# Signals and Systems

## 1. Continuous-Time and Discrete-Time Signals

continuous-time signals x(t) discrete-time signals x[n]

#### 1.1 Signal Energy and Power

the total energy

$$E_{\infty} riangleq \lim_{T o \infty} \int_{-T}^{T} |x(t)|^2 \, \mathrm{d}t = \int_{-\infty}^{\infty} |x(t)|^2 \, \mathrm{d}t$$

$$E_{\infty} riangleq \lim_{N o \infty} \sum_{n=-N}^{+N} |x[n]|^2 = \sum_{n=-\infty}^{+\infty} |x[n]|^2$$

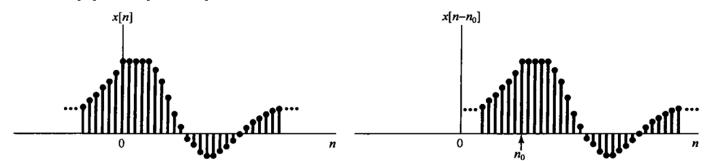
the time-averaged power

$$P_{\infty} riangleq \lim_{T o \infty} rac{1}{2T} \int_{-T}^{T} |x(t)|^2 \, \mathrm{d}t$$

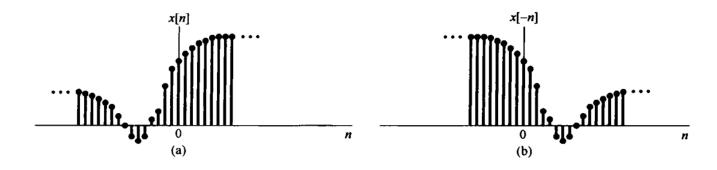
$$P_{\infty} riangleq \lim_{N o \infty} rac{1}{2N+1} \sum_{n=-N}^{+N} |x[n]|^2$$

## 2. Transfermations of the Independent Variable

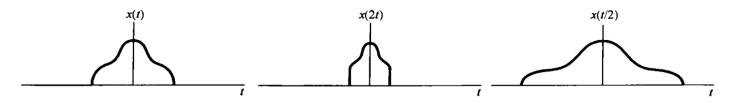
time shift x[n] and  $x[n-n_0]$ 



 ${\rm time\ reversal\ } x[-n]$ 



time scaling x(2t) and  $x(\frac{t}{2})$ 



It is often of interest to determine the effect of transforming the independent variable of x(t) to  $x(\alpha t + \beta)$ , where  $\alpha$  and  $\beta$  are given numbers.

#### 2.1 Periodic Signals

$$x(t) = x(t+T)$$

The **fundamental period**  $T_0$  of x(t) is the smallest positive value of T for which it holds.

$$x[n] = x[n+N]$$

The **fundamental period**  $N_0$  of x[n] is the smallest positive value of N for which it holds.

A signal that is not periodic will be referred to as an **aperiodic** signal.

#### 2.2 Even and Odd Signals

even signals 
$$x(-t)=x(t)$$
 and  $x[-n]=x[n]$  odd signals  $x(-t)=-x(t)$  and  $x[-n]=-x[n]$ 

any signal can be broken into a sum of two signals, one of which is even and one of which is odd the **even part** of x(t):  $\mathcal{E}_v\{x(t)\}=\frac{1}{2}[x(t)+x(-t)]$  the **odd part** of x(t):  $\mathcal{O}_d\{x(t)\}=\frac{1}{2}[x(t)-x(-t)]$ 

## 3. Exponential and Sinusoidal Signals

# 3. 1 Continuous-Time Complex Exponential and Sinusoidal Signals

The continuous-time complex exponential signal is of the form  $x(t)=C\mathrm{e}^{at}.$ 

real exponential signals C and a are real

periodic complex exponential signals  $x(t)=\mathrm{e}^{\mathrm{j}\omega_0 t}$ 

it is periodic,  $T_0=rac{2\pi}{\omega_0}$ 

sinusoidal signals  $x(t) = A\cos(\omega_0 t + \phi)$ 

**Euler**'s relation  $\mathrm{e}^{\mathrm{j}\omega_0 t} = \cos(\omega_0 t) + \mathrm{j}\sin(\omega_0 t)$ 

fundamental frequency  $|\omega_0|$ 

harmonically related complex exponential  $\phi_k(t)=\mathrm{e}^{\hspace{1pt}\mathrm{j} k\omega_0 t} \quad k=0,\pm 1,\pm 2,...$ 

#### general complex exponential signals

 ${\cal C}$  expressed in polar form and a in rectangular form

we have 
$$C=|C|\mathrm{e}^{\mathrm{j} heta}$$
 and  $a=r+\mathrm{j}\omega_0$  then  $C\mathrm{e}^{at}=|C|\mathrm{e}^{rt}\mathrm{e}^{\mathrm{j}(\omega_0t+ heta)}$ 

Sinusoidal signals multiplied by decaying exponentials are commonly referred to as **damped sinusoids**.

