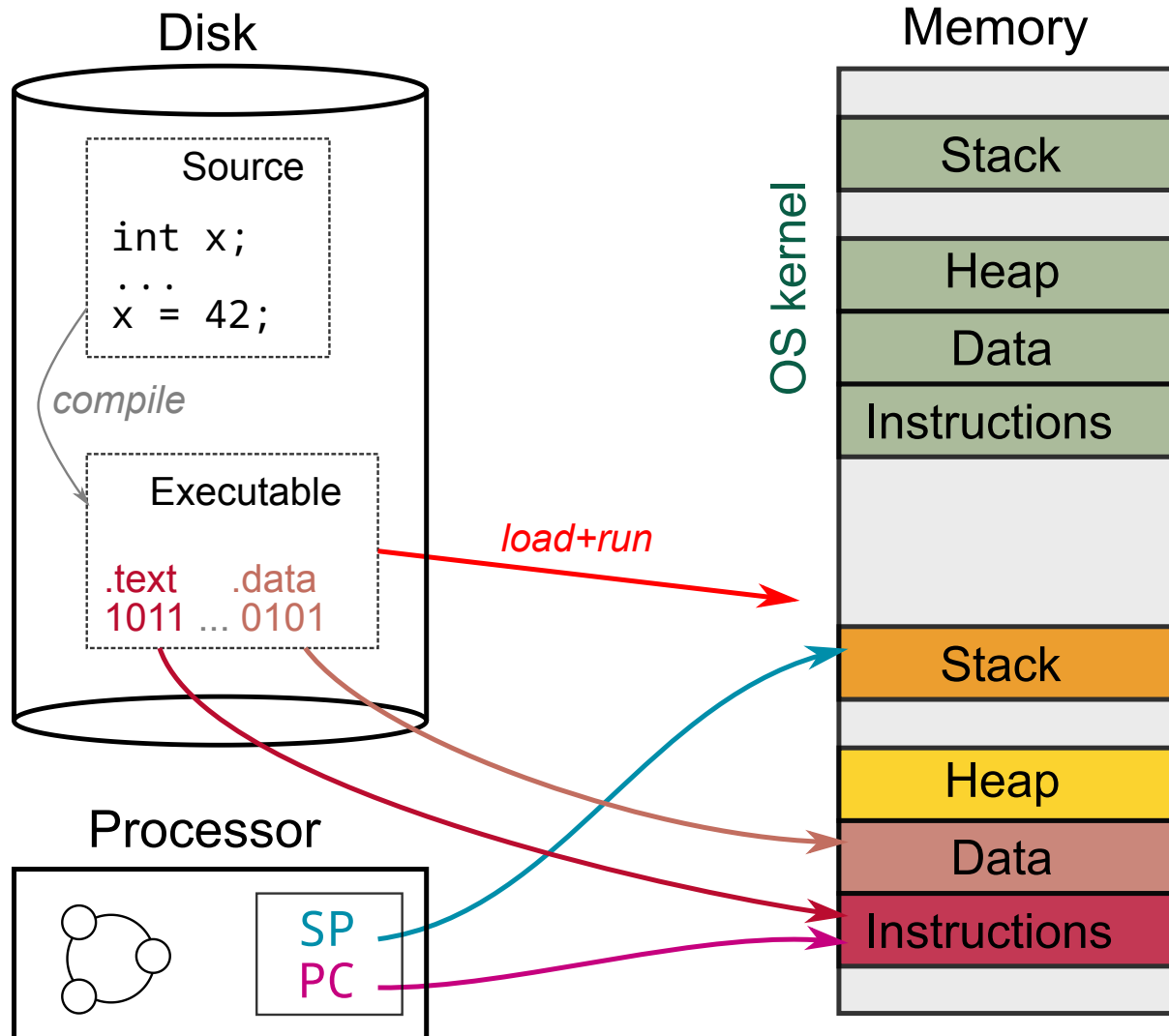


The Kernel Abstraction

Process abstraction

Process definition

A process is a program in execution



Process abstraction

Lack of protection

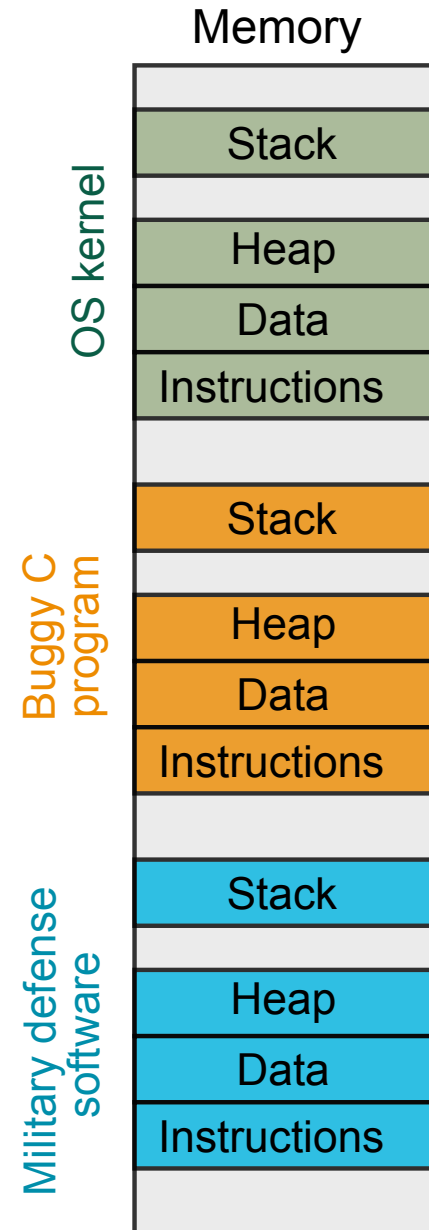
Multiple processes can be loaded in memory and run concurrently

