

# P, NP Theory - II

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## Contents

- What is an Algorithm ? Solving problems algorithmically
- Classifying the problems
- A Motivating Example
- Some Hard Problems
- Reductions
- **Non-determinism**
- Class P, NP
- NP Complete Problems
- Concluding Remarks

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## How to we deal with the hard problems ?

*If we are not able to solve these problems,  
at least  
we would be happy  
if we were able to **verify a given solution**  
to be optimal or not.....  
in polynomial time ???*

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## Nondeterminism

- **Deterministic Algorithms**
  - determinism - the property that the result of every operation is **uniquely defined**.
  - that can be implemented on the actual machine
- **Deterministic Polynomial Algorithms**
  - Deterministic algorithms that can be **solved reasonably fast**
    - whose complexity is bounded by  $O(n^c)$ ,  $c$  a positive constant,  $n$  input size as seen before.

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## Nondeterminism

- Theoreticians treat even  $n^{\text{million}}$  as solvable reasonably fast
  - even while practically their execution time is very long
- That is the reason why
  - we have to conceptually conceive non-determinism.

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## Understanding Nondeterminism

- A nondeterministic algorithm can be understood using three new functions
  - Choice(S)
    - Takes a set S as input & arbitrarily chooses one of the elements of the set S
    - e.g.  $x = \text{choice}(I, n)$ 
      - x is assigned any one of the integers in  $[1 \dots n]$  ....can be qualified in any manner we desire...
    - takes time  $O(1)$
  - Failure()
    - signals an unsuccessful completion of the algorithm
    - takes time  $O(1)$
  - Success()
    - signals a successful completion of the algorithm
    - takes time  $O(1)$

Which function(s)  
amongst these  
is/are  
deterministic?  
Nondeterministic?

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## Nondeterministic Search Algorithm

### Problem

- Searching for an element  $x$  in a given set of elements  $A[n]$ ,  $n \geq 1$ .
- Output An index  $j$ , such that  $A[j]=x$  OR  $j=0$  if  $x$  is not in  $A$ .
- Design the algorithm **NonDeterministicSearch( $x, A$ )**

**Algorithm NonDeterministicSearch( $x, A$ )**

```
1.  $j = \text{Choice}(1, n)$  ;
2. if  $A[j]=x$ , then write( $j$ ) ; Success() ;
3. write(0) ; Failure() ;`
```

- Algorithm has nondeterministic complexity  $O(1)$ . Why ?

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## Nondeterministic Sorting Algorithm

### Problem

- Sorting  $A[i]$ ,  $1 \leq i \leq n$ , an unsorted array of positive integer
- Output  $A[i]$ , sorted in nondecreasing order

**Algorithm NonDeterministicSorting( $A, n$ )**

```
1. for  $i = 1$  to  $n$ ,  $B[i] = 0$ ;
2. for  $i = 1$  to  $n$  {
3.    $j = \text{Choice}(1, n)$  ;
4.   if  $B[j] \neq 0$  then Failure() ;
5.    $B[j] = A[i]$  ;
6. }
7. for  $i = 1$  to  $n-1$  //Verify the order
8.   if  $B[i] > B[i+1]$  then Failure() ;
9. write  $B[1..n]$  ;
10. Success() ;
```

What is the  
overall  
Nondeterministic  
Complexity ??

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## Why Nondeterminism ?

- Nondeterministic algorithms in computational complexity theory.
  - are typically studied only on a theoretical framework.
  - outcome of an operation is not uniquely defined.....
    - but is limited to specified sets of possibilities. i.e. these can allow for multiple choices to be available for the next step of computation.....
      - at every step, creating many possible computational paths.
  - these algorithms do *not* arrive at a solution for every possible computational path,
    - but are guaranteed to arrive **at a correct solution** for some path i.e., **if the right choices** are made underway.

.....contd

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## Why Nondeterminism ?.....

- Nondeterministic algorithms in computational complexity theory.
  - the **choices can be interpreted as guesses** in a search process.
  - a large number of real-life problems can be naturally stated/solved in this way
    - hence nondeterminism can help define commonality amongst the problems.

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## Problem Boolean Satisfiability

- **Input**
  - A boolean formula  $F$  in CNF
- **Goal**
  - Check if  $F$  is satisfiable or not.
    - e.g. if  $F = (x_1 + x_2)$  can we assign at least one set of values to the literals of the formula so that  $F = 1$ .
- **How to solve this problem deterministically ?**
  - What could be the Brute-force approach ?
  - Time complexity ??
    - $O(2^n |F|)$
  - Cannot do any better than that.
- Hence, the nondeterministic solution.....