#### 3.2 Discrete-Time Complex Exponential and Sinusoidal Signals

The discrete-time complex exponential signal is of the form  $x[n] = C \alpha^n$ .

real exponential signals C and  $\alpha$  are real

sinusoidal signals |lpha|=1

then we have  $x[n] = A \mathrm{cos}(\omega_0 n + \phi)$ 

#### general complex exponential signals

we have 
$$C=|C|\mathrm{e}^{\mathrm{j}\theta}$$
 and  $\alpha=|\alpha|\mathrm{e}^{\mathrm{j}\omega_0}$ 

then 
$$Clpha^n=|C||lpha|^n\mathrm{cos}(\omega_0n+ heta)+\mathrm{j}|C||lpha|^n\mathrm{sin}(\omega_0n+ heta)$$

$$\mathrm{e}^{\mathrm{j}(\omega_0+2\pi)n}=\mathrm{e}^{\mathrm{j}\omega_0n}$$

The exponential at frequency  $\omega_0 + 2\pi$  is the same as that at frequency  $\omega_0$ , therefore, we need only consider a frequency interval of length  $2\pi$  in which to choose  $\omega_0$ .

The low-frequency discrete-time exponentials have values of  $\omega_0$  near  $2k\pi-k\in\mathbb{Z}$ , while the high frequencies are located near  $\omega_0=(2k+1)\pi-k\in\mathbb{Z}$ 

The signal  $e^{j\omega_0n}$  is periodic if  $\frac{\omega_0}{2\pi}=\frac{m}{N}$  is a rational number and is not periodic otherwise. its fundamental frequency is  $\frac{2\pi}{N}=\frac{\omega_0}{m}$ 

harmonically related complex exponential  $\phi_k[n]=\mathrm{e}^{\mathrm{j}k\frac{2\pi}{N}n}\quad k=0,\pm 1,\pm 2,...$  and  $\phi_{k+N}[n]=\phi_k[n]$ , which implies that there are only N distinct periodic exponentials in the set

#### 4. The Unit Impulse and Unit Step Functions

#### 4.1 The Discrete-Time Unit Impulse and Unit Step Sequences

unit impulse or unit sample

$$\delta[n] = egin{cases} 0, & n 
eq 0 \ 1, & n = 0 \end{cases}$$

unit step

$$u[n] = egin{cases} 1, & n \geq 0 \ 0, & n < 0 \end{cases}$$

There is a close relationship between the discrete-time unit impulse and unit step.

$$\delta[n] = u[n] - u[n-1]$$

$$u[n] = \sum_{m=-\infty}^n \delta[m] = \sum_{k=0}^n \delta[n-k]$$

and

$$x[n]\delta[n-n_0]=x[n_0]\delta[n-n_0]$$

# 4.2 The Continuous-Time Unit Step and Unit Impulse Functions

unit step function

$$u(t) = egin{cases} 1, & t \geq 0 \ 0, & t < 0 \end{cases}$$

unit impluse function

$$\delta(t) = \frac{\mathrm{d}u(t)}{\mathrm{d}t}$$

$$u(t) = \int_{-\infty}^{t} \delta(t) dt = \int_{0}^{\infty} \delta(t - \sigma) d\sigma$$
  
 $x(t)\delta(t - t_0) = x(t_0)\delta(t - t_0)$ 

## 5. Continuous-Time and Discrete-Time Systems

continuous-time system x(t) o y(t) discrete-time systems x[n] o y[n]

## 6. Basic System Properities

A system is said to be **memoryless** if its output for each value of the independent variable at a given time is dependent only on the input at that same time.

for example y(t) = x(t)

An example of a discrete-time system with memory is y[n] = x[n-1].

A system is said to be **invertible** if distinct inputs lead to distinct outputs.

for example y(t)=2x(t), for which the inverse system is  $w(t)=rac{1}{2}y(t)$ 

Examples of **noninvertible** systems are y[n] = 0

A system is **causal** if the output at any time depends only on values of the input at the present time and in the past.

A system is stable if small inputs lead to responses that do not diverge.

A system is time invariant if the behavior and characteristics of the system are fixed over time.

A system is linear if:

- 1.The response to  $x_1(t) + x_2(t)$  is  $y_1(t) + y_2(t)$ . (additivity)
- 2.The response to  $ax_1(t)$  is  $ay_1(t)$ , where a is any complex constant. (homogeneity)

#### superposition property

$$x[n] = \sum_k a_k x_k[n] o y[n] = \sum_k a_k y_k[n]$$