Issues

- Buggy process
 - Crash other processes
 - Crash the OS
 - Hog all the resources
- Malicious process

Solution

- Redefine process abstraction
- Include notion of protection



Process abstraction

Process RE-definition

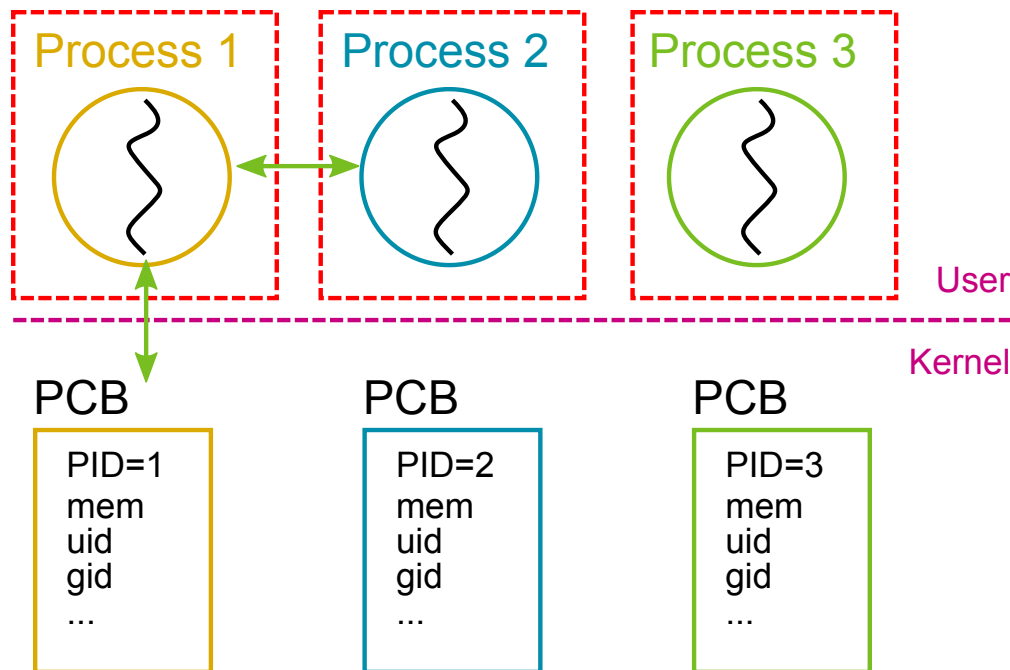
A process is a program in execution, **running with limited rights**

Protected execution

- Memory segments process can access
- Other permissions process has
 - E.g., what files it can access
 - Based on process' user ID, group ID

But efficient

- Restricting rights must not hinder functionality
- Efficient use of hardware
- Communication with OS and between processes is safe

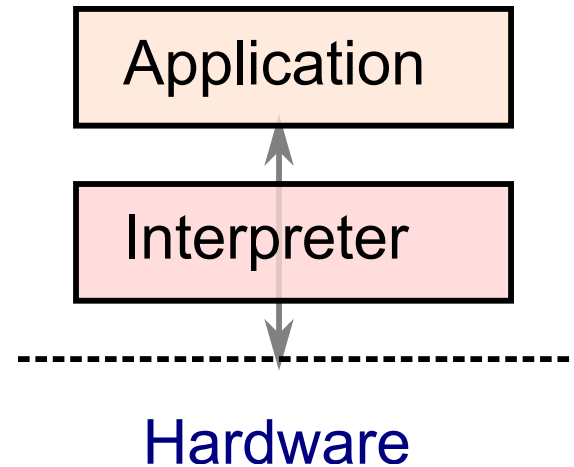


Process abstraction

Limited privilege execution

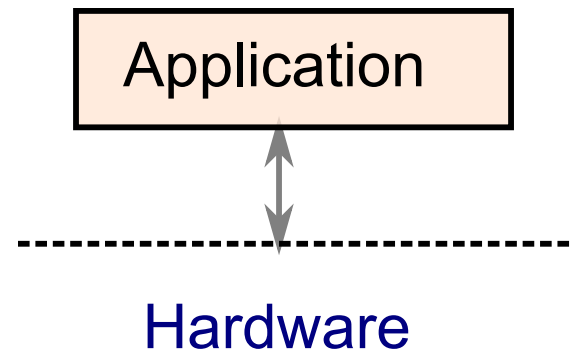
Interpreted execution

- Basic model in interpreted languages
 - Javascript, Python, etc.
- Emulate each program instruction
 - If instruction is permitted, then perform it
 - Otherwise, stop process
- But execution quite slow...



Native execution

- Run unprivileged code directly on the CPU
 - Very fast execution
- But safe execution needs specific hardware support...



