Lecture 4

Hashing Methods

Lecture Content

1. Basics

2. Collision Resolution Methods

- 2.1 Linear Probing Method
- 2.2 Quadratic Probing Method
- 2.3 Double Hashing Method
- 2.4 Coalesced Chaining Method
- 2.5 Separate/Direct Chaining Method
- 2.6 Cuckoo Hashing Method

- Search time in array is O(n).
- Search time in tree is $O(\log n)$.
- Ideally, search time in array-based hash table is constant O(1) in the average case.
- Array-based, linked list based, or tree-based hash table can be used.

- Some applications of hash tables are as follows.
- Hashing is a technique often used to implement an ADT dictionary.
- Compilers use hash tables to keep track of declared variables in source code. The data structure is called symbol table.
- Spelling checker: entire dictionary can be prehashed and words can be checked in constant time.

- In this lecture, we examine a data structure (i.e., hash table) which is designed specifically with the objective of providing efficient insertion and searching operations (deletion is not our primary objective).
- In order to meet the design objective (i.e., constant time performance), we do not require that there be any specific ordering of the items in the container.

• To achieve constant time performance objective, the implementation must be based in some way on an array rather than a linked list.

• This is because we can access the *k*-th element of an array in constant time, whereas the same operation in a linked list takes longer time.

- We are designing a container which will be used to hold some number of items of a given set *K*. We call the elements of the set *K* keys and *K* is called the key space.
- The general approach is to store the keys in an array. The position (also called location or index) i of a key k in the array is given by a function f(k), called a **hash function**, which determines the position of a given key directly from that key (i.e., i = f(k) is called the **hash code** of k).

• In the general case, we expect the size of the set of keys, denoted as |K|, to be relatively large in comparison with the number of items stored in the container M (denoted as M << |K|).

• In other words, the number of items stored in the container is significantly less than |K|. We use an array of size M to contain items.

• Consequently, what we need is a function

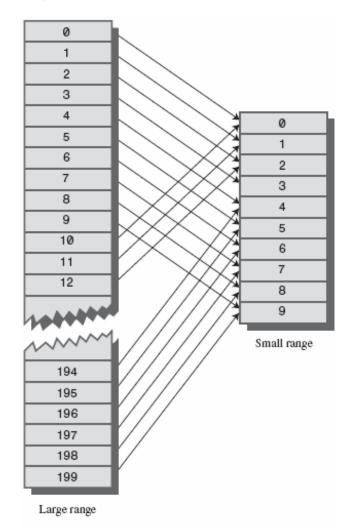
$$f: K \to \{0, 1, ..., M-1\}.$$

- This function maps (or transforms) the set of key values to be stored in the container to subscripts (indexes) in an array of length M.
- This function is called a hash function.

- In general, since |K| >> M, the mapping defined by a hash function will be a many-to-one mapping.
- That is, there will exist many pairs of distinct keys x and y, such that $x \neq y$, for which f(x) = f(y).
- This situation is called a **collision** and f is not a **perfect hash function**.
- Several approaches for dealing with collisions are explored in the following sections.

• Example: $K = \{0, 1, ..., 199\}, M = 10$, for each

key k in K, f(k) = k % M.



- The characteristics of a good hash function are as follows.
 - It avoids collisions.
 - It tends to spread keys evenly in the array.
 - It is easy to compute (i.e., computational time of a hash function should be O(1)).

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2. Collusion Resolution Methods

- Three methods in open addressing are linear probing, quadratic probing, and double hashing.
- These methods are of the division hashing method because the hash function is f(k) = k % M.
- Some other hashing methods are middle-square hashing method, multiplication hashing method, and Fibonacci hashing method, and so on.

- The hash table in this case is implemented using an array (i.e., adjacent list) containing M nodes (or elements), each node of the hash table has a field k used to contain the key of the node.
- *M* can be any positive integer but *M* is often chosen to be a prime number.
- When the hash table is initialized, all fields k are assigned to -1 (i.e., empty or vacant).

