# Introduction to Machine Learning

Mixture Models

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Latent Variable Models - Introduction

#### Mixture Models

Using Mixture Models

#### Parameter Estimation

Issues with Direct Optimization of the Likelihood or Posterior

#### **Expectation Maximization**

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EM for Mixture Models

K-Means as EM

### Latent Variable Models

- lacktriangle Consider a probability distribution parameterized by  $oldsymbol{ heta}$
- Generates samples (x) with probability  $p(x|\theta)$

#### 2-step generative process

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#### 2-step generative process

- 1. Distribution generates the hidden variable
- 2. Distribution generates the observation, given the hidden variable

# Magazine Example - Sampling an Article

- Assume that the editor has access to p(x)
- **x** a random variable that denotes an article

#### Direct Model

**Sample from**  $p(\mathbf{x})$  for an article

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#### Direct Model

► Sample from  $p(\mathbf{x})$  for an article

#### Latent Variable Model

- 1. First sample a topic z from a topic distribution p(z)
- 2. Pick an article from the topic-wise distribution  $p(\mathbf{x}|z)$

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#### Latent Variable Models - Introduction

- The observed random variable x depends on a hidden random variable z
- $\triangleright$  **z** is generated using a *prior* distribution p(z)
- $\triangleright$  x is generated using p(x|z)
- ▶ Different combinations of p(z) and p(x|z) give different latent variable models
  - 1. Mixture Models
  - 2. Factor analysis
  - 3. Probabilistic Principal Component Analysis (PCA)
  - 4. Latent Dirichlet Allocation (LDA)

### Mixture Models

A latent discrete state

$$z \in \{1,2,\ldots,K\}$$

- $ightharpoonup p(z) \sim Multinomial(\pi)$
- $\triangleright$  For every state k, we have a probability distribution for  $\mathbf{x}$

$$p(\mathbf{x}|z=k)=p_k(\mathbf{x})$$

Overall, probability for x

$$p(\mathbf{x}|\boldsymbol{\theta}) = \sum_{k=1}^{K} \pi_k p_k(\mathbf{x}|\boldsymbol{\theta})$$

- ▶ A **convex combination** of  $p_k$ 's
- $\blacktriangleright$   $\pi_k$  is the probability of  $k^{th}$  mixture component to be true
  - ightharpoonup Or, contribution of the  $k^{th}$  component
  - Or, the mixing weight

## Using Mixture Models

#### 1. Black-box Density Model

- ▶ Use  $p(\mathbf{x}|\boldsymbol{\theta})$  for many things
- Example: class conditional density

#### 2. Clustering

- ► Soft clustering
  - 1. First learn the parameters of the mixture model
    - Each mixture component corresponds to a cluster *k*
  - 2. Compute  $p(z = k | \mathbf{x}, \boldsymbol{\theta})$  for every input point  $\mathbf{x}$  (Bayes Rule)

$$p(z = k|\mathbf{x}, \boldsymbol{\theta}) = \frac{p(z = k|\boldsymbol{\theta})p(\mathbf{x}|z = k, \boldsymbol{\theta})}{\sum_{k'=1}^{K} p(z = k'|\boldsymbol{\theta})p(\mathbf{x}|z = k', \boldsymbol{\theta})}$$

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► **Given**: A set of scalar observations

$$x_1, x_2, \ldots, x_n$$

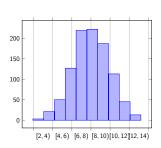
► **Task**: Find the generative model (form and parameters)

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1. Observe empirical distribution of *x* 

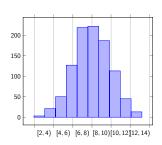


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- Observe empirical distribution of x
- Make choice of the *form* of the probability distribution (Gaussian)

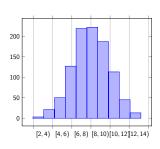


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▶ Task: Find the generative model (form and parameters)

- Observe empirical distribution of x
- Make choice of the form of the probability distribution (Gaussian)
- 3. Estimate parameters from the data using MLE or MAP ( $\mu$  and  $\sigma$ )

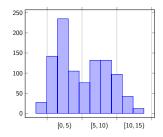


## When Data has Multiple Modes

- Single mode is not sufficient
- In reality data is generated from two Gaussians
- ▶ How to estimate  $\mu_1, \sigma_1, \mu_2, \sigma_2$ ?

