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Method 1 \rightsquigarrow Eigen Values and Eigen Vectors

Eigen Value

- Let A be square matrix.
- If there exists a non-zero vector X such that $AX = \lambda X$, then the scalar λ is known as **eigen value** of A.
- The set of all eigenvalues of matrix A is known as **Spectrum** of A.
- Eigen value is also known as characteristic root/latent value/proper roots.

Eigen Vector

- Let A be square matrix.
- If there exists a non-zero vector X such that $AX = \lambda X$, then the **non-zero** vector X is known as **eigen vector** of A corresponding to eigen value λ .
- Eigen vector is also known as characteristic vector/latent vector/proper vector corresponding to the eigen value λ of the matrix.

Eigen Space

- The **solution space** of the system $(A - \lambda I) \cdot X = 0$ is known as **eigen space** of matrix A corresponding to eigen value λ .
- i.e., $E_\lambda = \{ X \mid X \text{ is eigen vector of A corresponding to eigen value } \lambda \}$

Characteristic Equation

- Let A be a square matrix of order n and I be an identity matrix of order n, then $|A - \lambda I| = 0$ is known as characteristic equation, where λ is a scalar.
- The characteristic equation of matrix A of order 2×2 is

$$\lambda^2 - S_1\lambda + S_2 = 0$$

Where $S_1 = \text{tr}(A) = \text{Sum of eigen values}$

$$S_2 = |A| = \text{Determinant of A}$$

- The characteristic equation of matrix A of order 3×3 is

$$\lambda^3 - S_1\lambda^2 + S_2\lambda - S_3 = 0$$

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Where $S_1 = \text{tr}(A) = \text{Sum of eigen values}$

$S_2 = \text{Sum of minors of principal diagonal elements} = M_{11} + M_{22} + M_{33}$

$S_3 = |A| = \text{Determinant of } A$

Properties of Eigen Value and Eigen Vector

- (1) $\text{Trace}(A) = \text{Sum of all the eigen values of matrix } A.$
- (2) $|A| = \text{Product of all the eigen values of matrix } A.$
- (3) If one of the eigen value of matrix A is zero, then $|A| = 0$, hence A^{-1} does not exist.
- (4) The eigen values of triangular matrix are the elements on its principal diagonal.
- (5) The square matrix A and A^T have the same eigen values but eigen vectors need not to be same.
- (6) If λ is an eigen value of a non-singular matrix A and X is an eigen vector correspond to λ , then

Matrix	Eigen value
A^T	λ
A^k	λ^k
A^{-1}	$\frac{1}{\lambda}$
$A \pm kI$	$\lambda \pm k ; k \in \mathbb{R}$
kA	$k\lambda ; k \in \mathbb{R}$

→ Procedure to find the eigen values, eigen vectors for a matrix A of order 3×3

- (1) Write the characteristic equation $\lambda^3 - S_1\lambda^2 + S_2\lambda - S_3 = 0$ and find S_1, S_2 and S_3 .
- (2) Find the roots of the characteristic equation. These are the Eigen Values of A , say $\lambda_1, \lambda_2, \lambda_3$.
- (3) Solve the homogeneous system $(A - \lambda I) \cdot X = 0$ for each eigen value by using Gauss Elimination Method.
- (4) Eigen vector is the solution X of above system.

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Examples of Method-1: Eigen Values and Eigen Vectors

