

An aerial photograph of a coastline featuring a sandy beach, green vegetation, and turquoise ocean waves with white foam. A large teal rectangle is overlaid on the left side of the image, containing the title and authors' names.

Great Barrier Reef COTS Detection

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Introduction [1]

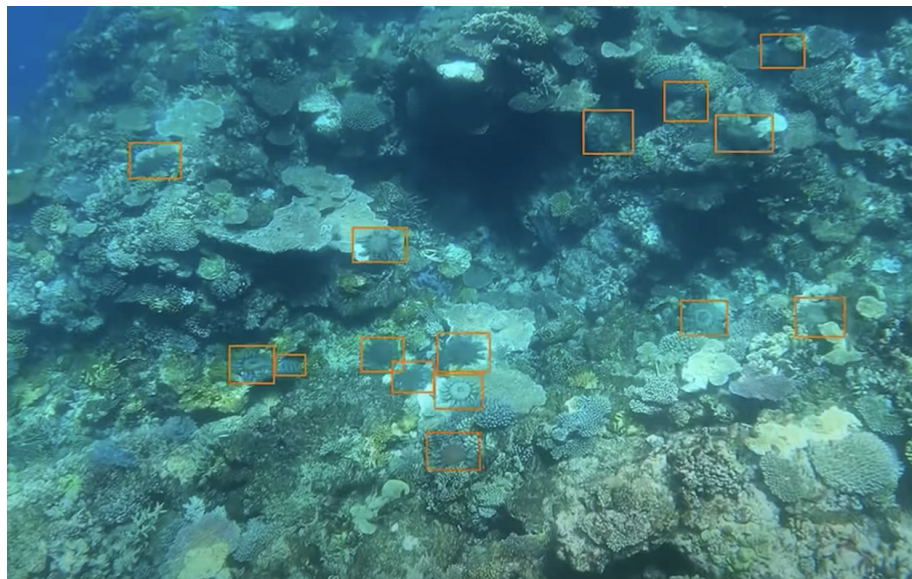
- Great Barrier Reef is a complex of coral reefs, shoals, and islets in the Pacific Ocean. UNESCO issued a second recommendation to include this site in the Danger list.
- COTs are marine invertebrates that feed on coral and can reach plague proportions and devastate hard coral communities (coral bleaching)
- Since 1962, crown-of-thorns starfish outbreaks have had a major impact on the many reefs. During an outbreak, which is when 15 or more COTS are found in a one-hectare area, the starfish can strip a reef of 90% of its living coral tissue.
- COTS are covered in spikes containing toxins and eat by extruding their stomachs out from their bodies, wrapping it around corals and digesting their tissues.

Data Information

video_id	sequence	video_frame	sequence_frame	image_id	annotations
0	40258	13	13	0-13	[]
0	40258	14	14	0-14	[]
0	40258	15	15	0-15	[]
0	40258	16	16	0-16	[{'x': 559, 'y': 213, 'width': 50, 'height': 32}]
0	40258	17	17	0-17	[{'x': 558, 'y': 213, 'width': 50, 'height': 32}]
0	40258	18	18	0-18	[{'x': 557, 'y': 213, 'width': 50, 'height': 32}]
0	40258	19	19	0-19	[{'x': 556, 'y': 214, 'width': 50, 'height': 32}]
0	40258	20	20	0-20	[{'x': 555, 'y': 214, 'width': 50, 'height': 32}]
0	40258	21	21	0-21	[{'x': 550, 'y': 214, 'width': 50, 'height': 32}]

└─ train_images
└─ video_0 - 6,709 images
└─ video_1 - 8,233 images
└─ video_2 - 8,562 images

TOTAL - 23,504 images



Faster RCNN Model

RCNN, Fast RCNN [2,3,8]

- Problems with RCNN
 - Takes lot of time to classify 2000 regions per image
 - Selective Search is a fixed algorithm with no learning
- Problems with Fast RCNN
 - Region proposal slows down the process

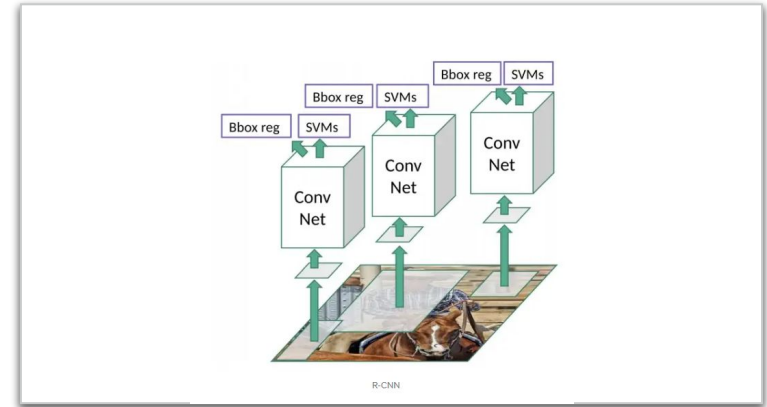


Figure 1: [Source](#)

