

# Design and Analysis of Algorithms, MTech-I (1<sup>st</sup> semester)

## Chapter 2: Divide and Conquer Design Approach

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- 1 Introduction
- 2 The Merge-sort Algorithm
- 3 Merge-sort Applications

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  - Brute force:  $n^2$ .
  - Divide-and-conquer:  $n \log n$ .

# Motivation

## DC algorithms often

- have lesser running times
- their running time can be determined by the standard tech to solve recurrences.

# The Sorting Problem

## Obvious sorting applications

- List files in a directory.
- Organize an MP3/MPEG library.
- List names in a phone book.
- Display Google PageRank results.

## Not so obvious sorting applications

- Data compression.
- Computer graphics.
- Interval scheduling.
- Computational biology.
- Minimum spanning tree.
- Supply chain management.
- Simulate a system of particles.
- Book recommendations on Amazon.
- Load balancing on a parallel computer

# The Sorting Problem...

The problem becomes easier if sorting applied

- Find the median.



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The problem becomes easier if sorting applied

- Find the median.
- Find the closest pair.
- Binary search in a database.
- Identify statistical outliers.
- Find duplicates in a mailing list.

# Merge Sort: The Basic Logic

## Overall Logic

- Divide array into two halves.



Jon von Neumann (1945)

A L G O R I T H M S

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divide  $O(1)$

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sort  $2T(n/2)$

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- Merge two halves to make sorted whole.



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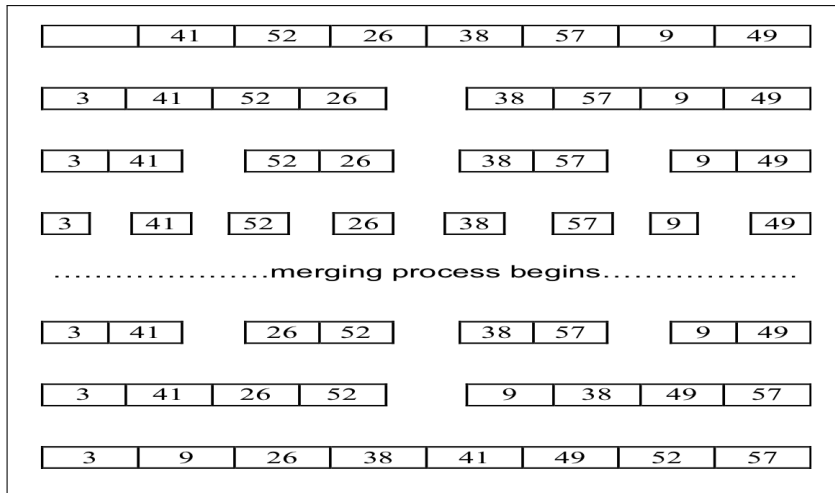
# The Conquer Logic: Merging

Merging. Combine two pre-sorted lists into a sorted whole.

- How to merge efficiently?
- Linear number of comparisons.
- Use temporary array.
- The Challenge: In-place merge. [Kronrud, 1969]
- The Demo of Merge



# Viewing Merge-sort in execution



# The Merge-sort pseudocode

The Algorithm Merge-sort( $A, p, r$ )

1 if ( $p < r$ )

2     then  $q \leftarrow \lfloor (p + r)/2 \rfloor$

3         MERGE-SORT( $A, p, q$ )

4         MERGE-SORT( $A, q+1, r$ )

5         MERGE( $A, p, q, r$ )

# The Merge procedure

```
Algorithm MERGE (A, p, q, r)
1      let i = p and j = q+1 and k = 1
2      while (i <= q) and (j <= r)
3          do      if A[i] <= A[j]
4                      then B[k] = A[i]
5                      i = i + 1, k = k + 1
6                      else B[k] = A[j]
7                      j = j + 1, k = k + 1
// here one of the subarrays is in B
8      if i > q then
9          for index = j to r
10             do B[k] = A[index]
11                k = k + 1
12             else for index = i to q
13                 do B[k] = A[index]
14                    k = k + 1
15     for index = p to r
16         do A[index] = B[index]
17     return
```

# The Merge Demo

Run the Demo MergeDemoFromPPT.mp4

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  - an equation which defines a function over the natural numbers say  $T(n)$ , in terms of its own values at one or more integers smaller than  $n$ .
  - expresses the resources used by the recursive procedures



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$C(n)$  - time to combine into solutions

$\theta(1)$  - time to solve the atomic subproblems - for small inputs such that  $n \leq c$  for some  $c$ .

