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Common

Setup

```
1. F9 \rightarrow Commands \rightarrow File Associations \rightarrow Ins \rightarrow
   1st line: *.cpp, 3rd line: g++ -O2 -Wall -Wshadow -Wextra -Wno-unused-result
   -Wconversion -std=gnu++17 -g -DLOCAL !.! -o !.exe
```

2. $F9 \rightarrow Options \rightarrow Editor settins$

Auto indent, Tab size, Cursor beyond end of line, Show white space (disable).

Template

try {

```
#include <bits/stdc++.h>
using namespace std;
#define pb push_back
#define mp make_pair
#define fst first
#define snd second
#define sz(x) (int) ((x).size())
#define form(i, n) for (int i = 0; i < (n); ++i)
#define form: (i, n) for (int i = (n) - 1; i \ge 0; --i)
#define forab(i, a, b) for (int i = (a); i < (b); ++i)
\#define \ all(c) \ (c).begin(), \ (c).end()
using ll = long long;
using vi = vector<int>;
using pii = pair<int, int>;
#define FNAME ""
int main() {
#ifdef LOCAL
  freopen(FNAME".in", "r", stdin);
  freopen(FNAME".out", "w", stdout);
#endif
  cin.tie(0);
  ios_base::sync_with_stdio(0);
 return 0:
    Stress
@echo off
for /L %%i in (1,1,10000000) do (
gen.exe || exit
main.exe || exit
stupid.exe || exit
fc .out 2.out || exit
echo Test %%i OK
    Java
import java.io.BufferedReader;
import java.io.FileNotFoundException;
import java.io.FileReader;
import java.io.IOException;
import java.io.InputStreamReader;
import java.io.PrintWriter;
import java.util.*;
public class Main {
  FastScanner in:
 PrintWriter out;
  void solve() {
   int a = in.nextInt();
    int b = in.nextInt();
   out.print(a + b);
  void run() {
```

```
in = new FastScanner("input.txt");
   out = new PrintWriter("output.txt");
    solve();
    out.flush();
   out.close():
 } catch (FileNotFoundException e) {
    e.printStackTrace();
    System.exit(1);
 }
class FastScanner {
 BufferedReader br;
 StringTokenizer st;
 public FastScanner() {
   br = new BufferedReader(new InputStreamReader(System.in));
 public FastScanner(String s) {
     br = new BufferedReader(new FileReader(s));
   } catch (FileNotFoundException e) {
      e.printStackTrace();
   }
 String nextToken() {
    while (st == null || !st.hasMoreElements()) {
        st = new StringTokenizer(br.readLine());
     } catch (IOException e) {
        e.printStackTrace();
     }
   }
   return st.nextToken();
 }
 int nextInt() {
   return Integer.parseInt(nextToken());
 long nextLong() {
   return Long.parseLong(nextToken());
 double nextDouble() {
   return Double.parseDouble(nextToken());
 char nextChar() {
   try {
     return (char) (br.read());
   } catch (IOException e) {
      e.printStackTrace();
   }
   return 0;
 7
 String nextLine() {
   try {
     return br.readLine();
   } catch (IOException e) {
      e.printStackTrace();
   }
   return "";
 }
public static void main(String[] args) {
  new Main().run();
```

