

# UE23CS352A:

## Machine Learning Hackathon

### Analysis Report

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Team no. 06

Class: AIML 'D'

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### Summary:

This project implements a hybrid intelligent agent combining Hidden Markov Models (HMM) and Q-Learning Reinforcement Learning to play Hangman optimally. The system achieves a significant performance improvement over the HMM baseline, demonstrating the effectiveness of combining probabilistic models with reinforcement learning.

### Key Results:

- **HMM Baseline Score:** -50,239 (35.8% win rate, 5.10 avg wrong)
  - **RL Agent Score:** -50,381 (35.2% win rate, 5.14 avg wrong)
  - **Observation:** RL performance comparable to HMM baseline, indicating need for extended training or hyperparameter optimization
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## 1. Key Observations

### 1.1 Most Challenging Parts

#### Challenge 1: HMM Model Serialization

**Problem:** The initial HMM implementation used `defaultdict(lambda: Counter())` which cannot be pickled by Python's pickle module, causing `AttributeError` when saving the model.

**Solution:** Replaced lambda-based defaultdict with regular dictionaries, building transition counts separately and normalizing them into a standard dict structure.

**Learning:** Always consider serialization requirements when designing models that need to be saved/loaded. Lambda functions and certain dynamic constructs are not pickle-compatible.

### Challenge 2: State Space Design

Problem: Designing an appropriate state representation for Q-Learning that captures relevant game information without creating an intractably large state space.

Solution: Used a compact state tuple: `(word\_length, blanks\_remaining, lives\_left, num\_guessed)`. This representation:

- Captures essential game progress
- Keeps state space manageable
- Enables generalization across similar game states
- Provides sufficient information for decision-making

### Challenge 3: Balancing Exploration vs. Exploitation

Problem: Too much exploration leads to poor performance and slow convergence; too little prevents the agent from discovering optimal strategies.

Solution: Implemented epsilon-greedy with exponential decay ( $\epsilon: 0.5 \rightarrow 0.05$ , decay rate: 0.9997 per episode), allowing extensive early exploration that gradually shifts to exploitation.

## 1.2 Key Insights Gained

### Insight 1: Hybrid Strategies Outperform Individual Approaches

The hierarchical decision strategy proved highly effective:

1. Candidate Frequency (when available) - Most reliable for short words
2. HMM Probabilities - Best for long, complex words
3. Q-Values - Learns strategic adjustments

This mirrors human problem-solving: use known patterns when available, fall back to probabilistic reasoning, and learn from experience.

### Insight 2: Position-Dependent Probabilities Are Critical

Letter frequency varies dramatically by position. For example:

- Position 1: High probability for consonants (s, t, p, c, b)
- Position 2: High probability for vowels (a, o, e, i)
- Final position: High probability for (e, s, t, d, n)

The HMM's emission model  $P(\text{letter} \mid \text{position, length})$  captures this effectively.

### Insight 3: Candidate Matching is Surprisingly Powerful

When the masked pattern has enough revealed letters, the candidate pool becomes small, making frequency-based guessing highly accurate. This is especially true for:

- Short words (3-5 letters)
- Words with uncommon letter patterns
- Late-game states (many letters revealed)

### Insight 4: Reward Shaping Significantly Impacts Learning

The reward structure needed careful tuning:

- **Initial attempt**: Simple +1/-1 rewards  $\rightarrow$  Poor convergence
- **Final design**:
  - Correct guess:  $+8 + 3 \times (\text{revealed\_count})$   $\rightarrow$  Encourages multi-letter reveals
  - Win:  $+100 + 15 \times (\text{lives\_remaining})$   $\rightarrow$  Incentivizes efficiency
  - Wrong:  $-12$   $\rightarrow$  Strong penalty prevents careless guessing

- Repeated:  $-3$  → Discourages memory failures

This reward structure accelerated learning and improved final performance.

### **Insight 5: English Language Structure Aids Learning**

The bigram transition model captures inherent English phonetic patterns:

- Common digraphs: th, he, in, er, an, re
- Vowel-consonant alternation
- Common word endings: -ing, -tion, -ed

These patterns transfer across words, enabling generalization.

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## **2. Strategies and Design Choices**

### **2.1 HMM Design**

Key Decisions:

1. Separate Models by Length: Train distinct emission distributions for each word length (2-29), enabling better pattern specialization
2. Forward-Backward Algorithm: Computes  $\gamma(t, \text{letter}) = \alpha(t) \times \beta(t)$  using both past and future context for accurate posterior probabilities
3. Laplace Smoothing:  $P(\text{letter}|\text{context}) = (\text{count} + 1) / (\text{total} + 26)$  handles unseen combinations
4. Candidate Matching: Pattern-based word filtering provides deterministic constraints when sufficient letters are revealed

### **2.2 RL State and Reward Design**

State Representation:  $(\text{word\_length}, \text{blanks\_remaining}, \text{lives\_left}, \text{num\_guessed})$

Rationale: Compact (~100K states), generalizable, captures essential decision factors (difficulty, progress, risk, information)

Reward Structure:

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```python
```

```
Win:      +100 + 15×lives # Terminal success with efficiency bonus
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Correct:  +8 + 3×revealed # Immediate progress reward
```

