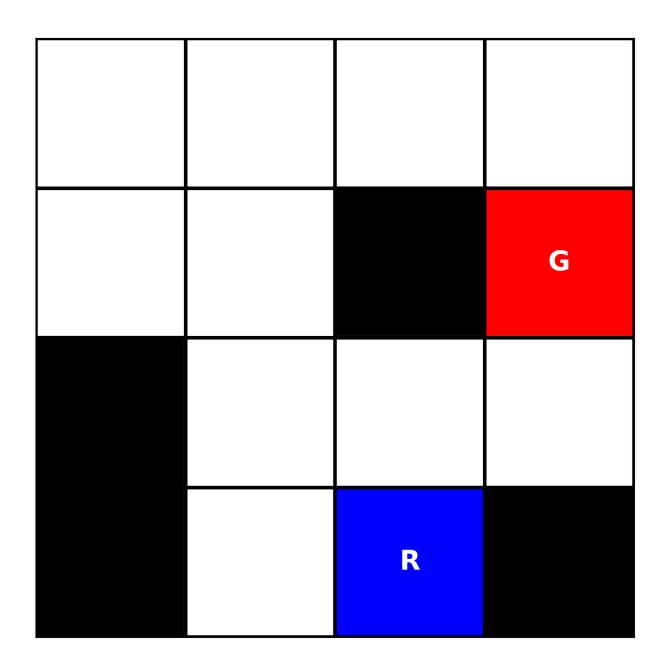


Solution: (MOVE-DOWN-FROM-TO ROBOT1 X2 Y3 X3 Y3)

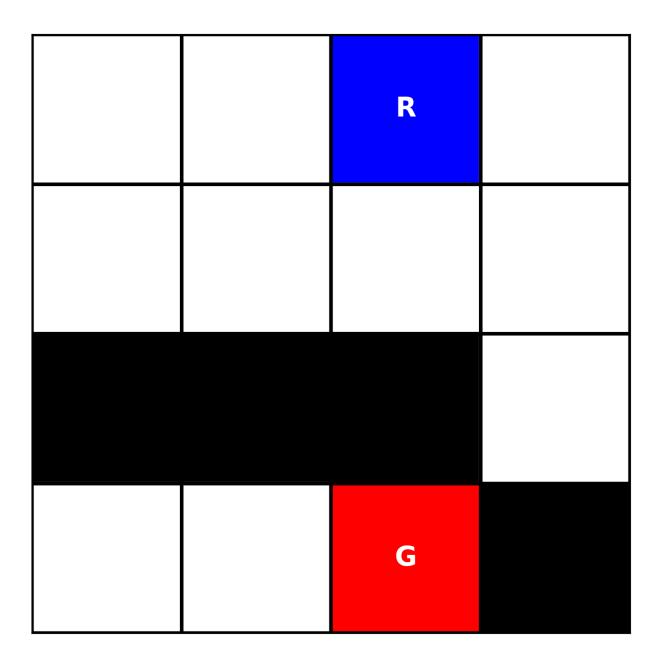
(MOVE-LEFT-FROM-TO ROBOT1 X3 Y3 X3 Y2)



