



POLITECNICO DI TORINO

DIGITAL SYSTEMS ELECTRONICS
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PROF. G. MASERA

Lab 04

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1 Gated SR latch

The circuit shown in *figure 1* implements a gated SR latch. Once coded into VHDL the Quartus Prime compiler uses separate memory components as shown in *figure 2* to depict the electric circuit.

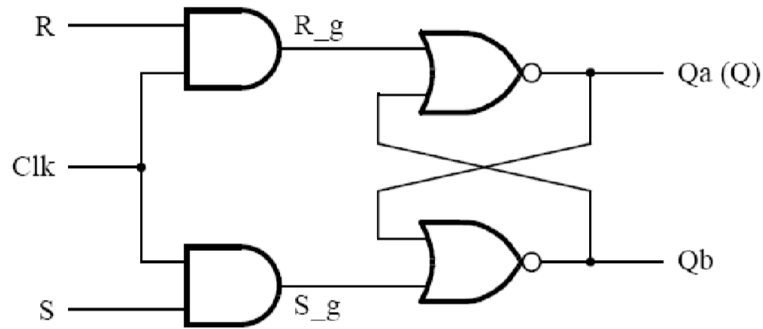


Figure 1: A gated SR latch circuit

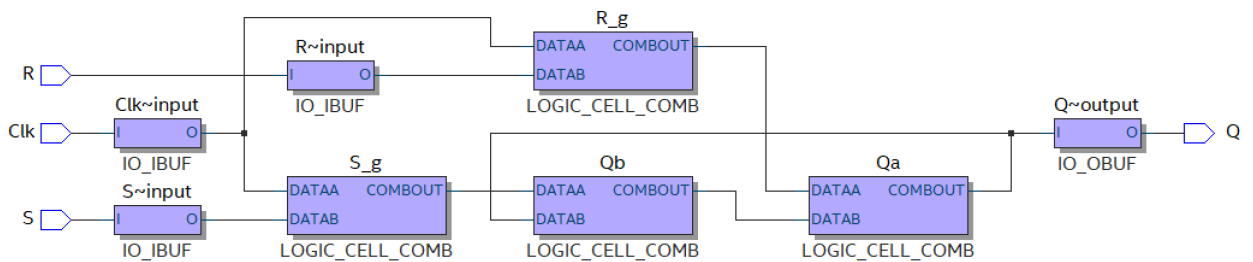


Figure 2: Quartus circuit implementation

Finally, a testbench has been written to test the behavior of the circuit, according to the table shown below:

Clk	S	R	$Q(t+1)$
0	x	x	$Q(t)$ (no change)
1	0	0	$Q(t)$ (no change)
1	0	1	0
1	1	0	1
1	1	1	x

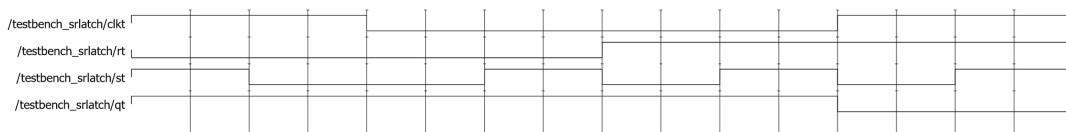


Figure 3: Modelsim Testbench waves

The testbench results are shown by means of the simulated waves shown in *figure 3*. Initially $CLK = 1$, the latch is enabled. For $S = 1$, $R = 0$ the set condition is triggered and $Q = 1$. Viceversa $Q = 0$ when $S = 0$, $R = 1$, in reset condition. Once $CLK = 0$ the latch is disabled entering in the memory condition as $S = 0$, $R = 0$. In the other hand for $S = 1$, $R = 1$ the latch behavior becomes unpredictable.

2 16-bit synchronous counter

The circuit in *figure 4* implements a 4-bit counter using T flip flops. A 16-bit version has been implemented using the same structure as shown in *figure 5*. Using the Quartus tools the maximum working frequency has been identified to be equal to $F = 374.53MHz$ as reported in *figure 6* using a total of 31 LEs.

