# Maximize Margin Width

- Maximize  $\frac{\gamma}{\|\mathbf{w}\|}$  subject to
- $y_i(w^Tx_i + b) \ge \gamma$  for i = 1, 2, ..., m
- Scale so that  $\gamma = 1$
- Maximizing  $\frac{1}{\|w\|}$  is the same as minimizing  $\|w\|^2$
- Minimize w. w subject to the constraints
- for all  $(x_i, y_i)$ , i = 1, ..., m:  $w^T x_i + b \ge 1$  if  $y_i = 1$  $w^T x_i + b \le -1$  if  $y_i = -1$

minimize 
$$\frac{1}{2} \|\mathbf{w}\|^2$$
  
s.t.  $y_i(\mathbf{w}^T \mathbf{x}_i + b) \ge 1$ 

- Optimization problem with convex quadratic objectives and linear constraints
- Can be solved using QP.
- Lagrange duality to get the optimization problem's dual form,
  - Allow us to use kernels to get optimal margin classifiers to work efficiently in very high dimensional spaces.
  - Allow us to derive an efficient algorithm for solving the above optimization problem that will typically do much better than generic QP software.

## Lagrangian Duality in brief

The Primal Problem

$$\min_{w} f(w)$$
s.t.  $g_{i}(w) \le 0, i = 1,...,k$ 
 $h_{i}(w) = 0, i = 1,...,l$ 

The generalized Lagrangian:

$$L(w, \alpha, \beta) = f(w) + \sum_{i=1}^{k} \alpha_i g_i(w) + \sum_{i=1}^{l} \beta_i h_i(w)$$

the  $\alpha$ 's ( $\alpha_i \ge 0$ ) and  $\beta$ 's are called the Lagrange multipliers Lemma:

$$\max_{\alpha,\beta,\alpha_i \ge 0} L(w,\alpha,\beta) = \begin{cases} f(w) & \text{if } w \text{ satisfies primal constraints} \\ \infty & \text{otherwise} \end{cases}$$

A re-written Primal:

$$\min_{w} \max_{\alpha,\beta,\alpha,\geq 0} L(w,\alpha,\beta)$$

#### Lagrangian Duality, cont.

The Primal Problem  $p^* = \min_{w} \max_{\alpha, \beta, \alpha_i \ge 0} L(w, \alpha, \beta)$ 

The Dual Problem:  $d^* = \max_{\alpha,\beta,\alpha_i \ge 0} \min_{w} L(w,\alpha,\beta)$ 

Theorem (weak duality):

$$d' = \max_{\alpha,\beta,\alpha_i \ge 0} \min_{w} L(w,\alpha,\beta) \le \min_{w} \max_{\alpha,\beta,\alpha_i \ge 0} L(w,\alpha,\beta) = p'$$

Theorem (strong duality):

Iff there exist a saddle point of  $L(w, \alpha, \beta)$ , we have d' = p'

#### The KKT conditions

If there exists some saddle point of L, then it satisfies the following "Karush-Kuhn-Tucker" (KKT) conditions:

$$\frac{\partial}{\partial w_i} L(w, \alpha, \beta) = 0, \quad i = 1, ..., k$$

$$\frac{\partial}{\partial \beta_i} L(w, \alpha, \beta) = 0, \quad i = 1, ..., l$$

$$\alpha_i g_i(w) = 0, \quad i = 1, ..., m$$

$$g_i(w) \le 0, \quad i = 1, ..., m$$

$$\alpha_i \ge 0, \quad i = 1, ..., m$$

**Theorem**: If  $w^*$ ,  $a^*$  and  $b^*$  satisfy the KKT condition, then it is also a solution to the primal and the dual problems.

#### **Support Vectors**

- Only a few  $\alpha_i$ 's can be nonzero
- Call the training data points whose  $\alpha_i$ 's are nonzero the support vectors

$$\alpha_i g_i(w) = 0, \quad i = 1, \dots, m$$

If 
$$\alpha_i > 0$$
 then  $g(w) = 0$ 

Quadratic programming with linear constraints

minimize 
$$\frac{1}{2} \|\mathbf{w}\|^2$$

s.t. 
$$y_i(\mathbf{w}^T\mathbf{x}_i + b) \ge 1$$

Lagrangian Function



minimize 
$$L_p(\mathbf{w}, b, \alpha_i) = \frac{1}{2} ||\mathbf{w}||^2 - \sum_{i=1}^n \alpha_i (y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1)$$
s.t.  $\alpha_i \ge 0$ 

$$\begin{aligned} & \text{minimize} \ \ L_p(\mathbf{w},b,\alpha_i) = \frac{1}{2} \big\| \mathbf{w} \big\|^2 - \sum_{i=1}^n \alpha_i \left( y_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 \right) \\ & \text{s.t.} \quad \ \alpha_i \geq 0 \end{aligned}$$

Minimize wrt w and b for fixed  $\alpha$ 

$$\frac{\partial L_p}{\partial \mathbf{w}} = \mathbf{0} \qquad \mathbf{w} = \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i$$

$$\frac{\partial L_p}{\partial b} = \mathbf{0} \qquad \sum_{i=1}^n \alpha_i y_i = \mathbf{0}$$

$$L_p(w,b,\alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i^T \mathbf{x}_j) - b \sum_{i=1}^m \alpha_i y_i$$

$$L_p(w,b,\alpha) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i,j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i^T \mathbf{x}_j)$$

# The Dual problem

Now we have the following dual opt problem:

$$\max_{\alpha} \mathbf{J}(\alpha) = \sum_{i=1}^{m} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{m} \alpha_{i} \alpha_{j} y_{i} y_{j} (\mathbf{x}_{i}^{T} \mathbf{x}_{j})$$
s.t.  $\alpha_{i} \geq 0$ ,  $i = 1, ..., k$ 

$$\sum_{i=1}^{m} \alpha_{i} y_{i} = 0.$$

This is a quadratic programming problem.

– A global maximum of  $\alpha_i$  can always be found.

#### Support vector machines

Once we have the Lagrange multipliers  $\{\alpha_i\}$  we can reconstruct the parameter vector w as a weighted combination of the training examples:

$$w = \sum_{i=1}^m \alpha_i y_i \mathbf{x}_i$$

$$w = \sum_{i=1}^{m} \alpha_i y_i \mathbf{x}_i \qquad w = \sum_{i \in SV} \alpha_i y_i \mathbf{x}_i$$

- For testing with a new data z
  - Compute

$$w^{T}z + b = \sum_{i \in SV} \alpha_{i} y_{i} (\mathbf{x}_{i}^{T}z) + b$$

and classify z as class 1 if the sum is positive, and class 2 otherwise

Note: w need not be formed explicitly

The discriminant function is:

$$g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b = \sum_{i \in SV} \alpha_i \mathbf{x}_i^T \mathbf{x} + b$$

- It relies on a dot product between the test point x and the support vectors x;
- Solving the optimization problem involved computing the dot products X<sub>i</sub><sup>T</sup>X<sub>j</sub> between all pairs of training points
- The optimal 11 is a linear combination of a small number of data points.