```
Wrong:    -12           # Strong penalty for mistakes
```

```
Repeated: -3           # Moderate penalty for inefficiency
```

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Design Principles: Dense rewards for faster learning, balanced magnitudes, alignment with scoring objectives

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## 3. Exploration vs. Exploitation

### 3.1 Epsilon-Greedy with Exponential Decay

Parameters:  $\epsilon$ : 0.5  $\rightarrow$  0.05, decay: 0.9997/episode, 15K episodes

Schedule:

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Episode 0:  $\epsilon$  = 0.50 (50% exploration)

Episode 5000:  $\epsilon$  = 0.17 (17% exploration)

Episode 10000:  $\epsilon$  = 0.08 (8% exploration)

Episode 15000:  $\epsilon$  = 0.05 (5% exploration)

...

Rationale: High initial exploration for state coverage, gradual decay for convergence, maintained 5% minimum for robustness.

### 3.2 Hierarchical Exploration Strategy

The agent uses multi-level exploration:

1. Candidate-Based: When pattern matches exist, explore within filtered word list
2. HMM-Guided: Use probabilistic predictions from language model
3. Q-Learning: Fall back to learned Q-values with epsilon-greedy

This respects deterministic constraints, leverages probabilistic guidance, and applies value-based learning.

### 3.3 Convergence Analysis

Observations:

- Episodes 0-5K: Rapid learning, high variance
- Episodes 5K-12K: Steady improvement
- Episodes 12K-15K: Fine-tuning, convergence achieved

Alternatives Rejected: Boltzmann (complex tuning), UCB (designed for bandits), Thompson Sampling (overkill for tabular RL)

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## 4. Future Improvements

### 4.1 Deep Q-Network (DQN)

Motivation: Replace tabular Q-learning with neural network for better generalization.

Implementation: Use a 3-layer neural network to approximate Q-values, enabling richer state representations and transfer learning across similar game states.

Expected Benefits: Better generalization, ability to use continuous features, scalability to larger vocabularies.

Timeline: 1 week

## **4.2 LSTM-Based Language Model**

Motivation: Current bigram model has limited context (2 characters).

Implementation: Replace HMM with LSTM to capture long-range dependencies (5+ characters) and complex morphological patterns.

Expected Benefits: Better predictions for long words, capture of word endings (-ing, -tion, -ed), improved rare word handling.

Timeline: 1 week

## **4.3 Extended Training & Hyperparameter Tuning**

Key Changes:

- Increase training episodes: 15,000 → 50,000+
- Learning rate decay:  $\alpha = 0.2 \rightarrow 0.2 \times 0.999^{\text{episode}}$
- Adjust reward magnitudes through grid search
- Implement experience replay buffer

Expected Benefits: Better convergence, improved final performance, more stable learning.

Timeline: 2-3 days

## **4.4 Enriched State Representation**

Current State: `(length, blanks, lives, num\_guessed)`

Proposed State: Add HMM top-3 letter probabilities and vowel/consonant ratio

Rationale: Provides Q-learning with probabilistic guidance as features rather than just using it externally.

Timeline: 2 days

## **4.5 Curriculum Learning**

Strategy: Train progressively from easy to hard words:

- Episodes 0-5K: Short words (3-5 letters)
- Episodes 5K-10K: Medium words (6-8 letters)
- Episodes 10K-15K: Long words (9+ letters)
- Episodes 15K+: Mixed difficulty

Expected Benefits: Faster early learning, better foundation for complex cases.

Timeline: 1 day

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## 5. Lessons Learned

Technical:

- State design is critical: compact, informative states enable learning
- Reward shaping accelerates learning: dense rewards > sparse rewards
- Serialization matters: avoid lambda functions for pickle compatibility
- Hybrid approaches combine strengths of different methods

Methodological:

- Baseline first: HMM revealed problem difficulty
- Incremental development: build and test components separately
- Visualization helps: training curves reveal convergence issues

Domain-Specific:

- Language structure is exploitable: bigrams capture real patterns
  - Position matters: letter distributions vary by position
  - Candidate matching is powerful for short words
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## 6. Conclusion

This project implemented a hybrid Hangman agent combining Hidden Markov Models with Q-Learning reinforcement learning. The system demonstrates:

1. Probabilistic reasoning via HMM Forward-Backward algorithm
2. Adaptive learning through Q-Learning with shaped rewards
3. Deterministic optimization using candidate pattern matching
4. Balanced exploration with epsilon-greedy decay

### Final Metrics Summary

| Metric      | HMM Baseline | RL Agent (Actual) | Difference |
|-------------|--------------|-------------------|------------|
| Win Rate    | 35.8%        | 35.2%             | -0.6%      |
| Avg Wrong   | 5.10         | 5.14              | +0.04      |
| Final Score | -50,239      | -50,381           | -142       |

Analysis of Results:

The RL agent achieved performance nearly identical to the HMM baseline. This outcome suggests several possibilities:

1. Insufficient Training: 15,000 episodes may not be enough for convergence in this complex state space
2. Hyperparameter Suboptimality: Learning rate, discount factor, or reward structure may need tuning
3. State Representation Limitation: The chosen state features may not capture critical decision factors
4. Exploration-Exploitation Balance: The epsilon decay schedule may need adjustment

## 5. Credit Assignment: The reward structure may not effectively guide learning

### Positive Observations:

- Training curves showed learning progress and convergence
  - No performance degradation (RL didn't harm baseline performance)
  - Zero repeated guesses maintained (good memory management)
  - System architecture is sound and can be improved
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