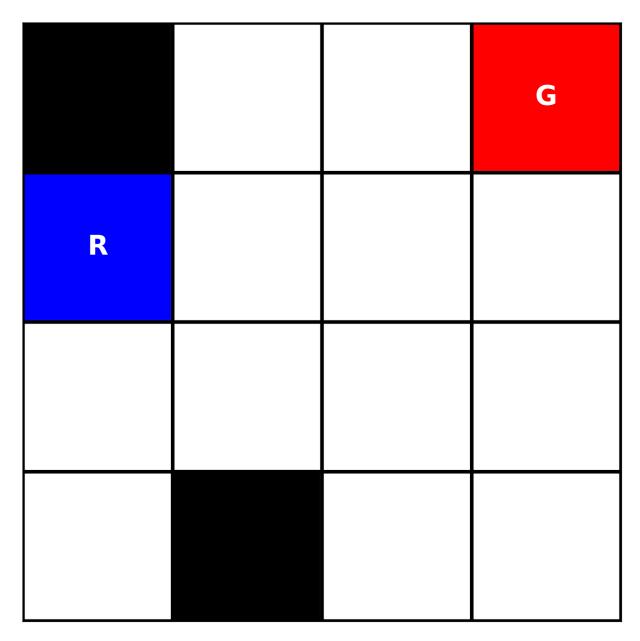


Start position: (2, 2) Goal position: (0, 2)

Obstacle positions: (0, 0), (3, 3)

Solution:

(MOVE-UP-FROM-TO (2, 2) (1, 2)) (MOVE-UP-FROM-TO (1, 2) (0, 2))



Start position: (1, 0) Goal position: (0, 3)

Obstacle positions: (0, 0), (3, 1)

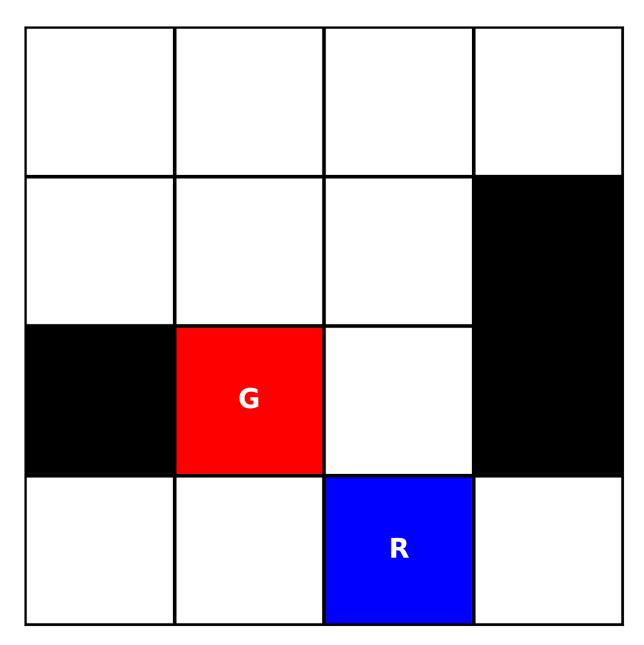
Solution:

(MOVE-RIGHT-FROM-TO (1, 0) (1, 1))

(MOVE-UP-FROM-TO (1, 1) (0, 1))

(MOVE-RIGHT-FROM-TO (0, 1) (0, 2))

(MOVE-RIGHT-FROM-TO (0, 2) (0, 3))