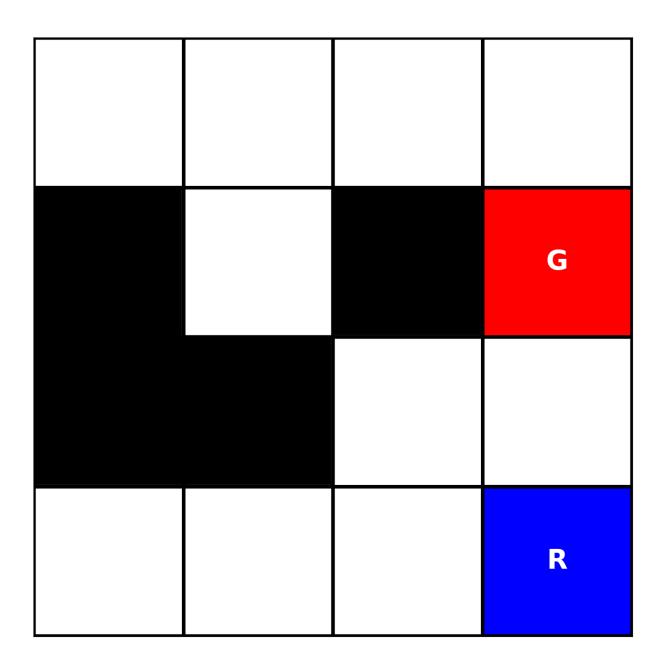
(MOVE-UP-FROM-TO ROBOT1 X3 Y2 X2 Y2)

(MOVE-RIGHT-FROM-TO ROBOT1 X2 Y2 X2 Y3)

(MOVE-UP-FROM-TO ROBOT1 X2 Y3 X1 Y3)

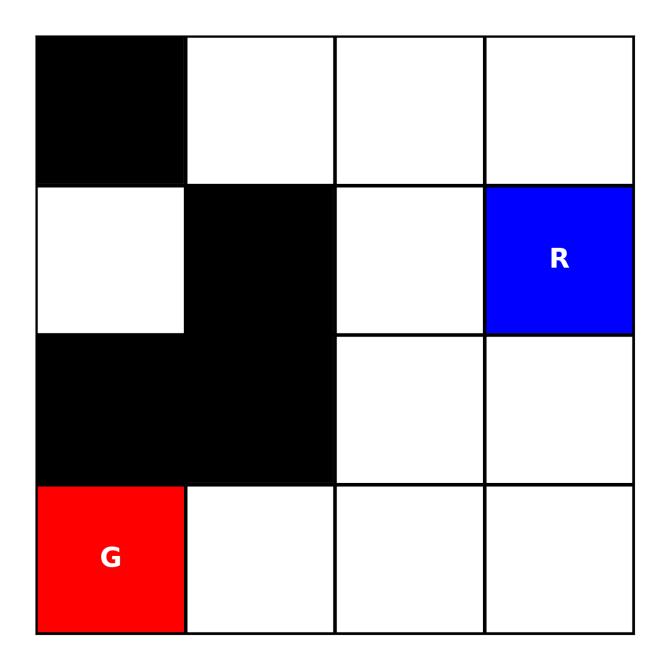


No plan



(MOVE-UP-FROM-TO ROBOT1 X3 Y3 X2 Y3)

(MOVE-UP-FROM-TO ROBOT1 X2 Y3 X1 Y3)



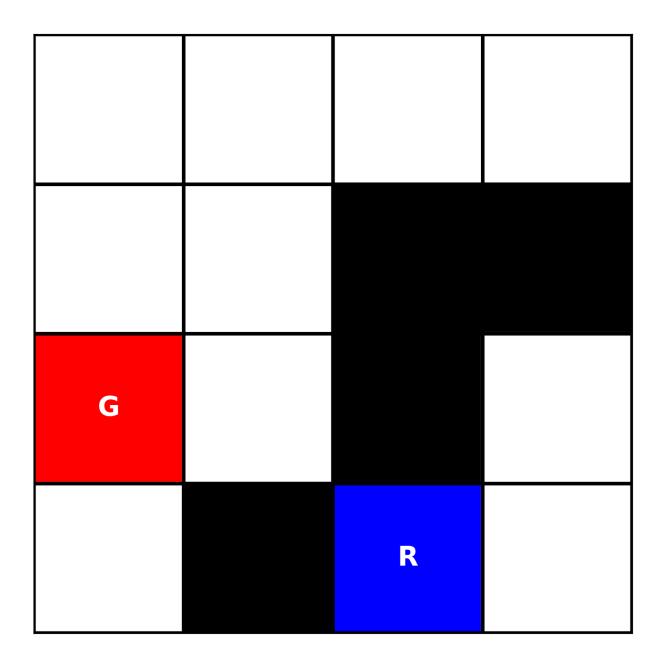
(MOVE-DOWN-FROM-TO ROBOT1 X1 Y3 X2 Y3)

