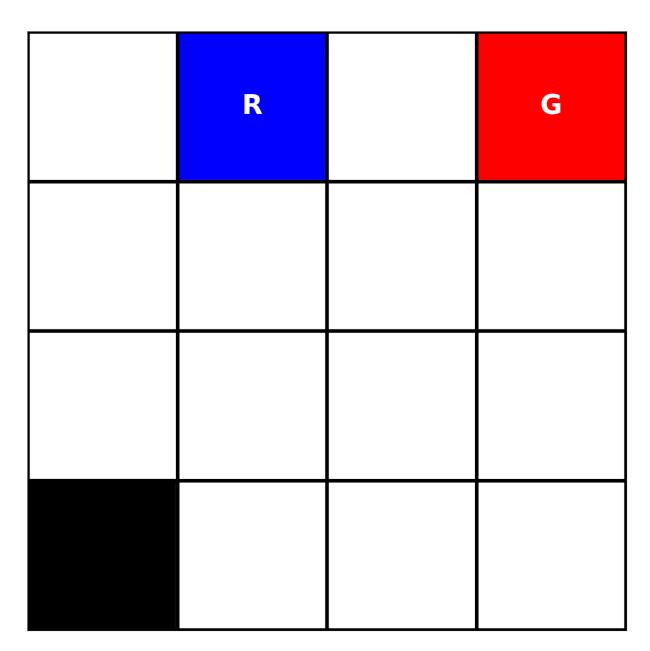
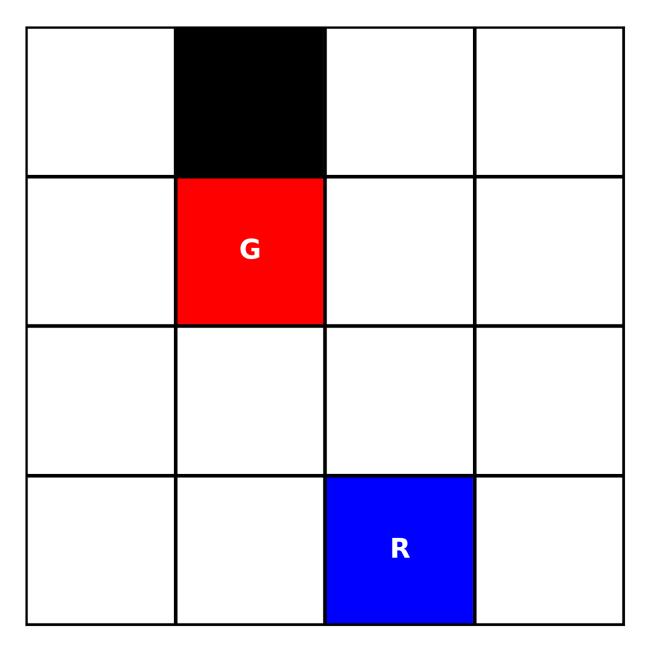


(MOVE-DOWN-FROM-TO ROBOT1 X0 Y0 X1 Y0) (MOVE-DOWN-FROM-TO ROBOT1 X1 Y0 X2 Y0)



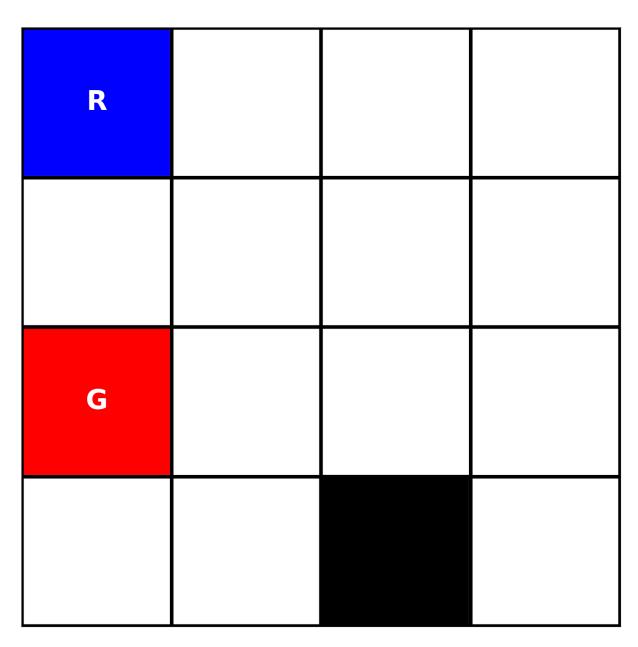
SOLUTION: (MOVE-RIGHT-FROM-TO ROBOT1 X0 Y1 X0 Y2) (MOVE-RIGHT-FROM-TO ROBOT1 X0 Y2 X0 Y3)