C	1	<p>Find the eigen values and corresponding eigen vectors of the matrix</p> $A = \begin{bmatrix} 5 & 0 & 1 \\ 1 & 1 & 0 \\ -7 & 1 & 0 \end{bmatrix}.$ <p>Answer: $\lambda = 2, 2, 2$, $X = \left[-\frac{1}{3} \quad -\frac{1}{3} \quad 1 \right]^T$</p>
C	2	<p>Find the eigen values and eigen bases for the eigen space of the matrix</p> $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}.$ <p>Answer: $\lambda = -1, -1, 2$</p> <p>Eigen Bases: $\{ (-1 \ 1 \ 0)^T, (-1 \ 0 \ 1)^T, (1 \ 1 \ 1)^T \}$</p>
C	3	<p>Find the eigen values of $A = \begin{bmatrix} -5 & 4 & 34 \\ 0 & 0 & 4 \\ 0 & 0 & 4 \end{bmatrix}$. Is it invertible?</p> <p>Answer: $-5, 0, 4$ & No</p>
C	4	<p>Find the eigen values and eigen vectors of the matrix $A = \begin{bmatrix} 3 & 1 & 4 \\ 0 & 2 & 6 \\ 0 & 0 & 5 \end{bmatrix}$.</p> <p>Answer: $\lambda = 2 \rightsquigarrow X = [-1 \ 1 \ 0]^T$, $\lambda = 3 \rightsquigarrow X = [1 \ 0 \ 0]^T$</p> <p>$\lambda = 5 \rightsquigarrow X = [3 \ 2 \ 1]^T$</p>
C	5	<p>If $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$, then find the eigen values and eigen vectors corresponding to each eigen value of A. Also, write the eigen space for each eigen values.</p> <p>Answer: $\lambda = -1 \rightsquigarrow X = [-1 \ 1]^T$, $\lambda = 1 \rightsquigarrow X = [1 \ 1]^T$</p> <p>$E_{-1} = \left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \cdot t \mid t \in \mathbb{R} \right\}$, $E_1 = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \cdot t \mid t \in \mathbb{R} \right\}$</p>

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C	6	<p>Let $A = \begin{bmatrix} 3 & 0 \\ 8 & -1 \end{bmatrix}$, the find eigen values of A, A^{25}, $3A$, A^{-1}, A^T, $A + 2I$ & $A^3 - 5I$.</p> <p>Answer: $A \rightsquigarrow -1, 3$, $A^{25} \rightsquigarrow -1, 3^{25}$, $3A \rightsquigarrow -3, 9$</p> <p>$A^{-1} \rightsquigarrow -1, \frac{1}{3}$, $A^T \rightsquigarrow -1, 3$, $A + 2I \rightsquigarrow 1, 5$</p> <p>$A^3 - 5I \rightsquigarrow -6, 22$</p>
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Method 2 \rightsquigarrow Power Method

- In many engineering problems, it is required to compute the numerically largest eigen value and corresponding eigen vector. In such cases, power method is convenient which is also well-suited for machine computations.
- This method can be used when the matrix A of order n has n linearly independent eigen vectors.
- The eigen values can be ordered in magnitude as $|\lambda_1| > |\lambda_2| \geq |\lambda_3| \geq \dots \geq |\lambda_n|$.
Here, λ_1 is known as dominant eigen value of A and the remaining eigen values $\lambda_2, \lambda_3, \dots, \lambda_n$, are known as sub-dominant eigen values of A.
i.e., if the eigenvalues of a matrix are 2, 5, and -13, then -13 is the dominant eigenvalue as $|-13| > |5| \geq |2|$.

Procedure for Finding Largest Eigen Value and Corresponding Eigen Vector

- For a square matrix A,
 - (1) Apply the formula $AX_i = \lambda_{i+1}X_{i+1}$; $i = 0, 1, 2, \dots$
 - (2) Let us consider initial eigen vector X_0 (X_0 is an arbitrary vector) as

$$X_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{OR} \quad X_0 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \text{OR} \quad X_0 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$
 - (3) Find X_1 by calculating $AX_0 = \lambda_1 X_1$; where λ_1 is dominant eigen value
 X_2 by calculating $AX_1 = \lambda_2 X_2$; where λ_2 is dominant eigen value

$$\vdots$$
 - (4) Repeat this process until $X_r = X_{r-1}$ up to desired level of accuracy.
 - (5) We get λ_r largest eigen value and X_r the corresponding eigen vector.
- This iterative procedure for finding the largest eigen value of a matrix is known as Rayleigh's power method.

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→ For Example:

We find largest eigen value and corresponding eigen vector of the matrix

$$A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$$

Let us consider, initial eigen vector $X_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

$$\text{Now we find } AX_0 = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 5 \\ 1 \end{bmatrix} = \mathbf{5} \begin{bmatrix} 1 \\ 0.2 \end{bmatrix} = \lambda_1 X_1$$

$$AX_1 = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0.2 \end{bmatrix} = \mathbf{5.8} \begin{bmatrix} 1 \\ 0.241 \end{bmatrix} = \lambda_2 X_2$$

$$AX_2 = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0.241 \end{bmatrix} = \mathbf{5.966} \begin{bmatrix} 1 \\ 0.248 \end{bmatrix} = \lambda_3 X_3$$

$$AX_3 = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0.249 \end{bmatrix} = \mathbf{5.994} \begin{bmatrix} 1 \\ 0.250 \end{bmatrix} = \lambda_4 X_4$$

$$AX_4 = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0.250 \end{bmatrix} = \mathbf{5.999} \begin{bmatrix} 1 \\ 0.25 \end{bmatrix} = \lambda_5 X_5$$

$$AX_5 = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0.25 \end{bmatrix} = \mathbf{6} \begin{bmatrix} 1 \\ 0.25 \end{bmatrix} = \lambda_6 X_6$$

Hence the largest eigen value is 6 and eigen vector is $\begin{bmatrix} 1 \\ 0.25 \end{bmatrix}$.

