Operating Systems-2 CS 3510 Spring 2019 Programming Assignment 2:

Implementing TAS, CAS and Bounded Waiting CAS

Mutual Exclusion Algorithms

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Task

The goal of this assignment is to implement TAS, CAS and Bounded Waiting with CAS mutual exclusion (ME) algorithms studied in the class. Implement these algorithms in C++.

Approach and Implementation

1. To achieve our above mentioned goal make a *testCS* function which takes thread_index as a parameter. We will pass this function along with the thread index to the each thread and calculate the average waiting time and max waiting time for all three mutual exclusion algorithm.

```
vector<thread> t; // Array of n threads
for(int i=0;i<n;i++) t.push_back(thread(testCS,i));
for(int i=0;i<n;i++) t[i].join();</pre>
```

- 2. Functions and data-types of the chrono library (and other libraries) like
 - a. std::chrono::system_clock, std::chrono::system_clock::now()
 - b. std::chrono::time_point
 - c. struct tm Time structure
 - d. struct tm *localtime(const time t *timer)

were used to calculate the average waiting time and max waiting time.

- int usleep(useconds_t usec) function was used to suspend the execution of the thread for microsecond intervals
- 4. **template <class RealType = double> class exponential_distribution**: This is a random number distribution that produces floating-point values according to an exponential distribution, which is described by the following probability density function:

$$p(x|\lambda) = \lambda e^{-\lambda x}$$
, $x > 0$

5. We make two exponential distributions and pass the value of $1/\lambda 1$, $1/\lambda 2$ in the constructor. Later this can be used to obtain random numbers t1 and t2 with values that are exponentially distributed with an average of $\lambda 1$, $\lambda 2$ seconds.

```
distribution1 = new exponential_distribution<double>(1/lt1);
distribution2 = new exponential_distribution<double>(1/lt2);
```

6. The implementation of the critical section varies in *testCS* function with the change in mutual exclusion algorithm.

```
void testCS(int id){
                         // test function
      chrono::time_point<chrono::system_clock> start_time,end_time;
      for(int i=0;i<k;i++){</pre>
            // Entry Section Starts
            string reqEnterTime=getSysTime();
            start_time = chrono::system_clock::now();
            // Critical Section Starts
            end_time = chrono::system_clock::now();
            fout<<i<<"th CS Requested at "<<reqEnterTime;</pre>
            fout<<" by thread "<< id <<endl;</pre>
            tmp=(end_time - start_time);
            waiting_time +=tmp;
            max_waiting_time = max(max_waiting_time,tmp);
            fout<<i<<"th CS Entered at</pre>
                                          "<<getSysTime();</pre>
            fout<<" by thread "<< id <<endl;</pre>
            usleep((*distribution1)(generator)*scale);
            fout<<i<<"th CS Exited at</pre>
                                         "<<getSysTime();</pre>
            fout<<" by thread "<< id <<endl;</pre>
            flag.clear();
            // Critical Section ends
            // Reminder Section starts
            usleep((*distribution2)(generator)*scale);
      }
}
```

7. Implementation of TAS

```
while(atomic_flag_test_and_set(&flag));
```

8. Implementation of CAS

```
while(!atomic_compare_exchange_strong(&flag,&flag1,true)) flag1=false;
```

9. Implementation of CAS-Bounded waiting

Here the **waiting[i]==true** represents that thread is waiting to enter the critical section.

A thread can enter the critical section if **waiting[i]==false or key==false**.

The later part of the code ensures that no thread starves for a long time.

```
while(waiting[id] && key){//Compare and Swap(Bounded waiting)implementation
        if(atomic_compare_exchange_strong(&flag,&flag1,true)) key=false;
        else flag1=false;

// Critical Section Starts
end_time = chrono::system_clock::now();
waiting[id]=false;
usleep((*distribution1)(generator)*scale);
int j=(id+1)%n;
while(j!=i && !waiting[j]) j=(j+1)%n;
if(j==i)flag =false;
else waiting[j]=false;
```

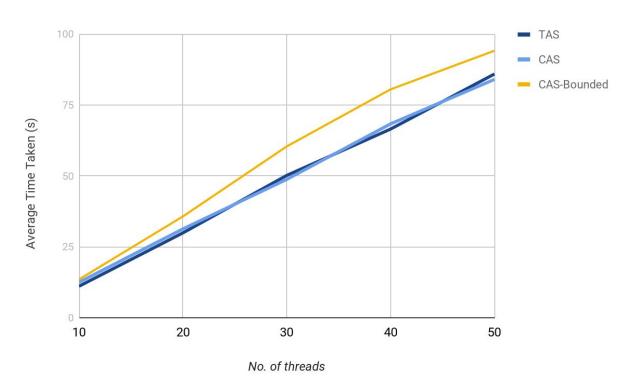
Input Parameters

N: No. of threads vary from 10 to 50 in steps of 10.

K = 10: No. of CS request by each thread

 $\lambda 1 = 2, \lambda 2 = 2$

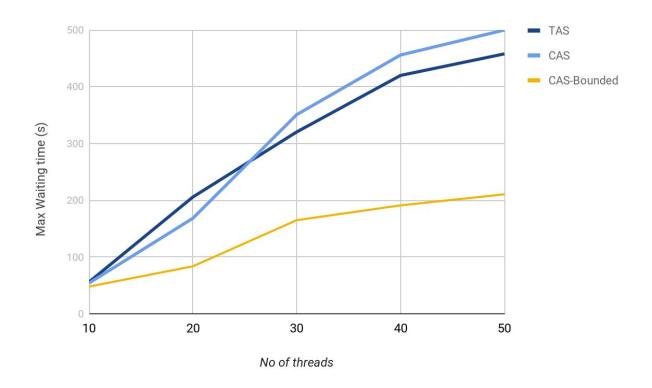
Graph 1: Avg Waiting Time vs No. of Threads



Output analysis of Graph 1

- 1. Average waiting time taken by TAS and CAS algorithm is almost the same.
- 2. Average waiting time taken by Bounded-CAS is greater than both TAS and CAS as it ensures that no thread starve.

Graph 2: Worst Waiting Time vs No of Threads



Output analysis of Graph 2

- 1. Worst waiting time taken by TAS and CAS algorithm is almost the same.
- 2. Worst waiting time taken by Bounded-CAS is much less than both TAS and CAS as it ensures that no thread starves.
- 3. The difference between the worst waiting times of Bounded-CAS and (TAS,CAS) with increases as the no of threads increase.