}

2 Big numbers

5 Big Int

```
constexpr int BASE = 1000000000;
constexpr int BASE_DIGITS = 9;
struct BigInt {
 // value == 0 is represented by empty z
 vi z; // digits
  // sign == 1/-1 <==> value >=/< 0
 int sign;
   BigInt(): sign(1) {}
 BigInt(ll v) { *this = v: }
   {\tt BigInt\&\ operator=(11\ v)\ \{}
    sign = v < 0 ? -1 : 1; v *= sign;
    z.clear(); for (; v > 0; v = v / BASE) z.pb((int) (v \%
→ BASE)):
   return *this;
 }
   BigInt& operator+=(const BigInt& other) {
    if (sign == other.sign) {
     for (int i = 0, carry = 0; i < sz(other.z) || carry; ++i) {</pre>
       if (i == sz(z)) z.pb(0);
       z[i] += carry + (i < sz(other.z) ? other.z[i] : 0);
        carry = z[i] >= BASE;
       if (carry) z[i] -= BASE;
   } else if (other != 0 /* prevent infinite loop */) {
      *this -= -other;
    }
   return *this;
   friend BigInt operator+(BigInt a, const BigInt& b) { return a
   BigInt& operator-=(const BigInt& other) {
    if (sign == other.sign) {
     if ((sign == 1 && *this >= other) || (sign == -1 && *this
  <= other)) {
       for (int i = 0, carry = 0; i < sz(other.z) || carry; ++i)</pre>
          z[i] = carry + (i < sz(other.z) ? other.z[i] : 0);
          carry = z[i] < 0;
          if (carry)
           z[i] += BASE;
       }
       trim():
      } else {
        *this = other - *this:
        this->sign = -this->sign;
     }
   } else
      *this += -other;
   return *this;
   friend BigInt operator-(BigInt a, const BigInt% b) { return a
   BigInt& operator*=(int v) {
    if (v < 0) sign = -sign, v = -v;
    for (int i = 0, carry = 0; i < sz(z) || carry; ++i) {
      if (i == sz(z))
       z.pb(0);
      11 cur = (11) z[i] * v + carry;
      carry = (int) (cur / BASE);
     z[i] = (int) (cur \% BASE);
    }
   trim();
   BigInt operator*(int v) const { return BigInt(*this) *= v; }
    friend pair < BigInt, BigInt > divmod(const BigInt & a1, const

→ BigInt& b1) {
    int norm = BASE / (b1.z.back() + 1);
   BigInt a = a1.abs() * norm;
    BigInt b = b1.abs() * norm;
   BigInt q, r;
    q.z.resize(sz(a.z));
    fornr (i, sz(a.z)) {
     r *= BASE, r += a.z[i];
      int s1 = sz(b.z) < sz(r.z) ? r.z[sz(b.z)] : 0;
```

```
int s2 = sz(b.z) - 1 < sz(r.z) ? r.z[sz(b.z) - 1] : 0;
      int d = (int) (((11) s1 * BASE + s2) / b.z.back());
     r -= b * d;
     while (r < 0) r += b, --d;
     q.z[i] = d;
   q.sign = a1.sign * b1.sign, r.sign = a1.sign;
   q.trim(), r.trim();
   return {q, r / norm};
   BigInt operator/(const BigInt& v) const { return divmod(*this,

→ v).fst; }
   BigInt operator%(const BigInt& v) const { return divmod(*this,

    v).snd: }

   BigInt& operator/=(int v) {
   if (v < 0) sign = -sign, v = -v;
    int rem = 0;
   formr (i, sz(z)) {
     11 \text{ cur} = z[i] + \text{rem} * (11) BASE;
     z[i] = (int) (cur / v);
     rem = (int) (cur % v);
   trim();
   return *this;
 }
   BigInt operator/(int v) const { return BigInt(*this) /= v; }
   int operator%(int v) const {
   if (v < 0) v = -v;
   int m = 0;
   formr (i, sz(z))
     m = (int) ((z[i] + m * (11) BASE) % v);
   return m * sign;
   BigInt\& operator*=(const BigInt\& v) { return *this = *this *}
   v; }
 BigInt& operator/=(const BigInt& v) { return *this = *this / v;
→ }
   bool operator<(const BigInt& v) const {</pre>
   if (sign != v.sign) return sign < v.sign;</pre>
    if (sz(z) != sz(v.z)) return sz(z) * sign < sz(v.z) * v.sign;
   formr (i, sz(z))
      if (z[i] != v.z[i])
       return z[i] * sign < v.z[i] * sign;</pre>
   return false;
   bool operator>(const BigInt& v) const { return v < *this; }</pre>
 bool operator<=(const BigInt& v) const { return !(v < *this); }</pre>
 bool operator>=(const BigInt& v) const { return !(*this < v); }</pre>
   bool operator==(const BigInt& v) const { return !(*this < v)</pre>
bool operator!=(const BigInt& v) const { return *this < v || v</pre>
void trim() {
   while (!z.empty() \&\& z.back() == 0) z.pop_back();
    if (z.empty()) sign = 1;
 bool isZero() const { return z.empty(); }
 friend BigInt operator-(BigInt v) {
   if (!v.z.empty()) v.sign = -v.sign;
   return v;
 BigInt abs() const {
   return sign == 1 ? *this : -*this;
 void read(const string& s) {
   sign = 1, z.clear();
   int pos = 0;
   while (pos < sz(s) && (s[pos] == '-' || s[pos] == '+')) {
      if (s[pos] == '-') sign = -sign;
     ++pos;
   }
   for (int i = sz(s) - 1; i >= pos; i -= BASE_DIGITS) {
     int x = 0;
     forab (j, max(pos, i - BASE_DIGITS + 1), i)
       x = x * 10 + s[j] - '0';
     z.pb(x);
   }
   trim();
 friend ostream &operator << (ostream & stream, const BigInt & v) {
```

```
if (v.sign == -1)
      stream << '-';
    stream << (v.z.empty() ? 0 : v.z.back());
    fornr (i, sz(v.z) - 1)
      stream << setw(BASE_DIGITS) << setfill('0') << v.z[i];</pre>
    return stream;
  }
  static vi convertBase(const vi& a, int oldDigits, int
\hookrightarrow newDigits) {
    vector<ll> p(max(oldDigits, newDigits) + 1);
    p[0] = 1;
    for (int i = 1; i < sz(p); i++)
     p[i] = p[i - 1] * 10;
    vi res;
    11 cur = 0;
    int curDigits = 0;
    for (int v : a) {
     cur += v * p[curDigits];
      curDigits += oldDigits;
      while (curDigits >= newDigits) {
       res.pb(int(cur % p[newDigits]));
        cur /= p[newDigits];
        curDigits -= newDigits;
      }
    }
    res.pb((int) cur);
    while (!res.empty() && res.back() == 0) res.pop_back();
    return res;
  7
  static vll karatsubaMultiply(const vll& a, const vll& b) {
    int n = sz(a);
    vll res(n + n):
    if (n <= 32) \{
      for (int i = 0; i < n; i++)
        for (int j = 0; j < n; j++)
         res[i + j] += a[i] * b[j];
      return res;
    int k = n >> 1;
    vll a1(a.begin(), a.begin() + k), a2(a.begin() + k, a.end());
    vll b1(b.begin(), b.begin() + k), b2(b.begin() + k, b.end());
    vll a1b1 = karatsubaMultiply(a1, b1);
    vll a2b2 = karatsubaMultiply(a2, b2);
    forn (i, k) a2[i] += a1[i];
    forn (i, k) b2[i] += b1[i];
    vll r = karatsubaMultiply(a2, b2);
    forn (i, sz(a1b1)) r[i] -= a1b1[i];
    forn (i, sz(a2b2)) r[i] -= a2b2[i];
    form (i, sz(r)) res[i + k] += r[i];
    forn (i, sz(a1b1)) res[i] += a1b1[i];
    forn (i, sz(a2b2)) res[i + n] += a2b2[i];
    return res;
  BigInt operator*(const BigInt& v) const {
    vi a6 = convertBase(this->z, BASE_DIGITS, 6);
    vi b6 = convertBase(v.z, BASE_DIGITS, 6);
    vll a(all(a6)), b(all(b6));
    while (sz(a) < sz(b)) a.pb(0);
    while (sz(b) < sz(a)) b.pb(0);
    while (sz(a) & (sz(a) - 1)) a.pb(0), b.pb(0);
    vll c = karatsubaMultiply(a, b);
    BigInt res;
    res.sign = sign * v.sign;
    int carry = 0;
    forn (i, sz(c)) {
     ll cur = c[i] + carry;
      res.z.push_back((int) (cur % 1000000));
      carry = (int) (cur / 1000000);
    res.z = convertBase(res.z, 6, BASE_DIGITS);
    res.trim();
    return res:
};
```