In the implementation of the 16-bits counter respect to the 4-bit counter no differences as observed in terms of architecture.

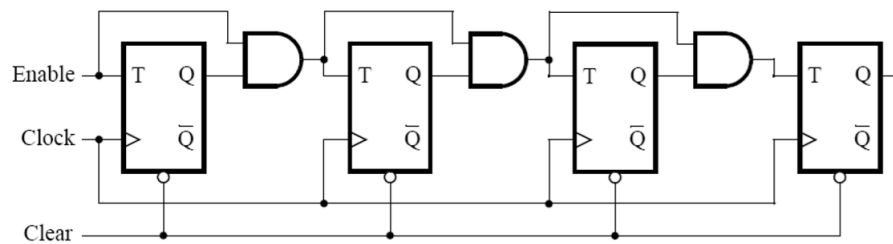


Figure 4: 4-bit counter

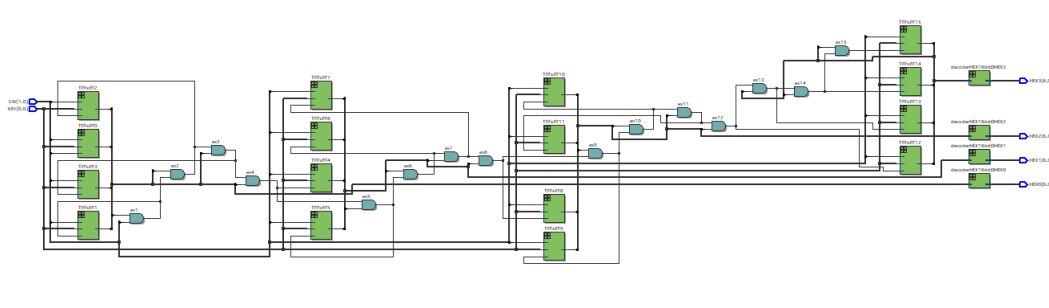


Figure 5: 4-bit counter

Fmax	Restricted Fmax	Clock Name
374.53 MHz	374.53 MHz	KEY0

Figure 6: Maximum working frequency

Finally a testbench has been designed to check the functionality of the circuit, the results are shown in *figure 6* where the counting process is shown using the HEX display. Notice that the circuit is firstly initialized resetting the current state of every FF. Then the counting process has been started enabling the circuit and applying a clock to every FF.

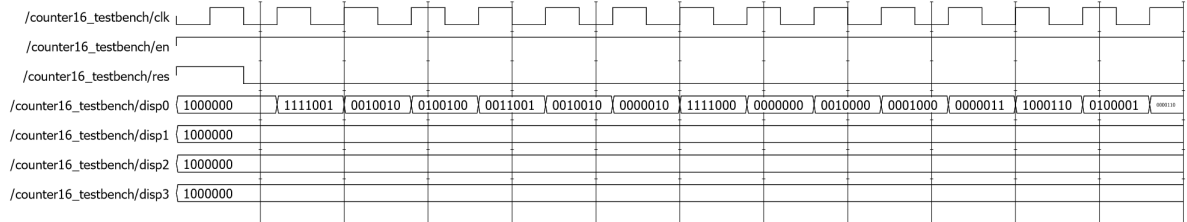


Figure 7: Modelsim Testbench waves

3 16-bit synchronous counter version 2

In this section the counter has been implemented by means of a process using the statement $Q \leq Q + 1;$, therefore giving the synthesis tool maximum freedom on the implementation. As we can see from the RTL view in figure 8 the tool instantiated 16 D-FFs as memory elements and two sets of multiplexers and an adder to implement the counting behavior and the Enable/Clear functions. This implementation different from the one in the previous section. Here the tool instantiated just D-FFs, Multiplexers and one adder. Those are all elements which are standard elements for an FPGA. Actually, adders and D-FFs have a special places where they are allocated and in an FPGA all logic functions are mapped in Multiplexers. This implementations uses just 9 logic elements and can work up to $xxxxMHz$ instead the previous one uses 31LEs and has $f_{max} = 374.53MHz$.

