NIKHII BHAT

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Education

NORTHEASTERN UNIVERSITY BACHELOR OF SCIENCE IN COMPUTER ENGINEERING & COMPUTER SCIENCE

MAY 2021

GPA: 3.98/4.00

Honors Program

Activities: TA for Discrete Structures, Founding Member of Northeastern Robotics & Automation Society, Mentor for FTC Robotics Team, Teacher at MIT Splash, Honors Living Learning Assistant for Northeastern Honors Program, Build Studio Engineer at Northeastern Generate **Coursework:** Computer Vision, Algorithms and Data Structures, Object Oriented Design, Embedded Design: Enabling Robotics

Skills

LANGUAGES – Experienced: Python, C++| Proficient: Java, Swift | Exposure: HTML, MATLAB **TECHNOLOGIES –** OpenCV, ROS, Arduino, Git

Employment

SOFTWARE ENGINEERING CO-OP GREENSIGHT AGRONOMICS

IANUARY 2019 - IULY 2019

Python, OpenCV, ROS, C++

- Developed an autonomous drone navigation system using OpenCV which won the company \$30,000 in the Verizon 5G Robotics Challenge
- Designed a self-correcting algorithm for heliostat motion, by using OpenCV coupled with a PID controller to account for GPS errors
- Implemented SLAM navigation algorithms using a combination of 2D LIDAR and depth cameras for an autonomous ground robot
- Created and deployed a ROS network of 100 interconnected devices to track the sun and generate solar power

DATA ANALYST INTERN BARNES AEROSPACE

MAY 2018 - AUGUST 2018

Python, NumPy, Pandas, VBA

- Reduced turbine center frame inspection times by 30% by developing a Python program to implement statistical process control
- Created an interactive GUI using Python linked to an external SQL database allowing for supervisors to view consolidated error reports within any timeframe and location – this program is now used across the manufacturing plant
- Developed an algorithm in Python to categorize part defects based on problem description fields utilizing regular expression matching
- Programmed a VBA application to dynamically schedule manufacturing operations, accounting for variable lead times and delivery delays

UNDERGRADUATE RESEARCH ASSISTANT NORTHEASTERN UNIVERSITY FIELD ROBOTICS LAB

OCTOBER 2017 - APRIL 2018

C++, ROS, Python, ViSP

- Programmed a real time kinematic GPS driver using C++, and implemented it into the autonomous car ROS environment
- Implemented an image labeling platform using Python to label underwater fish datasets
- Furthered development in drone navigation techniques utilizing AprilTag image detection with ViSP and OpenCV

ROBOTICS AMBASSADOR CONNECTICUT SCIENCE CENTER

JUNE 2014 - AUGUST 2015

Arduino, C++

- Increased accessibility for disabled patrons of the Hartford Farmer's Market by manufacturing an autonomous shopping robot utilizing Arduinos, GPS Shields and IR sensors to follow the customer
- Designed and built a robotics exhibit involving driver-controlled soccer robots playing against an Arduino-based autonomous goalie

Leadership

NORTHEASTERN IEEE AUGUST 2017 – PRESENT

VICE PRESIDENT

Facilitated and ran club meetings for the largest professional engineering society at Northeastern

CARFER SUMMIT CHAIR

Organized an ECE career fair attended by over 100 ECE students by reaching out to companies across the Greater Boston area

REACH COLLEGE CONSULTING

MAY 2018 - PRESENT

CEO & CO-FOUNDER

- Founded a company to help students with the entire college application process, from selecting schools to interview preparation
- Improved the SAT scores of 100% of clients, and helped 2 clients achieve perfect scores

Personal Projects

FANCILY
A machine-learning iOS
app to recommend daily
outfits from a user's close
based on individual
stylistic preferences

DON'T TOUCH MY OJ An OpenCV & Raspberry Pi

An OpenCV & Raspberry Pi based vision system which sends a text alert when other people take your food from the fridge.

SESQUIPEDALIAN

A Words with Friends solver, which read the current game board using OpenCV based OCR and produces the highest scoring move.

ALL OF THE LIGHTS

A Python program which pulsates multicolored LEDs based on the mood and BPM of the current song by querying the Spotify API

ENDLESS TRIVIA

A multiplayer Python game which uses the Wikipedia API to generate an endless amount of random trivia questions of varying difficulties