## DAA-Quiz#4-4thNov2021-NPTheory-1

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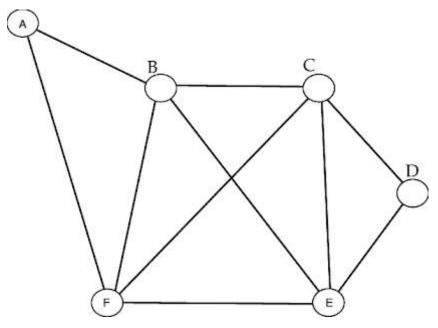
DAAQuiz#4-Chap1=NPTheory-4thNov2022

## DAAQuiz#4-Chap1=NPTheory-4thNov2022

- 1. The quiz must be attempted using your SVNIT email ID only. If attempted using any other email ID, it would NOT be considered. There will not be any exceptions to this.
- 2. Please attend the quiz that is assigned to you.
- 3. Total Questions: 50, Total Marks: 100. TimeDuration: 50 minutes. There is NO negative marking in this quiz. But, in future quizzes there will be and then for every FOUR wrong answers, 1 mark would be deducted.
- 4. Google classroom may not show the scores. Please do not assume that is your real
- 5. Time: 50 minutes. So, any guiz that is received after 11:21 am, shall NOT be graded and shall be considered as Not Attempted. Therefore, do not continue attending till 11:20 - stop at 11:20 and let the quiz be submitted and received in the next one minute.
- 6. In the regular classes, randomly any student would be asked to answer one of the quiz questions. If the student is not able to answer the question correctly and if the same has been found to have been attempted correctly in the quiz, all the marks earned for that quiz would be treated as a zero, without any questions asked/entertained. So, answer a question only if you know the correct answer.

:

Consider the graph shown in the diagram. The Maximum Clique in the given 2 points graph is given by the vertices \_\_\_\_\_ and is of size \_\_\_\_\_.



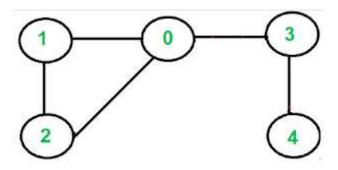
- (B, C, E, F), 4
- (D, B, C, E, F), 5
- (A, B, C, E, F), 5
- (C, E, F), 3

Clear selection

Given an undirected graph G = (V, E) and a probable circuit of the graph 2 points visiting every vertex once, the problem statement "Given a graph G = (V, E) and a circuit of vertices, does the given circuit indeed constitute a simple cycle that contains every node in V, exactly once, except for the start vertex" is an example of a \_\_\_\_\_ that \_\_\_\_\_.

- optimization problem, can be solved in polynomial time
- decision problem, can be solved in polynomial time
- optimization problem, cannot be solved in polynomial time
- O decision problem, cannot be solved in polynomial time

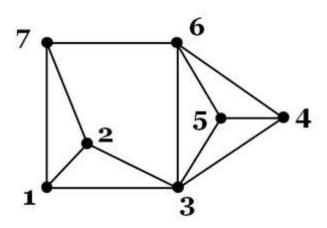
Given the graph as shown in Fig , the two distinct cliques in the graph are as 2 points follows: one is a clique consisting of vertices \_\_\_\_\_ whereas the other is a \_\_\_\_ clique consisting of vertices \_\_\_\_\_.



- 2; {0,3}; Maximal; {0,1,2,3}
- 2; {1,3}; Maximal; {0,1,2}
- 2; {3,4}; Maximum; {0,1,2}
- 3; {0,1,2}; Maximum; {0,1}

Consider the graph G = (V, E) shown in the figure. When reducing the vertex 2 points cover of this graph to a set-cover instance using appropriate gadget construction, the set cover would be given by the subsets \_\_\_\_\_\_.

[Assume that Si depicts one of the subsets in the gadget constructed for this problem, corresponding to the vertex i in the graph, and so on].