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Examples of Method-2: Power Method

C	1	Find the largest eigen value and the corresponding eigen vector of the following matrix $A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$. Answer: 6, [1 0.25]^T
C	2	Find the largest eigen value and the corresponding eigen vector of the following matrix $A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}$. Answer: 2.41, [0.71 0.5 1]^T
C	3	Find the largest eigen value and the corresponding eigen vector of the following matrix $A = \begin{bmatrix} 15 & -4 & 3 \\ -10 & 12 & -6 \\ -20 & 4 & -2 \end{bmatrix}$. Answer: 13.52, [0.68 -0.5 -1]^T
C	4	Find the largest eigen value and the corresponding eigen vector of the following matrix $A = \begin{bmatrix} 1 & 1 & 1 \\ -1 & -3 & -3 \\ 2 & 4 & 4 \end{bmatrix}$. Answer: 2, [0.33 -0.67 1]^T

Method 3 \rightsquigarrow Gauss Jacobi Method

Introduction

- Numerical methods provide a way to solve problems quickly and easily as compare to analytic methods.
- Numerical methods are useful to solve problems whose analytic solution is not available or the analytic solution can't be generalized.
- Numerical methods are used to solve system of linear equations, to find roots of non-linear equations, to solve ODE, etc.
- In general, an equation is solved by factorization but in some cases, the method of factorization fails. In such cases, numerical methods can be used.

Iterative Method

- In this method, an approximation to the true solution is assumed initially to start method. By applying the method repeatedly, better and better approximation are obtained.
- For large systems, iterative methods are faster than direct methods and round-off error are also smaller.
- In fact, iteration is a self-correcting process and any error made at any stage of computation gets automatically corrected in the subsequent steps.
- There are two iterative methods which is
 - (1) Gauss Jacobi Method
 - (2) Gauss Seidel Method

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Gauss Jacobi Method

→ This method is applicable to the system of equations in which leading diagonal elements of the coefficient matrix are dominant (large in magnitude) in their respective rows.

→ Procedure to find solution system of simultaneous linear equation:

(1) Consider the system of equations:

$$\left. \begin{aligned} a_1x + b_1y + c_1z &= d_1 \\ a_2x + b_2y + c_2z &= d_2 \\ a_3x + b_3y + c_3z &= d_3 \end{aligned} \right\} \dots \dots (1)$$

Where co-efficient matrix A must be diagonally dominant,

$$|a_1| \geq |b_1| + |c_1|$$

i. e., $|b_2| \geq |a_2| + |c_2|$ and the inequality is strictly greater than for **at least**

$$|c_3| \geq |a_3| + |b_3|$$

one row.

(2) Solving the system (1) for x, y, z respectively,

$$\text{We obtain, } \left. \begin{aligned} x &= \frac{1}{a_1} (d_1 - b_1y - c_1z) \\ y &= \frac{1}{b_2} (d_2 - a_2x - c_2z) \\ z &= \frac{1}{c_3} (d_3 - a_3x - b_3y) \end{aligned} \right\} \dots \dots (2)$$

(3) We start with $x_0 = 0$, $y_0 = 0$ & $z_0 = 0$ in equation (2) and we get

$$x_1 = \frac{1}{a_1} (d_1 - b_1y_0 - c_1z_0) = \frac{d_1}{a_1}$$

$$y_1 = \frac{1}{b_2} (d_2 - a_2x_0 - c_2z_0) = \frac{d_2}{b_2}$$

$$z_1 = \frac{1}{c_3} (d_3 - a_3x_0 - b_3y_0) = \frac{d_3}{c_3}$$

(4) Again, substituting these value x_1, y_1, z_1 in eq. (2), the next approximation is obtained.

(5) Repeat this process until the values of x, y, z are obtained to desire level of accuracy.

