Design and Analysis of Algorithms, MTech-I (1st semester) Chapter 6: NP Theory - I

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Broad Contents of the talks

• Talk1: Complexity Classes of Problems and a few "Hard" problems.

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- Talk3: Non-determinism, Working with NPHard, NPComplete.

- Talk1: Complexity Classes of Problems and a few "Hard" problems.
 - What does solving problems algorithmically, mean?
 - Classifying problems
 - A Motivating Example to illustrate hardness
 - Some Hard Problems

- **1** Talk2: Relating Problem Hardness & Polynomial Reductions
 - Reductions
 - 4 How can we relate hardness of two problems ?
 - Mow can we relate solvability of two problems?
 - Polynomial Reduction of one problem to the other
 - Polynomial Equivalence of one problem to the other
 - Three methods of reductions: illustrations

- **3** Talk3: Non-determinism, Working with NPHard, NPComplete.
 - The concept of non-determinism

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 - The Class P, NP, EXP of problems
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 - Proofs associated
 - Summarizing

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- Two types of problems solving approaches
 - Algorithmic. What is the advantage? Is it required to be iterative?
 - Intuitive. Then, has to be iterative.

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- So, now why do we need an algorithm ?



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- Explore the ways to improve?

Polynomial or Intractable ?

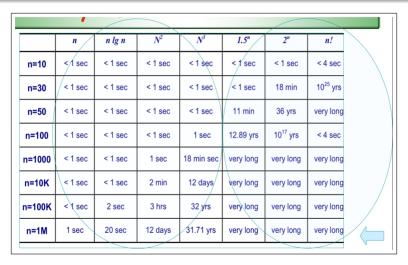


Figure: Complexity Orders related to the time of execution

Sorting

- Sorting
- Searching

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- Searching (O lg n), Sorting (O(n lg n)), Polynomial evaluation (O(n)......

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 - Closure property

- Can every problem have an efficient i.e. one that is bounded polynomially in time, solution?
- What then, are the non-efficient (i.e. inefficient!) solutions?

Non-efficient solutions

 A solution to a problem is generally considered to be non-efficient if it is found using the brute force approach.

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- Though this may not be true always.....

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- If the input size is n, typical time taken is 2^n .

Desiderata: Classifying Problems

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- In 1936, Alan Turing proved that the halting problem the question of whether or not a Turing machine halts on a given program is undecidable. This result was later generalized by Rice's theorem.

Should we waste our time designing an algorithm to a problem that is globally and over time believed to be undecidable OR intractable?

Machine scheduling to minimize the average job completion time

• Given a set of m processes $j_1, j_2, j_3, \ldots j_m$ with running times $t_1, t_2, t_3, \ldots t_t$ to be scheduled on specified n no of machines $m_1, m_2, m_3, \ldots m_n$ such that

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 - no process is executed by more than one machine
 - there is non-preemptive scheduling
 - the average job completion time is minimized.

Goal: Minimizing the average job completion time.....

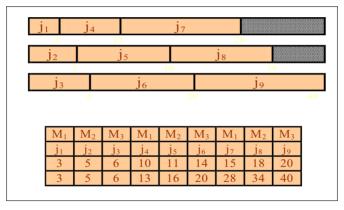


Figure: What is the Average job completion time?

Goal: To prove that the SJF (or SRTN, if premptive scheduling) scheduling indeed ensures optimal i.e. minimal average job completion time.....

Proof:

Machine scheduling to minimize the final completion time of machines used.

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 - the final completion time is minimized.

Goal: Minimizing the Final Completion time of processors.....

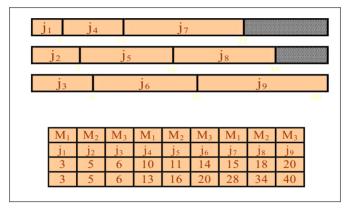


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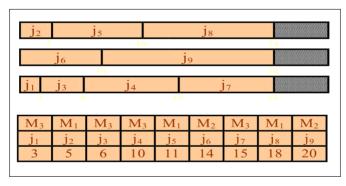


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- We wish to improve upon this finish time of whatever is the last job to execute i.e. we wish to evenly distribute the jobs across the two processors s.t.



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j_1	j_2

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- What would be the schedule in the previous example with this approach i.e. for the job mix with the jobs $j_1, j_2, j_3 \ldots j_7$ with running times 2,100,2,100,2,100,2?

• If we put the first job on P_1 , second job on P_2 for the job mix with the jobs $j_1, j_2, j_3 \dots j_7$ with running times 2,100,2,100,2,100,2, what is the schedule ?