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$T(n)$

$= \theta(1)$  for  $n \leq c$  for some  $c$ .

$= aT(n/b) + D(n) + C(n) \dots \dots$  otherwise. recurrence relation using boundary conditions and without it



# The Merge-sort recurrence relation

- $T(n)$  = number of comparisons to mergesort an input of size  $n$ .

$$T(n) \leq \begin{cases} 0 & \text{if } n = 1 \\ T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor) + n & \text{otherwise} \end{cases}$$

solve left half                  solve right half                  merging

Figure: Mergesort Recurrence Relation

- Guess solution  $T(n) = O(n \lg n)$
- We now show number of ways to prove this result

## Solving the recurrence : The Recursion Tree method

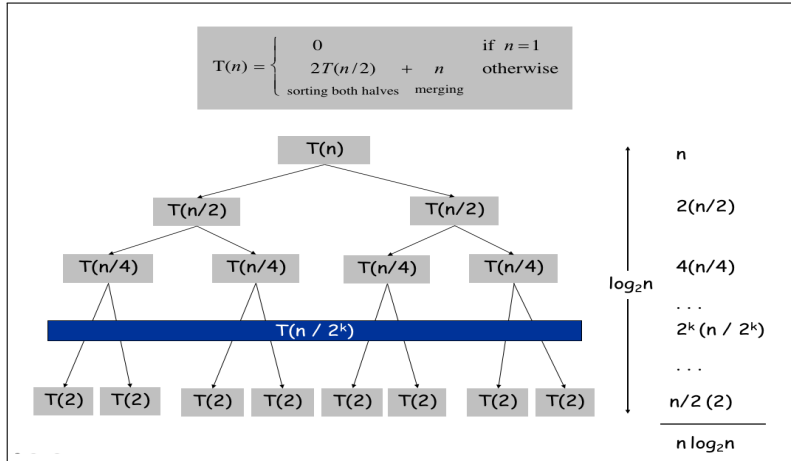


Figure: The Recursion Tree method

## Solving the recurrence: By iterative substitution

$$T(n) = \begin{cases} 0 & \text{if } n = 1 \\ 2T(n/2) + n & \text{otherwise} \end{cases}$$

sorting both halves      merging

Claim: If  $T(n)$  satisfies this recurrence, then  $T(n) = n \log_2 n$  - assuming  $n$  is a power of 2

Proof : ... ..

## Solving the recurrence : Proof by telescoping

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# Solving the recurrence : Proof by Mathematical Induction

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Claim: If  $T(n)$  satisfies this recurrence, then  $T(n) = n \log_2 n$  - assuming  $n$  is a power of 2

- Base case:  $n = 1$ .
- Inductive hypothesis:  $T(n) = n \lg n$ .
- Goal: show that  $T(2n) = 2n \lg (2n)$ .

Proof : ... ..

... ..

# Analysis of the Merge-sort recurrence

- What if  $n$  is not assumed to be a power of 2 ?

$$T(n) \leq \begin{cases} 0 & \text{if } n = 1 \\ T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor) + n & \text{otherwise} \end{cases}$$

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## Proof by induction on $n$

- Base case:  $n = 1$ .
- Define  $n_1 = \lfloor n/2 \rfloor$  ,  $n_2 = \lceil n/2 \rceil$
- Induction step: assume true for 1, 2, ... ,  $n-1$ .
- Proof: ... ..

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- Then, we have to solve the following recurrence ...