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## Nondeterministic Boolean Satisfiability

- **Phase I**
  1. for  $i=1$  to  $n$  do
  2. use Choice() to determine the value of  $x_i$ 's that will satisfy  $F$
- **Phase 2**
  1. Check if  $F$  is satisfied under the above criterion
- **Runtime**
  - Phase I..... $O(1) * n$  i.e.  $O(n)$
  - Phase 2..... $O(|F|)$
  - Total..... $O(n + |F|)$

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## Problem k-Clique

- Input  $G(V,E)$ ,  $k$
- Output “Yes”, if  $G$  has a clique of size  $k$  and “No” otherwise
  - e.g.

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## k-Clique Deterministic approach

- Input  $G(V,E)$ ,  $k$
- Output “Yes”, if  $G$  has a clique of size  $k$  and “No” otherwise
- Naïve/Deterministic approach
  - For every subset of  $k$  nodes, check if these  $k$  nodes form a clique
  - Time complexity
    - $\binom{n}{k} \binom{k}{2}$
    - i.e.  $O(n^k k^2)$
- The issue is can we do better than this ?

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## k-Clique Non-deterministic approach

### Phase 1

Using the Choice(), we investigate whether "for every node in the graph is this node a k-clique?"

Guess k nodes that form a clique

### Phase 2

Verify whether the above nodes indeed form a k-clique.

- Time Complexity
  - Phase 1 takes k units of time.....
  - Phase two takes  $(k \text{ choose } 2)$  i.e.                      units of time
  - $O(k + (k \text{ choose } 2))$  i.e.  $O(k^2)$ .

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## Complexity Classes

- A Complexity Class
  - Is a collection of **decision problems** (???) all of which can be solved in SAME resource bounds
    - i.e. within same time, space or randomness....
- The question is

*Why do we bring in the discussion and then focus on decision problems and not on search problems ?*

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## Different versions of problems

- Combinatorial Optimization problems
  - Answer is a number
- Decision problems
  - Answer is yes or no
- Construction problems
  - Answer is some object (set of vertices, function, ...)

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## Classes of Problems

- Combinatorial Optimization problems
  - how to we define these ?
- Output

*Our Focus on  
decision problems*

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## Classes of Problems

- Decision problems
  - variation of optimization problems
  - answer yes/no to a question
- Statement of a decision problem has two parts
  - instance description
  - question with variables defined in instance description with actual yes/no asked
- Many problems will have decision and optimization versions.
- For example ??

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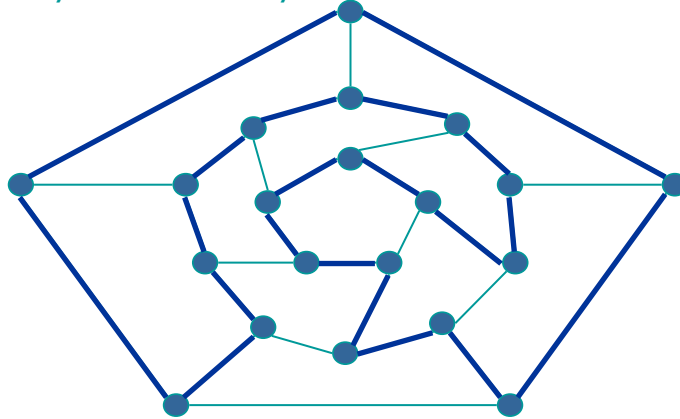
## Illustrating the difference

- Clique
  - optimization
    - instance For an undirected graph  $G = (V, E)$
    - question does  $G$  contain a clique of  $k$  vertices ?
      - say running time  $O(k^2n^k)$ .
      - Is it polynomial ?.....depends on the nature of  $k$
  - Decision
    - instance For an undirected graph  $G = (V, E)$  and an integer  $k$
    - question does  $G$  contain a clique of  $k$  vertices ?
      - say running time  $O(k^2n^k)$ .
      - Is it polynomial ? .....depends on the nature of  $k$

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## Hamiltonian Cycle

- given an undirected graph  $G = (V, E)$ , does there exist a simple cycle  $\Gamma$  that contains every node in  $V$  exactly once?