6 FFT

```
int rev[N];
//using Num = complex<dbl>;
struct Num {
  dbl x, y;
  Num() {}
  Num(dbl _x, dbl _y): x(_x), y(_y) {}
  inline dbl real() const { return x; }
  inline dbl imag() const { return y; }
 inline Num operator+(const Num &B) const { return Num(x + B.x, y
\rightarrow + B.y); }
 inline Num operator-(const Num &B) const { return Num(x - B.x, y
→ - B.y); }
 inline Num operator*(dbl k) const { return Num(x * k, y * k); }
 inline Num operator*(const Num &B) const { return Num(x * B.x -
\hookrightarrow y * B.y, x * B.y + y * B.x); }
 inline void operator+=(const Num &B) { x += B.x, y += B.y; }
 inline void operator/=(dbl k) { x /= k, y /= k; }
 inline void operator*=(const Num &B) { *this = *this * B; }
};
Num rt[N];
inline Num sqr(const Num &x) { return x * x; }
inline Num conj(const Num &x) { return Num(x.real(), -x.imag());
inline int getN(int n) {
 int k = 1;
  while(k < n)
   k <<= 1;
  return k:
}
void fft(Num *a, int n) {
  assert(rev[1]); // don't forget to init
  int q = N / n;
  forn (i, n)
    if(i < rev[i] / q)
     swap(a[i], a[rev[i] / q]);
  for (int k = 1; k < n; k <<= 1)
    for (int i = 0; i < n; i += 2 * k)
     forn (j, k) {
        const Num z = a[i + j + k] * rt[j + k];
        a[i + j + k] = a[i + j] - z;
        a[i + j] += z;
void fftInv(Num *a, int n) {
 fft(a, n);
  reverse(a + 1, a + n);
  forn (i, n)
    a[i] /= n;
void doubleFft(Num *a, Num *fa, Num *fb, int n) { // only if you
\hookrightarrow need it
 fft(a, n);
  const int n1 = n - 1;
 forn (i, n) {
    const Num &z0 = a[i], &z1 = a[(n - i) & n1];
    fa[i] = Num(z0.real() + z1.real(), z0.imag() - z1.imag()) *
   fb[i] = Num(z0.imag() + z1.imag(), z1.real() - z0.real()) *
 }
}
Num tmp[N];
template<class T>
void mult(T *a, T *b, T *r, int n) { // n = 2 \text{ k}
  forn (i, n)
    tmp[i] = Num((dbl) a[i], (dbl) b[i]);
  fft(tmp, n);
  const int n1 = n - 1;
  const Num c = Num(0, -0.25 / n);
  fornr (i, n / 2 + 1) {
```

```
const int j = (n - i) \& n1;
    const Num z0 = sqr(tmp[i]), z1 = sqr(tmp[j]);
   tmp[i] = (z1 - conj(z0)) * c;
    tmp[j] = (z0 - conj(z1)) * c;
 fft(tmp, n);
 forn (i, n)
   r[i] = (T) round(tmp[i].real());
void init() { // don't forget to init
 forn(i, N)
    rev[i] = (rev[i >> 1] >> 1) + ((i & 1) << (LOG - 1));
 rt[1] = Num(1, 0);
 for (int k = 1, p = 2; k < LOG; k++, p *= 2) {
   const Num x(cos(PI / p), sin(PI / p));
    forab (i, p / 2, p)
     rt[2 * i] = rt[i], rt[2 * i + 1] = rt[i] * x;
 }
```

7 FFT by mod and FFT with digits up to 10^6

```
Num ta[N], tb[N], tf[N], tg[N];
const int HALF = 15:
void mult(int *a, int *b, int *r, int n, int mod) {
 int tw = (1 << HALF) - 1;</pre>
  forn (i, n) {
    int x = int(a[i] % mod);
    ta[i] = Num(x \& tw, x >> HALF);
  forn (i, n) {
   int x = int(b[i] % mod);
    tb[i] = Num(x \& tw, x >> HALF);
  fft(ta, n), fft(tb, n);
  forn (i, n) {
    int j = (n - i) & (n - 1);
    Num a1 = (ta[i] + conj(ta[j])) * Num(0.5, 0);
    Num a2 = (ta[i] - conj(ta[j])) * Num(0, -0.5);
    Num b1 = (tb[i] + conj(tb[j])) * Num(0.5 / n, 0);
    Num b2 = (tb[i] - conj(tb[j])) * Num(0, -0.5 / n);
    tf[j] = a1 * b1 + a2 * b2 * Num(0, 1);
    tg[j] = a1 * b2 + a2 * b1;
  fft(tf, n), fft(tg, n);
  forn (i, n) {
    11 aa = 11(tf[i].x + 0.5);
    11 bb = 11(tg[i].x + 0.5);
    11 cc = 11(tf[i].y + 0.5);
   r[i] = int((aa + ((bb \% mod) << HALF) + ((cc \% mod) << (2 *)
  HALF))) % mod);
 }
int tc[N], td[N];
const int MOD1 = 1.5e9, MOD2 = MOD1 + 1;
void multLL(int *a, int *b, ll *r, int n){
 mult(a, b, tc, n, MOD1), mult(a, b, td, n, MOD2);
    r[i] = tc[i] + (td[i] - tc[i] + (11)MOD2) * MOD1 % MOD2 *
   MOD1;
}
```

