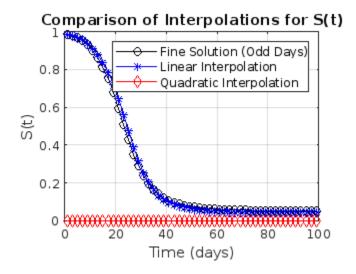
```
beta = 0.3; % rate of infection
gamma = 0.1; % rate of recovery
N = 1;
            % size of population
T = 100;
            % total simulation
h1 = 1;
             % finer
h2 = 2;
            % coarser
S0 = 0.99; % susceptible
I0 = 0.01; % infected
R0 = 0;
        % recovered
t_f = 0:h1:T; % fine steps
t_c = 0:h2:T; % coarse steps
% time step (finer)
S_f = zeros(size(t_f));
I_f = zeros(size(t_f));
R_f = zeros(size(t_f));
% initial conditions
S_f(1) = S0;
I_f(1) = I0;
R f(1) = R0;
% time step
for k = 1:length(t_fine)-1
    dS = -(beta/N) * S_f(k) * I_f(k);
    \label{eq:dI = (beta/N) * S_f(k) * I_f(k) - gamma * I_f(k);}
    dR = gamma * I_f(k);
    S_f(k+1) = S_f(k) + h1 * dS;
    I_f(k+1) = I_f(k) + h1 * dI;
    R_f(k+1) = R_f(k) + h1 * dR;
end
% coarser step
S_c = zeros(size(t_c));
I_c= zeros(size(t_c));
R_c = zeros(size(t_c));
%intial conditons
S_c(1) = S0;
I_c(1) = I0;
R_c(1) = R0;
% time step
for k = 1:length(t_c)-1
```

%%MAE384 Group Project PART II: Interpolation

```
dS = -(beta/N) * S_c(k) * I_c(k);
    dI = (beta/N) * S_c(k) * I_c(k) - gamma * I_c(k);
    dR = gamma * I_c(k);
    S_c(k+1) = S_c(k) + h2 * dS;
    I_c(k+1) = I_c(k) + h2 * dI;
    R_c(k+1) = R_c(k) + h2 * dR;
end
% interpolation of odd days
t_odd = 1:2:T-1;
% coaser linear interpolation
S_l = interp1(t_c, S_c, t_odd, 'linear');
I_l = interp1(t_c, I_c, t_odd, 'linear');
R_l = interp1(t_c, R_c, t_odd, 'linear');
% lagrange
S_q = interp1(t_c, S_coarser, t_odd, 'spline');
I_q = interp1(t_c, I_c, t_odd, 'spline');
R_q = interp1(t_c, R_c, t_odd, 'spline');
% finer odd
S_f_odd = interpl(t_f, S_f, t_odd);
I_f_odd = interpl(t_f, I_f, t_odd);
R_f_odd = interpl(t_f, R_f, t_odd);
% linear interpolation
Nint = length(t_odd);
EL2\_S\_l = sqrt(sum((S\_l - S\_f\_odd).^2) / Nint);
EL2_I_l = sqrt(sum((I_l - I_f_odd).^2) / Nint);
EL2_R_l = sqrt(sum((R_l - R_f_odd).^2) / Nint);
% quad. interpolation
el2_S_q = sqrt(sum((S_q - S_f_odd).^2) / Nint);
el2_I_q = sqrt(sum((I_q - I_f_odd).^2) / Nint);
el2_R_q = sqrt(sum((R_q - R_f_odd).^2) / Nint);
% error table
ErrorTable = table(["Linear"; "Quadratic"], ...
                   [EL2_S_1; el2_S_q], ...
                   [EL2_I_1; el2_I_q], ...
                   [EL2_R_l; el2_R_q], ...
                   'VariableNames', { 'Interpolation', 'S_Error', 'I_Error',
'R_Error'});
% error table
disp(ErrorTable);
% plot
figure;
plot(t_odd, S_f_odd, 'k-o', 'DisplayName', 'Fine Solution (Odd Days)');
hold on;
plot(t_odd, S_1, 'b-*', 'DisplayName', 'Linear Interpolation');
```

```
plot(t_odd, S_q, 'r-d', 'DisplayName', 'Quadratic Interpolation');
xlabel('Time (days)');
ylabel('S(t)');
legend;
title('Comparison of Interpolations for S(t)');
grid on;
```

Interpolation	S_Error	I_Error	R_Error
"Linear"	0.018109	0.010584	0.016495
"Ouadratic"	0.42824	0.010796	0.016658



Published with MATLAB® R2024b