

Depth Estimation in 2D images

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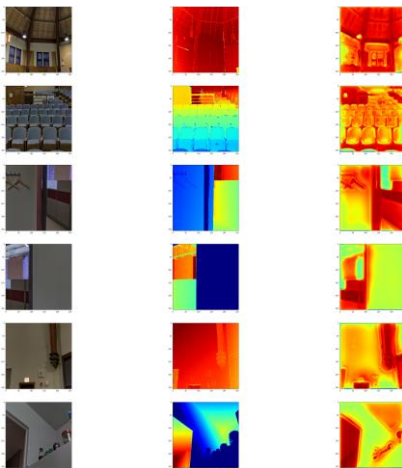
Abstract— This study is based on a Deep Learning approach to generate depth maps based on input 2d images. We train a CNN using the DIODE depth dataset and use it to generate depth maps and compare them with existing depth maps from the training set. This study uses dataset having both indoor and outdoor images from various scenes having varying depth.

Keywords—deep learning, depth, CNN, DIODE dataset, insert

I. INTRODUCTION (HEADING 1)

Depth estimation in monocular images often poses to be a challenging task as without any perception of depth it is difficult to visualize distance of objects from the screen. It is easier in stereoscopic images because of multiple images from several camera angles. Since depth estimation in general has its various applications ranging from scene reconstruction for 3D printing or just for the sake of visualizations. To tackle this problem we try to use Supervised Learning to train models which can accurately identify the distance of objects from the screen(camera) and form depth maps for each pixel for easier visualization. Using convolutional neural networks we can form depth maps to assign different colours based on a colormap gradient scale. For this purpose we will make use of the DIODE indoor dataset which contains high quality indoor images with their respective depth maps and masks.

Using a supervised learning method will help us in understanding the difference between a actual depth and the depth map predicted by the model.



II. LITERATURE REVIEW

- A. *Object Detection of Remote Sensing Airport Image Based on Improved Faster R-CNN: HAN Yongsai¹, MA Shiping², ZHANG Fei, LI Chenghao.* The model used here was an efficient version of Region based Convolutional Neural Network. The use case was remote sensing of airport images and detecting objects in the same. A deeper basic ResNet was used, and add a new fully connected layer to the end detection network and combine the SoftMax classifier and 4 logistic regression classifiers for object detection according to the inter-class correlation of the object.

Satellite images of Airports were used. The faster RCNN model uses Region Proposal Net (RPN) which results in more accuracy, efficiency. This framework identified objects such as airports, civil aviation aircraft, fighter jets, transport planes, helicopters, tanks, and bridge objects. Each proposed ROI is convoluted with $3 \times 3 \times n$ filters, pooling operation used on feature map obtained from convolution of last layer.

- B. *Real-Time Depth Estimation from 2D Images: Jack Zhu, Ralph Ma, They proposed model here is Transfer learning on real time images captured by camera, study the depth maps and estimate depths using heatmap on the NYU-dataset. They compared the transfer learning model on a pretrained and untrained network, compared performance differences. The lossy function used here is RMSE. Different pretrained model were used Mean, Make3d, Course Network, Course + Fine Network, Hierarchical VGG. Hierarchical VGG produced the best efficiency and the lowest RMSE values.*
- C. *Fast Automatic Vehicle Annotation for Urban Traffic Surveillance: Detection and Annotation for Vehicles (DAVE) model was suggested which simultaneously runs 2 CNNs. 1st CNN is responsible for Vehicle detection. 2nd CNN is responsible for Annotation. A shallow Fully Convolutional Fast Vehicle Proposal Network was suggested for extracting all vehicles pose, color, type, simultaneously. These two nets are jointly optimized so that abundant latent knowledge learned from the deep empirical ALN can be exploited to guide training the much simpler FVPN. The proposed DAVE framework outperforms RCNN, Fast RCNN, Faster RCNN.*
- D. *Depth Prediction from 2D Images: A Taxonomy and an Evaluation Study. They performed an Evaluation study by training the data on both supervised and unsupervised models. They compared multi view and Monocular models. The non-deep learning methods use stereo matching and have some disadvantages such as needing train data while runtime. The monocular is divided into Bootstrap and Iterative networks whose output is combined into a Refined network. The monocular 2D depth maps generated are refined and used as outputs.*

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III. PROPOSED WORK

IV. EXPERIMENTAL SETUP

To run our Keras models on DIODE dataset, we used Nvidia CUDA Development toolkit 11.2 on Laptop RTX 3060 which has around 3840 CUDA cores. The CPU used is AMD Ryzen 5800H which features eight SMT-enabled Zen 3 cores running at 3.2 GHz (base clock speed) to 4.4 GHz (Boost). Tegra TK1 Development kit. The TK1 provides an NVIDIA Kepler GPU with 192 CUDA cores, and a QuadCode ARM Cortex CPU. The board has 2GB RAM, split between GPU and CPU. We run Ubuntu 14.04 L4T, CUDA and CUDNN

versions 6.5. To avoid hitting memory limitations, we added a 4GB swapfile on a high speed SD card.

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$$a + b = \gamma \quad (1)$$

Note that the equation is centered using a center tab stop. Be sure that the symbols in your equation have been defined before or immediately following the equation. Use “(1)”, not “Eq. (1)” or “equation (1)”, except at the beginning of a sentence: “Equation (1) is . . .”

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- In your paper title, if the words “that uses” can accurately replace the word “using”, capitalize the “u”; if not, keep using lower-cased.
- Be aware of the different meanings of the homophones “affect” and “effect”, “complement” and “compliment”, “discreet” and “discrete”, “principal” and “principle”.
- Do not confuse “imply” and “infer”.
- The prefix “non” is not a word; it should be joined to the word it modifies, usually without a hyphen.
- There is no period after the “et” in the Latin abbreviation “et al.”.
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Table Head	Table Column Head		
	Table column subhead	Subhead	Subhead
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^a Sample of a Table footnote. (Table footnote)

Fig. 1. Example of a figure caption. (figure caption)

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ACKNOWLEDGMENT (*Heading 5*)

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REFERENCES

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- [1] G. Eason, B. Noble, and I. N. Sneddon, “On certain integrals of Lipschitz-Hankel type involving products of Bessel functions,” *Phil. Trans. Roy. Soc. London*, vol. A247, pp. 529–551, April 1955. (*references*)
- [2] J. Clerk Maxwell, *A Treatise on Electricity and Magnetism*, 3rd ed., vol. 2. Oxford: Clarendon, 1892, pp.68–73.
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- [5] R. Nicole, “Title of paper with only first word capitalized,” *J. Name Stand. Abbrev.*, in press.
- [6] Y. Yorozu, M. Hirano, K. Oka, and Y. Tagawa, “Electron spectroscopy studies on magneto-optical media and plastic substrate interface,” *IEEE Transl. J. Magn. Japan*, vol. 2, pp. 740–741, August 1987 [Digests 9th Annual Conf. Magnetism Japan, p. 301, 1982].
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