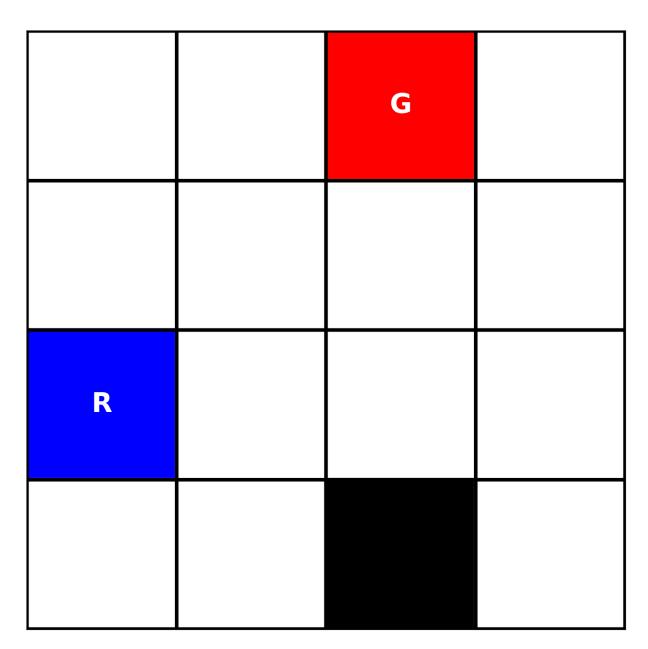
(MOVE-LEFT-FROM-TO ROBOT1 X3 Y2 X3 Y1)

(MOVE-UP-FROM-TO ROBOT1 X3 Y1 X2 Y1)

(MOVE-UP-FROM-TO ROBOT1 X2 Y1 X1 Y1)



SOLUTION: (MOVE-DOWN-FROM-TO ROBOT1 X0 Y0 X1 Y0) (MOVE-DOWN-FROM-TO ROBOT1 X1 Y0 X2 Y0)

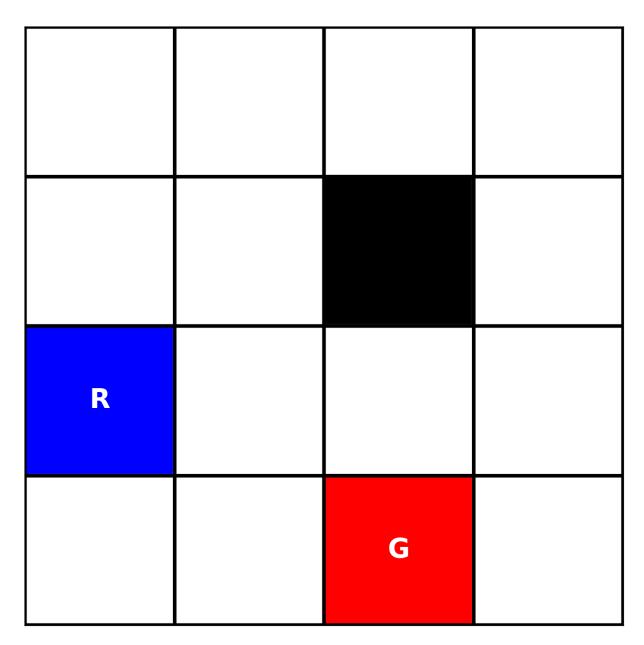


(MOVE-UP-FROM-TO ROBOT1 X2 Y0 X1 Y0)

(MOVE-UP-FROM-TO ROBOT1 X1 Y0 X0 Y0)