- © \$2, \$3, \$4, \$6, \$7
- S2, S3, S6, S7
- S2, S3, S5, S6, S7
- S1, S3, S4, S6, S7

Clear selection

Given the two problems viz. P as find the sum of two integers and Q as find 2 points the sum of 2<sup>n</sup> integers where n is any positive integer, one can prove that

- $\bigcap$  P  $\equiv$  Q
- P≤Q
- both P and Q belong to class NP.
- O Q≤P

Suppose the given problem is as follows: Given the jobs j_1, j_2, j_3j_5 2 points with running times t_1, t_2, t_3,t_5, where t_i's are respectively 2,2,2,3,3. Suppose the algorithm used to schedule the jobs is as follows: {Sort the jobs in descending order of their execution times. Then, schedule the first job on P_1, second job on P_2; but when scheduling j_3, schedule it on the least lightly loaded processor of the two processors.} Then, the final completion time is $\fillin$ and is the $\fillin$ .
7, sub-optimal
6, sub-optimal
7, optimal
O 6, optimal
Clear selection
Suppose a polynomial time algorithm is discovered that correctly computes 2 points the largest clique in a given graph. In this scenario, the complexity class P would be of the complexity class NP.
Superset
Subset
equal to that
one of these options.
Clear selection

The problems are those computational problems that are time whereas are those that are not solvable in polyne	•
o tractable, exponential, tractable	
tractable, polynomial, intractable	
intractable, exponential, tractable	
intractable, polynomial, tractable	
	Clear selection

Suppose the given problem is as follows: Given the jobs j\_1, j\_2, j\_3......j\_7 2 points with running times t\_1, t\_2, t\_3,......t\_7, where t\_i's are respectively 2,100,2,100,2,100,2. Suppose the algorithm used to schedule the jobs is as follows: {Sort the jobs in descending order of their execution times. Then, schedule the first job on P\_1, second job on P\_2; but when scheduling j\_3, schedule it on the least lightly loaded processor of the two processors.} Then, the final completion time is  $\left[\frac{1}{2}\right]$ 

- 202, suboptimal
- 200, optimal
- 204, suboptimal
- 104, optimal

Consider two problems viz. P and Q defined for a given graph G=(V,E). The problem P is "Single Source Shortest Path" problem. The problem Q is "All Pairs Shortest Path" problem. Thenof the following is true.
Q polynomially reduces to P
P is polynomially equivalent to Q
Neither P nor Q can be reduced to the other; either way.
P polynomially reduces to Q
Clear selection
Consider a connected graph $G = (V, E)$ , $ V  = 12$ and $ E  = 11$ . with the size $ 2 $ points of the Independent set $ S $ of this graph be $ S  = 5$ . Then, the size of the Maximum clique in the complement graph $ S $ is
<ul><li>5</li></ul>
<ul><li>○ 8</li></ul>
O 8

!

Let us assume on the first day in your cherished job, you are asked to design 2 points an algorithm to solve the following problem viz. " $\Pi 1$ : Given m available pieces of software of a system A and a set U of n capabilities that your organization would like your system A to have. Assume that the ith piece of software provides the set Si  $\subseteq$  U of capabilities." You are asked to design an algorithm to achieve all n capabilities using fewest pieces of software. Assume that you only can prove the relationship between the 3-SAT problem and the Maximum Independent Set (MIS) of a graph problem and then those that derive from this basic relationship. Then, to convince your Boss that it is futile to design an algorithm to solve the problem  $\Pi 1$  in polynomial time on arbitrary inputs, you would prove one of the following viz. \_\_\_\_\_\_.

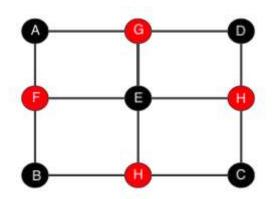
0	Π1 ≤ MIS ≤ Vertex-Cover ≤ 3SATOptio
0	3SAT ≤ MIS ≤ Vertex-Cover ≤ Π1
0	Π1 ≤ Vertex-Cover ≤ MIS ≤ 3SAT
0	3SAT ≤ Vertex-Cover ≤ MIS ≤ Π1

The polynomial time bound is preferable to use to depict the efficient algorithms because	2 points
most of the algorithms that have this time bound, exhibit complexity $O(n^c)$ , $c <= 2$ .	with
o most of the algorithms that have this time bound, do not exhibit complexity 0 with c<=2.	)(n^c),
most of the algorithms that have this time bound, exhibit complexity O(2^n).	
$\circ$ most of the algorithms that have this time bound, exhibit complexity O(n^c), v c<=4.	with
Clear s	election