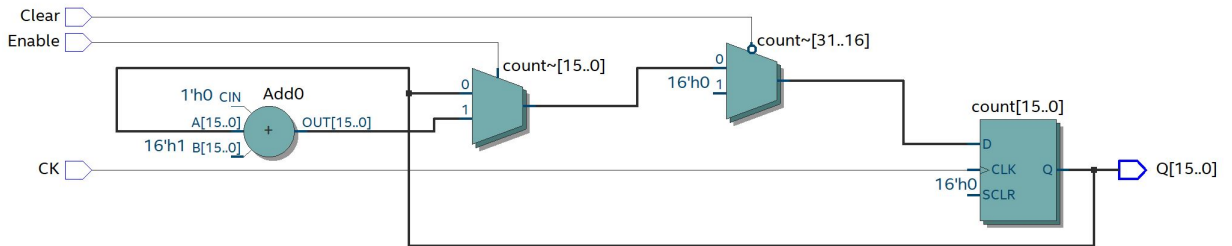


Figure 8: RTL view

4 Flashing digits from 0 to 9

The objective of this section of the laboratory is to design a circuit that shows all digits (from 0 to 9) sequentially on a DE10 7-segments display, The displayed digit changes every second. The desired timing is achieved by using the reference 50Mhz clock (CLOCK_50) of the DE10 board, that is the sole clock signal of the circuit.

The overall circuit is composed of 3 components: a counter that manages the 1-second timing (seconds_counter.vhd), a counter that stores and updates the displayed digit (digit_counter.vhd) and the BCD to 7-segments decoder.

The first counter (seconds_counter) scales the reference counter to 1 second. After 50 million clocks the counter generates a 1-second signal for 1 clock cycle which is passed as an enable signal to the digit counter. This counter returns as output the BCD encoding of the current digit that is used by the 7-segments decoder to drive the rightmost display (HEX0) of the board.

The circuit has an asynchronous reset mechanism associated with the KEY0 button of the board, it is used for initializing the circuit.