(MOVE-RIGHT-FROM-TO ROBOT1 X0 Y0 X0 Y1)

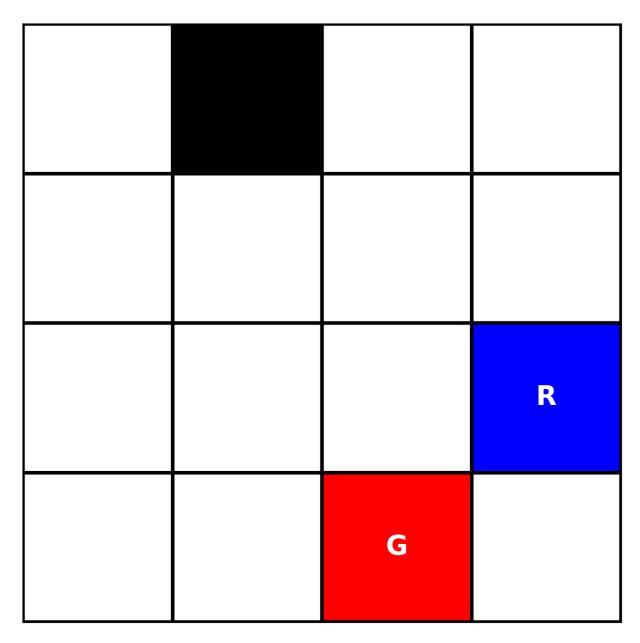
(MOVE-RIGHT-FROM-TO ROBOT1 X0 Y1 X0 Y2)



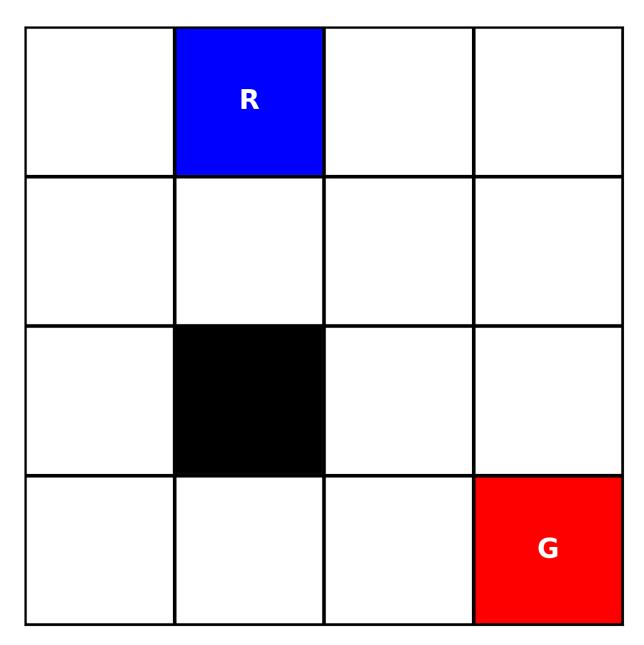
(MOVE-DOWN-FROM-TO ROBOT1 X2 Y0 X3 Y0)

(MOVE-RIGHT-FROM-TO ROBOT1 X3 Y0 X3 Y1)

(MOVE-RIGHT-FROM-TO ROBOT1 X3 Y1 X3 Y2)



SOLUTION: (MOVE-DOWN-FROM-TO ROBOT1 X2 Y3 X3 Y3) (MOVE-LEFT-FROM-TO ROBOT1 X3 Y3 X3 Y2)