(V,E	SHAM3 be the problem of finding a Hamiltonian cycle in a graph G =  (i) with   V   divisible by 3 and DHAM3 be the problem of determining (i.e. fying) if a Hamiltonian cycle exists in such graphs. Then, is true.	2 points
0	none of these	
0	SHAM3 polynomially reduces to DHAM3	
0	all of these	
0	DHAM3 is equivalent to SHAM3	
$\bigcirc$	DHAM3 polynomially reduces to SHAM3	

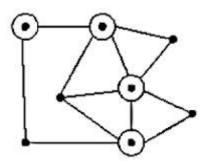
Consider the graph shown in the diagram. The Maximum Clique in the complement graph is given by the vertices \_\_\_\_\_ and is of size

2 points



- O none of these are correction options
- (A, B, C, D, E, F, G, H), 8
- (A,B, C, D, E), 5
- (E, F, G, H), 4

Given the graph as shown in the figure, it has a minimum vertex cover of 2 points size \_\_\_\_\_ nodes.



- 3, circled
- 3, uncircled-dotted
- 4, circled
- 4, uncircled-dotted,

Clear selection

Consider a set U defined as U= { Red, Yellow, Green, Blue } . Let Si be the given subsets of this set, with |Si| = 9. Then, when a gadget to relate this problem with a graph problem is designed, with graph G = (V, E), the number of vertices |V| in G, must be equal to \_\_\_\_\_.

- 3
- O 5
- ocannot be computed.

the comple	NF formula with F distinct clauses, each clause having 3 literals", exity of the function to determine whether F is satisfiable or not is such a function can be designed using approach.	2 points
O( F ^8	), dynamic programming	
O none o	f the choices given here	
O( F ^8	), brute-force	
O( F 8)	, brute-force	
	Clear sele	ection
	problem that belongs to the class NP. Then which one of the s not TRUE?	2 points
there is A polynomial time certifier which can be used to certify that given an instance and an answer to X, that answer is correct or incorrect in polynomial time.		
it can be proved that the optimisation version of the problem X cannot be solved polynomially.		
it can	pe proved that all the problems in class P can be verified polynomially	
there is no polynomial time certifier which can be used to certify that given an instance and an answer to X, that answer is correct or incorrect in polynomial time.		
	Clear sele	ection
	wo problems viz. P as find the sum of two integers and Q as find 2^n integers where n is any positive integer, one can prove that	2 points
P ≡ Q		
O P≤Q		
<b>Q</b> ≤ P		

:

Consider a graph $G = (V, E)$ , with $ V  = 9$ and $ E  = 15$ , and the Independent 2 points set of this graph S with $ S  = 5$ . Then, the size of the corresponding set cover instance in the gadget constructed for this graph is
O 5
cannot be computed
O 9
O 4
The complexity of the non-deterministic comparison based sorting 2 points algorithm NonDeterministicSorting(A, n) that takes a vector A of size n as input is
O(1)
O(n lg n)
O(lg n)
O(n)
Option 1
Ram and Shyam have been asked to comment on the solvability of a certain $2 \text{ points}$ problem $\Pi$ . Ram shows a polynomial time reduction from the 3-SAT problem to $\Pi$ , and Shyam shows a polynomial time reduction from $\Pi$ to 3-SAT. Which of the following can be inferred from these reductions?
Shyam is able to prove than Π is hard to solve, but Ram is not.
Option 5
Shyam is able to prove that 3-SAT is easier to solve as compared to Π
Ram is able to prove that Π is hard to solve, but Shyam is not.
Ram is able to prove that Π is easier to solve as compared to 3-SAT

Consider the reduction viz. 3-SAT  $\alpha$  SAT problem. Given a collection C= { C1, 2 points C2, C3, ......Cm } of clauses, where each clause consist of a set of literals drawn over a finite set of the Boolean variables U= { u1 , u2 , u3 , u4 , ...un } . Consider that we have to design an appropriate 3-SAT expression from the given SAT expression, one may use clauses ci  $\in$  C drawn on literals { z1 , z2 , z3 , ..zk } , where the z j 's are literals over U and auxiliary variables y{i,k-i} where i is the clause number to which a literal belongs to and k is the index of a literal in the clause. Then, say, we have a SAT expression as C = { z1 , z2 , z3} , consisting of three literals, the converted 3-SAT expression C" is

- $C = \{z1, z2, z3\}$
- $C = \{z1, z2, y_i, 1\}\{y_i, 1', y_i, 2, z3\}$
- $C = \{ z1, z2, y_i, 1 \} \{ z3, z4, z5 \}$
- none of these

"Given a CNF formula with F distinct clauses, with |F|=4 and with each 2 points clause having 5 literals", the complexity of the function to determine whether F is satisfiable or not is given by \_\_\_\_\_. Such a function can be designed using \_\_\_\_ approach.