(MOVE-DOWN-FROM-TO ROBOT1 X2 Y3 X3 Y3)

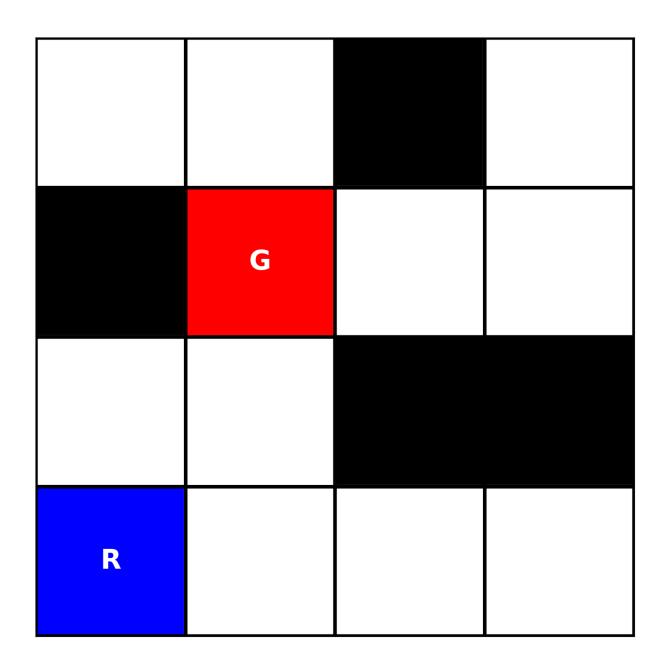
(MOVE-LEFT-FROM-TO ROBOT1 X3 Y3 X3 Y2)

(MOVE-LEFT-FROM-TO ROBOT1 X3 Y2 X3 Y1)

(MOVE-LEFT-FROM-TO ROBOT1 X3 Y1 X3 Y0)



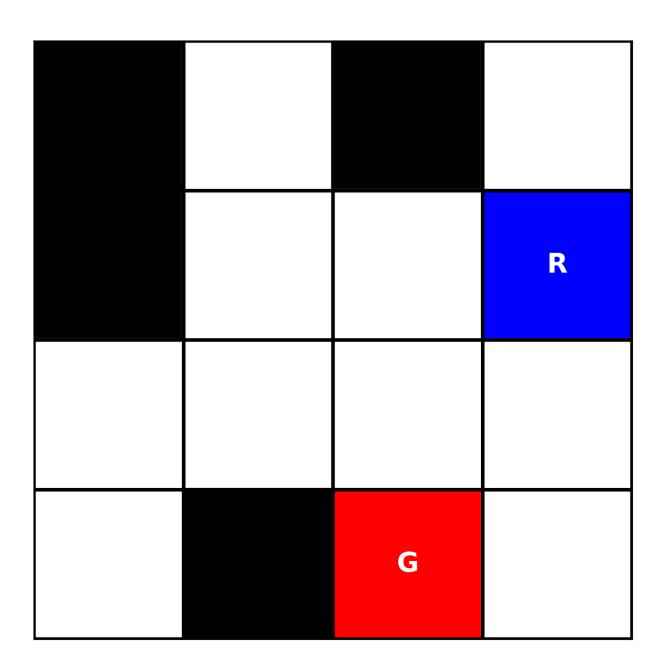
No plan



(MOVE-RIGHT-FROM-TO ROBOT1 X3 Y0 X3 Y1)

(MOVE-UP-FROM-TO ROBOT1 X3 Y1 X2 Y1)

