```
In [3]: import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt
    import seaborn as sns
    from keras.datasets import mnist
    from keras.utils import np_utils

In [2]: #import tensorflow
    #tensorflow.__version__

In [4]: # Load the dataset
    (x_train,y_train),(x_test,y_test)=mnist.load_data()

In [5]: print(x_train.shape,y_train.shape)
    (60000, 28, 28) (60000,)

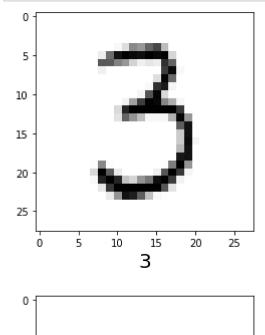
In [6]: print(x_test.shape,y_test.shape)
    (10000, 28, 28) (10000,)
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In [7]: x_train[0]

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Out[7]: array([[ 0,
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```





```
In [8]: # We have to convert 28X28 to 28X28X1
 In [9]: |x_train = x_train.reshape(x_train.shape[0],28,28,1)
 In [ ]: | # reshape
         28 and 28 represent the desired height and width dimensions of the images.
         1 represents the number of channels in the image. In this case, it's set to 1 b
         By reshaping the data using x_train.reshape(x_train.shape[0], 28, 28, 1),
         you are converting the original 2D images of size 28x28 into a 4D tensor.
         The first dimension represents the number of samples, the second and third
         dimensions represent the height and width of each image, and the fourth
         dimension represents the number of channels.
In [10]: x_train.shape
Out[10]: (60000, 28, 28, 1)
In [11]: x \text{ test} = x_{\text{test.reshape}}(x_{\text{test.shape}}[0], 28, 28, 1)
In [12]: x test.shape
Out[12]: (10000, 28, 28, 1)
In [13]: # Normalise the image
```

```
In [13]: | x_train = x_train/255
         x_test = x_test/255
         print(x_train[0])
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In [14]: # One hot encoding on y
         y_test
Out[14]: array([7, 2, 1, ..., 4, 5, 6], dtype=uint8)
In [16]: y_train
Out[16]: array([5, 0, 4, ..., 5, 6, 8], dtype=uint8)
In [17]: |y_train = np_utils.to_categorical(y_train)
         y_test = np_utils.to_categorical(y_test)
In [18]: y_train[0]
Out[18]: array([0., 0., 0., 0., 0., 1., 0., 0., 0., 0.], dtype=float32)
In [19]:
         pd.set_option('display.max_columns',None)
         y_train
Out[19]: array([[0., 0., 0., ..., 0., 0., 0.],
                 [1., 0., 0., ..., 0., 0., 0.]
                 [0., 0., 0., \ldots, 0., 0., 0.]
                 [0., 0., 0., \ldots, 0., 0., 0.]
                 [0., 0., 0., \ldots, 0., 0., 0.]
                 [0., 0., 0., ..., 0., 1., 0.]], dtype=float32)
```

```
In [20]: y_train[0]
Out[20]: array([0., 0., 0., 0., 0., 0., 0., 0., 0.], dtype=float32)
```

CNN model

```
In [21]: from keras.models import Sequential
from keras.layers import Dense,Flatten,Conv2D,MaxPooling2D

In [22]: model = Sequential()

In [23]: model.add(Conv2D(40,(4,4),input_shape=(28,28,1),padding='same',strides=(2,2)))
    model.add(MaxPooling2D(pool_size=(2,2)))  # 7x7x40
    model.add(Conv2D(100,(4,4)))  # 4x4x100
    model.add(MaxPooling2D(pool_size=(2,2)))  # 2x2x100
    model.add(Flatten())
    model.add(Dense(200,activation='relu'))
    model.add(Dense(50,activation='relu'))
    model.add(Dense(10,activation='softmax'))
    # (n + 2p -f)/s + 1
```

```
In []: # model.add(Conv2D(40,(4,4),input shape=(28,28,1),padding='same',strides=(2,2))
        """ # Conv2D: This is the convolutional layer in Keras.
        # 40: It specifies the number of filters or output channels in the layer.
        #(4, 4): It defines the size of the filters or the kernel.
        #input shape=(28, 28, 1): It specifies the shape of the input data. In this cas
        #padding='same': It adds padding to the input data to ensure that the output
        feature maps have the same spatial dimensions as the input.
        Padding helps retain more information from the edges of the images during
        convolution.
        #strides=(2, 2): It specifies the stride or step size of the filter during con-
        By adding this layer to the model, you are introducing a convolutional
        operation that convolves the filters over the input images.
        The filters extract features from the input data, capturing patterns and
        spatial information.
        The output shape of this layer depends on the padding, strides,
        and input shape. Since padding='same' is used, the output feature maps
        will have the same spatial dimensions as the input.
        The number of output channels is set to 40, as specified in the layer
        configuration.
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```