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- Single mode is not sufficient
- In reality data is generated from two Gaussians
- ▶ How to estimate  $\mu_1, \sigma_1, \mu_2, \sigma_2$ ?
- ▶ What if we knew  $z_i \in \{1, 2\}$ ?
  - z<sub>i</sub> = 1 means that x<sub>i</sub> comes from first mixture component
  - z<sub>i</sub> = 2 means that x<sub>i</sub> comes from second mixture component
- ► **Issue**:  $z_i$ 's are not known beforehand
- ► Need to explore 2<sup>N</sup> possibilities



## Optimizing Likelihood or Posterior is Not Possible

- ► For direct optimization, we find parameters that maximize (log-)likelihood (or (log-)posterior)
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- ► For direct optimization, we find parameters that maximize (log-)likelihood (or (log-)posterior)
- ightharpoonup Easy to optimize if  $z_i$  were all known
- $\triangleright$  What happens when  $z_i$ 's are not known
  - Likelihood and posterior will have multiple modes
  - Non-convex function harder to optimize

## Estimating Parameters of a Mixture Model

Recall the we want to maximize the log-likelihood of a data set with respect to  $\theta$ :

$$\hat{oldsymbol{ heta}} = \mathop{\mathsf{maximize}}_{oldsymbol{ heta}} \ell(oldsymbol{ heta})$$

▶ Log-likelihood for a mixture model can be written as:

$$\ell(\theta) = \sum_{i=1}^{N} \log p(\mathbf{x}_{i}|\theta)$$
$$= \sum_{i=1}^{N} \log \left[ \sum_{k=1}^{K} p(z_{k}) p_{k}(\mathbf{x}_{i}|\theta) \right]$$

► Hard to optimize (a summation inside the log term)

### A 2 Step Approach

- ► Repeat until converged:
  - 1. Start with some guess for  $oldsymbol{ heta}$  and compute the most likely value for  $z_i, orall i$
  - 2. Given  $z_i$ ,  $\forall i$ , update  $\theta$
- ▶ Does not explicitly maximize the log-likelihood of mixture model
- Can we come up with a better algorithm?

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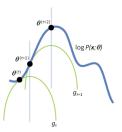
### A 2 Step Approach

- Repeat until converged:
  - 1. Start with some guess for  $oldsymbol{ heta}$  and compute the most likely value for  $z_i, \forall i$
  - 2. Given  $z_i$ ,  $\forall i$ , update  $\theta$
- Does not explicitly maximize the log-likelihood of mixture model
- Can we come up with a better algorithm?
  - ► Repeat until converged:
    - 1. Start with some guess for  $\theta$  and compute the probability of  $z_i = k, \forall i, k$
    - 2. Combine probabilities to update heta

## **Expectation Maximization Algorithm**

▶ A principled approach to maximize a function with latent variables

At iteration t, for a given value of  $\theta^{(t)}$ , let Q be a convex function that is a lower bound of  $I(\theta)$ 



Supplementary Figure 1. Convergence of the EM algorithm. Starting from initial parameters  $\theta^{(G)}$ , the E-step of the EM algorithm constructs a function  $\theta^a$  that lower-bounds the objective function  $\theta^a$  that lower-bounds the objective function  $\theta^a$   $\theta^$ 