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# *Solving Recurrences: Tutorial Problems*



# Solving the recurrences: By iterative substitution

Solve the following recurrences

- 1 Claim: If  $T(n)$  satisfies the recurrence  $T(n) = 2T(n/2) + n$ , then  $T(n) = n \log_2 n$  - assuming  $n$  is a power of 2
- 2 x

# Solving the recurrences: By Master's Theorem

Solve the following recurrences using Master's theorem

1.  $T(n) = 2T(n/2) + n$
2.  $T(n) = 3T(n/2) + n^2$
3.  $T(n) = T(n/2) + 2^n$
4.  $T(n) = 2^n T(n/2) + n^n$
5.  $T(n) = 16T(n/4) + n$
6.  $T(n) = 2T(n/2) + n \log n$
7.  $T(n) = 3T(n/4) + n^{0.51}$
8.  $T(n) = 16T(n/4) + n!$

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①  $T(n) = \sqrt{2}T(n/2) + \log n$

②  $T(n) = 3T(n/2) + n$

③  $T(n) = 3T(n/3) + \sqrt{n}$

④  $T(n) = 4T(n/2) + cn$

⑤  $T(n) = 3T(n/4) + n \log n$

⑥  $T(n) = 3T(n/3) + n/2$

⑦  $T(n) = 7T(n/3) + n^2$

⑧  $T(n) = 4T(n/2) + \log n$

# *MergeSort Applications: 1*

# Counting Inversion: Motivation

## Collaborative Flitering

- A number of websites use collaborative filtering to "identify" people with similar taste and then push the related contents to the entire collection.
- The meta-search engines execute the same query on many different search engines and then try to synthesize the results by looking for similarities.

There are many such other applications where *finding similarity* is required. What could be the metric ?

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- How to find the items *out of order* between two lists
- Songs  $i$  and  $j$  inverted if  $i < j$ , but  $a_i > a_j$ .
- Suppose your ranking of five songs is 5,4,3,2,1 and mine is in ascending order. How many are out of order ?

# Counting the items out of order

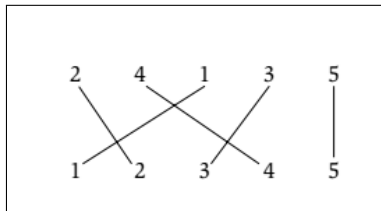
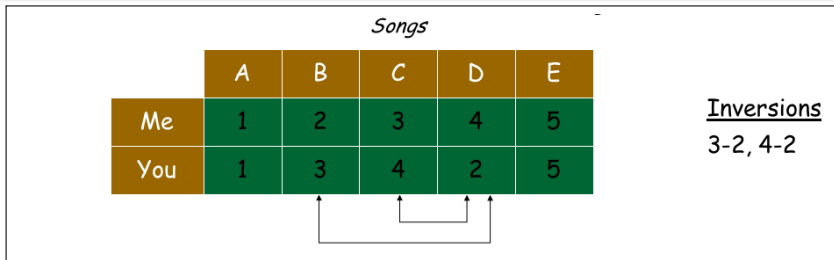


Figure: Similarity metric: Inversion: number of inversions between two rankings.

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- Hence, we need faster algorithms.....
- Asymptotically faster algorithm must compute total number **without even looking at each inversion individually.**

# Counting Inversion: Applications

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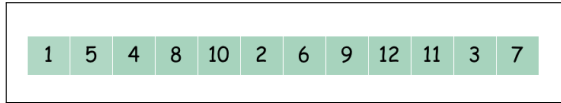
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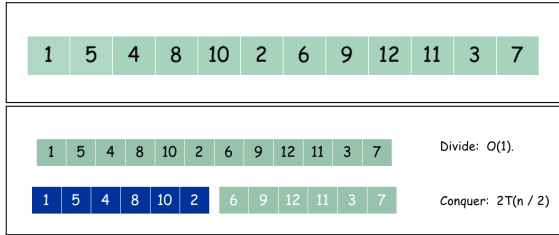
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- Nonparametric statistics (e.g., Kendall's Tau distance).