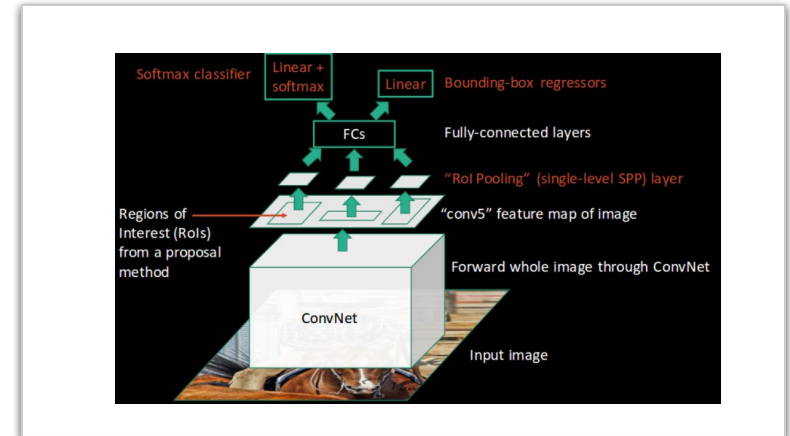


Figure 2: [Source](#)

Faster RCNN Model^[2,5]

R-CNN & Fast R-CNN uses selective search to find out the region proposals – slow and time-consuming.

Faster RCNN eliminates the selective search algorithm and let the network learn the region proposals.

Faster RCNN is composed from 3 parts:

- Part 1 : Convolution layers
- Part 2 : Region Proposal Network (RPN)
- Part 3 : Classes and Bounding Boxes prediction

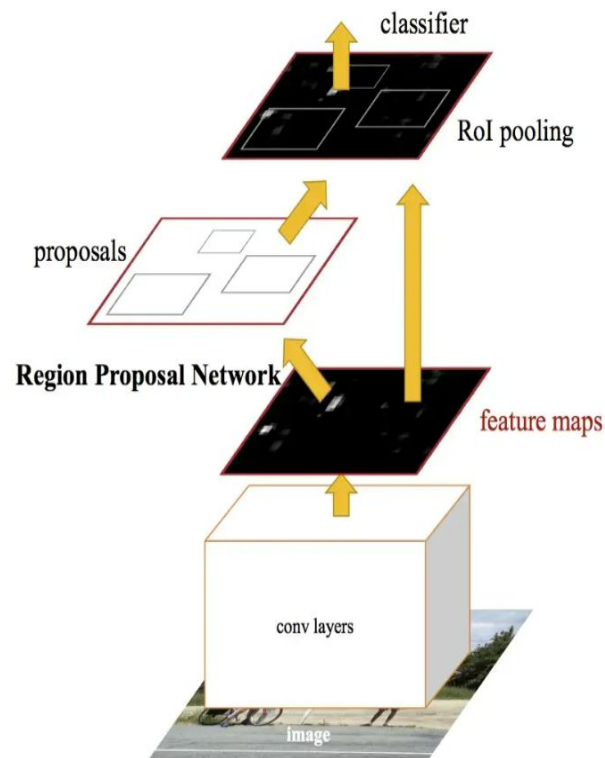
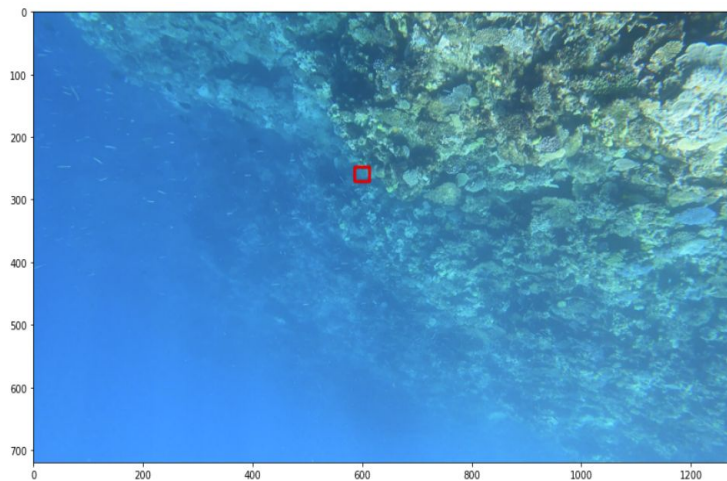
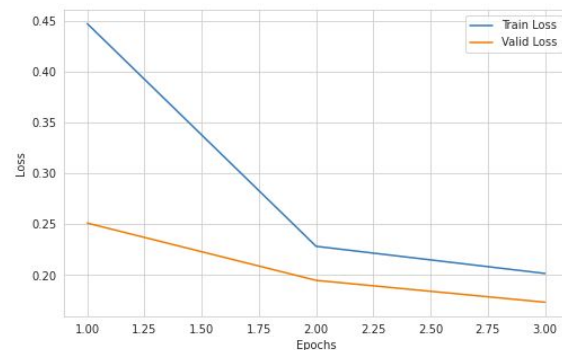


