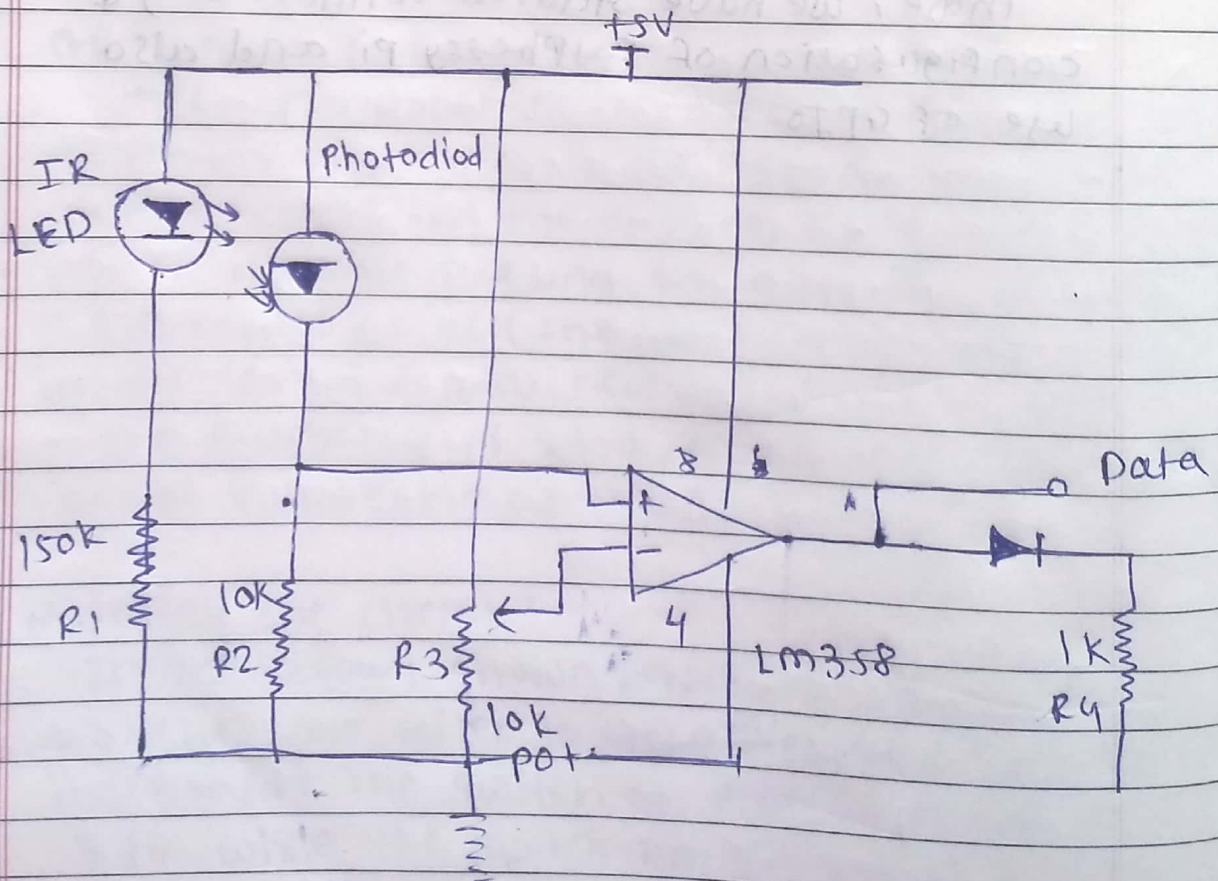


Aim : Understanding the connectivity of Raspberry Pi
Beginer board circuit with IP sensor write an application
to detect obstacle & notify user using LED's

Theory

1. **Emitter** : This component continuously emits the signal.
2. **Receiver** : It waits for the signal which is bounced back obstacle.
3. **Output** : Could be used as I/P for further processing of the signal.
4. **Ground** : - Ground / negative point of the circuit.
5. **Voltage** : I/P 3.3 V

⑤ ~~obj~~ Circuit diagram :



② circuit : to detect obstacles

Part 1 : Connecting IR sensor breadboard

- 1) IR sensor connect GPIO 18 from the Raspberry pi to A
- 2) connect out pin of sensor with the Breadboard
- 3) connect GND with -ve line on left side of breadb.
- 4) connect GND of IR sensor to Breadboard
- 5) connect GND from step 3 to Breadboard
- 6) connect VCC of the IR sensor to breadboard
- 7) connect 3V3 (pin# 1) to the line one left side of the breadboard
- 8) connect 3V3 to breadboard

Part 2 :- Connecting LED

- 1) connect GPIO 4 from the board to the breadboard
- 2) connect the point of LED to breadboard
- 3) connect -ve point of LED to breadboard

Part 3 :- Executing the code

- 1) Open terminal
- 2) navigate to directory where the above code is save
- 3) Type `$python3 obstacle.py` & press enter

Conclusion:

Thus we done Connectivity of Raspberry Pi / Beagle Board circuit with IR sensor. write an application to detect obstacle & utility. user using LEDs



IR Sensor Fig.1