# Counting Inversions : Logic





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# Counting Inversions : Logic

1	5	4	8	10	2	6	9	12	11	3	7
---	---	---	---	----	---	---	---	----	----	---	---

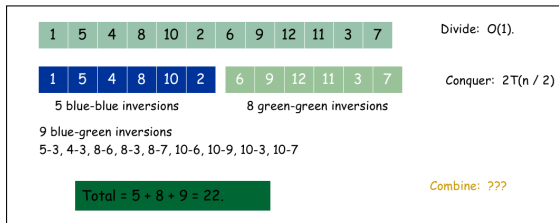
1	5	4	8	10	2	6	9	12	11	3	7	Divide: $O(1)$ .
1	5	4	8	10	2	6	9	12	11	3	7	Conquer: $2T(n/2)$

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1	5	4	8	10	2	6	9	12	11	3	7	Conquer: $2T(n/2)$
5 blue-blue inversions						8 green-green inversions						
5-4, 5-2, 4-2, 8-2, 10-2						6-3, 9-3, 9-7, 12-3, 12-7, 12-11, 11-3, 11-7						

# Counting Inversions: Divide and Conquer

- Divide: separate list into two pieces.
- Conquer: recursively count inversions in each half.
- Combine: count inversions where  $a_i$  and  $a_j$  are in different halves, and return sum of three quantities. Complexity ??

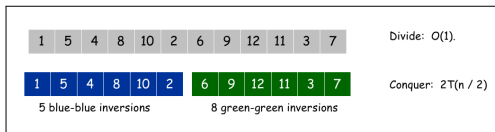


# Dry running Merge-and-count(A,B)

Given the two sorted subhalves A and B

- Combine: count blue-green inversions
- Assume each half is sorted.
- Count inversions where  $a_i$  and  $a_j$  are in different halves.
- Merge two sorted halves into sorted whole.

Apply the logic to the given two subhalves as below

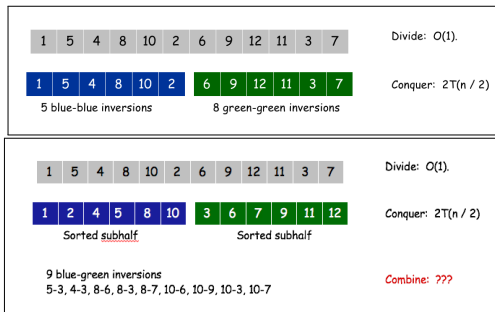


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# The Merge-Invert Demo

Run the Demo MergeInvertFromPPT

## Counting Inversions pseudocode: MergeandCount(A,B)

```
Algorithm Merge-and-count(A, B)
Maintain a Current pointer into each list ,
    initialized to point to the front elements
Maintain a variable Count for the number of inversions ,
    initialized to 0
While both lists are nonempty {
    Let  $a_i$  and  $b_j$  be the elements pointed to
        by the Current pointer
    Append the smaller of these two to the output list
    If  $b_j < a_i$  then
        increment Count by the number of
            elements remaining in A
        Advance the Current pointer in the list from
            which the smaller element
            was selected.
}
```

# Complexity

3	7	10	14	18	19
---	---	----	----	----	----

2	11	16	17	23	25
6	3	2	2	0	0

13 blue-green inversions:  $6 + 3 + 2 + 2 + 0 + 0$

Count:  $O(n)$

2	3	7	10	11	14	16	17	18	19	23	25
---	---	---	----	----	----	----	----	----	----	----	----

Merge:  $O(n)$

$$T(n) \leq T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil) + O(n) \Rightarrow T(n) = O(n \log n)$$



# Counting Inversion: Implementation

Algorithm Sort-and-Count(L):

\\ Pre-condition: [Merge-and-Count] A and B are sorted.

\\ Post-condition. [Sort-and-Count] L is sorted.

1. if list L has one element
2. return 0 and the list L
3. Divide the list into two halves A and B
4.  $(r_A, A) \leftarrow \text{Sort-and-Count}(A)$
5.  $(r_B, B) \leftarrow \text{Sort-and-Count}(B)$
6.  $(r, L) \leftarrow \text{Merge-and-Count}(A, B)$
7. return  $r = r_A + r_B + r$  and the sorted list L

# *MergeSort Applications: 2*

# Mergesort Applications: Closest Pairs of Points

## Closest pair

Given  $n$  points in the plane, find a pair with smallest Euclidean distance between them.

What is the Euclidean distance between points  $p_1(x_1, y_1)$  and  $p_2(x_2, y_2)$  ?