- 132, brute force
- 128, dynamic programming
- 128, brute force
- 132, dynamic programming

Suppose the given problem is as follows: Given the jobs j_1, j_2, j_3j_7 2 points with running times t_1, t_2, t_3,t_7, where t_i's are respectively 2,100,2,100,2,100,2. These are required to be scheduled on say TWO processors such as to minimize the final completion time. Then, the optimal final completion time is and the algorithm that could be used to achieve the schedule is
200, sort the jobs in the descending order of their finish time and schedule them alternately on each processor.
202, sort the jobs in ascending order of their finish time and schedule them alternately on each processor.
O 200, schedule the first job on first processor, second on the second processor and then alternate the jobs between the processors.
200, brute-force
Consider the following claim, that you are asked to prove viz. "Given that for 2 points a graph G=(V,E), if S is an independent set, then V-S is a vertex cover", then of the following argument is a most appropriately valid statement useful in the proof.
of for an edge (u,v) not in S, either u in S or v in S.
of for an edge (u,v) in S, either u not in S or v not in S.
of for an edge (u,v) in S, both u, v in S.

A solution to a problem is generally considered to be efficient if its running 2 points time T(n) is
Omega(n^c), where c is some integer and n is the input size.
O(n^c), where c is some integer and n is the input size.
Theta(n^c), where c is some positive integer lesser than or equal to 3 and n is the input size.
O(n^c), where c is some positive integer and n is the input size.
The halting problem is an example of a/an problem i.e 2 points
decidable, cannot be solved on any machine
decidable, can be solved on a turing machine
undecidable, can be solved on a turing machine.
undecidable, cannot be solved on a turing machine
Let S be a hard problem decision problem and Q and R be two other 2 points decision problems not known to be hard. Q is polynomial time reducible to S and S is polynomial-time reducible to R. Which one of the following statements is true?
R is at least as hard a problem to solve as is Q.
Given an algorithm to solve S, we can solve the problem R also.
R is at the most as hard a problem to solve as in S.
The problem Q is at least as much hard to solve as S.

Suppose the given problem is as follows: Given the jobs j\_1, j\_2, j\_3.....j\_7 2 points with running times t\_1, t\_2, t\_3,......t\_7, where t\_i's are respectively 2,100,2,100,2,100,2. These are required to be scheduled on say TWO processors such as to minimize the final completion time. Then, the schedule shown in Fig is a/an \_\_\_\_\_ schedule and \_\_\_\_\_ approach can be used to design the algorithm.

P <sub>1</sub>	P <sub>2</sub>	Comment
j <sub>1</sub> (2)	j <sub>3</sub> (2)	
j <sub>5</sub> (2)		t <sub>1</sub> <=t <sub>3</sub>
	j <sub>7</sub> (2)	t <sub>1</sub> +t <sub>5</sub> <t<sub>3</t<sub>
j <sub>2</sub> (100)		t <sub>1</sub> +t <sub>5</sub> <=t <sub>3</sub> +t <sub>7</sub>
	j <sub>4</sub> (100)	t3+t7 <t1+t5+t2< td=""></t1+t5+t2<>
j <sub>6</sub> (100)		

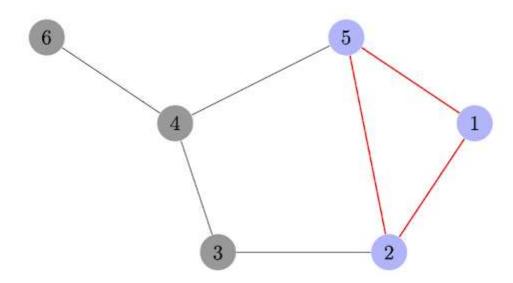
- suboptimal, greedy
- optimal, dynamic programming
- suboptimal, logical-argument-based
- osuboptimal, dynamic programming

Clear selection

Finding as large group of students as possible so that each pair therein is 2 points compatible to each other can be modeled as a \_\_\_\_\_\_.