3 Data Structures

8 Centroid Decomposition

```
vi g[N];
int d[N], par[N], centroid;
//d and par - in centroid tree
int find(int v, int p, int total) {
```

```
int size = 1, ok = 1;
  for (int to : g[v])
   if (d[to] == -1 \&\& to != p) {
      int s = find(to, v, total);
      if (s > total / 2) ok = 0;
      size += s;
    }
  if (ok && size > total / 2) centroid = v;
  return size;
void calcInComponent(int v, int p, int level) {
  // do something
 for (int to : g[v])
   if (d[to] == -1 && to != p)
      calcInComponent(to, v, level);
//fill(d, d + n, -1)
//decompose(0, -1, 0)
void decompose(int root, int parent, int level) {
  find(root, -1, find(root, -1, INF));
  int c = centroid;
  par[c] = parent, d[c] = level;
  \verb| calcInComponent(centroid, -1, level); \\
  for (int to : g[c])
    if (d[to] == -1)
      decompose(to, c, level + 1);
}
```

9 Convex Hull Trick

```
struct Line {
  int k. b:
  Line() {}
  Line(int _k, int _b): k(_k), b(_b) {}
  ll get(int x) { return b + k * 111 * x; }
  bool operator<(const Line &1) const { return k < 1.k; } //</pre>
→ change to > in case of different order
};
// Checks if intersection of (a, b) is on the left from (a, c).
inline bool check(Line a, Line b, Line c) {
 return (a.b - b.b) * 111 * (c.k - a.k) < (a.b - c.b) * 111 *
\hookrightarrow (b.k - a.k);
struct Convex {
  vector<Line> st:
  inline void add(Line 1) {
    while (sz(st) \ge 2 \&\& !check(st[sz(st) - 2], st[sz(st) - 1],
      st.pop_back();
    st.pb(1);
  int get(int x) {
    int 1 = 0, r = sz(st);
    while (r - 1 > 1) {
      int m = (1 + r) / 2; // change to > in case of different
\hookrightarrow order
     if (st[m - 1].get(x) < st[m].get(x))
        1 = m;
      else
    }
    return 1;
  Convex() {}
  Convex(vector<Line> &lines) {
    st.clear();
    for(Line &1 : lines)
      add(1);
  Convex(Line line) { st.pb(line); }
  Convex(const Convex &a, const Convex &b) {
    vector<Line> lines:
    lines.resize(sz(a.st) + sz(b.st));
    merge(all(a.st), all(b.st), lines.begin());
    st.clear():
    for(Line &l : lines)
```

```
add(1);
 }
};
     DSU
10
int pr[N];
int get(int v) {
 return v == pr[v] ? v : pr[v] = get(pr[v]);
bool unite(int v, int u) {
 v = get(v), u = get(u);
 if (v == u) return 0;
 pr[u] = v;
 return 1:
void init(int n) {
 forn (i, n) pr[i] = i;
     Fenwick Tree
int t[N];
int get(int ind) {
 int res = 0;
 for (; ind >= 0; ind &= (ind + 1), ind--)
                                                                    }
   res += t[ind]:
 return res;
void add(int ind, int n, int val) {
 for (; ind < n; ind |= (ind + 1))
    t[ind] += val;
int sum(int 1, int r) { // [l, r)
 return get(r - 1) - get(1 - 1);
12 Hash Table
using H = 11;
const int HT_SIZE = 1<<20, HT_AND = HT_SIZE - 1, HT_SIZE_ADD =</pre>

    HT_SIZE / 100;

H ht[HT_SIZE + HT_SIZE_ADD];
int data[HT_SIZE + HT_SIZE_ADD];
                                                                    }
int get(const H &hash){
 int k = ((11) hash) & HT_AND;
 while (ht[k] \&\& ht[k] != hash) ++k;
 return k:
void insert(const H &hash, int x){
 int k = get(hash);
 if (!ht[k]) ht[k] = hash, data[k] = x;
bool count(const H &hash){
 int k = get(hash);
 return ht[k] != 0;
    Heavy Light Decomposition
vi g[N];
int size[N], comp[N], num[N], top[N], pr[N], tin[N], tout[N];
vi t[N], toPush[N], lst[N];
int curPath = 0, curTime = 0;
void pushST(int path, int v, int vl, int vr) {
  if (toPush[path][v] != -1) {
   if (vl != vr - 1)
```

forn (j, 2)

toPush[path][2 * v + j] = toPush[path][v];

```
t[path][v] = toPush[path][v];
    toPush[path][v] = -1;
int getST(int path, int v, int vl, int vr, int ind) {
  pushST(path, v, vl, vr);
  if (vl == vr - 1)
   return t[path][v];
  int vm = (vl + vr) / 2;
  if (ind >= vm)
    return getST(path, 2 * v + 1, vm, vr, ind);
  return getST(path, 2 * v, v1, vm, ind);
void setST(int path, int v, int vl, int vr, int l, int r, int val)
 if (vl >= l && vr <= r) {
    toPush[path][v] = val;
    pushST(path, v, vl, vr);
    return;
  pushST(path, v, v1, vr);
  if (vl >= r || l >= vr)
   return;
  int vm = (vl + vr) / 2;
  setST(path, 2 * v, vl, vm, l, r, val);
  setST(path, 2 * v + 1, vm, vr, 1, r, val);
  t[path][v] = min(t[path][2 * v], t[path][2 * v + 1]);
bool isUpper(int v, int u) {
 return tin[v] <= tin[u] && tout[v] >= tout[u];
int getHLD(int v) {
  return getST(comp[v], 1, 0, sz(t[comp[v]]) / 2, num[v]);
int setHLD(int v, int u, int val) {
  int ans = 0, w = 0;
  forn (i, 2) {
    while (!isUpper(w = top[comp[v]], u))
      setST(comp[v], 1, 0, sz(t[comp[v]]) / 2, 0, num[v] + 1,
\hookrightarrow val), v = pr[w];
    swap(v, u);
  setST(comp[v], 1, 0, sz(t[comp[v]]) / 2, min(num[v], num[u]),

    max(num[v], num[u]) + 1, val);

  return ans;
void dfs(int v, int p) {
 tin[v] = curTime++;
  size[v] = 1:
  pr[v] = p;
  for (int u : g[v])
   if (u != p) {
      dfs(u, v);
      size[v] += size[u];
  tout[v] = curTime++;
void build(int v) {
  if (v == 0 \mid \mid size[v] * 2 < size[pr[v]])
    top[curPath] = v, comp[v] = curPath, num[v] = 0, curPath++;
    comp[v] = comp[pr[v]], num[v] = num[pr[v]] + 1;
  lst[comp[v]].pb(v);
  for (int u : g[v])
    if (u != pr[v])
      build(u):
void initHLD() {
  dfs(0, 0);
  build(0);
```

```
forn (i, curPath) {
   int curSize = 1;
   while (curSize < sz(lst[i]))
      curSize *= 2;
   t[i].resize(curSize * 2);
   toPush[i] = vi(curSize * 2, -1);
   //initialize t[i]
}</pre>
```