# Closest Pairs of Points: Applications

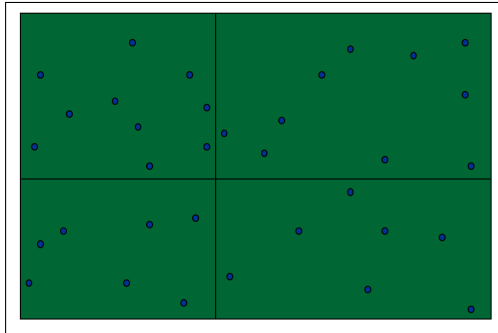
- Fundamental geometric primitive in
  - graphics, pattern recognition
  - computer vision, image processing, VLSI design
  - geographic information systems,
  - molecular modeling,
  - air traffic control.
  - Special case of nearest neighbor, Euclidean MST, Voronoi.

# Finding Closest Pairs.: Approaches

- Brute force: What will be the time for a brute force approach ?
- How would it work ?
- 1-D version....What is a 1-D version ?
- Approach. ....
  - Divide into two parts and compute within each. ....
  - $O(n \log n)$  easy if points are on a line.
  - Assumption: No two points have different x coordinate.
- What do learn from this exercise ?

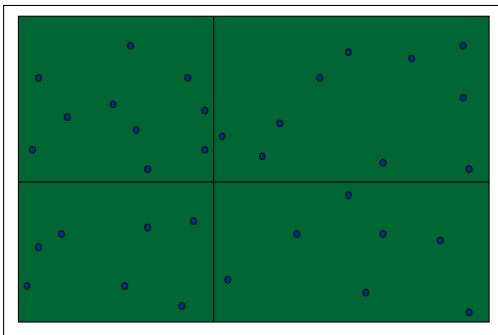
# Closest Pairs...First attempt

- Divide. Sub-divide region into 4 quadrants.



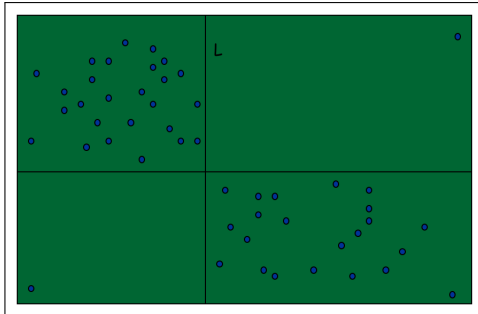
## Closest Pairs...First attempt

- Divide. Sub-divide region into 4 quadrants.
- What is the obstacle in this case ?



# Closest Pairs...First attempt...

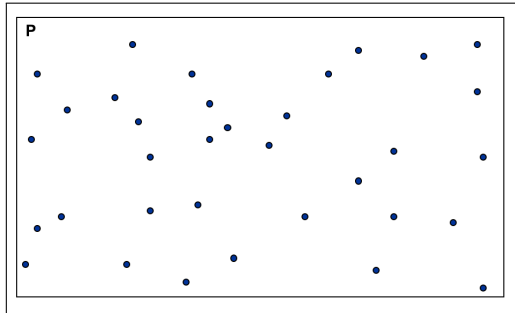
- The obstacle





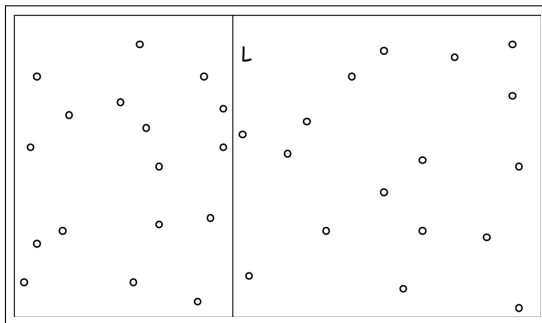
# Closest Pairs: D & C Approach

- Suppose we are given a sample point set  $P$  as shown below:



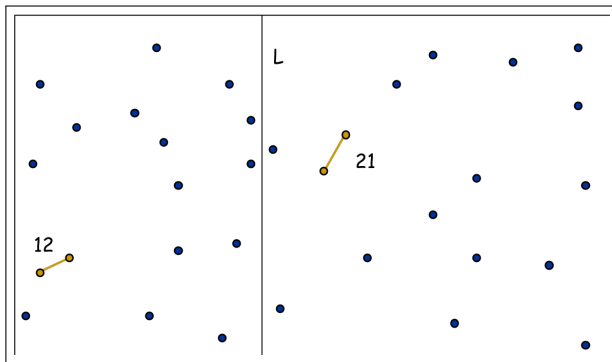
## Closest Pairs: D & C Approach...