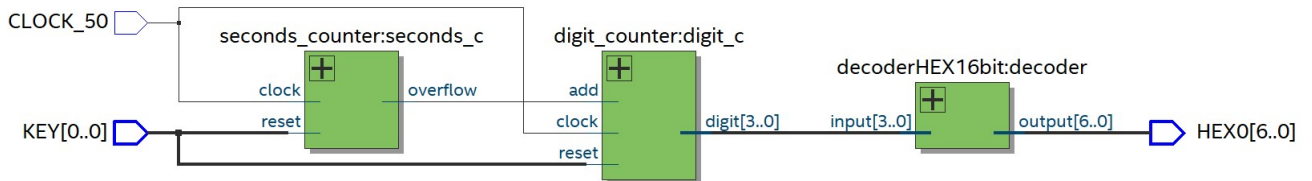


Figure 9: The RTL view of the circuit

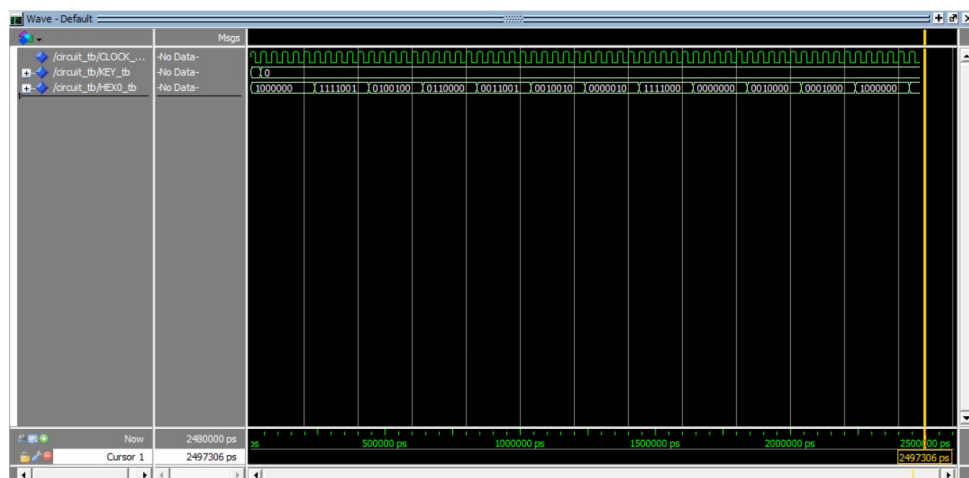


Figure 10: The result of the simulation of the circuit 4

4.1 Testing the circuit

Since the enormous amount of clock cycles need for counting a second, during the simulation with Modelsim the timing counter was modified to send the enable signal every 5 clock cycles (the modified lines for testing are present in the source file as comments).

The testbench of the circuit tests firstly the reset button and then iterates, through a for loop for, the complete cycle of all 10 digits plus the starting of another cycle.

5 Reaction Timer

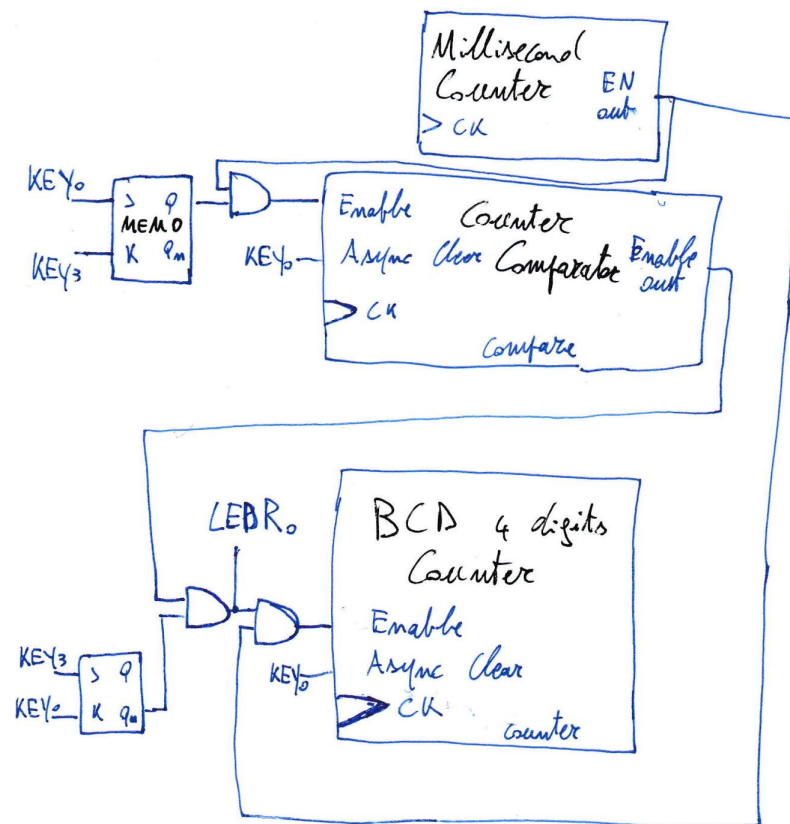


Figure 11: RTL view

The RT level circuit to implement the reaction timer is shown in *figurex*. Some non standard components are just the implementation of more standard elements in a single component. This was done in order to accelerate the vhdl description of the circuit and simplify the block scheme.

5.1 millisecond counter

The purpose of this block is to generate a pulse on the output port connected to *millisecond_{signal}* lasting for a clock cycle every millisecond. It has been implemented as a counter that resets and produces a pulse when it reaches the binary equivalent of 50000. With the DE1 *CLOCK_50* clock input at frequency 50MHz the circuit counts to 50000 in 1ms.

5.2 counter comparator

This unit starts to count after it is resetted. Its enable signal is in *and* with the *millisecond_{signal}* to enable the counter only every ms and not every clock cycle. When the counter reaches the value set by the inputs *SW₇₋₀* it stops and the *enable_{out}* output is asserted to 1 until the component is reset.