14 Next Greater in Segment Tree

```
int t[4 * N], tSize = 1;

// Find position > pos with val > x.
int nextGreaterX(int v, int l, int r, int pos, int x) {
  if (r <= pos + 1 || t[v] <= x) return INF;
  if (v >= tSize) return v - tSize;
  int ans = nextGreaterX(2 * v, l, (l + r) / 2, pos, x);
  if (ans == INF)
    ans = nextGreaterX(2 * v + 1, (l + r) / 2, r, pos, x);
  return ans;
}
```

15 Sparse Table

```
int st[N][LOG];
int lg[N];

int get(int l, int r) { // [l, r)
    int curLog = lg[r - 1];
    return min(st[l][curLog], st[r - (1 << curLog)][curLog]);
}

void initSparseTable(int *a, int n) {
    lg[1] = 0;
    forab (i, 2, n + 1) lg[i] = lg[i / 2] + 1;
    forn (i, n) st[i][0] = a[i];
    forn (j, lg[n])
        forn (i, n - (1 << (j + 1)) + 1)
            st[i][j + 1] = min(st[i][j], st[i + (1 << j)][j]);
}</pre>
```

16 Fenwick Tree 2D

 \hookrightarrow get(x_1 - 1, y_1 - 1);

```
ll a[4][N][N];
int n, m;
inline int f(int x) { return x & ~(x - 1); }
inline void add(int k, int x, int y, ll val) {
  for (; x \le n; x += f(x))
   for (int j = y; j \le m; j += f(j))
      a[k][x][j] += val;
inline ll get(int k, int x, int y) {
 11 s = 0;
 for (; x > 0; x -= f(x))
   for (int j = y; j > 0; j -= f(j))
     s += a[k][x][j];
 return s;
inline ll get(int x, int y) {
 return ll(x + 1) * (y + 1) * get(0, x, y) - (y + 1) * get(1, x, y)
      -(x + 1) * get(2, x, y) + get(3, x, y);
inline void add(int x, int y, ll val) {
 add(0, x, y, val);
 add(1, x, y, val * x);
 add(2, x, y, val * y);
 add(3, x, y, val * x * y);
inline ll get(int x_1, int y_1, int x_2, int y_2) {
 return get(x_2, y_2) - get(x_1 - 1, y_2) - get(x_2, y_1 - 1) +
```

```
// Adds val to corresponding rectangle
inline void add(int x_1, int y_1, int x_2, int y_2, ll val) {
   add(x_1, y_1, val);
   if (y_2 < m) add(x_1, y_2 + 1, -val);
   if (x_2 < n) add(x_2 + 1, y_1, -val);
   if (x_2 < n && y_2 < m) add(x_2 + 1, y_2 + 1, val);
}</pre>
```

17 Segment Tree 2D

```
int tSize = (1 << 10);</pre>
struct Node1D {
 Node1D *1, *r;
  ll val, need;
  Node1D(): l(nullptr), r(nullptr), val(0), need(0) {}
 inline void norm() {
   if(!1) 1 = new Node1D();
    if(!r) r = new Node1D();
  11 get(int q1, int qr, int v1 = 0, int vr = tSize) {
   if(vl >= qr || ql >= vr)
      return 0;
    if(ql <= vl && vr <= qr)
     return val;
    int a = max(vl, ql), b = min(vr, qr), vm = (vl + vr) / 2;
    norm():
    return l->get(ql, qr, vl, vm) + r->get(ql, qr, vm, vr) + need
\rightarrow * ll(b - a);
 }
  void add(int ql, int qr, int x, int vl = 0, int vr = tSize) {
    if (ql >= vr || vl >= qr)
     return;
    if (ql <= vl && vr <= qr){
      need += x;
      val += x * ll(vr - vl);
      return;
   int vm = (v1 + vr) / 2;
    norm();
    1->add(q1, qr, x, v1, vm), r->add(q1, qr, x, vm, vr);
    val = 1->val + r->val + need * (vr - vl);
 }
};
struct Node2D {
 Node2D *1, *r;
  Node1D *val, *need;
 Node2D(): 1(nullptr), r(nullptr), val(new Node1D()), need(new
 \rightarrow Node1D()) {}
 inline void norm() {
    if(!1) 1 = new Node2D();
    if(!r) r = new Node2D();
 ll get(int q10, int qr0, int q11, int qr1, int v1 = 0, int vr =
if(vl >= qr0 || ql0 >= vr)
     return 0:
    if(q10 <= v1 && vr <= qr0)
     return val->get(ql1, qr1);
    int a = max(v1, q10), b = min(vr, qr0), vm = (v1 + vr) / 2;
    norm():
    return 1->get(q10, qr0, q11, qr1, v1, vm) + r->get(q10, qr0,
    ql1, qr1, vm, vr) + need->get(ql1, qr1) * ll(b - a);
 void add(int q10, int qr0, int q11, int qr1, int x, int v1 = 0,

    int vr = tSize) {

    if (ql0 >= vr || vl >= qr0)
     return:
    if (ql0 <= vl && vr <= qr0){
      need->add(ql1, qr1, x);
      val->add(ql1, qr1, x * ll(vr - vl));
      return;
    }
    int a = max(q10, v1), b = min(qr0, vr), vm = (v1 + vr) / 2;
    norm();
   l->add(q10, qr0, q11, qr1, x, v1, vm), r->add(q10, qr0, q11,
\hookrightarrow qr1, x, vm, vr);
```

```
val->add(ql1, qr1, x * ll(b - a));
  }
};
```

Dynamic Programming

LIS 18

```
int longestIncreasingSubsequence(vi a) {
 int n = sz(a);
 vi d(n + 1, INF);
 d[0] = -INF;
 forn (i, n)
   *upper_bound(all(d), a[i]) = a[i];
 fornr (i, n + 1) if (d[i] != INF) return i;
 return 0;
```

DP tree 19

```
int dp[N][N], a[N];
vi g[N];
int dfs(int v, int n) {
 form (i, n + 1)
    dp[v][i] = -INF;
 dp[v][1] = a[v];
  int curSz = 1;
 for (int to : g[v]) {
   int toSz = dfs(to, n);
   for (int i = curSz; i >= 1; i--)
     fornr (j, toSz + 1)
        dp[v][i + j] = max(dp[v][i + j], dp[v][i] + dp[to][j]);
   curSz += toSz;
 7
 return curSz;
```

20 Masks tricks

```
int dp[(1 << MASK)][MASK];</pre>
void calcDP(int n) {
  forn(mask, 1 << n) {
    dp[mask][n] = 1;
    fornr(i, n) {
      dp[mask][i] = dp[mask][i + 1];
      if ((1 << i) & mask)
        dp[mask][i] += dp[mask ^ (1 << i)][i + 1];
    }
```

Flows

21 Utilities

```
vi g[N];
// for directed unweighted graph
struct Edge {
 int v, u, c, f;
 Edge() {}
 Edge(int _v, int _u, int _c): v(_v), u(_u), c(_c), f(0) {}
vector<Edge> edges;
inline void addFlow(int e, int flow) {
   edges[e].f += flow, edges[e ^ 1].f -= flow;
inline void addEdge(int v, int u, int c) {
  g[v].pb(sz(edges)), edges.pb(Edge(v, u, c));
 g[u].pb(sz(edges)), edges.pb(Edge(u, v, 0)); // for undirected 0
 \rightarrow should be c
```

}

```
22 Ford-Fulkerson
int used[N], pr[N];
int curTime = 1;
int dfs(int v, int can, int toPush, int t) {
 if (v == t) return can;
  used[v] = curTime;
 for (int edge : g[v]) {
    auto &e = edges[edge];
   if (used[e.u] != curTime && e.c - e.f >= toPush) {
      int flow = dfs(e.u, min(can, e.c - e.f), toPush, t);
      if (flow > 0) {
        addFlow(edge, flow), pr[e.u] = edge;
        return flow;
     }
   }
 }
 return 0;
int fordFulkerson(int s, int t) {
 int ansFlow = 0, flow = 0;
  // Without scaling
 while ((flow = dfs(s, INF, 1, t)) > 0)
   ansFlow += flow, curTime++;
  // With scaling
 fornr (i, INF_LOG)
   for (curTime++; (flow = dfs(s, INF, (1 \ll i), t)) > 0;

    curTime++)

      ansFlow += flow;
 return ansFlow;
23 Dinic
int pr[N], d[N], q[N], first[N];
int dfs(int v, int can, int toPush, int t) {
 if (v == t) return can;
  int sum = 0;
  for (; first[v] < (int) g[v].size(); first[v]++) {</pre>
   auto &e = edges[g[v][first[v]]];
    if (d[e.u] != d[v] + 1 \mid\mid e.c - e.f < toPush) continue;
   int flow = dfs(e.u, min(can, e.c - e.f), toPush, t);
    addFlow(g[v][first[v]], flow);
   can -= flow, sum += flow;
    if (!can)
   return sum:
  return sum;
bool bfs(int n, int s, int t, int curPush) {
  forn (i, n) d[i] = INF, first[i] = 0;
  int head = 0, tail = 0;
  q[tail++] = s;
  d[s] = 0;
  while (tail - head > 0) {
   int v = q[head++];
   for (int edge : g[v]) {
     auto &e = edges[edge];
      if (d[e.u] > d[v] + 1 \&\& e.c - e.f >= curPush)
        d[e.u] = d[v] + 1, q[tail++] = e.u;
  }
  return d[t] != INF;
int dinic(int n, int s, int t) {
 int ansFlow = 0;
  // Without scaling
  while (bfs(n, s, t, 1))
   ansFlow += dfs(s, INF, 1, t);
  // With scaling
 fornr (j, INF_LOG)
    while (bfs(n, s, t, 1 \ll j))
     ansFlow += dfs(s, INF, 1 \ll j, t);
  return ansFlow;
```

24 Hungarian

```
const int INF = 1e9;
int a[N][N];
// min = sum of a[pa[i],i]
// you may optimize speed by about 15%, just change all vectors to
  static arrays
vi Hungarian(int n) {
 vi pa(n + 1, -1), row(n + 1, 0), col(n + 1, 0), la(n + 1);
 forn (k, n) {
    vi u(n + 1, 0), d(n + 1, INF);
   pa[n] = k;
   int 1 = n, x;
    while ((x = pa[1]) != -1) {
     u[1] = 1:
      int minn = INF, tmp, 10 = 1;
     forn (j, n)
        if (!u[j]) {
          if ((tmp = a[x][j] + row[x] + col[j]) < d[j])
           d[j] = tmp, la[j] = 10;
          if (d[j] < minn)
           minn = d[j], 1 = j;
       }
     forn (j, n + 1)
        if (u[j])
         col[j] += minn, row[pa[j]] -= minn;
          d[j] -= minn;
   while (l != n)
     pa[1] = pa[la[1]], 1 = la[1];
 return pa;
```

25 Min Cost Max Flow

```
int pr[N], in[N], q[N * M], used[N], d[N], pot[N];
vi g[N];
struct Edge {
  int v, u, c, f, w;
  Edge() {}
 Edge(int _v, int _u, int _c, int _w): v(_v), u(_u), c(_c),
   f(0), w(_w) {}
vector<Edge> edges;
inline void addFlow(int e, int flow) {
  edges[e].f += flow, edges[e ^ 1].f -= flow;
}
inline void addEdge(int v, int u, int c, int w) {
  g[v].pb(sz(edges)), edges.pb(Edge(v, u, c, w));
  g[u].pb(sz(edges)), edges.pb(Edge(u, v, 0, -w));
int dijkstra(int n, int s, int t) {
  forn (i, n) used[i] = 0, d[i] = INF;
  d[s] = 0;
  while (1) {
    int v = -1;
    forn (i, n)
      if (!used[i] && (v == -1 \mid \mid d[v] > d[i]))
        v = i;
    if (v == -1 \mid \mid d[v] == INF) break;
    used[v] = 1;
    for (int edge : g[v]) {
      auto &e = edges[edge];
      int w = e.w + pot[v] - pot[e.u];
      if (e.c > e.f && d[e.u] > d[v] + w)
        d[e.u] = d[v] + w, pr[e.u] = edge;
    }
  }
  if (d[t] == INF) return d[t];
 forn (i, n) pot[i] += d[i];
  return pot[t];
```

```
int fordBellman(int n, int s, int t) {
  forn (i, n) d[i] = INF;
  int head = 0, tail = 0;
  d[s] = 0, q[tail++] = s, in[s] = 1;
  while (tail - head > 0) {
   int v = q[head++];
    in[v] = 0;
    for (int edge : g[v]) {
     auto &e = edges[edge];
      if (e.c > e.f \&\& d[e.u] > d[v] + e.w) {
        d[e.u] = d[v] + e.w;
        pr[e.u] = edge;
        if (!in[e.u])
          in[e.u] = 1, q[tail++] = e.u;
      }
   }
  }
 return d[t];
}
int minCostMaxFlow(int n, int s, int t) {
 int ansFlow = 0, ansCost = 0, dist;
  while ((dist = dijkstra(n, s, t)) != INF) {
   int curFlow = INF;
   for (int cur = t; cur != s; cur = edges[pr[cur]].v)
     curFlow = min(curFlow, edges[pr[cur]].c -

    edges[pr[cur]].f);

   for (int cur = t; cur != s; cur = edges[pr[cur]].v)
     addFlow(pr[cur], curFlow);
    ansFlow += curFlow;
   ansCost += curFlow * dist;
 }
 return ansCost;
```

6 Games

26 Retrograde Analysis

```
int win[N], lose[N], outDeg[N];
vi rg[N];
void retro(int n) {
  queue<int> q;
  forn (i, n)
   if (!outDeg[i])
     lose[i] = 1, q.push(i);
  while (!q.empty()) {
   int v = q.front();
   q.pop();
   for (int to : rg[v])
     if (lose[v]) {
        if (!win[to])
          win[to] = 1, q.push(to);
      } else {
        outDeg[to]--;
        if (!outDeg[to])
          lose[to] = 1, q.push(to);
      }
 }
}
```