Examples of Method-3: Gauss Jacobi Method

C	1	Solve the following system by using Gauss Jacobi method. $6x + 2y - z = 4, \quad x + 5y + z = 3, \quad 2x + y + 4z = 27$ Answer: (2, -1, 6)
C	2	Solve the following system by using Gauss Jacobi method. $2x + y + z = 0, \quad 3x + 5y + 2z = 15, \quad 2x + y + 4z = 8$ Answer: (0.5, 0.5, 0.5)
C	3	Solve the following system by using Gauss Jacobi method, correct up to two decimal places. $10x + y - z = 11.19, \quad x + 10y + z = 28.08, \quad -x + y + 10z = 35.61$ Answer: (1.23, 2.34, 3.45)
C	4	Solve by Gauss Jacobi method, correct up to two decimal places. $20x + 2y + z = 30, \quad x - 40y + 3z = -75, \quad 2x - y + 10z = 30$ starting with (1, 2, -1). Answer: (1.14, 2.13, 2.99)
C	5	Solve the following system by using Gauss Jacobi method. $27x + 6y - z = 85, \quad x + y + 54z = 110, \quad 6x + 15y + 2z = 72$ Answer: (2.425, 3.573, 1.926)

Method 4 \rightsquigarrow Gauss Seidel Method

Gauss Seidel Method

→ This is a modification of Gauss Jacobi method. In this method, we replace the approximation by the corresponding new ones as soon as they are calculated.

→ Procedure to find solution system of simultaneous linear equation:

(1) Consider the system of equations:

$$\left. \begin{aligned} a_1x + b_1y + c_1z &= d_1 \\ a_2x + b_2y + c_2z &= d_2 \\ a_3x + b_3y + c_3z &= d_3 \end{aligned} \right\} \dots \dots (1)$$

Where co-efficient matrix A must be diagonally dominant,

$$|a_1| \geq |b_1| + |c_1|$$

i. e., $|b_2| \geq |a_2| + |c_2|$ and the inequality is strictly greater than for **at least**

$$|c_3| \geq |a_3| + |b_3|$$

one row

(2) Solving the system (1) for x, y, z respectively,

$$\text{We obtain, } \left. \begin{aligned} x &= \frac{1}{a_1} (d_1 - b_1y - c_1z) \\ y &= \frac{1}{b_2} (d_2 - a_2x - c_2z) \\ z &= \frac{1}{c_3} (d_3 - a_3x - b_3y) \end{aligned} \right\} \dots \dots (2)$$

(3) We Start with $x_0 = 0, y_0 = 0$ & $z_0 = 0$ in the equation of x,

$$x_1 = \frac{1}{a_1} (d_1 - b_1y_0 - c_1z_0) = \frac{d_1}{a_1}$$

(4) Substituting $x = x_1$ & $z = z_0$ in the equation of y,

$$y_1 = \frac{1}{b_2} (d_2 - a_2x_1 - c_2z_0)$$

(5) Substituting $x = x_1$ & $y = y_1$ in the equation of z,

$$z_1 = \frac{1}{c_3} (d_3 - a_3x_1 - b_3y_1)$$

(6) Repeat this process until the values of x, y, z are obtained to desire level of accuracy.

Examples of Method-4: Gauss Seidel Method

C	1	Solve the following system by using Gauss Seidel method. $10x_1 + x_2 + x_3 = 6, \quad x_1 + 10x_2 + x_3 = 6, \quad x_1 + x_2 + 10x_3 = 6$ Answer: (0.5, 0.5, 0.5)
C	2	Solve the following system by using Gauss Seidel method. $9x + y + z = 10, \quad 2x + 10y + 3z = 19, \quad 3x + 4y + 11z = 0$ Answer: (1, 2, -1)
C	3	Solve the following system by using Gauss Seidel method, correct up to three decimal places. $27x + 6y - z = 85, \quad x + y + 54z = 110, \quad 6x + 15y + 2z = 72$ Answer: (2.425, 3.573, 1.926)
C	4	By using Gauss Seidel method solve the following system up to seven iterations. $12x_1 + 3x_2 - 5x_3 = 1, \quad x_1 + 5x_2 + 3x_3 = 28, \quad 3x_1 + 7x_2 + 13x_3 = 76$ Use initial condition: $(x_1^0, x_2^0, x_3^0) = (1, 0, 1)$. Answer: (1, 3, 4)

***** End of the Unit *****