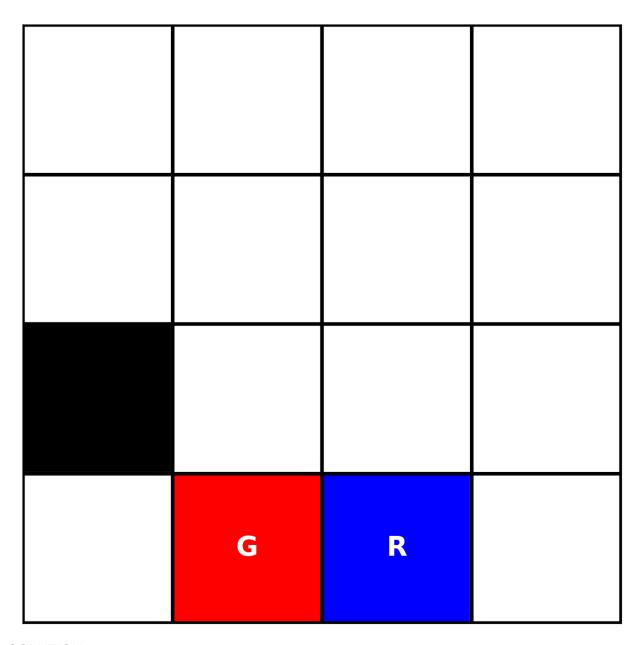
(MOVE-RIGHT-FROM-TO ROBOT1 X0 Y1 X0 Y2)

(MOVE-RIGHT-FROM-TO ROBOT1 X0 Y2 X0 Y3)

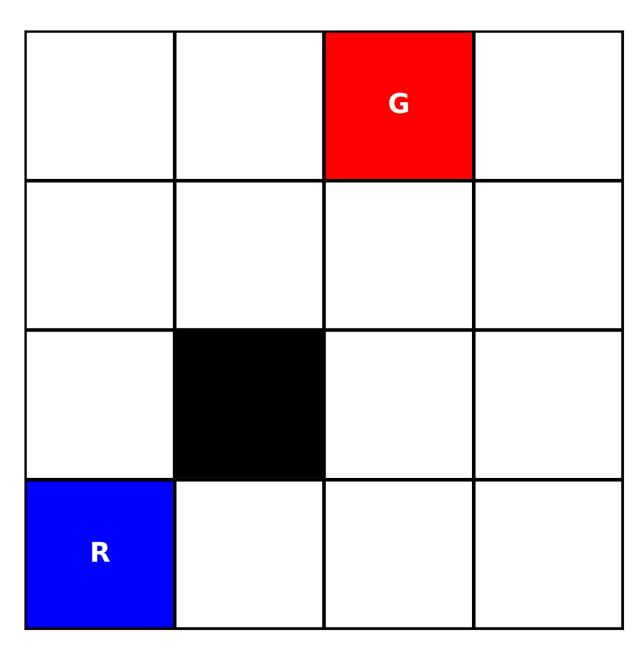
(MOVE-DOWN-FROM-TO ROBOT1 X0 Y3 X1 Y3)

(MOVE-DOWN-FROM-TO ROBOT1 X1 Y3 X2 Y3)

(MOVE-DOWN-FROM-TO ROBOT1 X2 Y3 X3 Y3)



SOLUTION: (MOVE-LEFT-FROM-TO ROBOT1 X3 Y2 X3 Y1)



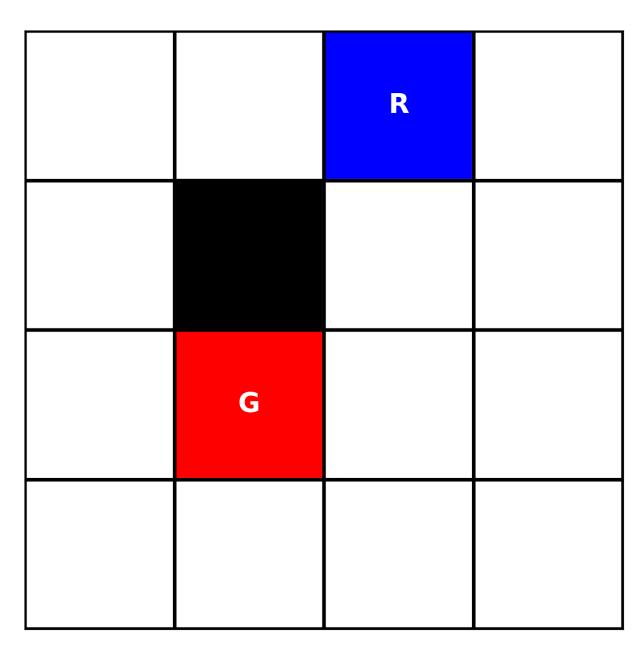
(MOVE-UP-FROM-TO ROBOT1 X3 Y0 X2 Y0)

