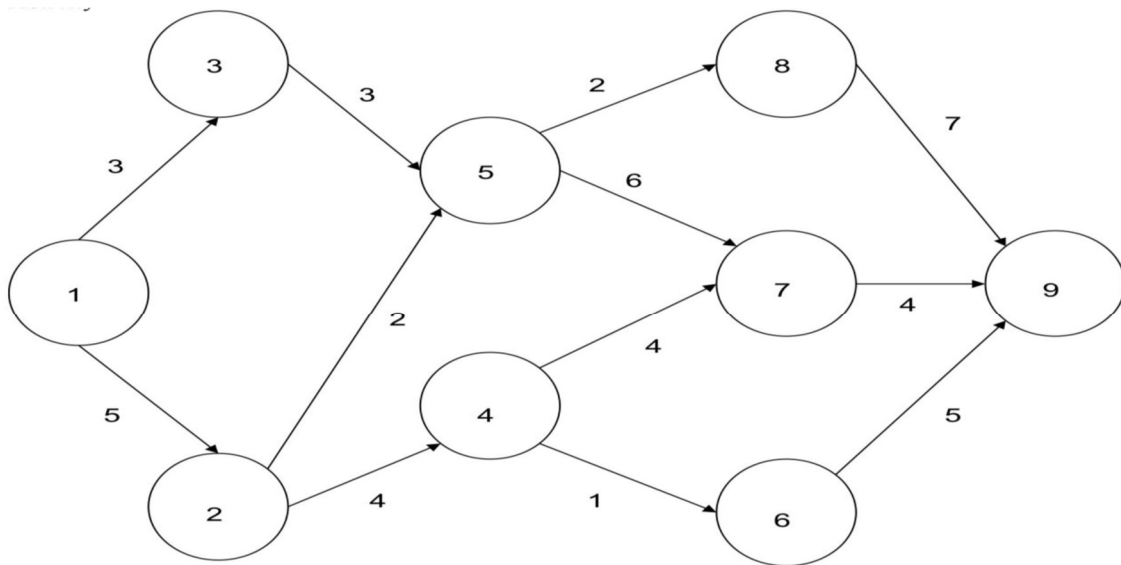


Assignment 6

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Question 1:

Formulate and solve the binary integer programming (BIP) model for this problem using library lpsolve or equivalent in R.



Solution:

Z_{\max} is the objective function, and the longest path is the critical path;

$$Z_{\max} = 3X_{13} + 5X_{12} + 3X_{35} + 2X_{25} + 2X_{58} + 4X_{24} + 6X_{57} + 4X_{47} + 1X_{46} + 7X_{89} + 4X_{79} + 5X_{69}$$

where X_{ij} (i=starting node, j= ending node)

Starting node:

$$\text{Node 1: } 3X_{13} + 5X_{12} = 1$$

Ending node:

$$\text{Node 9: } 7X_{89} + 4X_{79} + 5X_{69} = 1$$

Intermediate nodes:

$$\text{Node 2: } 5X_{12} = 2X_{25} + 4X_{24}$$

$$\text{Node 3: } 3X_{13} - 3X_{35} = 0$$

Node 4: $4X_{24} - 1X_{46} = 4X_{47}$

Node 5: $3X_{35} + 2X_{25} = 2X_{58} + 6X_{57}$

Node 6: $1X_{46} = 5X_{69}$

Node 7: $6X_{57} + 4X_{47} = 4X_{79}$

Node 8: $2X_{58} = 7X_{89}$

Where X_{ij} are binary

The longest path is the critical path which is between the nodes (1-2-5-7-9)

So, the arcs between the objective function is $X_{12}-X_{25}-X_{57}-X_{79}$

R Program:

Loading libraries

```
library(lpSolveAPI)
lp <- make.lp(0,12)
lp.control(lp, sense="max")

## $anti.degen
## [1] "fixedvars" "stalling"
##
## $basis.crash
## [1] "none"
##
## $bb.depthlimit
## [1] -50
##
## $bb.floorfirst
## [1] "automatic"
##
## $bb.rule
## [1] "pseudononint" "greedy"          "dynamic"          "rcostfixing"
##
## $break.at.first
## [1] FALSE
##
## $break.at.value
## [1] 1e+30
##
## $epsilon
##      epsb      epsd      epsel      epsint  epsperturb  epspivot
##      1e-10      1e-09      1e-12      1e-07      1e-05      2e-07
##
## $improve
## [1] "dualfeas" "thetagap"
##
## $infinite
## [1] 1e+30
##
```

```

## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
## 1e-11 1e-11
##
## $negrange
## [1] -1e+06
##
## $obj.in.basis
## [1] TRUE
##
## $pivoting
## [1] "devex" "adaptive"
##
## $presolve
## [1] "none"
##
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric" "equilibrate" "integers"
##
## $sense
## [1] "maximize"
##
## $simplextype
## [1] "dual" "primal"
##
## $timeout
## [1] 0
##
## $verbose
## [1] "neutral"

# objective function
time <- c(5, 3, 4, 2, 3, 1, 4, 6, 2, 5, 4, 7)
set.objfn(lp, 1*time)
set.type(lp, 1:12, "binary")
# starting node
add.constraint(lp,c(1,1),"=",1,indices = c(1,2))
# intermediate node
add.constraint(lp,c(1,-1,-1),"=",0,indices = c(1,3,4))
add.constraint(lp,c(1,-1),"=",0,indices = c(2,5))
add.constraint(lp,c(1,-1,-1),"=",0,indices = c(3,6,7))
add.constraint(lp,c(1,1,-1,-1),"=",0,indices = c(4,5,8,9))
add.constraint(lp,c(1, -1),"=",0,indices = c(6,10))
add.constraint(lp,c(1,1,-1),"=",0,indices = c(7,8,11))

```

```

add.constraint(lp,c(1,-1),"=",0,indices = c(9,12))
# End node
add.constraint(lp,c(1,1,1),"=",1,indices = c(10,11,12))
solve(lp)

## [1] 0

get.objective(lp)

## [1] 17

get.variables(lp)

## [1] 1 0 0 1 0 0 0 1 0 0 1 0

get.constraints(lp)

## [1] 1 0 0 0 0 0 0 0 1

arc <- c("x12", "x13", "x24", "x25", "x35", "x46", "x47", "x57", "x58", "x69",
, "x79", "x89")
variables<-get.variables(lp)
output<-data.frame(arc,variables)
output

##      arc variables
## 1  x12           1
## 2  x13           0
## 3  x24           0
## 4  x25           1
## 5  x35           0
## 6  x46           0
## 7  x47           0
## 8  x57           1
## 9  x58           0
## 10 x69           0
## 11 x79           1
## 12 x89           0

```

Question 2:

Formulating the lp function.

2a) Solution

Determine the maximum return on the portfolio. What is the optimal number of shares to buy for each of the stocks? What is the corresponding dollar amount invested in each stock?

```

lps<-make.lp(0,8)
lp.control(lps,sense="max")

## $anti.degen
## [1] "fixedvars" "stalling"
##
## $basis.crash
## [1] "none"
##
## $bb.depthlimit
## [1] -50
##
## $bb.floorfirst
## [1] "automatic"
##
## $bb.rule
## [1] "pseudononint" "greedy"          "dynamic"          "rcostfixing"
##
## $break.at.first
## [1] FALSE
##
## $break.at.value
## [1] 1e+30
##
## $epsilon
##      epsb      epsd      epsel      epsint  epsperturb  epspivot
##      1e-10      1e-09      1e-12      1e-07      1e-05      2e-07
##
## $improve
## [1] "dualfeas" "thetagap"
##
## $infinite
## [1] 1e+30
##
## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
##      1e-11      1e-11
##
## $negrange
## [1] -1e+06
##
## $obj.in.basis
## [1] TRUE
##
## $pivoting
## [1] "devex"      "adaptive"
##

```

```
## $presolve
## [1] "none"
##
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric" "equilibrate" "integers"
##
## $sense
## [1] "maximize"
##
## $simplextype
## [1] "dual" "primal"
##
## $timeout
## [1] 0
##
## $verbose
## [1] "neutral"
```