- Suppose we are given a sample point set  $P$  as shown below:
- Divide: Draw a vertical line  $L$  so that roughly  $(1/2)n$  points are there on each side.



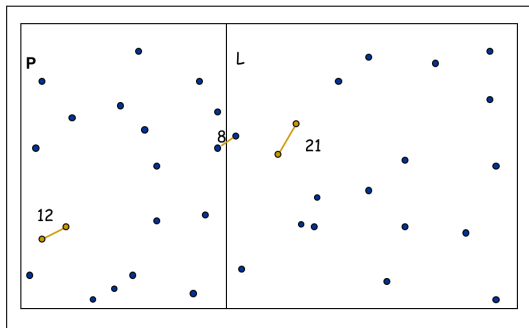
## Closest Pairs: D & C Approach...

- Divide: Draw a vertical line  $L$  so that roughly  $(1/2)n$  points are there on each side.
- Conquer: Find the closest pair in each side recursively.
- What is the partial recurrence relation ?



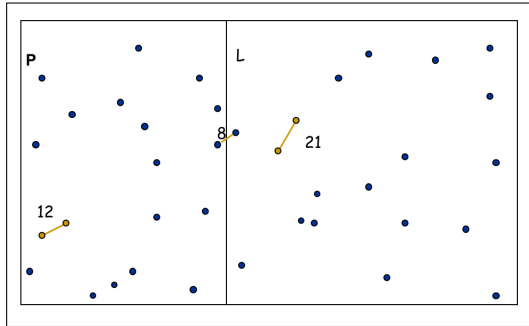
## Closest Pairs: D & C Approach...

- Divide: Draw a vertical line  $L$  so that roughly  $(1/2)n$  points are there on each side.
- Conquer: Find the closest pair in each side recursively.
- Combine: Find closest pair with one point in each side.
- Return the best of 3 solutions.



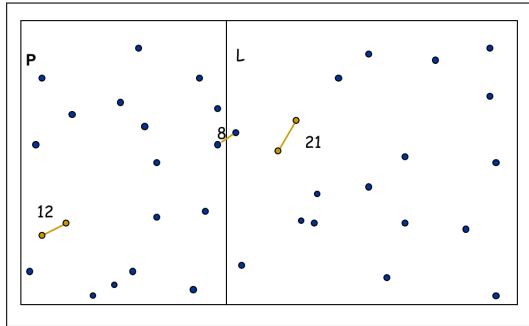
# Closest Pairs: D & C Approach...

- How does the recurrence relation now take shape ?



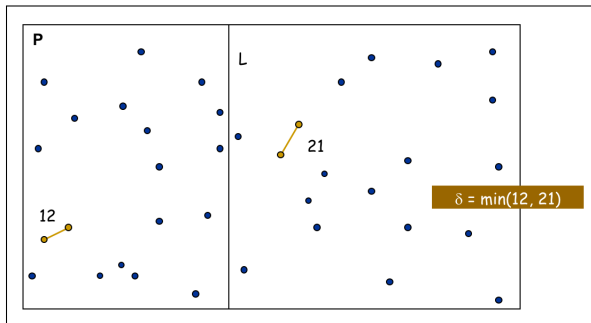
# Closest Pairs: D & C Approach...

- What is the time required for combining ?