(MOVE-UP-FROM-TO ROBOT1 X2 Y0 X1 Y0)

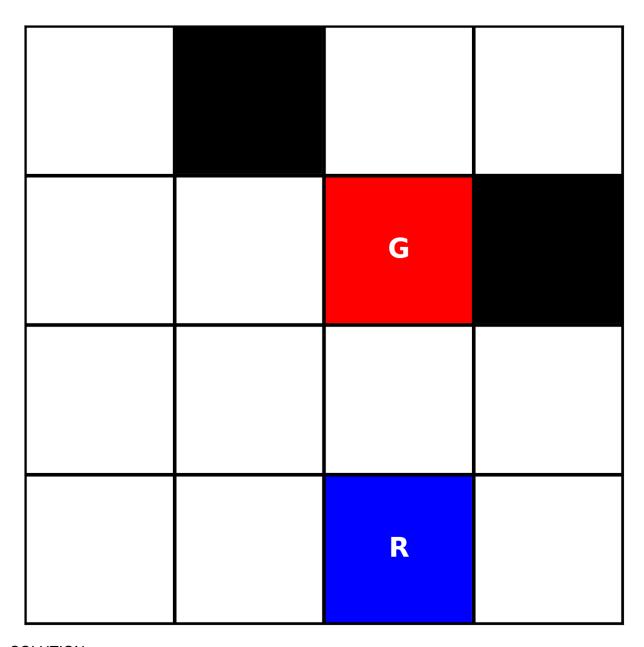
(MOVE-UP-FROM-TO ROBOT1 X1 Y0 X0 Y0)

(MOVE-RIGHT-FROM-TO ROBOT1 X0 Y0 X0 Y1)

(MOVE-RIGHT-FROM-TO ROBOT1 X0 Y1 X0 Y2)

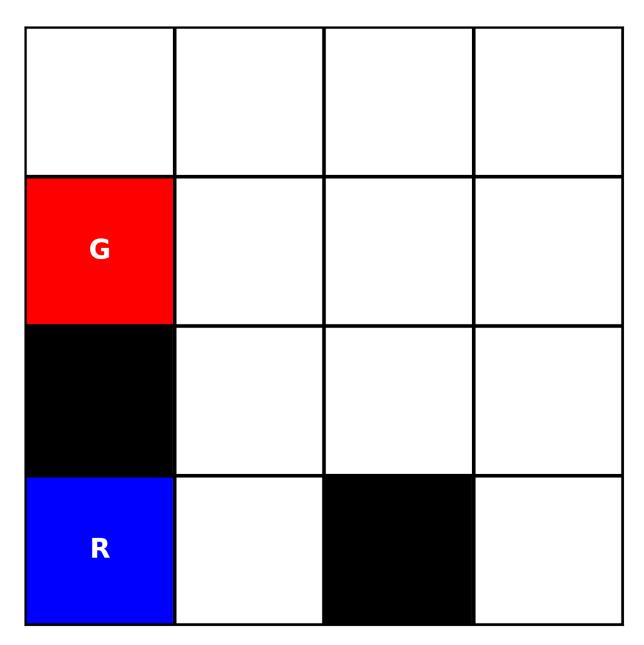


(MOVE-DOWN-FROM-TO ROBOT1 X0 Y2 X1 Y2) (MOVE-DOWN-FROM-TO ROBOT1 X1 Y2 X2 Y2) (MOVE-LEFT-FROM-TO ROBOT1 X2 Y2 X2 Y1)



(MOVE-UP-FROM-TO ROBOT1 X3 Y2 X2 Y2)

(MOVE-UP-FROM-TO ROBOT1 X2 Y2 X1 Y2)