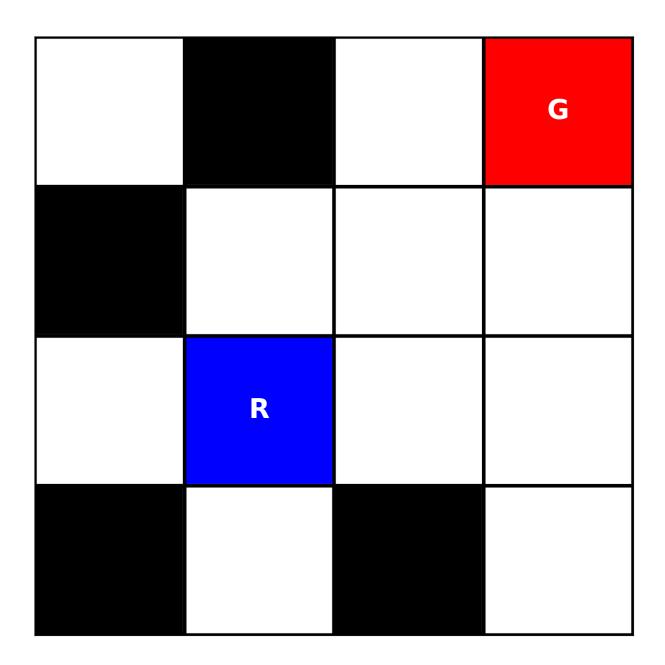
(MOVE-UP-FROM-TO ROBOT1 X2 Y1 X1 Y1)



(MOVE-DOWN-FROM-TO ROBOT1 X1 Y3 X2 Y3)

(MOVE-DOWN-FROM-TO ROBOT1 X2 Y3 X3 Y3)

(MOVE-LEFT-FROM-TO ROBOT1 X3 Y3 X3 Y2)

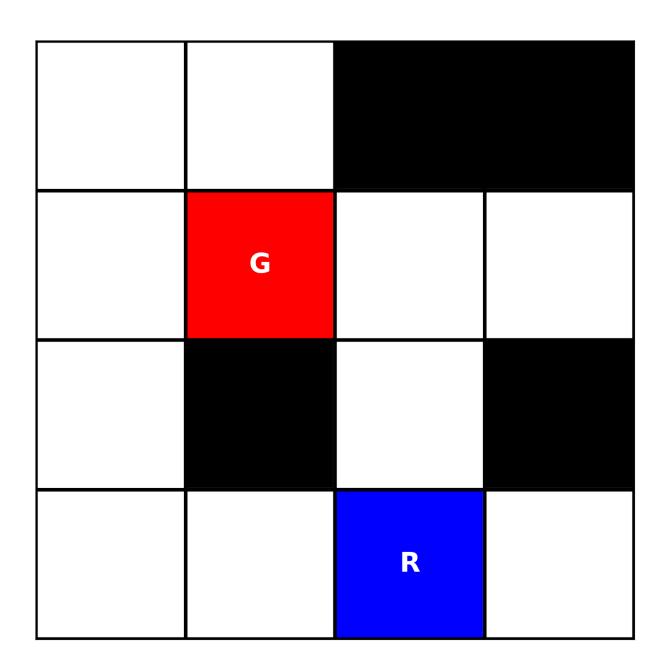


(MOVE-RIGHT-FROM-TO ROBOT1 X2 Y1 X2 Y2)

(MOVE-RIGHT-FROM-TO ROBOT1 X2 Y2 X2 Y3)

(MOVE-UP-FROM-TO ROBOT1 X2 Y3 X1 Y3)

(MOVE-UP-FROM-TO ROBOT1 X1 Y3 X0 Y3)



(MOVE-UP-FROM-TO ROBOT1 X3 Y2 X2 Y2)

(MOVE-UP-FROM-TO ROBOT1 X2 Y2 X1 Y2)

(MOVE-LEFT-FROM-TO ROBOT1 X1 Y2 X1 Y1)