Dual-mode operation

Concept

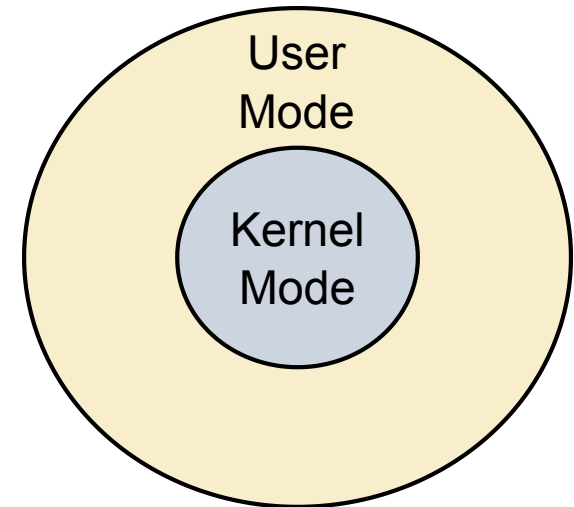
- Distinct execution modes supported directly in hardware
 - Indicated by a bit in processor status register (e.g., 0 or 1)
 - Can be more than one mode on some processor architectures

Kernel mode

- Execution with full privileges on the hardware
 - Read/write to any memory location
 - Access to any I/O device
 - Read/write to any disk sector
 - Send/receive any packet
 - Etc.

User mode

- Limited privileges on the hardware
 - As granted by the operating system



Dual-mode operation

Hardware support

Privileged instructions

- Potentially unsafe instructions prohibited when in user mode
- Only available in kernel mode

Memory protection

- Memory accesses outside of process' memory limits prohibited
- Prevent process from overwriting kernel's or other processes' memory

Timer interrupts

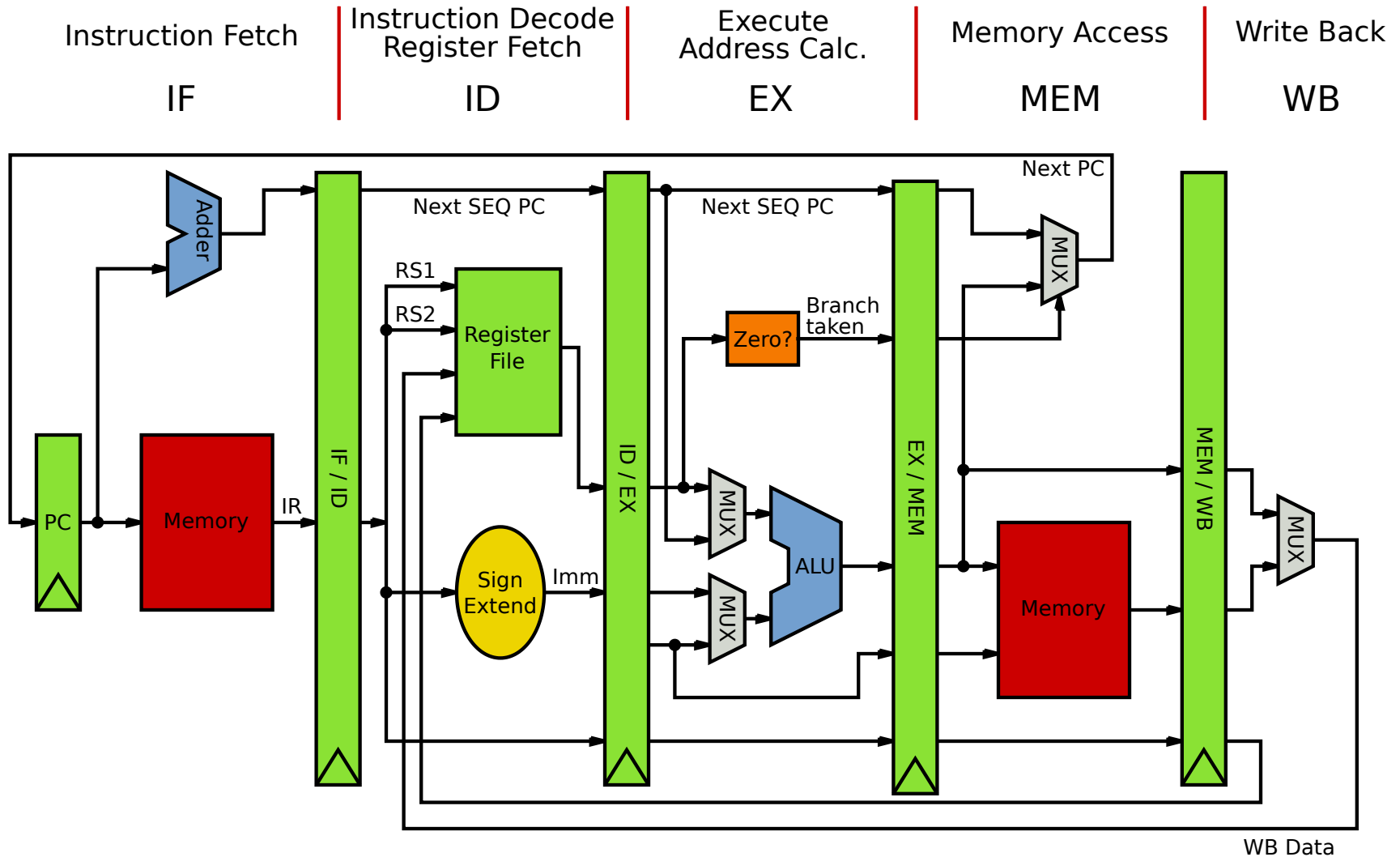
- Kernel periodically regains control on CPU
- Prevent running process from hogging hardware

