## EN.550.661: Nonlinear Optimization I

Instructor: Daniel P. Robinson

Homework Assignment #2

Starred exercises require the use of Matlab.

**Exercise** 2.1\* Write a MATLAB m-function that performs Newton's Method for finding a zero of a function  $F: \mathbb{R}^n \to \mathbb{R}^n$ . The function call should have the form

where Fun is of type *string* that holds the name of a Matlab m-function, x0 is an initial guess at a zero, maxit is the maximum number of iterations allowed, printlevel determines the amount of printout required, and tol is the final stopping tolerance. The Matlab m-function Fun should have the form

$$[F,J] = Fun(x)$$

where F and J should contain the value and Jacobian of a desired function at the point x. In the code, if the parameter printlevel has the value zero, then no printing should occur; otherwise, a single line of output is printed (in column format) per iteration. On output, the parameters x, F, and J should contain the final iterate, function value, and Jacobian matrix computed by the algorithm. The parameter iter should contain the total number of iterations performed. Finally, status should have the value 0 if the final stopping tolerance was obtained and the value 1 otherwise.

**Exercise**  $2.2^*$  Let A be a given real symmetric matrix.

(a) Define an iteration of Newton's Method for solving the n+1 nonlinear equations

$$(A - \lambda I)x = 0$$
 and  $x^T x = 1$ 

in the n+1 unknowns  $(x,\lambda)$ . Note that a zero  $(x,\lambda)$  is an eigenpair of the matrix A.

(b) Use the code you wrote for Exercise 2.1 to find an eigenpair  $(x, \lambda)$  for the matrix

$$A = \begin{pmatrix} 4 & 2 & 1 \\ 2 & 3 & 0 \\ 1 & 0 & 1 \end{pmatrix} \quad \text{with starting point} \quad x_0 = \begin{pmatrix} 1/5 \\ -1/5 \\ 4/5 \end{pmatrix} \quad \text{and} \quad \lambda_0 = 1.$$

**Exercise 2.3:** Consider the function  $f: \mathbb{R}^3 \to \mathbb{R}$  defined by

$$f(x) = e^{x_3}x_1^2 + x_2^2 + x_3^2\cos(x_1)$$

- (a) Derive the gradient  $\nabla f(x)$  and Hessian  $\nabla^2 f(x)$ .
- (b) Compute f(x),  $\nabla f(x)$ , and  $\nabla^2 f(x)$  at  $\bar{x} = (0,0,0)$  and  $\hat{x} = (0,0,-1)$ . In both cases, compute the spectral decomposition of the Hessian matrix and indicate whether the necessary and sufficient conditions for being a local unconstrained minimizer are satisfied.
- (c) For each of the points  $\bar{x}$  and  $\hat{x}$ , compute the Newton direction  $p^N$  and determine if it is a descent direction for f.
- (d) If the Hessian is indefinite at  $\bar{x}$  or  $\hat{x}$ , compute a modified Newton direction  $p^M$ . Find the value of the directional derivative along  $p^M$ .