P_1	P_2	Comment
$j_1(2)$	$j_2(100)$	
$j_3(2)$		$t_1 < t_2$
$j_4(100)$		$t_1 + t_3 < t_2$
	$j_{5}(2)$	$t_2 < t_1 + t_3 + t_4$
	$j_6(100)$	$t_2 + t_5 < t_1 + t_3 + t_4$
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- What is the earliest finish time now?
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 - What is the schedule that we obtain for the previous example with this approach? What is the finish time of the last process to complete?

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Motivating Example: Counterexample: Attempt#3...

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Figure: Optimal Schedule

• Jobs $j_1, j_2, j_3, \ldots, j_n$ with running times $t_1, t_2, t_3, \ldots, t_n$ to be scheduled on say three processors such as to minimize the final completion time, i.e. last job finishes the earliest...for the schedule give below

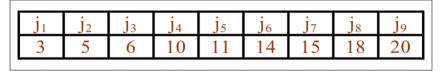


Figure: Minimize the Final Completion time with three processors

• What is the final completion time ?

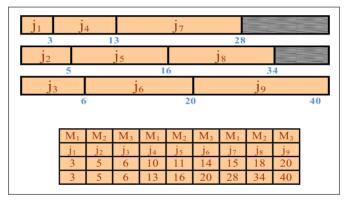


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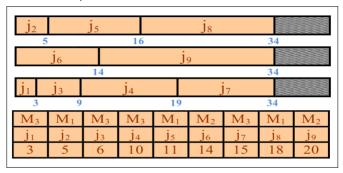


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• How could have this schedule been achieved?

• Applying the brute force......

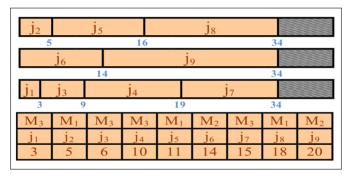


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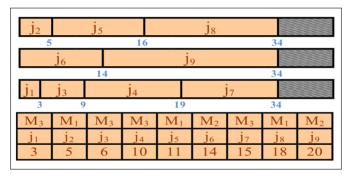


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Why study NP Theory?

- So, now what is the rationale behind exploring the NP theory?
- The rationale is......
- Well, the rationale is to understand that there are problems that are going to take infeasible amount of time on a deterministic machine and so one may not waste energytrying to solve them......

Can you think of a similar computational problem ?

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Classifying Problems

Tractable problems = Efficiently solvable ????

Intractable problems = Inefficiently solvable ????

Figure: Classifying problems

The Frustrating news

No reasonably fast algorithms have been found Intractability of these problems cannot be proved

Figure: Our Focus now onwards is on Intractable problems

- Computation has become pervasive in all walks of life a standard tool in about every academic field
 - whole subfields of Chemistry, Biology, Physics, Economics OR
 - others devoted to large-scale computational modelling, simulations and problem solving.
- We need to understand therefore, the limitations of computational power. . . .

- Study of P, NP theory
 - helps understand, handle various topics in allied sciences
 - helps what can be feasibly solved and what cannot be also
 - enables one to EXPLOIT the advantage due to HARDNESS of various computational problems
 - e.g.....

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 - Possible answers

- Is there a polynomial-time algorithm that solves the problem?
 - Possible answers
 - yes

- Is there a polynomial-time algorithm that solves the problem?
 - Possible answers
 - yes
 - no

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 - no
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 - because it can be proved that all algorithms take exponential time
 - because it can be proved that no algorithm exists at all to solve this problem
 - don't know
 - don't know, but if such algorithm were to be found, then it would provide a means of solving many other problems in polynomial time

Some Hard Problems

Other interesting hard problems

- A large group of students to be grouped to work on projects so as to ensure compatibility
- Matching students in pairssolvable
- Hard problems
 - Making a group of three so that each pair in each trio is compatible to each other..... ???

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 - Finding as large group of students as possible so that each pair therein is compatible to each other.....???
 - Wanting the student to sit across a table so that no incompatible students sit next to each other???
 - Putting students into three groups so that each student is in the same group with his/her compatible partner...???

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- Cliques in Social Networks human groups form cliques on the basis of age, gender, race, ethnicity, religion/ideology, and many other things
- What is a clique in a graph G(V,E)?

 \bullet A graph G=(V, E) is a Clique if every two nodes in V are connected by an edge

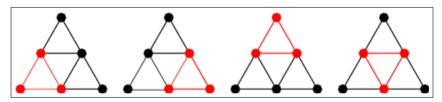


Figure: 3-Clique

- \bullet A graph G=(V, E) is a Clique if every two nodes in V are connected by an edge
- K-CLIQUE

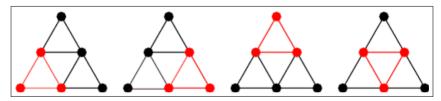


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- A graph G=(V, E) is a Clique if every two nodes in V are connected by an edge
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 - Given a graph G=(V,E), if k-vertices in a graph are connected to each other then, it is a k-clique e.g.