Mode switch

- Safe and efficient way to switch mode
- From user mode to kernel mode, and vice-versa

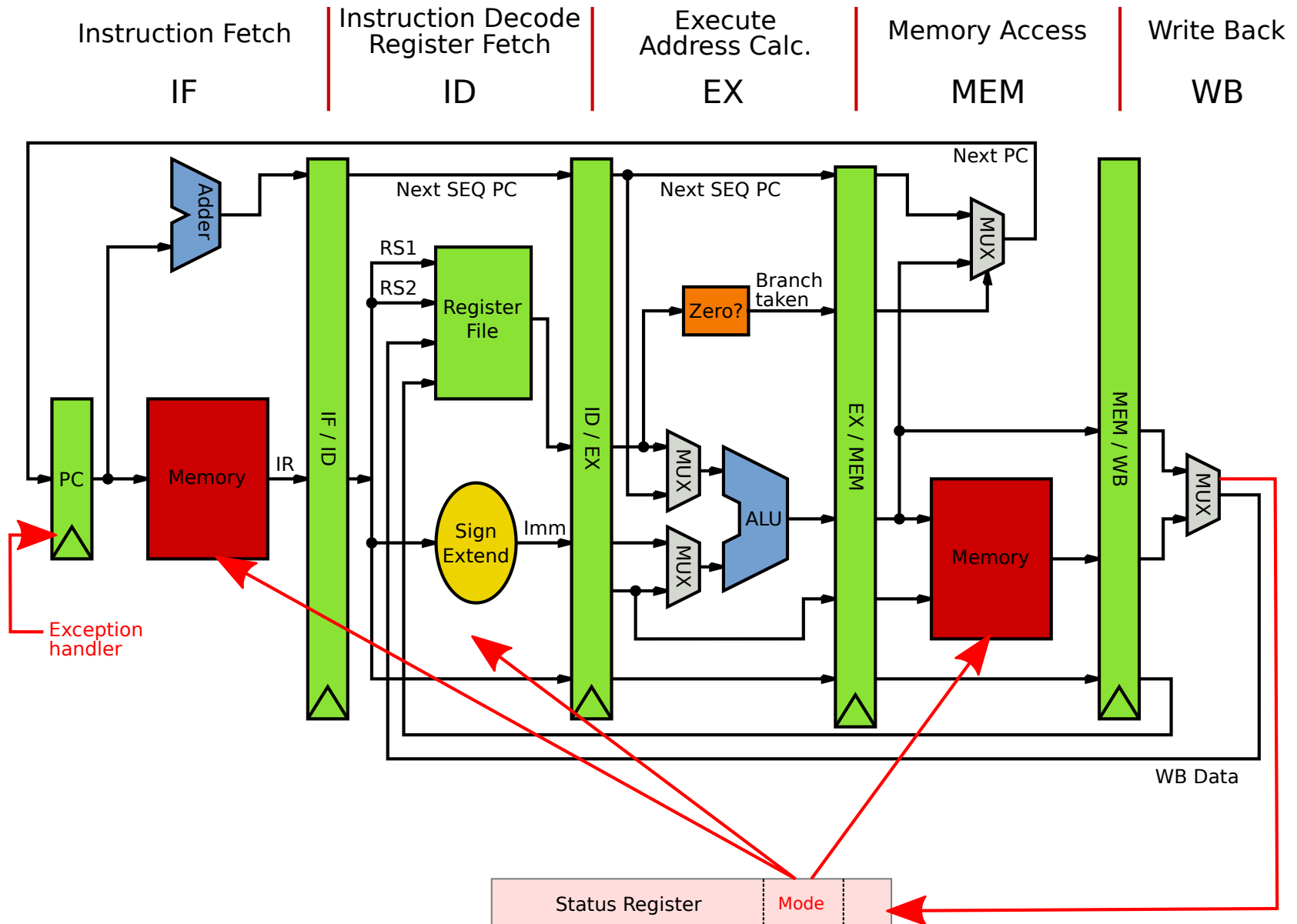
Dual-mode operation

Typical 5-stage pipeline



Dual-mode operation

"Dual-mode" 5-stage pipeline



ECS 150 - The Kernel Abstraction

Prof. Joël Porquet-Lupine

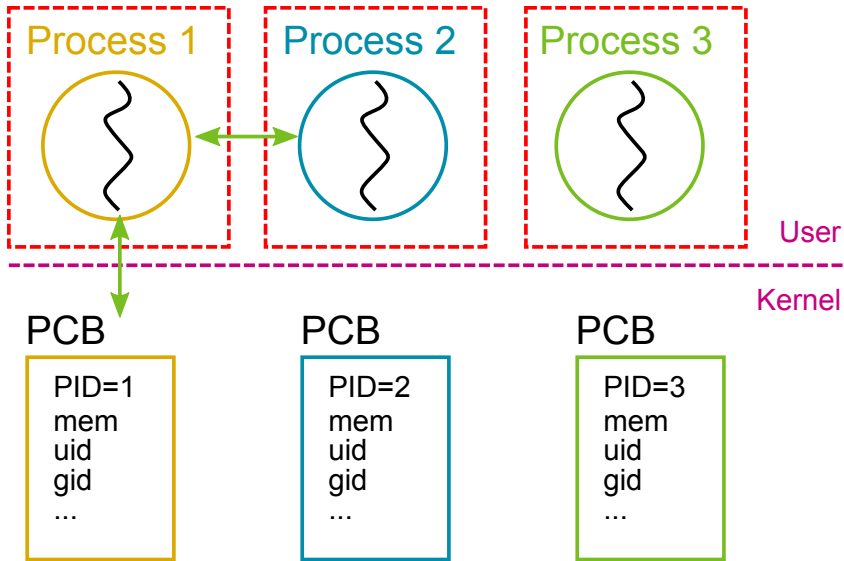
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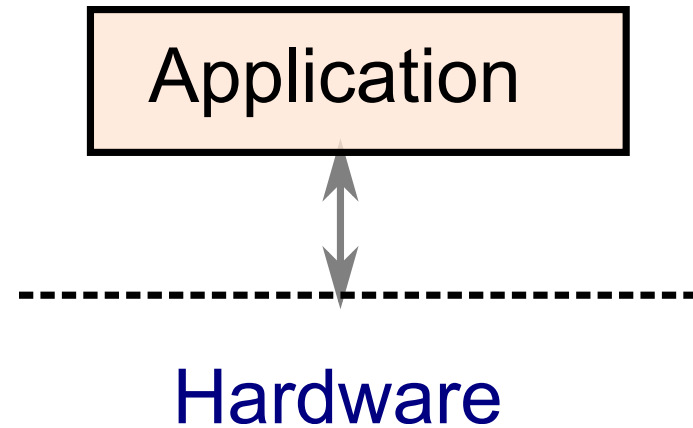
Recap

Process abstraction, v2.0

Protected execution

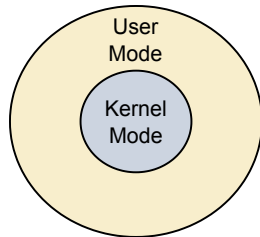


Native execution



Dual-mode operation

User mode vs kernel mode



Hardware support

- Privileged instructions
- Memory protection
- Timer interrupts
- Mode switch

Privileged instructions

Definition