Figure 3: [Source](#)

Faster RCNN Model Results

Performed on a subset of data.



Fine Tune YOLOv5s



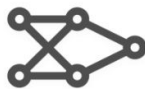
Nano
YOLOv5n

4 MB_{FP16}
6.3 ms_{V100}
28.4 mAP_{COCO}



Small
YOLOv5s

14 MB_{FP16}
6.4 ms_{V100}
37.2 mAP_{COCO}



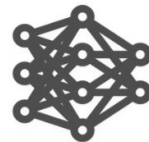
Medium
YOLOv5m

41 MB_{FP16}
8.2 ms_{V100}
45.2 mAP_{COCO}



Large
YOLOv5l

89 MB_{FP16}
10.1 ms_{V100}
48.8 mAP_{COCO}



XLarge
YOLOv5x

166 MB_{FP16}
12.1 ms_{V100}
50.7 mAP_{COCO}

YOLOv5 [7, 9, 10, 11]

- YOLOv5 launched in 2020, is one of the most advanced object identification algorithms available.
- YOLOv5 comes in four main versions: small (s), medium (m), large (l), and extra large (x), each offering progressively higher accuracy rates. Each variant also takes a different amount of time to train.
- Uses CNN that detects objects using a single neural network to process the entire picture and predicts bounding boxes and probabilities of each component.

Architecture:

- **Backbone:** used to extract key features/ useful characteristics from an input image
- **Neck:** used to create feature pyramids. Feature pyramids help models in object scaling by identifying the same object in various sizes and scales.
- **Head:** final detection where anchor boxes are used to construct final output vectors with class probabilities, object scores and bounding boxes.

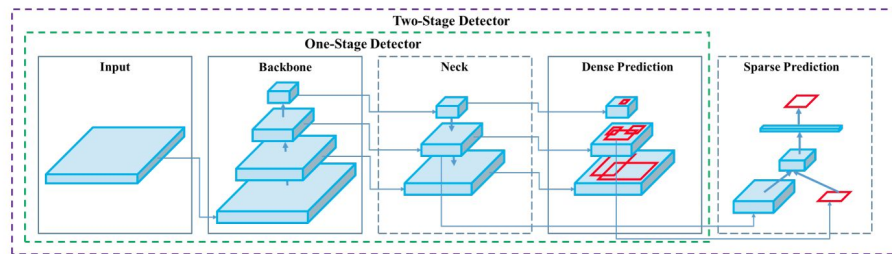


Figure 4: [Source](#)

Data Workflow

	video_id	sequence	video_frame	sequence_frame	image_id	annotations	no_of_bboxes
0	0	40258	16	16	0-16	[{'x': 559, 'y': 213, 'width': 50, 'height': 32}]	1
1	0	40258	17	17	0-17	[{'x': 558, 'y': 213, 'width': 50, 'height': 32}]	1
2	0	40258	18	18	0-18	[{'x': 557, 'y': 213, 'width': 50, 'height': 32}]	1

