (1)



Bella, Ubertini, Succi 2001

# Examples (2)



H Chen, S Kandasamy, R Shock, S. Orszag, S. Succi, V. Yakhot, Science (2003)



## HOW A WING PRODUCES LIFT