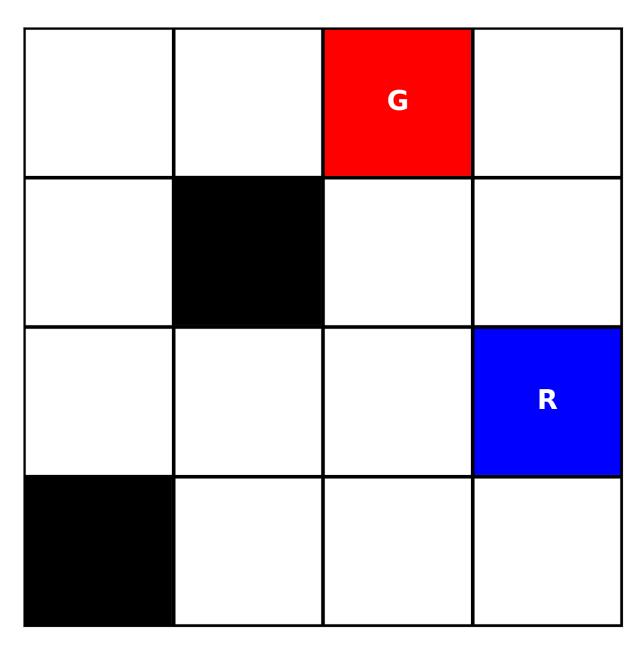


(MOVE-RIGHT-FROM-TO ROBOT1 X3 Y0 X3 Y1)

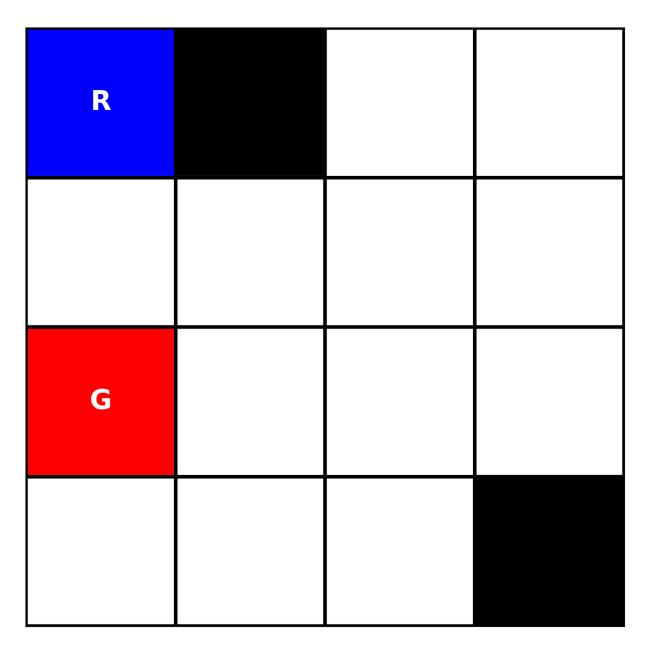
(MOVE-UP-FROM-TO ROBOT1 X3 Y1 X2 Y1)

(MOVE-UP-FROM-TO ROBOT1 X2 Y1 X1 Y1)

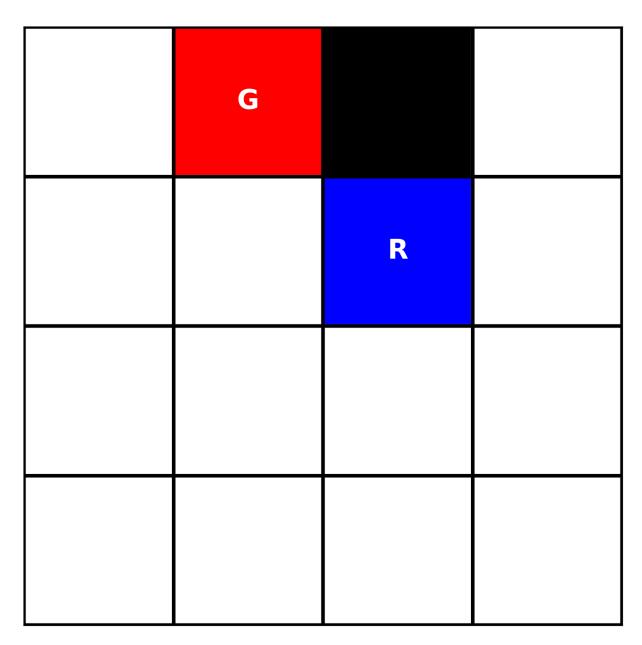
(MOVE-LEFT-FROM-TO ROBOT1 X1 Y1 X1 Y0)