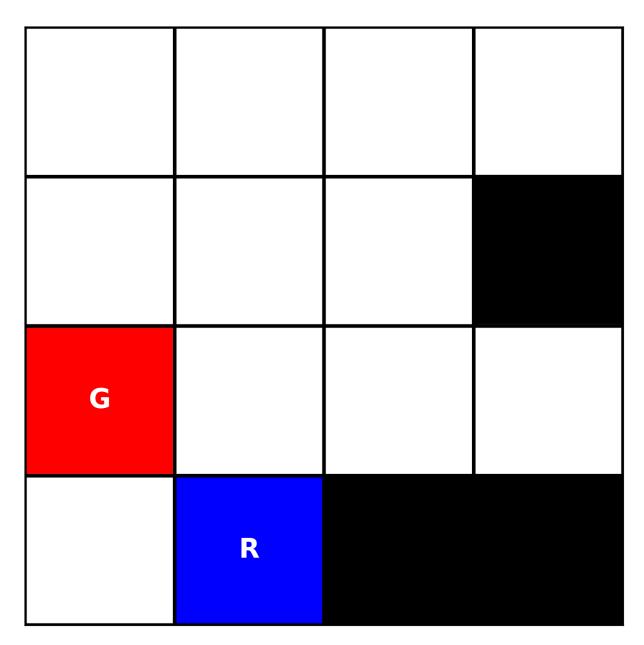


Start position: (3, 2) Goal position: (2, 1)

Obstacle positions: (2, 0), (1, 3), (2, 3)

Solution:

(MOVE-LEFT-FROM-TO (3, 2) (3, 1)) (MOVE-UP-FROM-TO (3, 1) (2, 1))

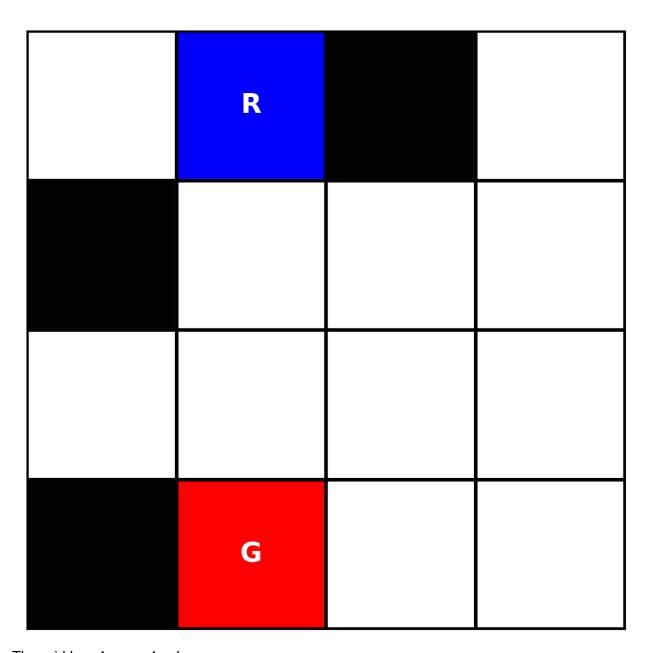


Start position: (3, 1) Goal position: (2, 0)

Obstacle positions: (1, 3), (3, 2), (3, 3)

SOLUTION:

(MOVE-LEFT-FROM-TO (3, 1) (3, 0)) (MOVE-UP-FROM-TO (3, 0) (2, 0))



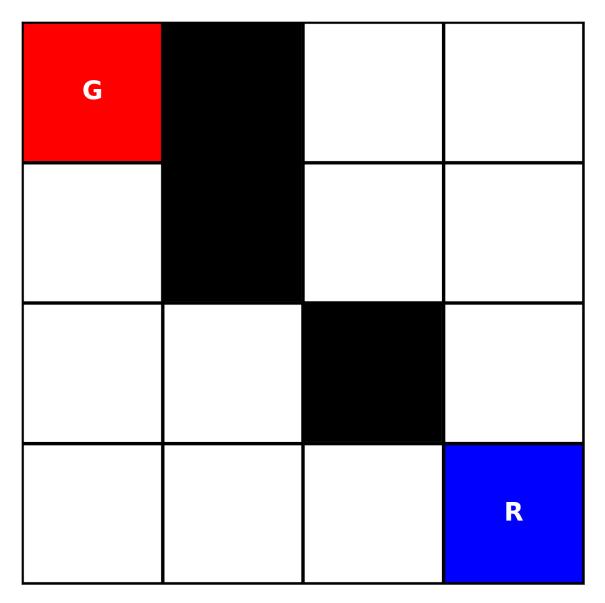
Start position: (0, 1) Goal position: (3, 1)

Obstacle positions: (0, 2), (1, 0), (3, 0)

Solution:

 $\begin{array}{ll} (\text{MOVE-DOWN-FROM-TO} \ \, (0,\,1)\,(1,\,1)) \\ (\text{MOVE-DOWN-FROM-TO} \ \, (1,\,1)\,(2,\,1)) \end{array}$

(MOVE-DOWN-FROM-TO (2, 1) (3, 1))



Start position: (3, 3) Goal position: (0, 0)

Obstacle positions: (0, 1), (1, 1), (2, 2)

SOLUTION:

(MOVE-DOWN-FROM-TO (0, 0) (1, 0))

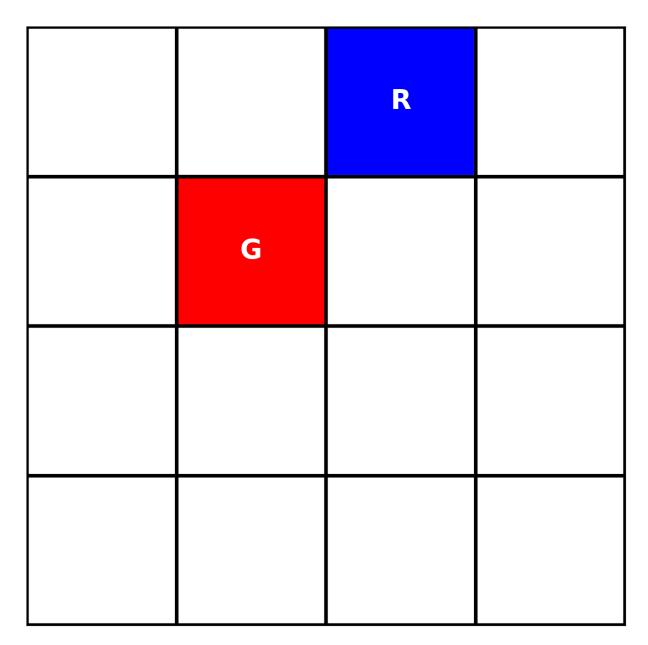
(MOVE-DOWN-FROM-TO (1, 0) (2, 0))

(MOVE-DOWN-FROM-TO (2, 0) (3, 0))

(MOVE-RIGHT-FROM-TO (3, 0) (3, 1))

(MOVE-RIGHT-FROM-TO (3, 1) (3, 2))

(MOVE-RIGHT-FROM-TO (3, 2) (3, 3))

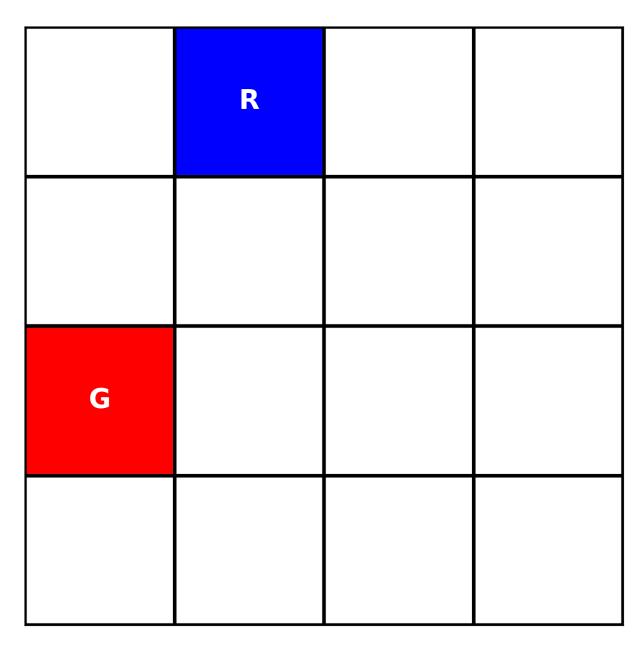


Start position: (0, 2) Goal position: (1, 1)

Obstacle positions: NO OBSTACLES IN THIS GRID

SOLUTION:

(MOVE-DOWN-FROM-TO (0, 2) (1, 2)) (MOVE-LEFT-FROM-TO (1, 2) (1, 1))



Start position: (0, 1) Goal position: (2, 0)