In [24]: model.summary()

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 14, 14, 40)	680
<pre>max_pooling2d (MaxPooling2D)</pre>	(None, 7, 7, 40)	0
conv2d_1 (Conv2D)	(None, 4, 4, 100)	64100
<pre>max_pooling2d_1 (MaxPooling 2D)</pre>	g (None, 2, 2, 100)	0
flatten (Flatten)	(None, 400)	0
dense (Dense)	(None, 200)	80200
dense_1 (Dense)	(None, 50)	10050
dense_2 (Dense)	(None, 10)	510
=======================================	:===========	========

Total params: 155,540 Trainable params: 155,540 Non-trainable params: 0

In [26]: # Compile the model

In [25]: model.compile(loss='categorical_crossentropy', metrics=['Accuracy'],optimizer=

```
In [26]: model.fit(x train,y train,batch size=1000, epochs=10)
        Epoch 1/10
        60/60 [============== ] - 96s 1s/step - loss: 0.8069 - Accurac
        y: 0.7826
        Epoch 2/10
        60/60 [============= ] - 56s 919ms/step - loss: 0.1724 - Accu
        racy: 0.9489
        Epoch 3/10
        60/60 [============= ] - 51s 851ms/step - loss: 0.1125 - Accu
        racy: 0.9669
        Epoch 4/10
        60/60 [============= ] - 63s 1s/step - loss: 0.0840 - Accurac
        y: 0.9758
        Epoch 5/10
        60/60 [============ ] - 87s 1s/step - loss: 0.0669 - Accurac
        y: 0.9803
        Epoch 6/10
        60/60 [============= ] - 69s 1s/step - loss: 0.0602 - Accurac
        y: 0.9819
        Epoch 7/10
        60/60 [=========== ] - 56s 935ms/step - loss: 0.0506 - Accu
        racy: 0.9849
        Epoch 8/10
        60/60 [============= ] - 70s 1s/step - loss: 0.0443 - Accurac
        y: 0.9864
        Epoch 9/10
        60/60 [============= ] - 73s 1s/step - loss: 0.0366 - Accurac
        y: 0.9890
        Epoch 10/10
        60/60 [============ ] - 71s 1s/step - loss: 0.0332 - Accurac
        y: 0.9902
Out[26]: <keras.callbacks.History at 0x222d2dcf130>
In [ ]: # model.fit(x_train,y_train,batch_size=1000, epochs=10)
        x train: This parameter represents the input training data. It consists of a co
        y train: This parameter represents the corresponding labels or target values for
        batch_size: This parameter determines the number of samples processed in each i
        epochs: This parameter specifies the number of times the entire training datase
        During the training process, the model will iterate over the training data in b
In [2]: # SAving and Loading the model
        model_json = model.to_json()
```

```
In [ ]: | model json
In [30]: with open("model.json", "w") as json_file:
             json_file.write(model_json)
In [31]: | model.save_weights("model_mnist.h5")
In [32]: # Loading the model
In [33]: json_file = open('model.json', 'r')
In [34]: loaded_model_json = json_file.read()
In [35]: from keras.models import model_from_json
         loaded_model = model_from_json(loaded_model_json)
In [36]: loaded_model.load_weights("model_mnist.h5")
In [37]: |# Evaluate the model
In [39]: #loaded model.evaluate(x test,y test)
In [40]: y_test.shape
Out[40]: (10000, 10)
In [42]: y_pred = loaded_model.predict(x_test)
 In [2]: y_pred
In [44]: y_pred_labels = [np.argmax(i) for i in y_pred]
```

```
In [45]:
          y_pred_labels
Out[45]: [7,
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In [46]: y_test = [np.argmax(i) for i in y_test]
In [47]: for i in range(200,250):
              plt.imshow(x_test[i], cmap='Greys')
              plt.xlabel(y_pred_labels[i],fontsize=20)
              plt.show()
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In [48]: from sklearn.metrics import confusion_matrix,accuracy_score
```

```
CNN on MNIST dataset - Jupyter Notebook
In [49]: cm = confusion_matrix(y_test,y_pred_labels)
           plt.figure(figsize=(15,12))
In [52]:
           sns.heatmap(cm,annot=True,vmax=1000,vmin=0,cmap='Blues')
Out[52]: <AxesSubplot:>
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In [53]: | accuracy_score(y_test,y_pred_labels)
Out[53]: 0.9861
```

In []: