

() AND function:

$$X = \begin{bmatrix} 1 \\ x_1 \end{bmatrix} W = \begin{bmatrix} -1.5 \\ 1 \end{bmatrix} \Rightarrow X = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$
By Considering all feature vectors:

(1.X1+1×2-1.5=

$$X^{T} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} & W = \begin{bmatrix} -1.5 \\ 1 \\ 1 \\ 1 \end{bmatrix} & 3 \times 1$$

$$(X^{T}W) = \begin{bmatrix} -1.5 \\ -0.5 \\ -0.5 \\ 0.5 \end{bmatrix}_{AXI} \underbrace{OR}_{W}X = \begin{bmatrix} -1.5 - 0.5 - 0.5 & 0.5 \end{bmatrix}_{IX4}$$

$$Y(x^Tw) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
 Non-linear  $f^n$ :

Thereshold  $f^n Y(x) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ;  $x \ge 0$ 

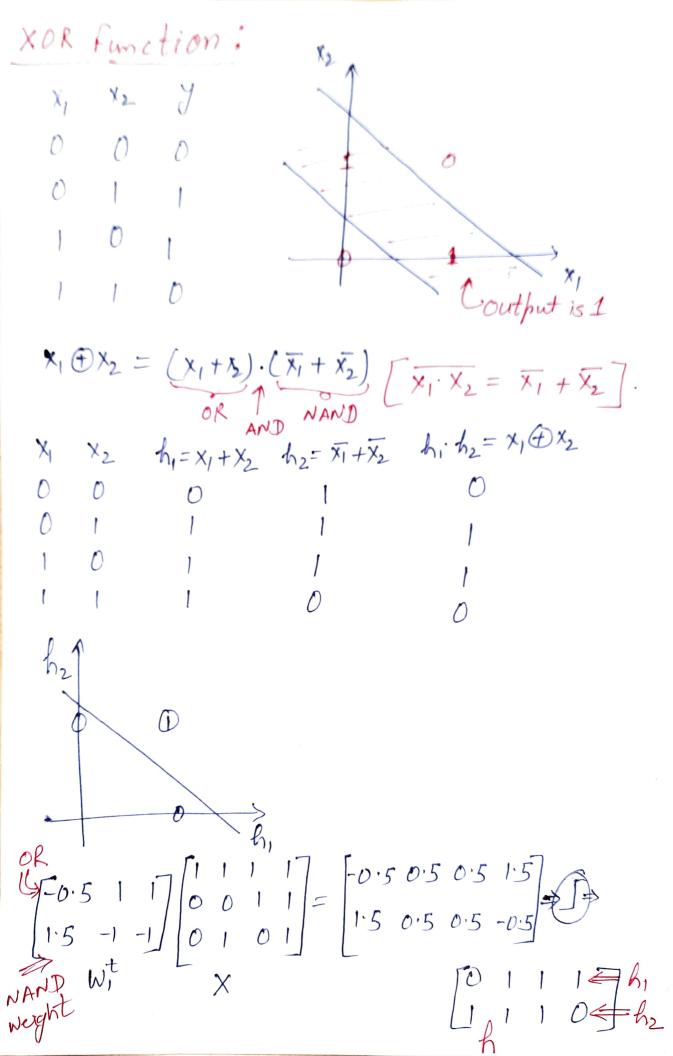
$$y = f(w^{t}x) - f(\frac{2}{1-0}w^{t}x)$$

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$$x^{T}w = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} -0.5 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -0.5 \\ 0.5 \\ 0.5 \\ 1.5 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

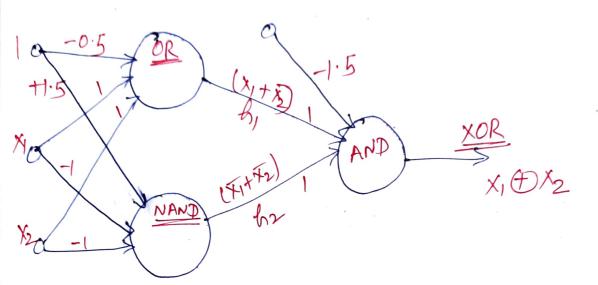
$$x_{1} \xrightarrow{-0.5} 0R$$

$$x_{1} \xrightarrow{1} w^{t_{x}} \xrightarrow{1} 0R$$



$$f_{1}W_{2} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} -1.57 \\ 0.5 \\ 0.5 \end{bmatrix} \Rightarrow \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\times_{1} \notin X_{2}$$



Cost Function (xli) x (fuit (xli)) = training instance with stance label (xli)  $\frac{1}{x^{(i)}}$   $\frac{1}{x}$  m = # training instances $\hat{\mathcal{G}}^{(i)} = f_{w,b}(x^{(i)})$  $f_{w,b}(x^{(i)}) = wx^{(i)} + b$ Cost function: Mean Squared  $J(w,b) = \frac{1}{2m} \left( \hat{y}(i) - y^{(i)} \right)^2$ Objective: Find w.b wich that  $\hat{\mathcal{J}}^{(i)}$  is close to  $\mathcal{J}^{(i)}$  of  $(\boldsymbol{x}^{(i)}, \mathcal{J}^{(i)})$ . Model: fw,b(x) = wx+b Parameters: w.b Cost function:  $J(w,b) = \frac{1}{2m} \underbrace{\int_{w,b}^{w} (f_{w,b}^{(i)}) - y^{(i)}}_{2m}$ minimize J(W.b) Goal:

Gradient descent algorithm:  $w = w - \propto \frac{\partial}{\partial w} J(w, b)$  $\frac{\partial}{\partial w} J(w,b) = derivative of cost f'' w.r.tow.$  $b = b - \alpha \frac{\partial}{\partial b} J(w,b)$ 

NOTE: Update W & b <u>simultaneously</u> based on old W & b value.

Correct Simultaneous update:  $temp_-w = w - \frac{\partial J(w,b)}{\partial w}$ 

 $temp_b = b - \sqrt{\frac{2}{2h}} \mathcal{J}(W_i b)$ 

W = temp - Wb = temp-b

Incorrect way: temp-W=W-ZDJ(W.b) w = temp - w

temp-b= b- < 3 7(w.b) b = temp-b.