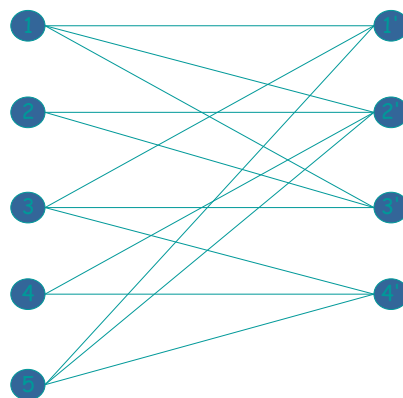
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## Hamiltonian Cycle (contd)

- HAM-CYCLE** given an undirected graph  $G = (V, E)$ , does there exist a simple cycle  $\Gamma$  that contains every node in  $V$ .



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## Traveling Salesperson problem

- **Minimum Tour problem**
  - Optimization problem
    - Given a complete, weighted graph find a minimum-weight Hamiltonian cycle
  - Decision problem
    - Given a complete, weighted graph and an integer  $k$ , is there a Hamiltonian cycle with total weight at most  $k$ ?

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- **Class P, NP**
- NP Complete Problems
- Concluding Remarks

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## Class P

### ■ P

- the class of decision problems that are solvable deterministically in  $O(p(n))$ , where  $p(n)$  is a polynomial on  $n$
- the class of decision problems that are polynomially bounded.

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## Solving the Decision Problems

- Can every decision problem be solved in polynomial time ?
  - Obviously not !!
  - Some decision problems cannot be solved at all by any algorithm
    - Undecidable problems e.g. The Halting problem
  - Proving that the Halting problem can not be solved at all.....
  - Are there any decidable but intractable problems ?
    - Yes, they are

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## Solving the Decision Problems...

- However, as seen before.....the important aspect is
  - that there are decidable problems for which neither the polynomial time algorithm has been found nor impossibility of doing so can be proved

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## Class NP

- NP – Nondeterministic Polynomial and not Nonpolynomial !!
  - the set of all the **decision problems** that **can be solved** using nondeterministic algorithms in polynomial time
  - Loosely
    - the class of decision problems for which a given proposed solution for a given input can be checked quickly in polynomial time.

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## Class NP

- Recollect that

- A nondeterministic algorithm is a two stage procedure that takes as input an instance  $i$  of a decision problem
  - Guessing (nondeterministic) stage
    - an arbitrary string  $S$  is generated that can be thought of as a candidate solution to the given instance  $i$
  - Verification (Deterministic) stage
    - a deterministic algorithm takes both  $i$  and  $S$  as its input and outputs yes if  $S$  represents a solution to instance  $i$ ; otherwise returns no.

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## Class NP (contd)

- Thus, NP can also be thought of as
  - the collection of problems that have polynomially i.e. efficiently **verifiable** solutions
    - that can be solved in polynomial time on a machine that can pursue infinitely many paths of the computation in parallel

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## Certification in NP

### def

- Algorithm  $C(s, t)$  is a **certifier** for problem  $X$  if for every string  $s$ ,  $s \in X$  there exists a string  $t$  such that  $C(s, t) = \text{yes}$ .

← "certificate" or "witness"

↑  
 $C(s, t)$  is a poly-time algorithm and  
 $|t| \leq p(|s|)$  for some polynomial  $p(\cdot)$ .

### Certification algorithm intuition.

- Certifier views things from "managerial" viewpoint.
- Certifier doesn't determine whether  $s \in X$  on its own; rather, it checks a proposed proof  $t$  that  $s \in X$ .

### NP

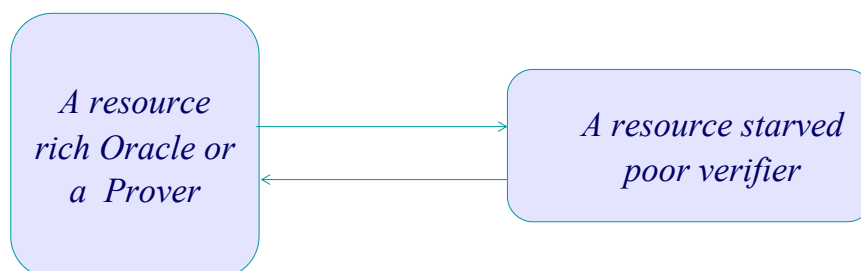
- Decision problems for which there exists a **poly-time certifier**.