- Instructions only available to code running in kernel mode
- Processor exception if user code tries to execute privileged instruction

Example

```
int main(void)
{
    printf("Hello!\n");

    /* Try deactivating
     * hardware interrupts */
    asm ("cli" ::: "memory");

    while (1)
        printf("I win?\n");

    return 0;
}
```

x86_cli.c

```
$ ./x86_cli
Hello!
Segmentation fault (core dumped)
```

Illegal instructions are reported as segmentation faults
on x86/Linux

And more...

- Toggle processor mode
- Modify memory protection
- Flush/invalidate caches/TLBs
- Halt or reset processor
- Etc.

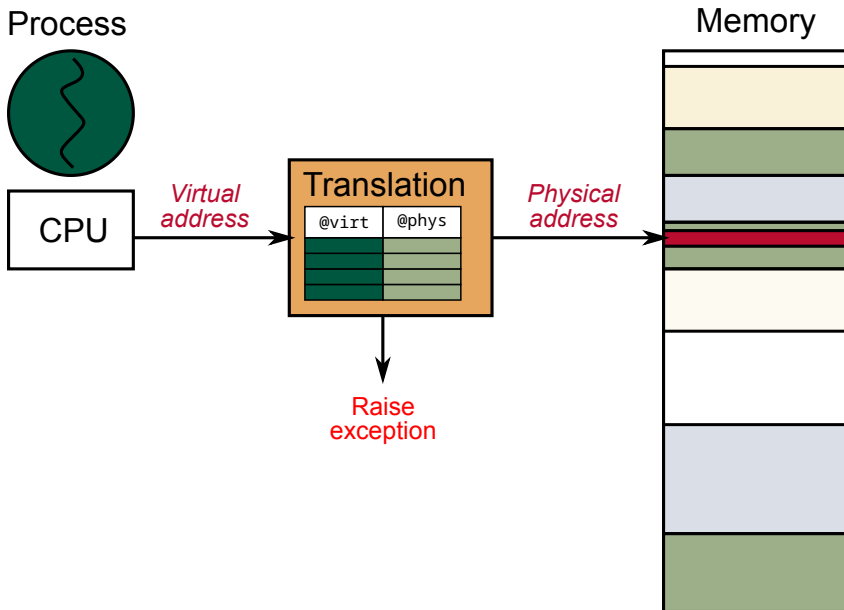
Memory protection

Concept

- Enforce memory boundaries to processes
- Processor exception if code tries to access unauthorized memory