Obstacle positions: NO OBSTACLES IN THIS GRID

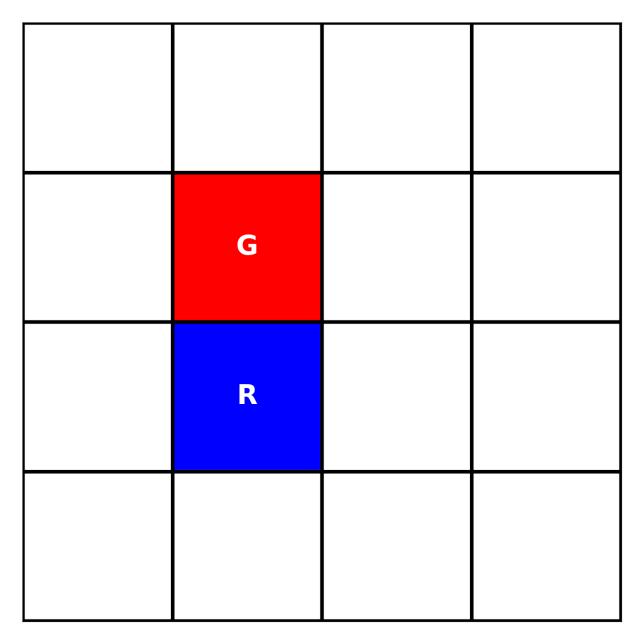
SOLUTION:

(MOVE-LEFT-FROM-TO (0, 1) (0, 0))

(MOVE-DOWN-FROM-TO (0, 0) (1, 0))

(MOVE-DOWN-FROM-TO (1, 0) (2, 0))

(MOVE-DOWN-FROM-TO (2, 0) (3, 0))

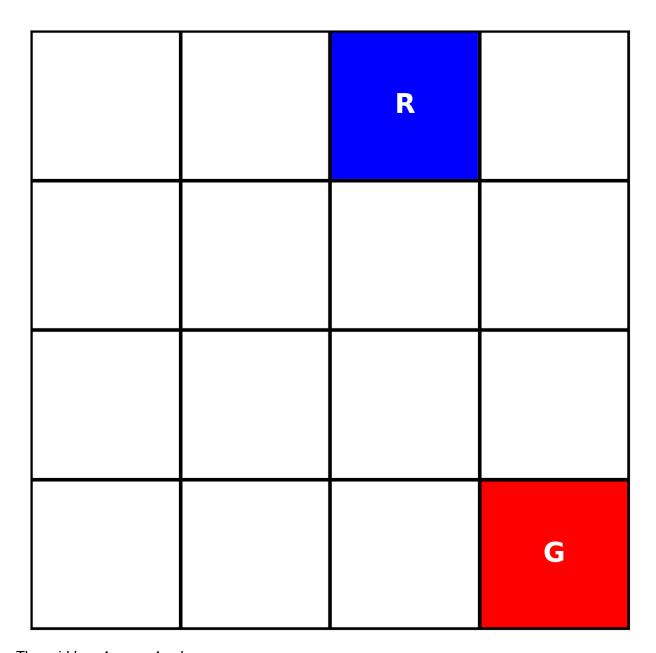


Start position: (2, 1) Goal position: (1, 1)

Obstacle positions: NO OBSTACLES IN THIS GRID

SOLUTION:

(MOVE-UP-FROM-TO (2, 1) (1, 1))



Start position: (0, 2) Goal position: (3, 3)

