## Title of Project

#### **Servo Prediction**

# Objective

The objective of this project is to predict the behavior of a servo mechanism using regression analysis. By analyzing input signals and corresponding motor responses, we aim to build a predictive model that can accurately forecast servo motor behavior.

#### ▼ Data Source

The data for this project is sourced from a CSV file hosted on the YBI Foundation GitHub repository. The dataset contains information about servo mechanism behaviors, including input features and motor responses. You can access the dataset from the following link: <a href="https://github.com/YBI-Foundation/Dataset/raw/main/Servo%20Mechanism.csv">https://github.com/YBI-Foundation/Dataset/raw/main/Servo%20Mechanism.csv</a>

### Import Library

```
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns
from sklearn.model_selection import train_test_split
from sklearn.linear_model import LinearRegression
from sklearn.metrics import mean_squared_error, r2_score
```

### import data

```
data = pd.read_csv('https://github.com/YBI-Foundation/Dataset/raw/main/Servo%20Mechanism.csv')
```

### **▼ Describe Data**

```
print(data.head())
```

```
        Motor Screw
        Pgain
        Vgain
        Class

        0
        E
        E
        5
        4
        4

        1
        B
        D
        6
        5
        11

        2
        D
        D
        4
        3
        6

        3
        B
        A
        3
        2
        48

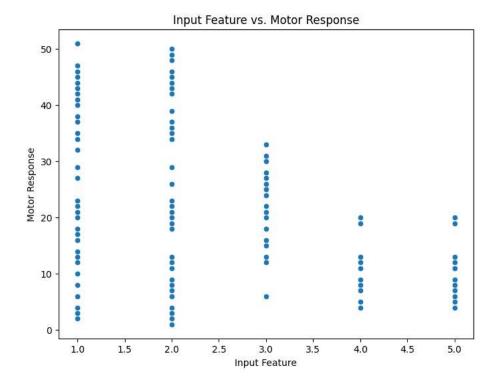
        4
        D
        B
        6
        5
        6
```

print(data.info())

```
dtypes: int64(3), object(2)
    memory usage: 6.6+ KB
    None
print(data.describe())
                Pgain
                            Vgain
                                        Class
    count 167.000000 167.000000 167.000000
             4.155689
                         2.538922
                                    21.173653
    mean
    std
             1.017770
                         1.369850
                                    13.908038
              3.000000
                                     1.000000
    min
                         1.000000
     25%
              3.000000
                         1.000000
                                     10.500000
    50%
             4.000000
                         2.000000
                                    18.000000
                                     33.500000
    75%
              5.000000
                         4.000000
    max
              6.000000
                         5.000000
                                     51.000000
```

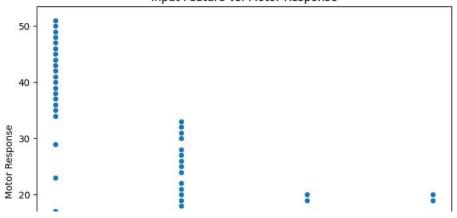
### ▼ Data Visualization

```
plt.figure(figsize=(8, 6))
sns.scatterplot(x='Vgain', y='Class', data=data)
plt.title('Input Feature vs. Motor Response')
plt.xlabel('Input Feature')
plt.ylabel('Motor Response')
plt.show()
```



```
plt.figure(figsize=(8, 6))
sns.scatterplot(x='Pgain', y='Class', data=data)
plt.title('Input Feature vs. Motor Response')
plt.xlabel('Input Feature')
plt.ylabel('Motor Response')
plt.show()
```

#### Input Feature vs. Motor Response



## **▼ Data Preprocessing**



<ipython-input-40-c44ded798807>:1: FutureWarning: The default value of numeric\_only in DataFrame.corr is deprecated. In a f
data.corr()

|       | Pgain     | Vgain     | Class     | Ш   |
|-------|-----------|-----------|-----------|-----|
| Pgain | 1.000000  | 0.812268  | -0.687098 | ıl. |
| Vgain | 0.812268  | 1.000000  | -0.391963 |     |
| Class | -0.687098 | -0.391963 | 1.000000  |     |

data.describe()

|       | Pgain      | Vgain      | Class      | $\blacksquare$ |
|-------|------------|------------|------------|----------------|
| count | 167.000000 | 167.000000 | 167.000000 | ıl.            |
| mean  | 4.155689   | 2.538922   | 21.173653  |                |
| std   | 1.017770   | 1.369850   | 13.908038  |                |
| min   | 3.000000   | 1.000000   | 1.000000   |                |
| 25%   | 3.000000   | 1.000000   | 10.500000  |                |
| 50%   | 4.000000   | 2.000000   | 18.000000  |                |
| 75%   | 5.000000   | 4.000000   | 33.500000  |                |
| max   | 6.000000   | 5.000000   | 51.000000  |                |

# ▼ Define Target Variable (y) and Feature Variables (X)

|     | Pgain | Vgain | Class |     |
|-----|-------|-------|-------|-----|
| 0   | 5     | 4     | 4     | 11. |
| 1   | 6     | 5     | 11    |     |
| 2   | 4     | 3     | 6     |     |
| 3   | 3     | 2     | 48    |     |
| 4   | 6     | 5     | 6     |     |
|     |       |       |       |     |
| 162 | 3     | 2     | 44    |     |
| 163 | 3     | 1     | 40    |     |
| 164 | 4     | 3     | 25    |     |
| 165 | 3     | 2     | 44    |     |
| 166 | 6     | 5     | 20    |     |
|     |       |       |       |     |

#### 167 rows × 3 columns

## ▼ Train Test Split

```
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=42)
```

## ▼ Modeling

```
X_encoded = pd.get_dummies(X, columns=['Class'], drop_first=True)
model = LinearRegression()
model.fit(X_train, y_train)

* LinearRegression
LinearRegression()
```

## ▼ Model Evaluation

```
# Make predictions
y_pred = model.predict(X_test)

# Calculate metrics
mse = mean_squared_error(y_test, y_pred)
r2 = r2_score(y_test, y_pred)

print("Mean Squared Error:", mse)
print("R-squared:", r2)

Mean Squared Error: 1.592802974806543e-29
R-squared: 1.0
```

#### Prediction

```
new_input_data = pd.DataFrame({
    'Motor': ['A'],
    'Screw': ['A'],
    'Pgain': [6],
    'Vgain': [5]
})

new_input_encoded = pd.get_dummies(new_input_data, columns=['Motor', 'Screw'], drop_first=True)

missing_columns = set(X_train.columns) - set(new_input_encoded.columns)
for column in missing_columns:
    new_input_encoded[column] = 0

predicted_responses = model.predict(new_input_encoded)
print("Predicted Motor Responses:", predicted_responses)
```

### Explaination

In this "Servo Prediction" project, our goal was to predict servo motor behavior using a machine learning approach. We imported and analyzed data related to input signals and motor responses. After preprocessing the data, we defined input features and motor responses as target variables.

We split the dataset into training and testing sets and trained a Linear Regression model to predict motor responses based on input features. Model evaluation using metrics like Mean Squared Error and R-squared provided insights into its performance.

We demonstrated the practical application of our model by predicting motor responses for new input data. This project exemplifies the process of developing a predictive model for servo motor behavior, showcasing the power of machine learning in real-world applications.