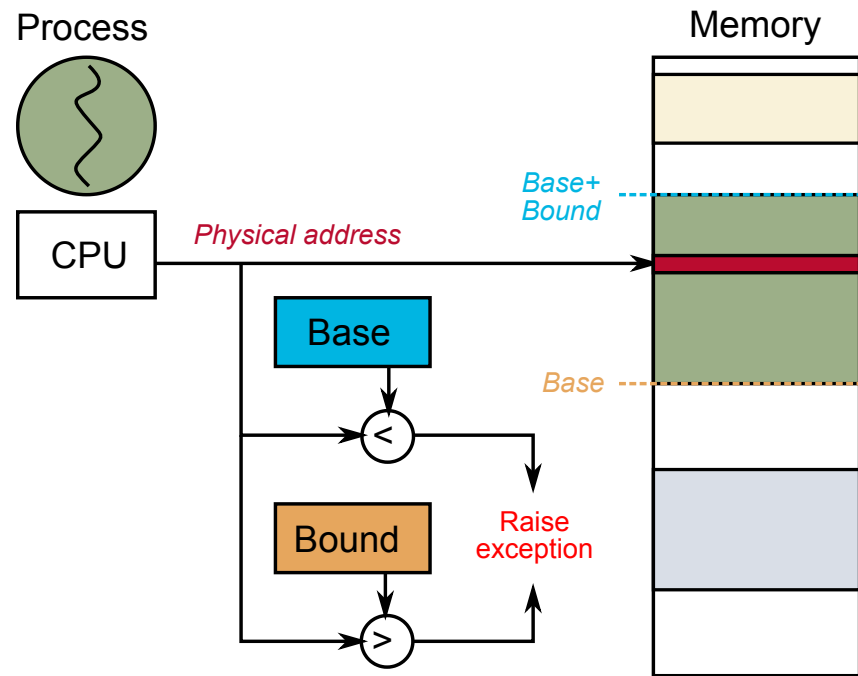
Virtual memory

- Runtime translation between virtual and physical address spaces



Basic segmentation

- Memory area defined by base and bound pair



Timer interrupts

Boot sequence

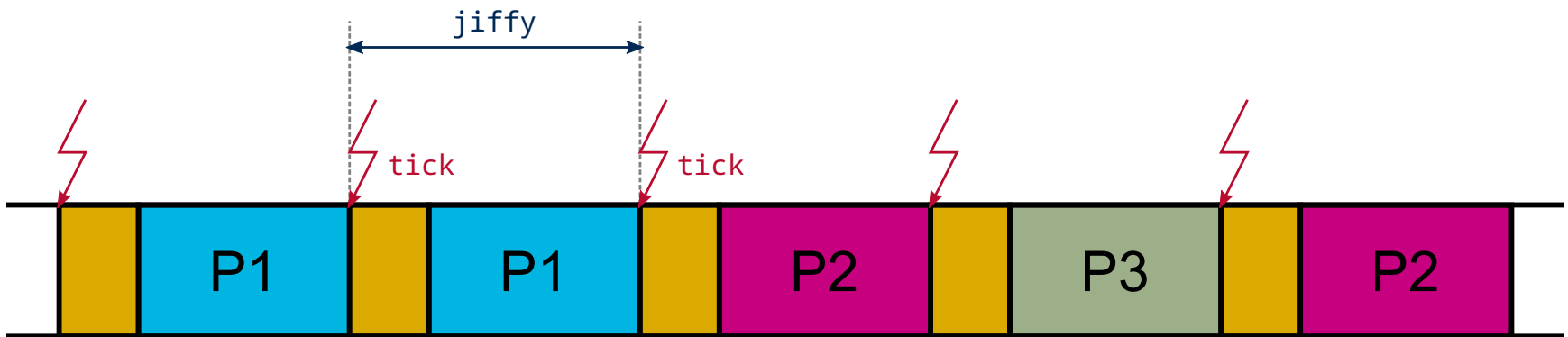
- Upon powering on the computer
 - Privilege mode set to kernel mode
 - PC set to address of boot code (e.g., BIOS)
- Boot code runs
 - Loads kernel image into memory
 - Jumps to kernel's entry point
- Kernel code runs
 - Machine setup (devices, virtual memory, interrupt vector table, etc.)
 - Chooses the first *user* process to run, loads it, and jumps to it
 - Privilege bit set to user mode
 - PC set to process' entry point
- First process runs
 - Need a way for kernel to re-take control...



Timer interrupts

Hardware timer

- Periodically interrupts the processor
 - Frequency of interruption set by the kernel
 - Returns control to the kernel exception handler
- Also used to maintain accurate and precise time of day



Mode switching

User mode to kernel mode

Exceptions

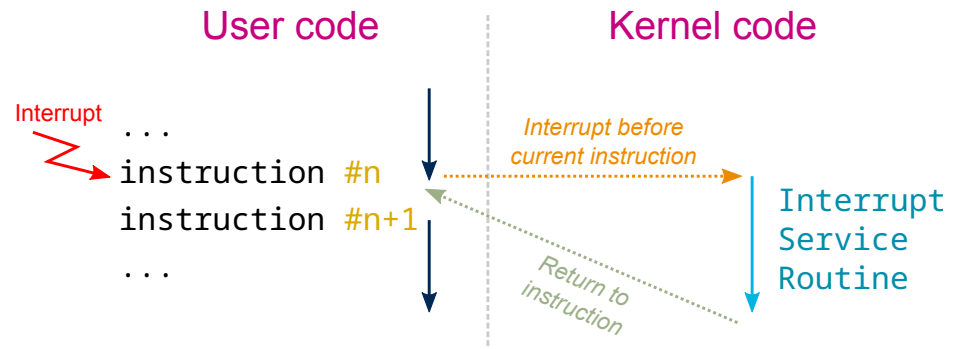
- Triggered by program behavior
- Intentional or unintentional
- Synchronous events

```
asm ("cli" ::: "memory");
```

```
int *a = NULL;  
*a = 42;
```