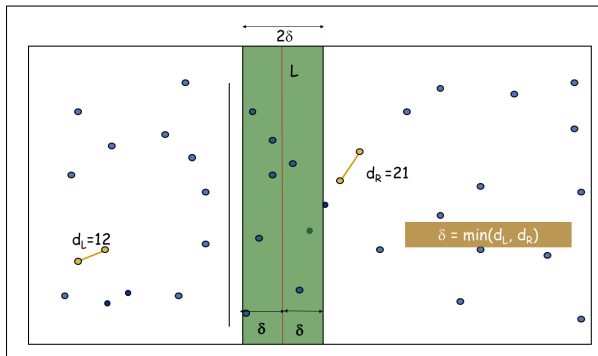
## Closest Pairs: Second D & C Approach

- Find closest pair with one point in each side, assuming that distance  $< \delta$  i.e.  
 $\delta = \min(d_L, d_R)$



## Closest Pairs: Second D & C Approach

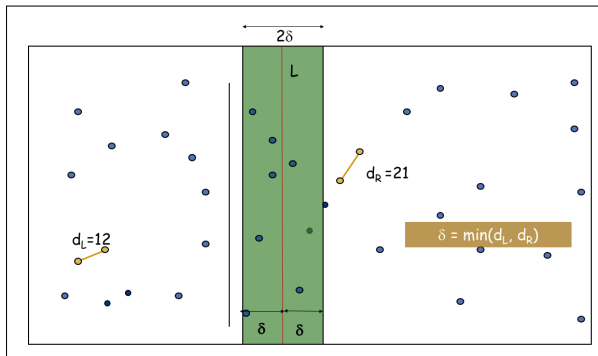
- What is the primary observation and inference especially having computed  $d_L$  and  $d_R$  and  $\delta = \min(d_L, d_R)$  ?





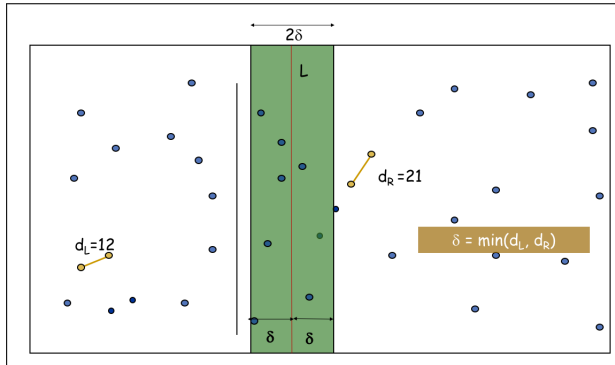
## Closest Pairs: Second D & C Approach

- What is the primary observation and inference especially having computed  $d_L$  and  $d_R$  and  $\delta = \min(d_L, d_R)$  ?
- we need to compute  $d_C$  i.e. the distance between two points splitting across the left and the right subhalves ONLY if the  $d_C$  improves upon the  $d_L$  and  $d_R$ .



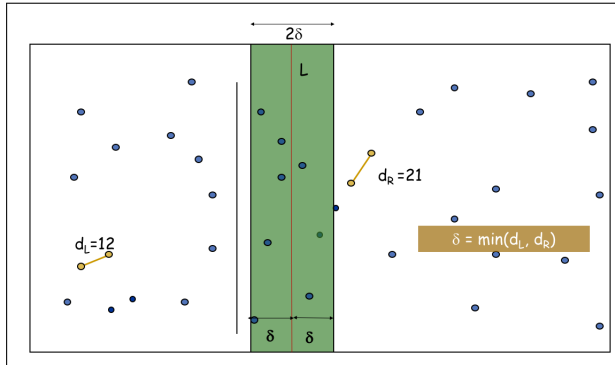
## Closest Pairs: Second D & C Approach...

- How many points could be there in this strip ?



## Closest Pairs: Second D & C Approach...

- Then, how to compute the distance  $\min(\delta(dL, dR), dC)$  ?



## Closest Pairs: Second D & C Approach...

- Then, how to compute the distance  $\min(\delta(d_L, d_R), d_C)$  ?

Algorithm ComputeMin()

```

1. for i = 1 to Num_points_in_the_strip
2     for j = (i+1) to Num_points_in_the_strip
3         if (dist( $P_i$ ,  $P_j$ ) <  $\delta$ )
4              $\delta = \text{dist}(P_i, P_j)$ 
    
```

Not efficient

- With all the points located in the strip, the complexity is  $\theta(n^2)$
- Thus, there is a need to improve upon this approach.....