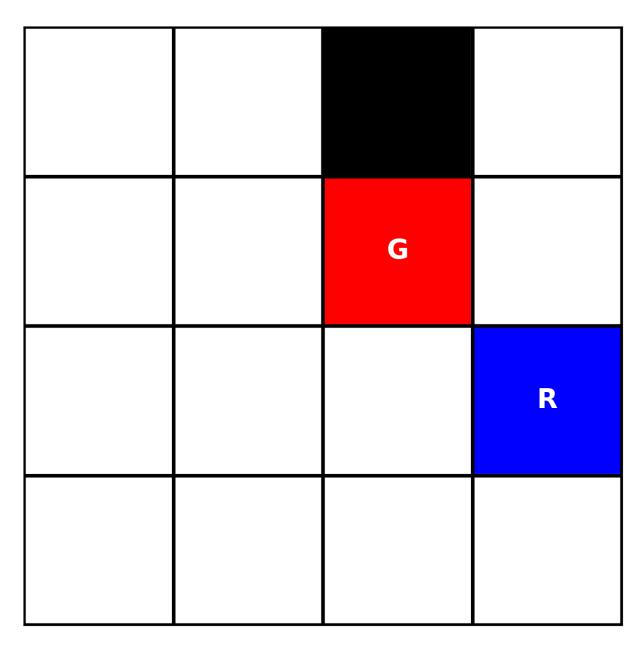
SOLUTION: (MOVE-UP-FROM-TO ROBOT1 X2 Y3 X1 Y3) (MOVE-UP-FROM-TO ROBOT1 X1 Y3 X0 Y3) (MOVE-LEFT-FROM-TO ROBOT1 X0 Y3 X0 Y2)



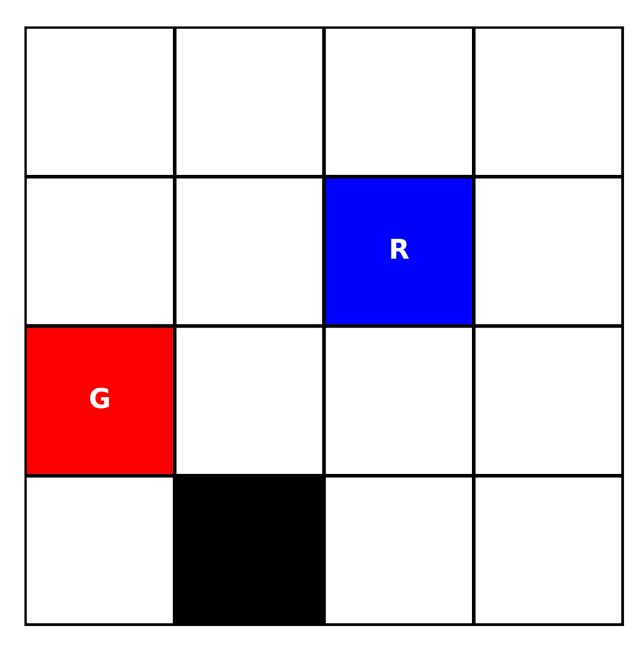
SOLUTION: (MOVE-DOWN-FROM-TO ROBOT1 X0 Y0 X1 Y0) (MOVE-DOWN-FROM-TO ROBOT1 X1 Y0 X2 Y0)



(MOVE-LEFT-FROM-TO ROBOT1 X1 Y2 X1 Y1) (MOVE-UP-FROM-TO ROBOT1 X1 Y1 X0 Y1)



(MOVE-LEFT-FROM-TO ROBOT1 X2 Y3 X2 Y2) (MOVE-UP-FROM-TO ROBOT1 X2 Y2 X1 Y2)



(MOVE-LEFT-FROM-TO ROBOT1 X1 Y2 X1 Y1) (MOVE-LEFT-FROM-TO ROBOT1 X1 Y1 X1 Y0) (MOVE-DOWN-FROM-TO ROBOT1 X1 Y0 X2 Y0)