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## Prover Verifier View



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## Certifiers-Certificates Composite

- **COMPOSITES.** Given an integer  $s$ , is  $s$  composite?
- **Certificate**
  - A nontrivial factor  $t$  of  $s$ . Note that such a certificate exists iff  $s$  is composite. Moreover  $|t| \leq |s|$ .
- **Certifier**
- **Instance.**  $s = 437,669$ .
- **Certificate.**  $t = 541$  or  $809$ .
- **Conclusion.** COMPOSITES is in NP.  $\longleftarrow 437,669 = 541 \times 809$

```
boolean C(s, t) {
    if (t ≤ 1 or t ≥ s)
        return false
    else if (s is a multiple of t)
        return true
    else
        return false
}
```

## Certifiers-Certificates 3-Satisfiability

- **SAT**
  - Given a CNF formula  $\Phi$ , is there a satisfying assignment?
- **Certificate**
  - An assignment of truth values to the  $n$  boolean variables.
- **Certifier**
  - Check that each clause in  $\Phi$  has at least one true literal.
- **Ex.**

instance  $s \quad (\overline{x_1} \vee x_2 \vee x_3) \wedge (x_1 \vee \overline{x_2} \vee x_3) \wedge (x_1 \vee x_2 \vee x_4) \wedge (\overline{x_1} \vee \overline{x_3} \vee \overline{x_4})$

$x_1 = 1, x_2 = 1, x_3 = 0, x_4 = 1$

certificate  $t$

- **Conclusion.** SAT is in NP.

## Certifiers-Certificates Hamiltonian Cycle

- **HAM-CYCLE**

- Given an undirected graph  $G = (V, E)$ , does there exist a simple cycle  $C$  that visits every node?

- **Certificate**

- A permutation of the  $n$  nodes.

- **Certifier**

- Check that the permutation contains each node in  $V$  exactly once, and that there is an edge between each pair of adjacent nodes in the permutation.

- **Conclusion.** HAM-CYCLE is in NP.

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## Certifiers-Certificates k-CLIQUE

- A graph  $G=(V, E)$  is a Clique if every two nodes in  $V$  are connected by an edge

- **K-CLIQUE**

- Given a graph  $G=(V,E)$ , prove that  $k$ -clique is in NP.

- **Proof**

- define  $CLIQUE = \{ \langle G, K \rangle \mid G \text{ is an undirected graph with a } k\text{-clique} \}$

- **Certificate**

- the collection of  $k$  vertices of the graph

- **Certifier**

- Take as input some string  $c$  as  $(\langle G, k \rangle, c)$
- Test whether  $c$  is a set of  $k$  nodes in  $G$
- Test whether  $G$  contains all edges connecting nodes in  $c$
- If so, proved.

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## Certifiers-Certificates SUBSET SUM

- Tutorial Assignment.....

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## Revisiting P, NP, EXP

- P
  - Decision problems for which there is a **poly-time algorithm**.
- EXP
  - Decision problems for which there is an **exponential-time algorithm**.
- NP
  - Decision problems for which there is a **poly-time certifier**.

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## Revisiting P, NP, EXP (contd)

▪ Claim.  $P \subseteq NP$ .

▪ Proof

▪ Consider any problem  $X$  in  $P$ .

- By definition, there exists a poly-time algorithm  $A(s)$  that solves  $X$ .
- Certificate  $t = \varepsilon$ , certifier  $C(s, t) = A(s)$ .
- Therefore, the fact.

Remember, we said an Algorithm  $C(s, t)$  is a **certifier** for problem  $X$ :  
iff for every string  $s$ ,  $s \in X$   
there exists a string  $t$  such  
that  $C(s, t) = \text{yes}$ .

## Revisiting P, NP, EXP (contd)

▪ Claim.  $NP \subseteq EXP$ .

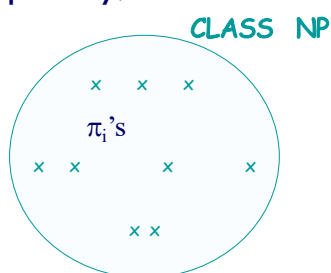
▪ Proof

▪ Consider any problem  $X$  in  $NP$ .