Interrupts

- Triggered by I/O devices
- (Better) alternative to *polling*
- Asynchronous events



System calls

- Request from process for kernel to perform operation on its behalf
- Intentional, synchronous events

```
read:  
    movq $SYS_read, rax  
    movq $fd, rdi  
    movq $buf, rsi  
    ...  
    syscall
```


Mode switching

Kernel mode to user mode

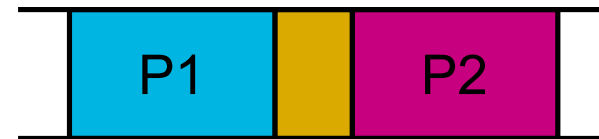
Return from interrupt or system call

- Resume suspended execution



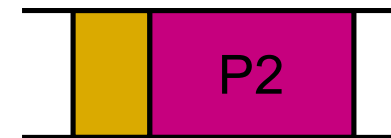
Process context switch

- Resume some other process



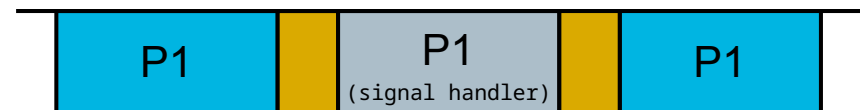
New process start

- Jump to first instruction in program



Signal

- Asynchronous notification
- If signal handler defined



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Recap

Mode switching

User to kernel

- Exceptions
 - Caused by program behavior
 - Synchronous
- Interrupts
 - Triggered by I/O devices
 - Asynchronous
- System calls
 - Service request to kernel
 - Synchronous

Kernel to user

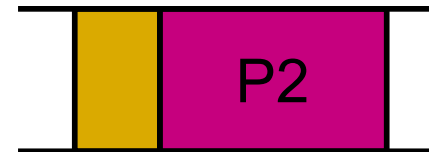
- Return from interrupt or system call



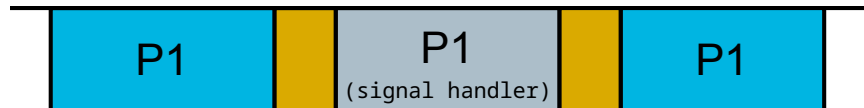
- Context switch between processes



- New process start



- Signal handler



Mode switching

Safe and efficient switching

- Protect from corrupting the kernel
 - Entry door to the kernel for processes
- Reduce overhead of kernel
 - Maximize CPU cycles for processes

Requirements

1. Atomic transfer of control
2. Exception vector
3. Transparent, restartable execution

Mode switching

Atomic transfer of control

- Safe transition between modes must be atomic
 - I.e., in one *unbreakable*, logical step
- CPU mode, PC, stack, memory protection, etc. changed at the same time

User to kernel switch

- Save cause for jump
 - Interrupt, Exception, Syscall?
- Save current PC
- Jump to kernel entry point(s)
- Switch from user to kernel mode
- Change memory protection
- Disable interrupts



Kernel to user switch

- Jump to process (restore PC)
- Switch from kernel to user mode
- Change memory protection
- Restore interrupts



Mode switching

Exception vector

- Provide limited number of entry points into the kernel
- Table set up by kernel: function pointers to exception handlers

Software-managed

- Single kernel entry point for CPU
 - Fixed or configurable address
- Software dispatch based on exception cause

```
exception_vector:  # Kernel entry point
# Retrieve cause from system register
mfc0    k1, CP0_CAUSE
# Extract exception code
andi    k1, k1, 0x7c
# Use code as index in array
lw      k0, exception_handlers(k1)
# Jump to proper handler
jr      k0
```

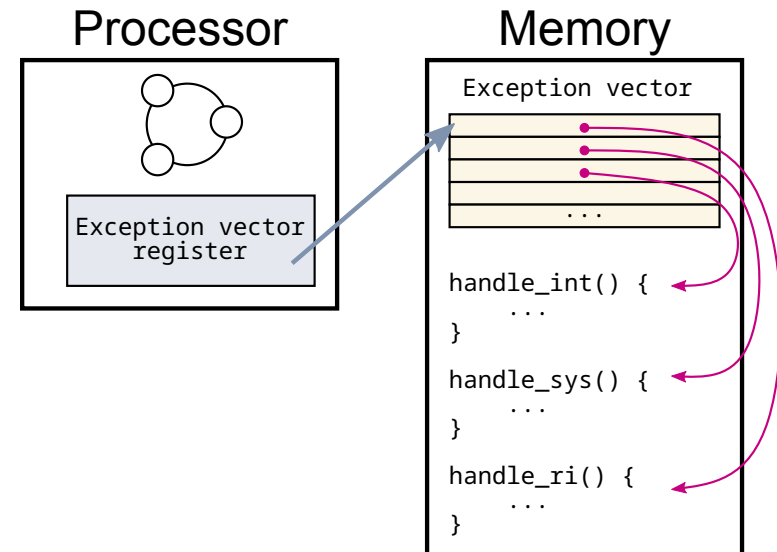
Example MIPS processor

Example MIPS processor

```
/* Exception handler init */
exception_handlers[0] = handle_int;
exception_handlers[8] = handle_sys;
exception_handlers[10] = handle_ri;
...
```