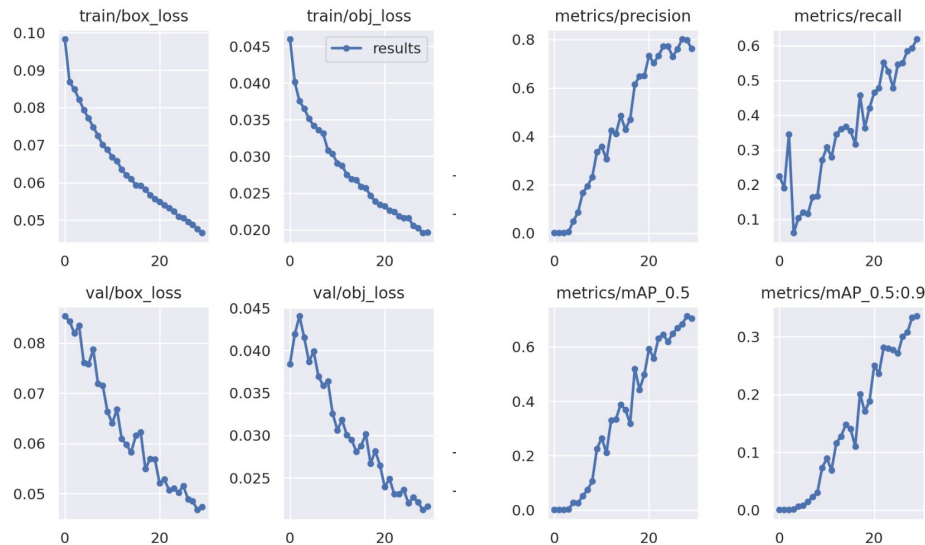


	video_id	sequence	video_frame	sequence_frame	image_id	annotations	no_of_bboxes	bbox	image_path
0	0	40258	16	16	0-16	[{'x': 559, 'y': 213, 'width': 50, 'height': 32}]	1	[[0, 0.45625, 0.7986111111111112, 0.0390625, 0...	/content/drive/shortcut-targets-by-id/1BJ54wg...
1	0	40258	17	17	0-17	[{'x': 558, 'y': 213, 'width': 50, 'height': 32}]	1	[[0, 0.45546875, 0.7972222222222223, 0.0390625...	/content/drive/shortcut-targets-by-id/1BJ54wg...
2	0	40258	18	18	0-18	[{'x': 557, 'y': 213, 'width': 50, 'height': 32}]	1	[[0, 0.4546875, 0.7958333333333333, 0.0390625,...	/content/drive/shortcut-targets-by-id/1BJ54wg...

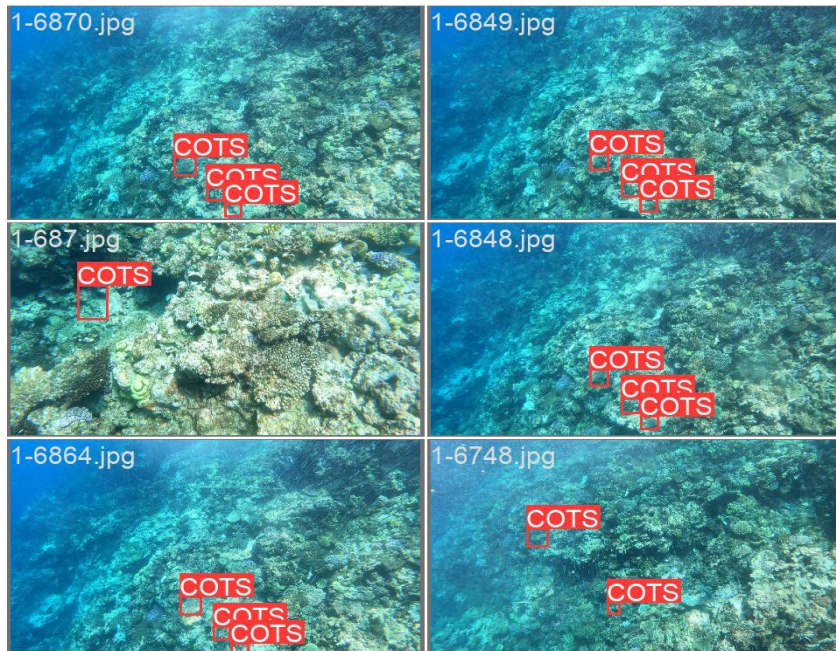
Training & Validation [6, 9]

- The dataset was trained on 30 epochs and the weights were saved as per pytorch model format (.pt).
- Trained on Google Colab GPU.