# Steps in EM

- ► EM is an iterative procedure
- $\triangleright$  Start with some value for  $\theta$
- At every iteration t, update  $\theta$  such that the log-likelihood of the data goes up
  - ▶ Move from  $\theta^{t-1}$  to  $\theta$  such that:

$$\ell(oldsymbol{ heta}) - \ell(oldsymbol{ heta}^{t-1})$$

is maximized

#### EM - Continued

Complete log-likelihood for any LVM

$$\ell(\boldsymbol{\theta}) = \sum_{i=1}^{N} \log p(\mathbf{x}_i, \mathbf{z}_i | \boldsymbol{\theta})$$

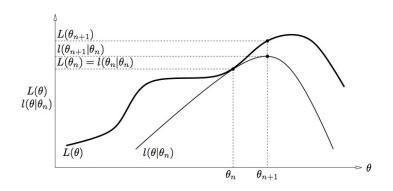
 $\triangleright$  Cannot be computed as we do not know  $\mathbf{z}_i$ 

### Expected complete log-likelihood

$$Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{t-1}) = \mathbb{E}[\ell(\boldsymbol{\theta}|D, \boldsymbol{\theta}^{t-1})]$$

 $\blacktriangleright$  Expected value of  $\ell(\theta|D,\theta^{t-1})$  for all possibilities of  $\mathbf{z}_i$ 

# EM Operation



- 1. Initialize  $\theta$
- 2. At iteration t, compute  $Q(\theta, \theta^{t-1})$
- 3. Maximize Q() with respect to  $\theta$  to get  $\theta^t$
- 4. Goto step 2

### Using EM for MM Parameter Estimation

- EM formulation is generic
- $\triangleright$  Calculating (E) and maximizing (M) Q() needs to be done for specific instances

### Q for MM

$$Q(\theta, \theta^{t-1}) = \mathbb{E}\left[\sum_{i=1}^{N} \log p(\mathbf{x}_i, z_i | \theta)\right]$$

$$= \sum_{i=1}^{N} \sum_{k=1}^{K} r_{ik} \log \pi_k + \sum_{i=1}^{N} \sum_{k=1}^{K} r_{ik} \log p(\mathbf{x}_i | \theta_k)$$

$$r_{ik} \triangleq p(z_i = k | \mathbf{x}_i, \theta^{t-1})$$

## E-Step

ightharpoonup Compute  $r_{ik}, \forall i, k$ 

$$r_{ik} = p(z_i = k|\mathbf{x}_i, \boldsymbol{\theta}^{t-1})$$

$$= \frac{\pi_k p(\mathbf{x}_i|\boldsymbol{\theta}_k^{t-1})}{\sum_{k'} \pi'_k p(\mathbf{x}_i|\boldsymbol{\theta}_k^{t't-1})}$$

ightharpoonup Compute Q()

## M-Step

- Maximize Q() w.r.t.  $\theta$
- $lackbox{} heta$  consists of  $m{\pi} = \{\pi_1, \pi_2, \dots, \pi_K\}$  and  $m{\theta} = \{m{\theta}_1, m{\theta}_2, \dots, m{\theta}_K\}$
- For Gaussian Mixture Model (GMM)  $(\theta_k \equiv (\mu_k, \Sigma_k))$ :

$$\pi_k = \frac{1}{N} \sum_i r_{ik} \tag{1}$$

$$\mu_k = \frac{\sum_i r_{ik} \mathbf{x}_i}{\sum_i r_{ik}}$$
 (2)

$$\Sigma_k = \frac{\sum_i r_{ik} \mathbf{x}_i \mathbf{x}_i^{\top}}{\sum_i r_{ik}} - \mu_k \mu_k^{\top}$$
 (3)

### Is K-Means an EM Algorithm?

- ► Similar to GMM
  - 1.  $\Sigma = \sigma^2 \mathbf{I}_D$
  - 2.  $\pi_k = \frac{1}{K}$
  - 3. The most probable cluster for  $x_i$  is computed as the prototype closest to it (hard clustering)

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### References