#As we are implementing integer programming we will set the type to integer

```
set.objfn(lps,c(4,6.5,5.9,5.4,5.15,10,8.4,6.25))
set.type(lps,c(1:8), type = "integer")
add.constraint(lps,c(40,50,80,60,45,60,30,25),"<=",2500000,indices = c(1:8))
add.constraint(lps,1000,">=",0,indices = 1)
add.constraint(lps,1000,">=",0,indices = 2)
add.constraint(lps,1000,">=",0,indices = 3)
add.constraint(lps,1000,">=",0,indices = 4)
add.constraint(lps,1000,">=",0,indices = 5)
add.constraint(lps,1000,">=",0,indices = 6)
add.constraint(lps,1000,">=",0,indices = 7)
add.constraint(lps,1000,">=",0,indices = 8)
add.constraint(lps,40,">=",100000,indices = 1)
add.constraint(lps,50,">=",100000,indices = 2)
add.constraint(lps,80,">=",100000,indices = 3)
add.constraint(lps,60,">=",100000,indices = 4)
add.constraint(lps,45,">=",100000,indices = 5)
add.constraint(lps,60,">=",100000,indices = 6)
add.constraint(lps,30,">=",100000,indices = 7)
add.constraint(lps,25,">=",100000,indices = 8)
add.constraint(lps,c(40,50,80),"<=",1000000,indices = c(1,2,3))
add.constraint(lps,c(60,45,60),"<=",1000000,indices = c(4,5,6))
add.constraint(lps,c(30,25),"<=",1000000,indices = c(7,8))
solve(lps)
```

```
## [1] 0

get.objective(lps)

## [1] 487145.2
```

```

get.variables(lps)

## [1] 2500 6000 1250 1667 2223 13332 30000 4000

get.constraints(lps)

## [1] 2499975 2500000 6000000 1250000 1667000 2223000 13332000 30000000
## [9] 4000000 100000 300000 100000 100020 100035 799920 900000
## [17] 100000 500000 999975 1000000

```

According to the problem returns can be given by

Returns = (Price per share) * (Growth rate of share) + (Dividend per share)

Hence the objective function is

$Z_{\max} = 4XS_1 + 6.5XS_2 + 5.9XS_3 + 5.4XH_1 + 5.15XH_2 + 10XH_3 + 8.4XC_1 + 6.25XC_2$

Constraints:

Investment constraint:

$40XS_1 + 50XS_2 + 80XS_3 + 60XH_1 + 45XH_2 + 60XH_3 + 30XC_1 + 25XC_2 \leq 2500000$

The stock must be a multiple of 1000

$1000XS_1 \geq 0$; $1000XS_2 \geq 0$; $1000XS_3 \geq 0$

$1000XH_1 \geq 0$; $1000XH_2 \geq 0$; $1000XH_3 \geq 0$

$1000XC_1 \geq 0$; $1000XC_2 \geq 0$

Maximum amount invested in 1 sector = 2.5 million * 40% = 1 million

No more than 40% should be assigned to the 3 sectors,

$40XS_1 + 50XS_2 + 80XS_3 \leq 1000000$

$60XH_1 + 45XH_2 + 60XH_3 \leq 1000000$

$30XC_1 + 25XC_2 \leq 1000000$

Where $XS_1, XH_1, XC_1 \geq 0$

Minimum investment in each stock = .1 million

Least \$100,000 must be invested in 8 stocks

$40XS_1 \geq 100000$

$50XS_2 \geq 100000$

$80XS_3 \geq 100000$

$60XH_1 \geq 100000$

$45XH_2 \geq 100000$

$60XH_3 \geq 100000$

$30XC_1 \geq 100000$

$25XC_2 \geq 100000$

Where $XS_j, XH_j, XC_j \geq 0$ are integers.

Optimal number of shares to buy each of the stock

$$S1 = 100000 / 40 = 2500$$

$$S2 = 100000 / 50 = 2000$$

$$S3 = 300000 / 80 = 3750$$

$$H1 = 100000 / 60 = 1666.67$$

$$H2 = 100000 / 45 = 2222.22$$

$$H3 = 800000 / 60 = 13333.33$$

$$C1 = 900000 / 30 = 30000$$

$$C2 = 100000 / 25 = 4000$$

The amount invested in each stock

40% investment in sector 3 : $C1 = 900000$, $C2 = 100000$;

40% investment in sector 2 ($H1$, $H2$, $H3$) : $H1 = 100000$, $H2 = 100000$, $H3 = 800000$;

Balance in sector 1 ($S1$, $S2$, $S3$) : $S1 = 100000$, $S2 = 300000$, $S3 = 100000$;