- graph n-coloring problem
- Vertex Cover problem
- Minimal Independent Set problem
- Maximum Clique problem

Given the graph as shown in Fig , the two distinct cliques in the graph are as 2 points follows: one of the maximal clique consists of vertices \_\_\_\_\_ whereas \_\_\_\_ is not a maximal clique.



- (1,2,5)
- (3,4), {4,5}
- (4,6), {2,3}
- (4,6), {4,5}

Clear selection

A \_\_\_\_\_ approach/algorithmic-approach is the one in which an attempt 2 points is made to search the entire solution space of the problem instance to look for the optimal answer and has complexity \_\_\_\_\_ typically for input size n.

- o brute-force based, O(2^n)
- O Dynamic Programming, O(n)
- Greedy, (O(n lg n))
- O Divide and Conquer, O(lg n)

Consider that for a graph $g=(V,E)$ , you are given that S is an independent set $2 \text{ points}$ of the graph G. Consider an edge $(u,v)$ in E. Then is true.		
either u notin V-S or v notin V-S		
u notin V-S and v notin V-S		
u in S and v in S		
u notin S or v in S		
Suppose the given problem is as follows: Given the jobs j_1, j_2, j_3j_5 2 points with running times t_1, t_2, t_3,t_5, where t_i's are respectively 4,4,4,5,5. Suppose the algorithm used to schedule the jobs is as follows: Then, the optimal final completion time is		
12		
O 13		
O 8		
O 10		
Clear selection		
Consider the following claim, that you are asked to prove viz. "Given that for 2 points a graph G=(V,E), if V-S is a vertex cover, then S is an independent set", then of the following argument is a most appropriately valid statement useful in the proof.		
if u not in S and v notin S, then (u,v) is not a valid edge because V-S is a vertex cover.		
if u in S and v in S, then (u,v) is a valid edge in E.		
if u in S and v in S, then (u,v) is not a valid edge in E because V-S is a vertex cover.		
if u in S and v not in S, then (u,v) is not a valid edge because V-S is a vertex cover.		

!

Let S be a hard problem decision problem and Q and R be two other

decision problems not known to be hard. Q is polynomial time reducible to S

and S is polynomial-time reducible to R. Which one of the following
statements is true?

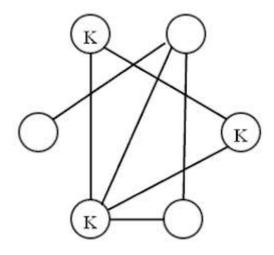
R is at least as hard a problem to solve as is Q.

The problem Q is at least as much hard to solve as S.

R is at the most as hard a problem to solve as in S.

Consider the graph shown in the figure and the vertices marked as K. These  $^2$  points vertices are forming a(n) \_\_\_\_\_ in the graph, whereas the compliment vertices in the compliment graph of this graph form a(n) \_\_\_\_\_ of size

Given an algorithm to solve S, we can solve the problem R also.



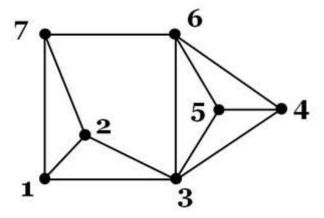
- Indenpendent set, Vertex cover, 3
- 3-clique, Independent set, 3
- Indenpendent set, maximum clique, 3
- 3-clique, Vertex-cover, 3

Consider a connected graph G = (V, E), |V| = 12 and |E| = 11 with the size of 2 points the Vertex cover S of this graph be |S| = 5. Then, the size of the Maximum clique in the complement graph G' is \_\_\_\_\_\_.

- $\bigcirc$  6
- 0 8
- 7
- **(**) 5

Clear selection

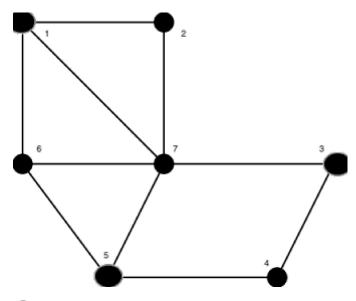
Given the graph as shown in Fig , the graph has \_\_\_\_\_ maximal 3-clique, 2 points \_\_\_\_\_ 4-clique and the independent set in the compliment graph has maximum \_\_\_\_ vertices.



- 5,2,4
- 6,1,3
- 6, 1, 4
- 5,1,3

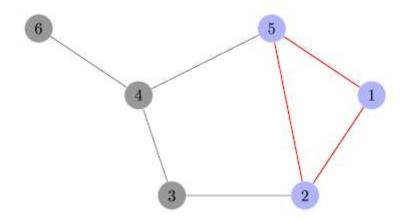
vertic	me that G=(V,E) be a given connected graph that has a clique S of ces such that   S   = k. Let GC be its compliment graph. Let (u,v) be any in GC . Then, and are true.	2 points
O E	Either u OR v is not in S, At least one of u or v belong to V-S.	
O r	none of the above can be inferredption 1	
O E	Both of u and v are not in S, None of u or v belong to V-S.	
O E	Both of u and v are not in S, At least one of u or v belong to V-S.	
NonE and r	asymptotic complexity of Nondeterministic Search algorithm DeterministicSearch(x, A), that takes a vector A with n elements as input eturns the index of an element x in A, if found and a 0, otherwise is  ———————————————————————————————————	2 points

Given the graph as shown in the figure, it has a minimum vertex cover of 2 points size \_\_\_\_\_\_, given by the nodes \_\_\_\_\_.



- 4, {2,4,6,7}
- 3, {1,3,5}
- 3, {2,4,7}
- 4, {1,3,6,5}

Given the graph as shown in Fig , the graph has \_\_\_\_\_ maximal cliques 2 points and \_\_\_\_\_ maximum 3-clique.



- **4**,1
- 6,1
- 5,1
- 2,2

Clear selection

Consider that you are given an art-gallery problem  $\Pi 1$  in which the question 2 points is to place guards within the art gallery so that all corridors are visible at any time. In order to either design an algorithm to solve this problem or to prove that the problem is hard to solve, you would use \_\_\_\_\_.

- the independent-set problem as the basis for reduction
- the vertex-cover problem as the basis for reduction.
- the 3-SAT problem as the basis for reduction
- the maximum-clique problem as the basis for reduction

A Complexity Class P or NP or EXP - <u>each</u> individually - is a collection of 2 points		
of decision problems all of which cannot be solved in SAME resource bounds		
of optimization problems all of which can be solved in SAME resource bounds		
of decision problems all of which can be solved in the SAME, respective, resource bounds		
of optimization problems that are hard to solve.		
Clear selection		
A polynomial time bound of an algorithm's complexity is considered as 2 points One of the reasons not true (not applicable to this observation) is		
efficient, most algorithms have polynomial time bounds		
o inefficient, if an algorithm's time complexity is $O(n^c)$ , then c for most algorithms is normally lesser than 3.		
inefficient, polynomial operation does not satisfy closure property.		
efficient, polynomial operation satisfies closure as well as graph properties.		
efficient, polynomial bounds allow machine independence.		
efficient, if an algorithm's time complexity is O(n^c), then c for most algorithms is normally lesser than 3.		
Clear selection		

!

An algorithm with time bound is considered to be efficient, because 2 points it exhibits a property known as property; which implies that		
polynomial, closure, if we add/combine two algorithms with polynomial time bounds, the resulting algorithm also has polynomial time bound.		
o polynomial, machine independence, if we add/combine two algorithms with polynomial time bounds, the resulting algorithm also has a polynomial time bound.		
o polynomial, closure, using multiple algorithms with polynomial time bounds has no effect on the overall time taken by the algorithm to execute.		
o polynomial, closure, if we add/combine two algorithms with polynomial time bounds, the resulting algorithm has an exponential time bound.		
Clear selection		
For the two problems P and Q, if we are given that problem P ≤ Q 2 points (polynomially), it implies that and also that  the problem P is at least as difficult as Q; given an algorithm to solve P, one can solve Q using the algorithm and some function(s).  the hardness of solving Q does not exceed that of solving P; given an algorithm to solve, given an algorithm to solve P and some function, one can solve the problem Q  the hardness of solving Q may equal or exceed that of solving P; given an algorithm to solve Q, one can solve P using that algorithm and some function(s).  the problems P and Q are equally hard to solve; using an algorithm for one, the other problem can be solved		
Clear selection		
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