## Closest Pairs: Second D & C Approach...

### Two approaches

- We assume that with  $n$  points in the entire plane, there are only  $O(n^{0.5})$  points in the strip on an average. . . .
- We can do a brute force on the points lying in the strip.
- What will be the time taken by this approach for brute force then ?
- What will be the total run time ?
- But, then is it possible ?? Can it be assumed in the worst case ?

## Closest Pairs: Second D & C Approach...

- Improved approach : Sort the points in the strip based on their y coordinaes....

Algorithm ComputeMinImproved()

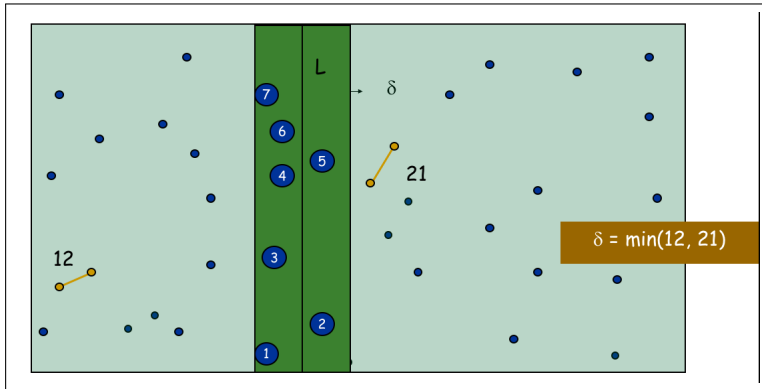
```

1. for i = 1 to Num_points_in_the_strip
2.     for j = (i+1) to Num_points_in_the_strip
3.         if (  $P_i$  and  $P_j$  's y coordinates differ by
                more than  $\delta$  )
4.             break; //Go to the next P
5.         else
6.             if (  $\text{dist}(P_i, P_j) < \delta$  )
7.                  $\delta = \text{dist}(P_i, P_j)$ 

```

## Closest Pairs: Second D & C Approach...

- only need to consider points within  $\delta$  of line  $L$ .
- Sort points in  $2\delta$ -strip by their  $y$  coordinate.



## Closest Pairs: Second D & C Approach...

- only need to consider points within  $\delta$  of line L.
- Sort points in  $2\delta$ -strip by their y coordinate.
- How many points to be considered in the worst case ?

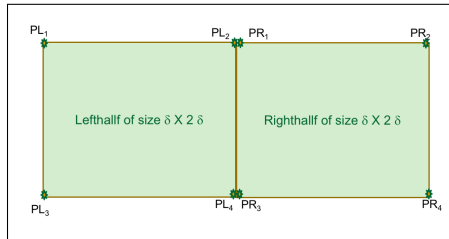


## Closest Pairs: Second D & C Approach...

- Let  $s_i$  be the point in the  $2\delta$ -strip, with the  $i$ -th smallest y-coordinate.
- Claim. If  $|i - j| \geq 7$ , then the distance between the distinct points  $s_i$  and  $s_j$  is at least  $\delta$
- Proof.

### Proof

Proof to be worked out.



## Closest Pairs: Second D & C Approach...

### Time for computing $d_C$

Because only seven points are considered for each  $p_i$ , the time for computing  $d_C$  that is better than  $\delta$  is  $O(n)$ .

Thus, we appear to have a  $O(n \log n)$  solution to the closest pairs of points problem.

# Closest Pairs algorithm

Algorithm ClosestPair( $p_1, \dots, p_n$ )

1. Compute separation line  $L$  such that half the points  
are on one side and half on the other side
2.  $\delta_1 = \text{Closest-Pair}(\text{left half})$
3.  $\delta_2 = \text{Closest-Pair}(\text{right half})$
4.  $\delta = \min(\delta_1, \delta_2)$
5. Delete all points further than  $\delta$  from separation  
line  $L$
6. Sort remaining points by  $y$ -coordinate.
7. Scan points in  $y$ -order and compare distance between  
each point and next 11 neighbors.  
If any of these distances is less  
than  $\delta$ , update  $\delta$ .
8. return  $\delta$ .

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  - We have assumed that a list of points sorted by  $y$  coordinates is already available.

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This is certainly better than the brute force  $O(n^2)$  work.

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*B L A N K   P A G E*

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