Formulating lp problem without integer restrictions

```
lps1<-make.lp(0,8)
lp.control(lps1,sense="max")

## $anti.degen
## [1] "fixedvars" "stalling"
##
## $basis.crash
## [1] "none"
##
## $bb.depthlimit
## [1] -50
##
## $bb.floorfirst
## [1] "automatic"
##
## $bb.rule
## [1] "pseudononint" "greedy"          "dynamic"          "rcostfixing"
##
## $break.at.first
## [1] FALSE
##
## $break.at.value
## [1] 1e+30
##
## $epsilon
##      epsb      epsd      epsel      epsint  epsperturb  epspivot
##      1e-10      1e-09      1e-12      1e-07      1e-05      2e-07
##
## $improve
## [1] "dualfeas" "thetagap"
```



```

##
## $infinite
## [1] 1e+30
##
## $maxpivot
## [1] 250
##
## $mip.gap
## absolute relative
## 1e-11 1e-11
##
## $negrange
## [1] -1e+06
##
## $obj.in.basis
## [1] TRUE
##
## $pivoting
## [1] "devex" "adaptive"
##
## $presolve
## [1] "none"
##
## $scalelimit
## [1] 5
##
## $scaling
## [1] "geometric" "equilibrate" "integers"
##
## $sense
## [1] "maximize"
##
## $simplextype
## [1] "dual" "primal"
##
## $timeout
## [1] 0
##
## $verbose
## [1] "neutral"

#Formulating without integer
set.objfn(lps1,c(4,6.5,5.9,5.4,5.15,10,8.4,6.25))
add.constraint(lps1,c(40,50,80,60,45,60,30,25),"<=",2500000,indices = c(1:8))
add.constraint(lps1,1000,">=",0,indices = 1)
add.constraint(lps1,1000,">=",0,indices = 2)
add.constraint(lps1,1000,">=",0,indices = 3)
add.constraint(lps1,1000,">=",0,indices = 4)
add.constraint(lps1,1000,">=",0,indices = 5)
add.constraint(lps1,1000,">=",0,indices = 6)

```

```

add.constraint(lps1,1000,">=",0,indices = 7)
add.constraint(lps1,1000,">=",0,indices = 8)
add.constraint(lps1,40,">=",100000,indices = 1)
add.constraint(lps1,50,">=",100000,indices = 2)
add.constraint(lps1,80,">=",100000,indices = 3)
add.constraint(lps1,60,">=",100000,indices = 4)
add.constraint(lps1,45,">=",100000,indices = 5)
add.constraint(lps1,60,">=",100000,indices = 6)
add.constraint(lps1,30,">=",100000,indices = 7)
add.constraint(lps1,25,">=",100000,indices = 8)
add.constraint(lps1,c(40,50,80),"<=",1000000,indices = c(1,2,3))
add.constraint(lps1,c(60,45,60),"<=",1000000,indices = c(4,5,6))
add.constraint(lps1,c(30,25),"<=",1000000,indices = c(7,8))
solve(lps1)

## [1] 0

get.objective(lps1)

## [1] 487152.8

get.variables(lps1)

## [1] 2500.000 6000.000 1250.000 1666.667 2222.222 13333.333

[7] 30000.000 4000.000

get.constraints(lps1)

[1] 2500000 2500000 6000000 1250000 1666667 2222222 13333333

[8] 30000000 4000000 100000 300000 100000 100000 100000

[15] 800000 900000 100000 500000 1000000 1000000

```

2b) Solution

2b) Compare the solution in which there is no integer restriction on the number of shares invested. By how much (in percentage terms) do the integer restrictions alter the value of the optimal objective function? By how much (in percentage terms) do they alter the optimal investment quantities?

The number of stocks are:

$$S1 = 100000 / 40 = 2500$$

$$S2 = 100000 / 50 = 2000$$

$$S3 = 300000 / 80 = 3750$$

$$H1 = 100000 / 60 = 1666.67$$

$H2 = 100000 / 45 = 2222.22$
 $H3 = 800000 / 60 = 13333.33$
 $C1 = 900000 / 30 = 30000$
 $C2 = 100000 / 25 = 4000$

The amount invested in each stocks:

40% investment in sector 3 : $C1 = 900000$, $C2 = 100000$;
40% investment in sector 2 ($H1$, $H2$, $H3$) : $H1 = 100000$, $H2 = 100000$, $H3 = 800000$;
Balance in sector 1 ($S1$, $S2$, $S3$) : $S1 = 100000$, $S2 = 300000$, $S3 = 100000$;

Considering lp problem with integer restrictions and without integer restrictions there is a difference of \$7.6($487152.8 - 487145.2$).

The value of the objective function differs by 0.00156%.

The investment quantities are altered as follows: $S1 = S2 = 0$, $S3 = 0\%$, $H1 = 0.03996\%$ increased, $H2 = 0.03501\%$ decreased, $H3 = 75.01\%$ increased and $C1 = C2 = 0$