• When a node with the key *k* needs to be added into the hash table, the hash function

$$f(k) = k \% M$$

will specify the address i = f(k) (i.e., an index of an array) within the range [0, M-1].

- If there is no conflict (i.e., the cell i is unoccupied), then this node is added into the hash table at the address i.
- If a conflict takes place, then the hash function rehashes first time f_1 to consider the next address (i.e., i + 1). If conflict occurs again, then the hash function rehashes second time f_2 to examine the next address (i.e., i + 2). This process repeats until the available address found then this node will be added at this address.

• The rehash function at the time t (i.e., the collision number t = 1, 2, ...) is presented as follows

$$f_t(k) = (f(k) + t) \% M = (i + t) \% M$$

• When searching a node, the hash function f(k) will identify the address i (i.e., i = f(k)) falling between 0 and M - 1.

• Example: insert keys 32, 53, 22, 92, 17, 34, 24, 37, and 56 into a hash table of size M = 10.

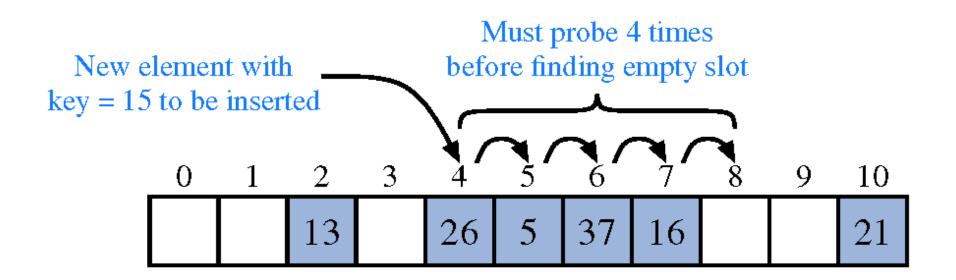
(a)		
0	-1	
1	-1	
2	32	
3	53	
4	-1	
5	-1	
6	-1	
7	-1	
8	-1	
9	-1	

(b)		
0	-1	
1	-1	
3	32	
3	53	
5	22	
5	92	
6	-1	
7	-1	
8	-1	
9	-1	

(c)		
0	-1	
1	-1	
3	32	
3	53	
4	22	
5	92	
6	34	
7	17	
8	-1	
9	-1	

(d)		(e)	
0	-1	0	56
1	-1	1	-1
3	32	2	32
3	53	3	53
4	22	4	22
5 6	92	5	92
6	34	6	34
7	17	7	17
8	24	8	24
9	37	9	37

• Example: Insertion the keys 13, 26, 5, 37, 16, and 15 into a hash table with integer keys using hash function $f(k) = k \mod 11$. The value f(k) is called the hash code of the key k.



• The drawback of the linear probing method is that it causes the primary clustering problem.

• That is, it creates a long sequence of filled slots.

• In other words, primary clustering occurs when the keys hashed to different locations trace the same sequence in looking for an empty location.

• Quadratic probing is an attempt to keep clusters from forming.

• The idea is to probe more widely separated cells, instead of those adjacent to the primary hash site.

• The hash table in this case is implemented using an array (i.e., adjacent list) containing M nodes, each node of the hash table has a field k used to contain the key of the node.

• When the hash table is initialized, all fields k are assigned to -1.

• When a node with the key *k* needs to be added into the hash table, the hash function

$$f(k) = k \% M$$

will specify the address i within the range [0, M - 1] (i.e., i = f(k)).

- If there is no conflict, then this node is added into the hash table at the address *i*.
- If a conflict takes place, then the hash function rehashes first time f_1 to consider the address f(k) + 1^2 . If conflict occurs again, then the hash function rehashes second time f_2 to examine the address f(k) + 2^2 . This process repeats until the available address found then this node will be added at this address.

• The rehash function at the time t (i.e., the collision number t = 1, 2, ...) is presented as follows.

$$f_t(k) = (f(k) + t^2) \% M = (i + t^2) \% M$$

• When searching a node, the hash function f(k) will identify the address i (i.e., i = f(k)) falling between 0 and M - 1.

