## 2 Process Control

```
1.
          void exit(int status);
          void _exit(int status);
          void _Exit(int status);
          int atexit(void (*function)(void));
2.
          char *getenv(const char *name);
          int putenv(const char *str);
          int setenv(const char *name, const char *val, int overwrite);
          int unsetenv(const char *name);
3.
          int setjmp(jmp_buf env);
          void longjmp(jmp_buf env, int val);
4.
          pid_t fork(void);
          pid_t vfork(void);
          pid_t getpid(void);
          pid_t getppid(void);
5.
          pid_t wait(int *statloc);
          pid_t waitpid (pid_t pid, int *statloc, int opt);
          opt: WCONTINUED WUNTRACED WNOHANG
          macros (termination status):
          WIFEXITED(statloc)
                  WEXITSTATUS (statloc)
          WIFSIGNALED(statloc)
                  WTERMSIG(statloc)
                  WCOREDUMP (statloc)
          WIFSTOPPED(statloc)
                  WSTOPSIG(statloc)
          WIFCONTINUED (statloc)
6.
          int execl(const char *path, const char *arg, ...);
          int execlp(const char *file, const char *arg, ...);
          int execle(const char *path, const char *arg, ..., char *const
               envp[]);
          int execv(const char *path, char *const argv[]);
          int execvp(const char *file, char *const argv[]);
          int execvpe(const char *file, char *const argv[], char *const
              envp[]);
7.
          uid_t getuid(void);
          uid_t geteuid(void);
          gid_t getgid(void);
          gid_t getegid(void);
          int setuid(uid_t uid);
```

```
int seteuid(uid_t euid);
int setgid(gid_t gid);
int setegid(gid_t egid);

8.    int system(const char *command);

9.    pid_t getpgrp(void);
   pid_t getpgid(pid_t pid);
   int setpgid(pid_t pid, pid_t pgid);
   pid_t getsid(pid_t pid);
   pid_t setsid(void);
```