- By definition, there exists a poly-time certifier  $C(s, t)$  for  $X$ .
- To solve input  $s$ , run  $C(s, t)$  on all strings  $t$  with  $|t| \leq p(|s|)$ .
- Return **yes**, if  $C(s, t)$  returns **yes** for any of these

## NP-Hard

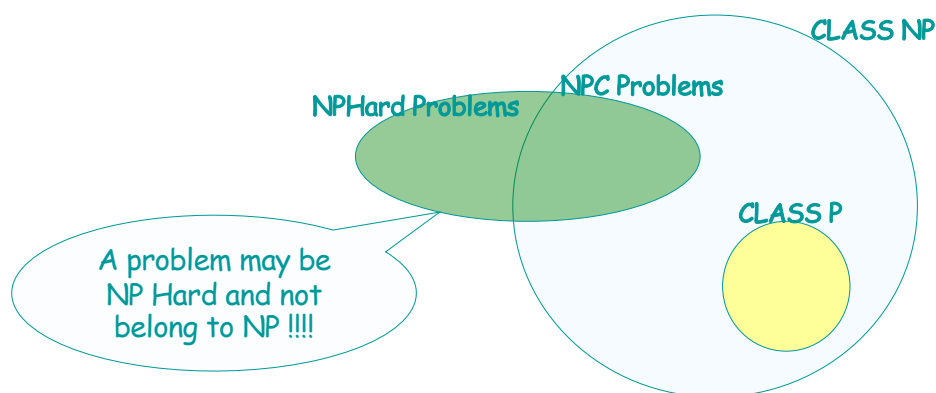
- A problem  $\pi$  is NP-Hard if for every problem  $\pi_i \in \text{NP}$ ,  $\pi_i$  reduces to  $\pi$ .
  - i.e.  $\pi$  is at least as difficult as  $\pi_i$  OR
  - i.e.  $\pi$  is at least as difficult as every problem in class NP.
- Graphically,



Here, every  $\pi_i$  in CLASS NP is polynomially reducible to a problem  $\pi$  that is outside NP,

## NP Complete Problems

- A problem  $\pi$  is NPC if  $\pi$  is NP-Hard and  $\pi \in \text{NP}$ .
- Thus, based on the above we can conceive of the Venn-diagram as below



## NP Completeness

- Cook and Levin 's theory
  - There are certain problems in NP
    - whose individual complexity is related to that of the entire class.
    - i.e. if a poly time algorithm were to exist for any problem in this class, all problems in NP would be polynomial time solvable.
- These problems are called NP-complete problems.

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## NP Completeness

- A problem P is NP-complete if one can prove that
  - P is in NP, and
  - show that there is some other problem Q - known to be an NPC – is poly-time reducible to the problem P.
    - the hard part of that was proving the *first* example of an NP-complete problem
    - that was done by Steve Cook in Cook's Theorem

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## Theorem $P = NP$

- Fact Let  $\pi$  be any NPC problem. If  $\pi \in P$ , then  $P = NP$ .
- Proof
  - Let  $\pi_1$  be any problem in NP.
  - Now, if  $\pi_1$  is an NPC problem, then by definition of NPC,  $\pi_1$  is also NP-Hard and so  $\pi_1 \propto \pi$ .
  - Now, if  $\pi \in P$ , then since  $\pi_1 \propto \pi$ ,  $\pi_1$  is also in P
  - Therefore,  $P = NP$ .
- However, the belief is that if  $\pi$  is any NPC problem, then  $\pi \notin P$ .
- So,  $P \neq NP$ .

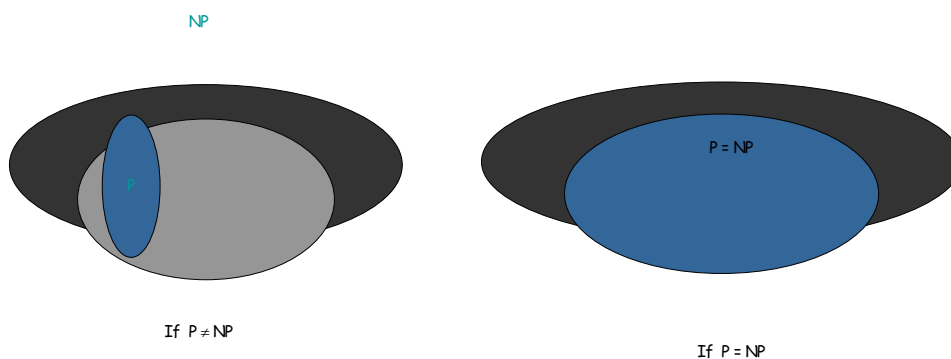
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## The Main Question P Versus NP

- Does  $P = NP$ ? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]
  - Is the decision problem as easy as the certification problem?



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## The Main Question P Versus NP...

- Does  $P = NP$ ? [Cook 1971, Edmonds, Levin, Yablonski, Gödel]
  - Is the decision problem as easy as the certification problem?
- If yes
  - Efficient algorithms for 3-COLOR, TSP, FACTOR, SAT, ...
- If no
  - No efficient algorithms possible for 3-COLOR, TSP, SAT, ...
- Consensus opinion on  $P = NP$ ? Probably no.

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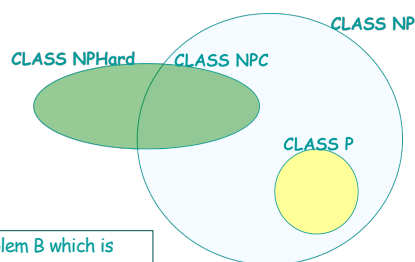
## Theorem

- Prove that if a problem  $B$  is NP-complete and  $B \leq_p C$  for  $C$  in NP, then  $C$  is NP-Complete.

A problem  $\Pi$  is NPC if it belongs to the class NP and for every problem  $\Pi_i \in NP$ ,  $\Pi_i$  reduces to  $\Pi$ .

### Proof

- We are given  $C$  is in NP and
  - to prove that  $C$  is NPC we must now show that every problem in class NP is polynomial time reducible to  $C$ .
- We are given that  $B$  is NP-complete.
  - That is, every problem in NP is  $\leq_p B$
  - But, we are given that  $B \leq_p C$
  - Therefore, every problem  $A$  in NP is  $\leq_p C$
  - Therefore,  $C$  is NP-complete



A problem  $A$  is NP-complete if one can prove that  $A$  is in NP, and there is some problem  $B$  which is already proven to be an NPC is poly-time reducible to a problem  $A$ .

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## 0/1 Knapsack problem: A special mention

- Is 0/1 knapsack problem solvable using dynamic programming?
- Why is then its solution referred to as pseudo-polynomial time solution?
- /\*write here from the notes page \*/

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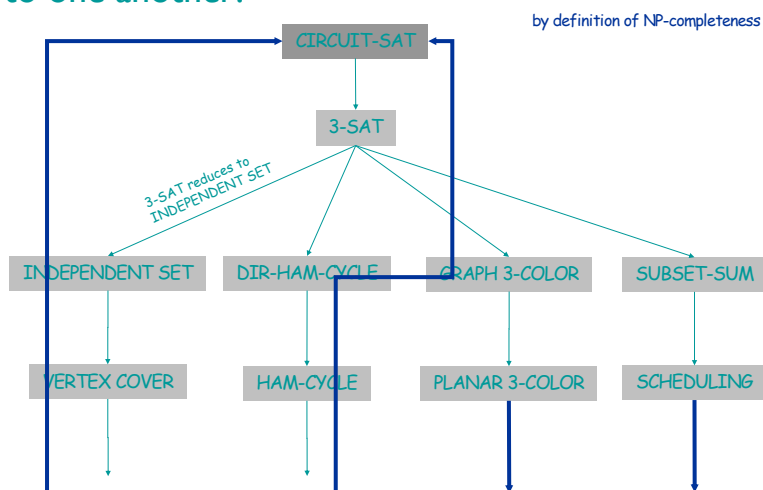
## Any problems that are NPH but not NPC?

- Can there be any problem that is NPH but not NPC ?
- When can a problem be NPH but not NPC ?
- The following problems are NPH but not NPC

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## NP-Completeness

- **Observation.** All problems below are NP-complete and polynomial reduce to one another!



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## Some NP-Complete Problems

- Six basic genres of NP-complete problems and paradigmatic examples.
  - Packing problems SET-PACKING, INDEPENDENT SET.
  - Covering problems SET-COVER, VERTEX-COVER.
  - Constraint satisfaction problems SAT, 3-SAT.
  - Sequencing problems HAMILTONIAN-CYCLE.
  - Partitioning problems 3D-MATCHING 3-COLOR.
  - Numerical problems SUBSET-SUM, KNAPSACK.
  - Practice. Most NP problems are either known to be in P or NP-complete.
- Notable exceptions. Factoring, graph isomorphism, Nash equilibrium.

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## Concluding Remarks

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## References

- Text by CLRS
- Text by Garey and Johnson
- Text by Klienber Tardos
- NPTEL Videos
- Special gratitude to Prof Rajsekaran, IUCEE Course Instructor at Infosys, July 2009.

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*To Teach is to Learn twice  
!!!!  
Hence, Thank You !!!*