Hardware-managed

- CPU aware of vector
- Automatic hardware dispatch



Mode switching

Transparent, restartable execution

- Processes should never know when they are interrupted
- Save/restore execution context (processor registers)

Software-managed

```
handle_int:
    # Save all registers
    SW  $1, 4(sp)
    SW  $2, 8(sp)
    SW  $3, 12(sp)
    ...
    # Jump to C function
    # that processes interrupt requests
    jal do_irq

    # Restore all registers
    ...
    lw  $3, 12(sp)
    lw  $2, 8(sp)
    lw  $1, 4(sp)

    # Jump back to process
    eret
```

Example MIPS processor

Hardware-managed

- Processor saves all the registers in a provided memory region
 - Task state segment (TSS) on x86 processors
- Rarely used in practice
 - E.g., not used by Linux or Windows

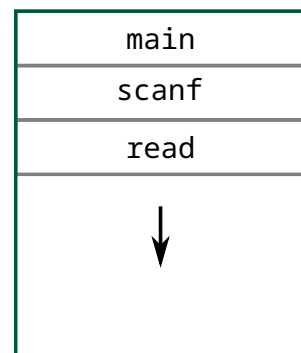
Kernel stack

Definition

- Kernel has its own stack, located in kernel memory
- Different from process' stack

User process

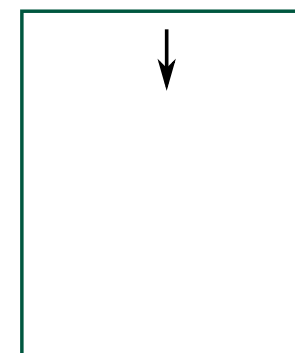
```
main() {  
    scanf();  
}  
scanf() {  
    read(0, ...);  
}  
read() {  
    asm("syscall");  
}
```



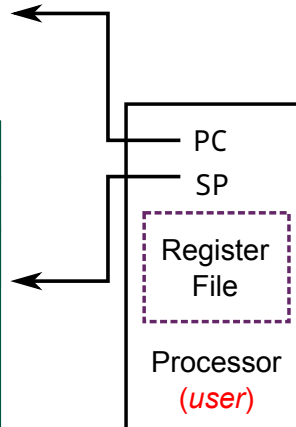
User stack

Kernel

```
handle_sys:  
    SAVE_ALL  
    jal do_sys  
    RESTORE_ALL  
do_sys() {  
    read_sys();  
}  
read_sys() {  
    ...  
}
```



Kernel stack



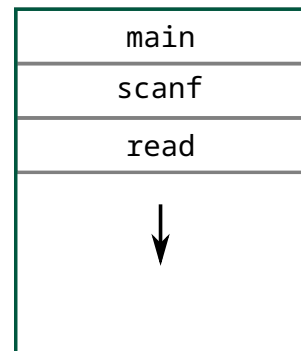
Kernel stack

Context saving

- Kernel stack is used to save associated process context

User process

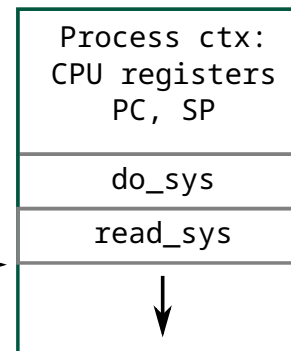
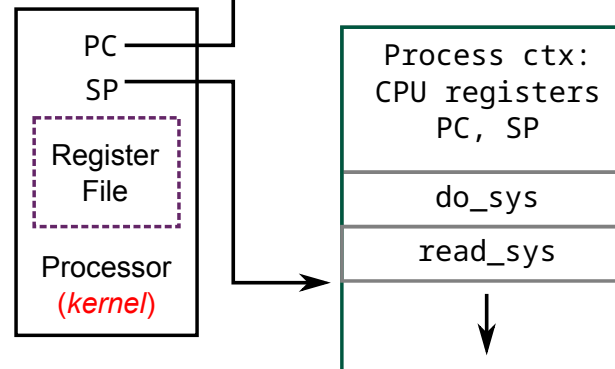
```
main() {  
    scanf();  
}  
scanf() {  
    read(0, ...);  
}  
read() {  
    asm("syscall");  
}
```



User stack

Kernel

```
handle_sys:  
    SAVE_ALL  
    jal do_sys  
    RESTORE_ALL  
do_sys() {  
    read_sys();  
}  
read_sys() {  
    ...  
}
```



Kernel stack

- Not a good idea to reuse process's stack pointer
 - Reliability: no guarantee user stack is valid
 - Security: kernel data shouldn't leak to user space

Kernel stack

One kernel stack per process

- Kernel saves its own state when switching between two processes