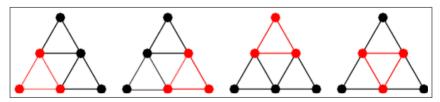


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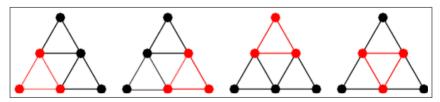


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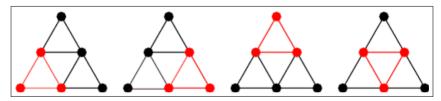


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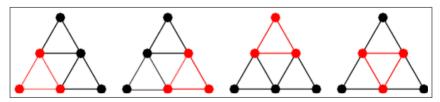


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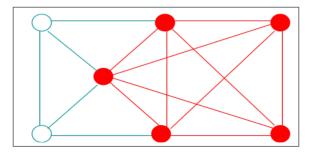


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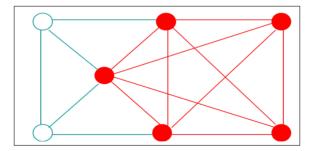


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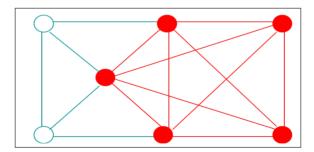


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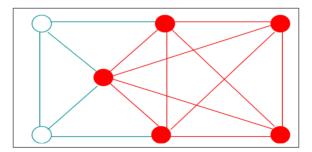


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 - is a clique of the largest possible size in a given graph.

• Maximum clique - triangle 1,2,5

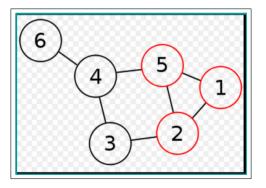


Figure: Maximum/Maximal clique

Maximal and Maximum Clique...

- Maximum clique triangle 1,2,5
- Four Maximal cliques pairs of (2,3), (3,4),(4,5), (4,6)

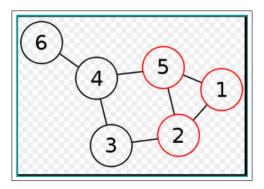


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- Note the clique and independent set problems..... Are they related ?

The clique and independent set problems

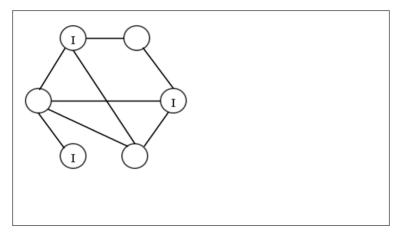


Figure: IS it a clique or an independent set?

The clique and independent set problems

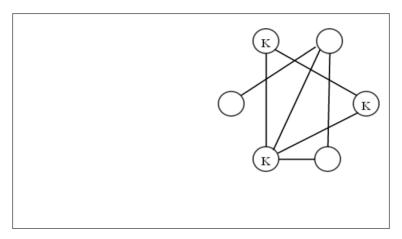


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Boolean Satisfiability: Terminologies

- Propositional (boolean) variable a variable that may be assigned value true or false
- Literal A Boolean variable or its negation.
- Propositional formula an expression that is either a propositional variable or a propositional constant or an expression of boolean operator and its operands
- Clause: a disjunction sequence of literals separated by V
- \bullet Conjunctive normal form A regular form of propositional formula ϕ that is the conjunction of clauses

Boolean Satisfiability ...

- An example propositional CNF formula is $\phi = (\bar{x_1} \ V \ x_2 \ V \ x_3) \ (x_1 \ V \ \bar{x_2} \ V \ x_3) \ (x_2 \ V \ x_3)$ where x_1, x_2, x_3 are propositional variables
- Truth assignment a boolean valued function on the set i.e.
 an assignment of values true or false to each propositional variable in the set
- Satisfiability When does a truth assignment is said to satisfy a formula ?
- SAT Given a CNF formula ϕ , does it have a satisfying truth assignment?

Boolean Satisfiability Problem

- Input : A boolean formula F in CNF
- Goal:
 - Check if F is satisfiable or not.
 - e.g. if $F = (x_1 + x_2)$ can we assign at least one set of values to the literals of the formula so that F = 1.
- How to solve this problem deterministically ?
- What could be the Brute-force approach?
- Time complexity ??
- $O(2^n|F|)$
- Cannot do any better than that.

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