Obstacle positions: NO OBSTACLES IN THIS GRID

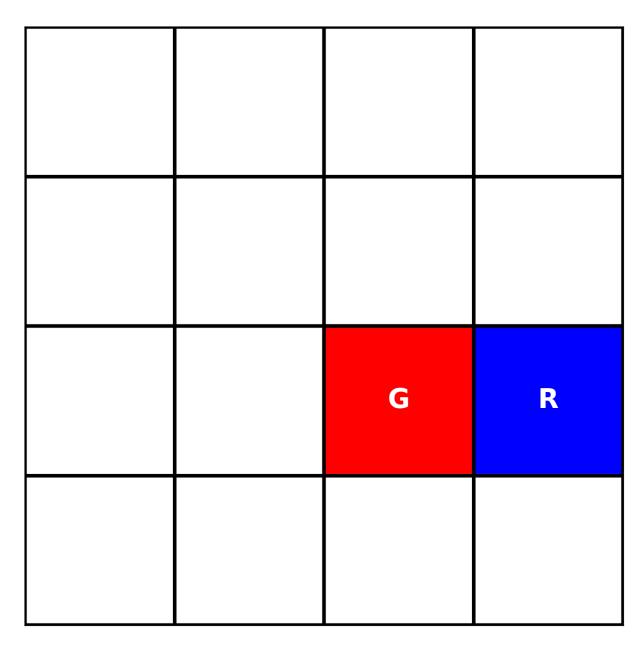
SOLUTION:

(MOVE-RIGHT-FROM-TO (0, 2) (0, 3))

(MOVE-DOWN-FROM-TO (0, 3) (1, 3))

(MOVE-DOWN-FROM-TO (1, 3) (2, 3))

(MOVE-DOWN-FROM-TO (2, 3) (3, 3))

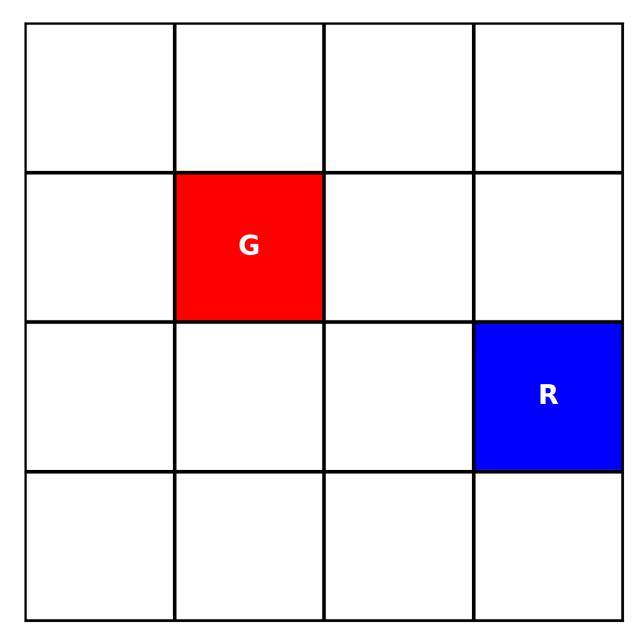


Start position: (2, 3) Goal position: (2, 2)

Obstacle positions: NO OBSTACLES IN THIS GRID

SOLUTION:

(MOVE-LEFT-FROM-TO (2, 3) (2, 2))

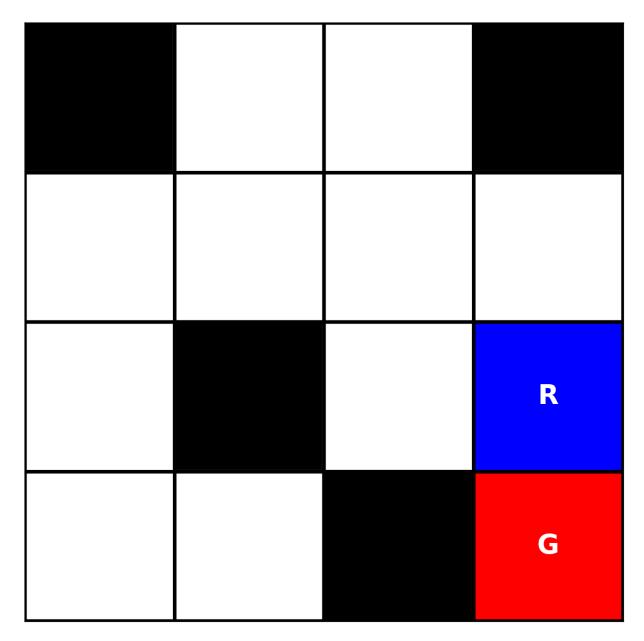


Start position: (2, 3) Goal position: (1, 1)

Obstacle positions: NO OBSTACLES IN THIS GRID

SOLUTION:

(MOVE-LEFT-FROM-TO (2, 3) (2, 2)) (MOVE-LEFT-FROM-TO (2, 2) (2, 1)) (MOVE-UP-FROM-TO (2, 1) (1, 1))

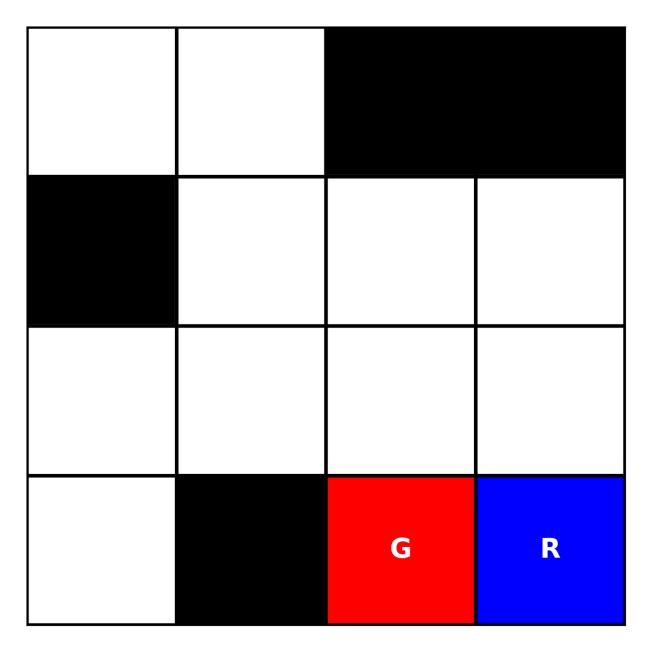


Start position: (2, 3) Goal position: (3, 3)

Obstacle positions: (0, 0), (0, 3), (2, 1), (3, 2)

SOLUTION:

(MOVE-DOWN-FROM-TO (2, 3) (3, 3))

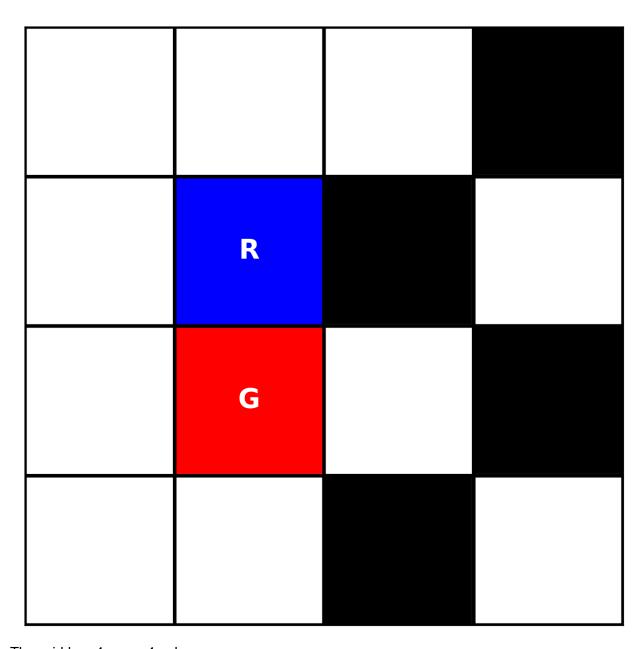


Start position: (3, 3) Goal position: (3, 2)

Obstacle positions: (0, 2), (0, 3), (1, 0), (3, 1)

SOLUTION:

(MOVE-LEFT-FROM-TO (3, 3) (3, 2))