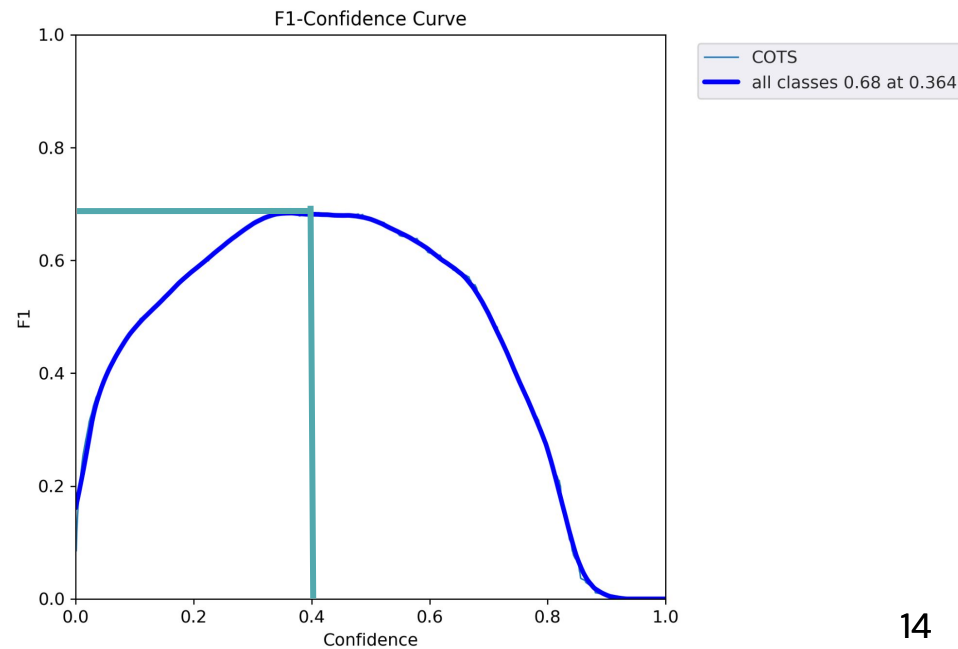
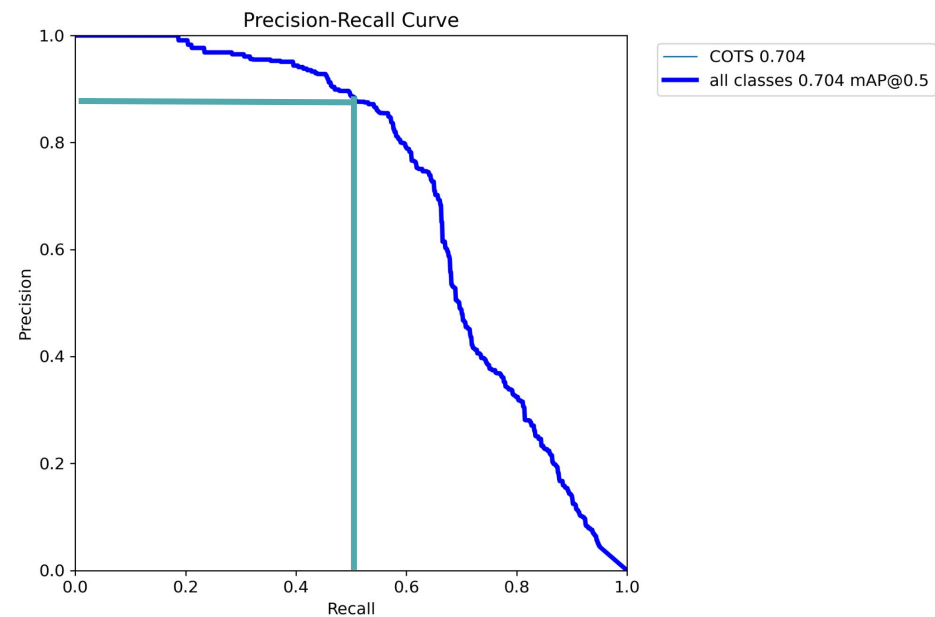
Evaluation metrics: There are various metrics used to measure the accuracy and performance of an object detection model – precision, recall, and mAP (mean average precision)



YOLOv5 Results



YOLOv5 Evaluation



Future Scope & Conclusion [9]

- YOLOv5 is much faster than Faster R-CNN model.
- YOLO is capable of processing the image only once and simultaneously detecting and classifying the images.
- The accuracy of YOLOv5 model was better than Faster R-CNN.
- We only trained YOLOv5 with 30 epochs; increasing the epochs could give better results.
- YOLOv5s has very less parameters compared to YOLOv5m, YOLOv5l, YOLOv5x and YOLOv5x6. Hence, these models can be explored too with higher computation power.
- Ensemble techniques using YOLOv5 and YOLOX (another version) can be explored.



Thank you!

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