• Example: insert the keys 10, 15, 16, 20, 30, 25, 26, and 36 into a hash table of size M = 10.

(a)		
0	10	
1	-1	
3	-1	
3	-1	
4	-1	
5	15	
6	16	
6 7	-1	
8	-1	
9	-1	

(0)

(b)		
0	10	
1	20	
3	-1	
3	-1	
5	-1	
5	15	
6	16	
7	-1	
8	-1	
9	-1	

(c)		
0	10	
1	20	
2	-1	
3	-1	
5	30	
I	15	
6	16	
7	-1	
8	-1	
9	25	

<u>(a)</u>		<u>(e)</u>	
0	10	0	10
1	20	1	20
3	-1	2	36
3	-1	3	-1
4	30	4	30
5	15	5	15
6	16	6	16
7	26	7	26
8	-1	8	-1
9	25	9	25

• The problem with quadratic probing method is that it causes the secondary clustering problem.

• Secondary clustering occurs when keys which hash to the same location trace the same sequence in looking for an empty location.

- To eliminate secondary clustering problem, we can use another approach: double hashing.
- Double hashing is one of the most effective methods of probing an open addressed hash table.
- It works by adding the **hash codes** of two hash functions. This method uses two functions f and g as the hash functions.

• When a node with the key *k* needs to be added into the hash table, the first hash function

$$f(k) = k \% M = i$$

will specify the address i within a range [0, M - 1] (i.e., i = f(k)), where M is a prime number.

• A prime number *M* produces fewer collisions.

- If there is no conflict, this node is added into the hash table at the address *i*.
- If a conflict takes place, the second hash function g(k) = c (k % c) = j, where the constant c is a prime number less than hash table size M and j is called step size, is used.

Then, the first hash function rehashes the first time to consider the address $f_1(k) = (f(k) + j) \% M = (i + j) \% M = i_1$.

If conflict happens again, the first hash function rehashes the second time to consider the address $f_2(k) = (f_1(k) + j) \% M = i_2$. This process repeats until the available address found then this node will be added at this address.

• The rehash function at the time t (i.e., the collision number t = 1, 2, ...) is presented as follows.

$$f_t(k) = (f_{t-1}(k) + j) \% M = (i_{t-1} + j) \% M$$
, where $f_0(k) = i_0 = i = f(k)$, $j = g(k) = c - (k \% c)$, c and M are primes, $c < M$.

• Double hashing requires that the size of the hash table is a prime number (e.g., M = 11).

• **Example**: insert the keys 14, 17, 25, 37, 34, 16, and 26 into a hash table of size M = 11, c = 5.

0	-1
1	-1
2	-1
3	14
4	-1
5	-1
6	17
7	-1
8	-1
9	-1
10	-1

0	-1
1	34
3	-1
3	14
4	37
5	16
6	17
7	-1
8	25
9	-1
10	-1

0	-1
1	34
2	-1
3	14
4	37
5	16
6	17
7	-1
8	25
9	26
10	-1

Probes

	110003
$14 \mod 11 = 3 \checkmark$	1
$17 \mod 11 = 6 \checkmark$	1
25 mod 11 = 3 \times	2
$37 \mod 11 = 4 \checkmark$	1
34 mod $11 = 1$	1
$16 \mod 11 = 5 \checkmark$	1
26 mod 11 = 4 \times	5

0	-1
1	-1
3	-1
3	14
4	-1
5	-1
6	17
7	-1
8	-1
9	-1
10	-1

0	-1
1	34
3	-1
3	14
4	37
5	16
6	17
7	-1
8	25
9	-1
10	-1

0	-1
1	34
2	-1
3	14
4	37
5	16
6	17
7	-1
8	25
9	26
10	-1

•
$$j = 5 - (25 \% 5) = 5$$
,
 $i_1 = (i_0 + j) \% 11 = (i + j) \% 11 = (3 + 5) \% 11 = 8$

Probes

$$14 \mod 11 = 3 \checkmark 1$$

 $17 \mod 11 = 6 \checkmark 1$
25 mod 11 = 3 × **2**

$$37 \mod 11 = 4 \checkmark 1$$

$$34 \mod 11 = 1 \checkmark 1$$

$$16 \mod 11 = 5 \checkmark$$

$$26 \mod 11 = 4 \times 4$$

0	-1
1	-1
3	-1
3	14
4	-1
5	-1
6	17
7	-1
8	-1
9	-1

10

0	-1
1	34
2	-1
3	14
4	37
5	16
6	17
7	-1
8	25
9	-1
10	-1

0	-1
1	34
2	-1
3	14
4	37
5	16
6	17
7	-1
8	25
9	26
10	-1

•
$$j = 5 - (26 \% 5) = 4$$
,

$$i_1 = (i_0 + j) \% 11 = (4 + 4) \% 11 = 8, \times$$

$$i_2 = (i_1 + j) \% 11 = (8 + 4) \% 11 = 1, \times$$

$$i_3 = (i_2 + j) \% 11 = (1 + 4) \% 11 = 5, \times$$

$$i_4 = (i_3 + j) \% 11 = (5 + 4) \% 11 = 9 \checkmark$$

- The hash table in this case is implemented using an array containing *M* nodes.
- Each node of the hash table is a class consisting of two fields as follows.

Field k: contains the key of the node.

Field *next*: contains a reference to next node if conflict occurs.

• When the hash table is initialized, all fields *k* and *next* are assigned to -1.

- When a node with the key k needs to be added into the hash table, the hash function f(k) = k % M = i will identify the address i within the range [0, M 1].
- If there is no conflict, then this node will be added into the hash table at address *i*.

- If a conflict happens, then this node will be added into the hash table at the first available address, say *j*, from the bottom of the hash table. The field *next* of **the last node** at index *i* **in the chain** will be updated to *j*.

• Example: insert the keys 10, 15, 26, 30, 25, and 35 into a hash table of size 10.

	(a)		
0	10	-1	0
1	-1	-1	1
2	-1	-1	2
3	-1	-1	3
4	-1	-1	4
5	15	-1	5
6	26	-1	6
7	-1	-1	7
8	-1	-1	8
9	-1	-1	9

	(b)	
0	10	9
1	-1	-1
3	-1	-1
3	-1	-1
4	-1	-1
5	15	-1
6	26	-1
7	-1	-1
8	-1	-1
9	30	-1

• Example: insert the keys 10, 15, 26, 30, 25, and 35 into a hash table of size 10.

	(b)	
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	-1
6	26	-1
7	-1	-1
8	-1	-1
9	30	-1

	(c)	
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	-1	-1
8	25	-1
9	30	-1

• Example: insert the keys 10, 15, 26, 30, 25, and 35 into a hash table of size 10.

	(c)	
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	-1	-1
8	25	-1
9	30	-1

	(c)	
0	10	9
1	-1	-1
2	-1	-1
3	-1	-1
4	-1	-1
5	15	8
6	26	-1
7	35	-1
8	25	7
9	30	-1

(~)

2.5 Separate (or Direct) Chaining Method

• The hash table is implemented by using singly linked list.

- Nodes on the hash table are hashed into M (e.g., M
- = 10) singly linked lists (from list 0 to list M 1).

• Nodes conflicted at the address i are directly connected in the list i, where $0 \le i \le M - 1$.

2.5 Direct (or Separate) Chaining Method

• When a node with the key k is added into the hash table, the hash function f(k) = k % M will identify the address i between 0 and M - 1 corresponding the singly linked list i where this node will be added.

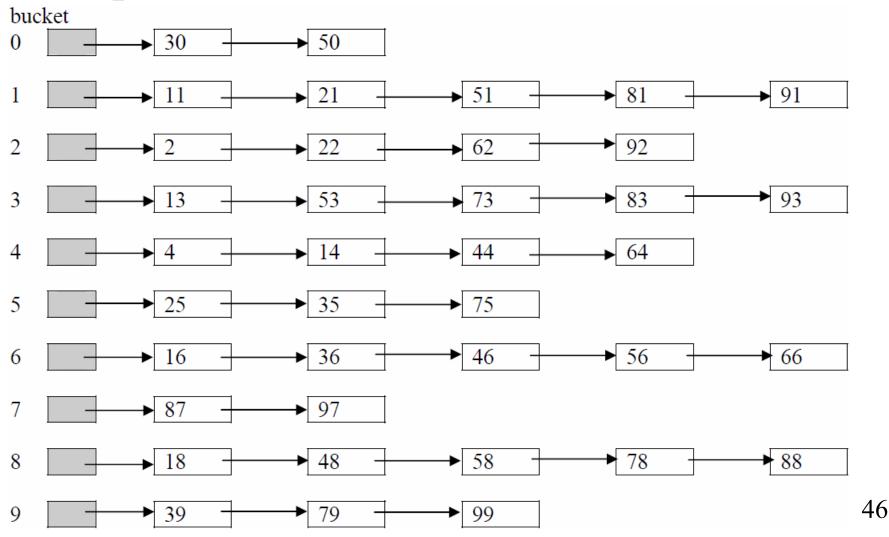
2.5 Direct (or Separate) Chaining Method

• When a node needs to be searched on the hash table, the hash function f(k) = k % M will specify the address i within the range [0, M - 1] corresponding the singly linked list i that may contain the node.

• Searching a node on the hash table turns out the problem of searching an element on the singly linked list.

2.5 Direct (or Separate) Chaining Method

• Example: insert 13, 4, 16, 87, 11, 30, 2, 18, 25, ...



- In the cuckoo hashing scheme, we use two hash tables T_0 and T_1 , each of size M.
- In addition, we use a hash function h_0 for T_0 and a different hash function h_1 for T_1 .
- For any given key $k \in K$, there are two possible places where we can store the key k, namely, either in $T_0[h_0(k)]$ or $T_1[h_1(k)]$.
- For example, the key k = A(0, 2) will be stored at index 0 in T_0 and at index 2 in T_1 (i.e., $h_0(k) = 0$, $h_1(k) = 2$).

procedure insert(*k*)

if
$$(k = T_0[h_0(k)])$$
 or $(k = T_1[h_1(k)])$ then return; $i \leftarrow 0$

```
loop t times if T_i[h_i(k)] is empty then
```

 $T_i[h_i(k)] \leftarrow k$

return

```
temp \leftarrow T_i[h_i(k)]
```

 $T_i[h_i(k)] \leftarrow k$ // cuckoo eviction, kicking out, displace

$$k \leftarrow temp$$

$$i \leftarrow (i+1) \mod 2 // i = 0, 1$$

Rehash all the items including k using new hash functions h_0 and h_1 .

function search(k) return $(k = T_0[h_0(k)])$ or $(k = T_1[h_1(k)])$ end;

• **Example**: insert the keys A(0, 2), B(0, 0), C(1, 4), D(1, 0), E(3, 2), F(3, 4) into the hash tables T_0 and T_1

Table 0		
0		
1		
2		
3		
4		

Tab	Table 1		
0			
1			
2			
3			
4			

A: 0, 2 B: 0, 0 C: 1, 4 D: 1, 0 E: 3, 2 F: 3, 4

Table 0		
0 A		
1		
2		
3		
4		

		_			_
Tab	le 0		Table 1		A: 0,
0	A		0		
1			1		
2			2		
3			3		
4			4		
Cuckoo hash table after insertion of A					

A: 0, 2

Table 0		
0	В	
1		
2		
3		
4		

Table 1		
0		
1		
2	A	
3		
4		

A: 0, 2

B: 0, 0

Cuckoo hash table after insertion of B // temp = A, k = A, i = 1,

Table 0	
0	В
1	С
2	
3	
$\overline{4}$	

Tab	Table 1	
0		
1		
2	A	
3		
4		

A: 0, 2 B: 0, 0C: 1, 4

Table 0		
0	В	
1	D	
2		
3	Е	
4		

Tab	Table 1	
0		
1		
2	A	
3		
4	C	

A: 0, 2 B: 0, 0C: 1, 4 D: 1, 0 E: 3, 2

Cuckoo hash table after insertion of D, and then E// temp = C, k = C, i = 1,Cuckoo hash table after insertion of C