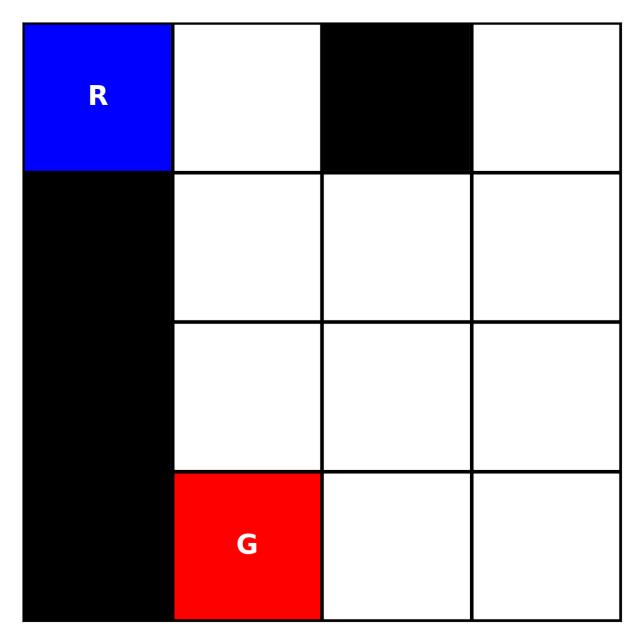


Start position: (1, 1) Goal position: (2, 1)

Obstacle positions: (0, 3), (1, 2), (2, 3), (3, 2)

SOLUTION:

(MOVE-DOWN-FROM-TO (1, 1) (2, 1))



Start position: (0, 0) Goal position: (3, 1)

Obstacle positions: (0, 2), (1, 0), (2, 0), (3, 0)

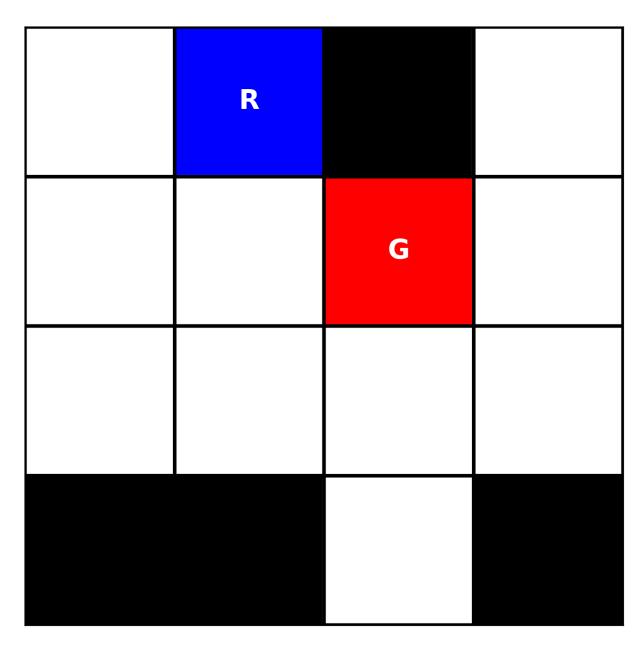
SOLUTION:

(MOVE-RIGHT-FROM-TO (0, 0) (0, 1))

(MOVE-DOWN-FROM-TO (0, 1) (1, 1))

(MOVE-DOWN-FROM-TO (1, 1) (2, 1))

(MOVE-DOWN-FROM-TO (2, 1) (3, 1))

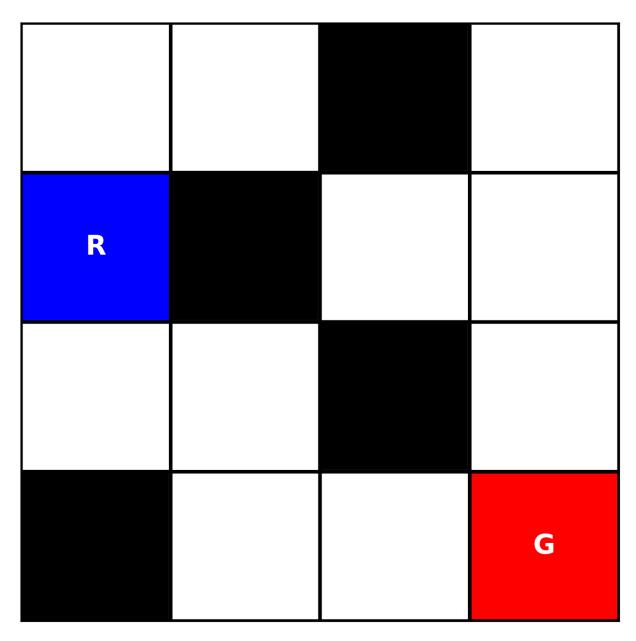


Start position: (0, 1) Goal position: (1, 2)