5.3 BCD 4digits counter

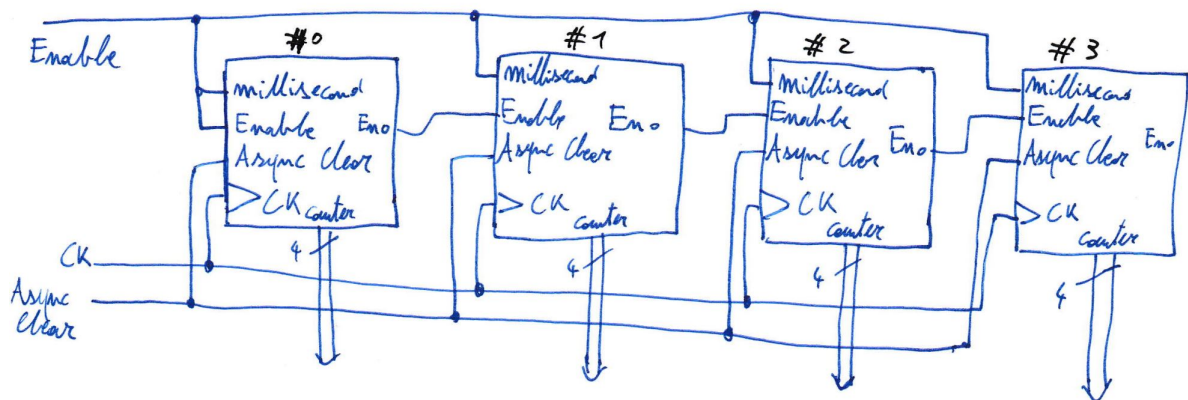


Figure 12: RTL view

This component is made by four *BCDcounters* connected in a way that they count, modulus 10, numbers up to four digits. Each digit is represented binary using the *BCD* code and is connected to a decoder driving its respective 7-segments display. As shown in *figurexx* each *BCDcounter* has an input *enable* and output *enable_{out}*, those signals are connected together between consecutive *BCDcounters*. In particular the *enable_{out}* output is asserted to 1 when the digit displayed is 9 in order to enable the following counter in the next period and properly display the number. The period for the counter is set to 1ms by the input *millisecond* which is directly connected to the *Enable* signal of the *BCD 4 digits counter*.

5.4 JK-FFs and connections between blocks

Two memory elements have been used to implement the requested behavior. The *MEM0* element is responsible to generate the enable signal for the *counter_comparator* when occurs pulse of *KEY₀*. The *KEY₀* input is connected also to the *Asynchronous_clear* input of the *counter_comparator* in order to start to count from 0 when *KEY₀* is pressed.

The *MEM1* generate a signal useful to stop the *BCD₄digits_counter* to count and turn off the *LEDR₀*. when *KEY₃* is pressed. In particular the *LEDR₀* is active from when the time set by the *SW₇₋₀* is eplaced (thanks *counter_comparator*) and up to when *KEY₃* is pressed and the complemented output of *MEM1* is 0. The *BCD₄digits_counter* is active in the same amount of time, but since it has to count every millisecond its enable is in *and* with the *millisecond_signal*.

5.5 Testbench

To be able to verify easily the behaviour of the circuit a new version:”LAB4_ES5_tt has been created. This version does not include the 7-segments decoder, therefore the output is directly taken from the *BCD_4digits_counter*. The *Millisecond_counter_tt* only counts up to 3 instead of 50000 and the clock period has been set to 20ps Then one measurement cycle is executed with the following timing in order to ensure that both counters reach their respective maximum value.

Cycle	Waiting time	Reaction time
	2550ps	1025600ps

In another file: *testbench_LAB4_ES5_tt* a proper simulation with the real timings has been done. There the following measurement cycles are executed:

Cycle	Waiting time	Reaction time
	3ms	17ms
	1ms	21ms

Relatively short duration have been chosen in order to make the simulation faster.