Table 0		
0	В	
1	D	
2		
3	F	
4		

Table 1	
0	
1	
2	A
3	
4	С

A: 0, 2	
B: 0, 0	
C: 1, 4	
D: 1, 0	
E: 3, 2	
F: 3, 4	

Cuckoo hash table starting the insertion of Finto the hash table. First, F displaces E.

$$// temp = E, k = E, i = 1,$$

Table 0		
0	Α	
1	D	
2		
3	F	
4		

Table 1	
0	
1	
2	E
3	
4	С

Tab	le 1	A: 0, 2
0		B: 0, 0
1		C: 1, 4
2	Е	D: 1, 0
3		E: 3, 2
4	С	F: 3, 4

Continue the insertion of F into the hash table.

Next, A displaces B.

$$// temp = B, k = B, i = 1,$$

Table 0	
0	В
1	D
2	
3	F
4	

Tab	Table 1	
0		
1		
2	E	
3		
4	С	

A:	0,	2
В:	0,	0
C:	1,	4
D:	1,	0
E:	3,	2
F:	3,	4

Continue the insertion of F into the hash table.

Next, E displaces A.

$$// temp = A, k = A, i = 0,$$

Table 0		
0	A	
1	D	
2		
3	F	
4	-	

Table 1	
0	В
1	
2	Е
3	
4	C

`ab	le 1	A: 0, 2
)	В	B: 0, 0
		C: 1, 4
2	Е	D: 1, 0
}		E: 3, 2
1	С	F: 3, 4

Completing the insertion of F into the hash table. Miraculously, B finds an empty position in Table 1.

- We cannot successfully insert G with hash locations (1, 2).
- G displaces D, D displaces B, B displaces A, A displaces E, E displaces F, F displaces C, and C displaces G which was placed there at the start.
- *G* is inserted into its alternate in Table 1 (location 2). *G* displaces *A*, *A* displaces *B*, *B* displaces *D*, *D* displaces *C*, *C* displaces *F*, *F* displaces *E*, and *E* displaces *G* from position 2.
- At this point, the initial hash tables appear again. A cycle is detected. A rehash is required.

• A family H of hash functions is 2-universal if for any two distinct keys x and y in K, where $x \neq y$, and for a hash function h chosen uniformly at random from H, we have

Probability(h(x) = h(y)) $\leq 1 / M$, where M is the hash table size.

• The universal family H of hash functions is defined as follows.

$$H = \{h_{a,b}(x) = ((ax + b) \bmod p) \bmod M, \text{ where } 1 \le a \le p - 1, 0 \le b \le p - 1\},$$

where a and b are chosen randomly and p is a prime larger than the largest input key.

• H has p(p-1) possible hash functions.

• For example, three random choices of (a, b) yield three different hash functions:

$$h_{3,7}(x) = ((3x + 7) \mod p) \mod M$$

 $h_{4,1}(x) = ((4x + 1) \mod p) \mod M$
 $h_{8,0}(x) = ((8x) \mod p) \mod M$

Exercises

Write the following complete Java programs

- LP. java for linear probing method,
- QP. java for quadratic probing method,
- DH. java for double hashing method,
- CC. java for coalesced chaining method, and
- SC. java separate/direct chaining method.

Hash Code for a String

• The hash code of a given string s can be computed as follows.

$$f(s) = a_0 x^{n-1} + a_1 x^{n-2} + \dots + a_{n-2} x + a_{n-1},$$

// a polynomial of degree n-1

where a_i is the Unicode of s_i for $0 \le i \le n - 1$ and x is a positive constant (e.g., x = 31).

Hash Code for a String

```
int f = 0, n = length(s);
for (int i = 0; i < n; i++)
  f = f * x + a[i];</pre>
```

References

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