Obstacle positions: (0, 2), (3, 0), (3, 1), (3, 3)

SOLUTION:

(MOVE-DOWN-FROM-TO (0, 1) (1, 1)) (MOVE-RIGHT-FROM-TO (1, 1) (1, 2))



Start position: (1, 0) Goal position: (3, 3)

Obstacle positions: (0, 2), (1, 1), (2, 2), (3, 0)

SOLUTION:

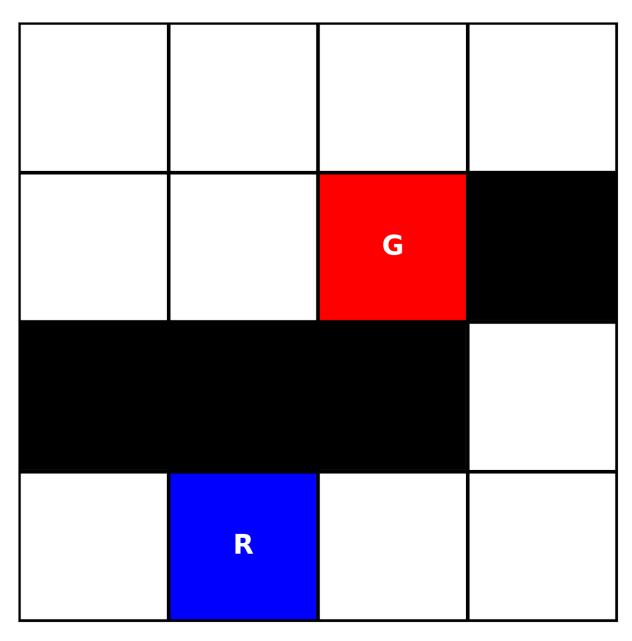
(MOVE-DOWN-FROM-TO (1, 0) (2, 0))

(MOVE-RIGHT-FROM-TO (2, 0) (2, 1))

(MOVE-DOWN-FROM-TO (2, 1) (3, 1))

(MOVE-RIGHT-FROM-TO (3, 1) (3, 2))

(MOVE-RIGHT-FROM-TO (3, 2) (3, 3))

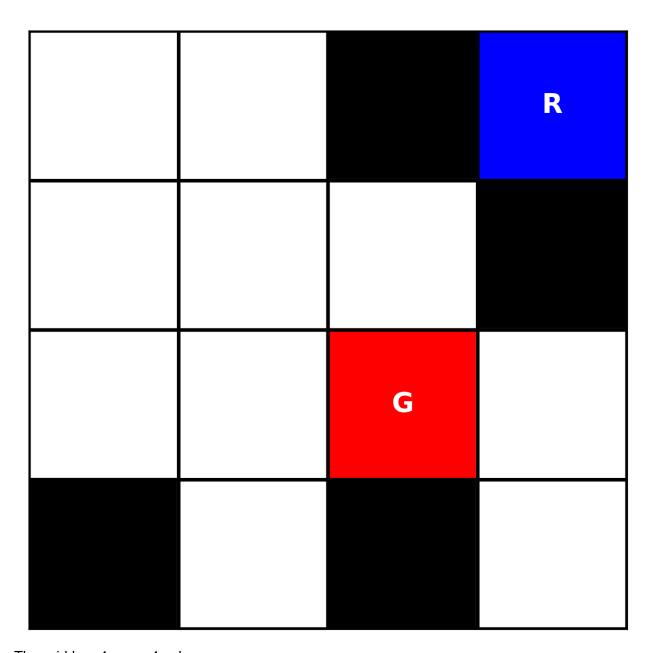


Start position: (3, 1) Goal position: (1, 2)

Obstacle positions: (1, 3), (2, 0), (2, 1), (2, 2)

SOLUTION:

NO PLAN FOUND



Start position: (0, 3) Goal position: (2, 2)

Obstacle positions: (0, 2), (1, 3), (3, 0), (3, 2)

SOLUTION:

NO PLAN FOUND.