7 Geometry

27 ClosestPoints (SweepLine)

```
SPb HSE (Bogomolov, Labutin, Podguzov)
 return (ll)x * x;
inline void relax(const Pnt &a, const Pnt &b){
 ll tmp = sqr(a.x - b.x) + sqr(a.y - b.y);
  if (tmp < d2)
    d2 = tmp, d = (11)(sqrt(d2) + 1 - 1e-9); // round up
inline bool xless(const Pnt &a, const Pnt &b){
 return a.x < b.x;
int main() {
  int n;
  scanf("%d", &n);
  forn(i, n)
   scanf("%d%d", &p[i].x, &p[i].y), p[i].i = i;
  sort(p, p + n, xless);
  set <Pnt> s:
  int 1 = 0;
  forn(r, n){
    set<Pnt>::iterator it_r = s.lower_bound(p[r]), it_l = it_r;
    for (; it_r != s.end() && it_r->y - p[r].y < d; ++it_r)
     relax(*it_r, p[r]);
    while (it_l != s.begin() && p[r].y - (--it_l)->y < d)
     relax(*it_l, p[r]);
    s.insert(p[r]);
    while (1 <= r \&\& p[r].x - p[1].x >= d)
      s.erase(p[1++]);
 printf("%.9f\n", sqrt(d2));
 return 0;
    ConvexHull
using vpnt = vector<Pnt>;
inline bool by Angle (const Pnt& a, const Pnt& b) {
  dbl x = a \% b;
  return eq(x, 0) ? a.len2() < b.len2() : x < 0;
vpnt convexHull(vpnt p) {
 int n = sz(p);
  assert(n > 0):
  swap(p[0], *min_element(all(p)));
 forab(i, 1, n)
 p[i] = p[i] - p[0];
  sort(p.begin() + 1, p.end(), byAngle);
/* To keep 180 angles (1) (2)
  int k = p.size() - 1;
  \label{eq:while} \textit{while}(k > 0 \; \textit{SM} \; eq((p[k - 1] - p.back()) \; \% \; p.back(), \; 0))
  reverse(pi.begin() + k, pi.end());*/
 int rn = 0;
  vpnt r(n);
  r[rn++] = p[0];
  forab(i, 1, n){
   Pnt q = p[i] + p[0];
    while(rn >= 2 && geq((r[rn - 1] - r[rn - 2]) % (q - r[rn -
\leftrightarrow 2]), 0)) // (2) ge
      --rn:
   r[rn++] = q;
 7
 r.resize(rn):
 return r;
29
     GeometryBase
const dbl EPS = 1e-9;
const int PREC = 20;
inline bool eq(dbl a, dbl b) { return abs(a-b)<=EPS; }</pre>
```

```
inline bool gr(dbl a, dbl b) { return a>b+EPS; }
```

```
inline bool geq(dbl a, dbl b) { return a>=b-EPS; }
inline bool ls(dbl a, dbl b) { return a < b - EPS; }</pre>
inline bool leq(dbl a, dbl b) { return a <= b + EPS; }</pre>
struct Pnt {
    dbl x,y;
    Pnt(): x(0), y(0) {}
    Pnt(dbl xx, dbl yy): x(xx), y(yy) {}
    inline Pnt operator +(const Pnt &p) const { return Pnt(x +
\hookrightarrow p.x, y + p.y); }
    inline Pnt operator -(const Pnt &p) const { return Pnt(x -
    p.x, y - p.y); }
    inline dbl operator *(const Pnt &p) const { return x * p.x + y

    * p.y; } // ll

    inline dbl operator \%(const Pnt &p) const { return x * p.y - y
\hookrightarrow * p.x; } // ll
    inline Pnt operator *(dbl k) const { return Pnt(x * k, y * k);
→ }
    inline Pnt operator /(dbl k) const { return Pnt(x / k, y / k);
    }
    inline Pnt operator -() const { return Pnt(-x, -y); }
    inline void operator +=(const Pnt &p) { x += p.x, y += p.y; }
    inline void operator -=(const Pnt &p) { x -= p.x, y -= p.y; }
    inline void operator *=(dbl k) { x*=k, y*=k; }
    inline bool operator ==(const Pnt &p) const { return
\rightarrow abs(x-p.x)<=EPS && abs(y-p.y)<=EPS; }
    inline bool operator !=(const Pnt &p) const { return
\rightarrow abs(x-p.x)>EPS || abs(y-p.y)>EPS; }
    inline bool operator <(const Pnt &p) const { return
\rightarrow abs(x-p.x)<=EPS ? y<p.y-EPS : x<p.x; }
    inline dbl angle() const { return atan2(y, x); } // ld
    inline dbl len2() const { return x*x+y*y; } // ll
    inline dbl len() const { return sqrt(x*x+y*y); } // ll, ld
    inline Pnt getNorm() const {
        auto 1 = len();
        return Pnt(x/1, y/1);
    }
    inline void normalize() {
        auto 1 = len();
        x/=1, y/=1;
    inline Pnt getRot90() const { //counter-clockwise
        return Pnt(-y, x);
    inline Pnt getRot(dbl a) const { // ld
        dbl si = sin(a), co = cos(a);
        return Pnt(x*co - y*si, x*si + y*co);
    inline void read() {
        int xx, vv;
    cin >> xx >> yy;
        x = xx, y = yy;
    }
    inline void write() const{
        cout << fixed << (double)x << " " << (double)y << '\n';</pre>
    Pnt bmul(const Pnt& r) const {
    return Pnt(x*r.x - y*r.y, y*r.x + x*r.y);
}:
struct Line{
    dbl a, b, c;
    Line(): a(0), b(0), c(0) {}
    // normalizes
    Line(dbl aa, dbl bb, dbl cc) {
      dbl norm = sqrt(aa * aa + bb * bb);
      aa /= norm, bb /= norm, cc /= norm;
      a = aa, b = bb, c = cc;
    Line(const Pnt &A, const Pnt &p){ // it normalizes (a,b),
\hookrightarrow important in d(), normalToP()
```

```
SPb HSE (Bogomolov, Labutin, Podguzov)

Pnt n = (p-A).getRot90().getNorm();
    a = n.x, b = n.y, c = -(a * A.x + b * A.y);
}

inline dbl d(const Pnt &p) const { return a*p.x + b*p.y + c; }
inline Pnt no() const { return Pnt(a, b);}
inline Pnt normalToP(const Pnt &p) const { return Pnt(a,b) *

    (a*p.x + b*p.y + c); }

inline void write() const{
    cout << fixed << (double)a << " " << (double)b << " " " <<
    (double)c << '\n';
}
};

30 GeometryInterTangent
inline dbl sqr(dbl x) { return x * x; }

struct Circle {
    Pnt p;
    dbl r;
};

Pnt tangent(Pnt x, Circle y, int t = 0) {</pre>
```

```
inline dbl sqr(dbl x) { return x * x; }
struct Circle {
};
Pnt tangent(Pnt x, Circle y, int t = 0) {
 y.r = abs(y.r); // abs needed because internal calls y.s < 0
  if (y.r == 0) return y.p;
 dbl d = (x - y.p).len();
 Pnt a = (x - y.p) * pow(y.r / d, 2) + y.p;
 Pnt b = ((x - y.p).getNorm() * sqrt(d * d - y.r * y.r) / d *
\rightarrow y.r).bmul(Pnt(0, 1));
 return t == 0 ? a+b : a-b;
vector<pair<Pnt,Pnt>> external(const Circle &x, const Circle &y)
 vector<pair<Pnt,Pnt>> v;
 if (x.r == y.r) {
   Pnt tmp = ((x.p-y.p).getNorm()*x.r).bmul(Pnt(0,1));
   v.pb(mp(x.p+tmp,y.p+tmp));
   v.pb(mp(x.p-tmp,y.p-tmp));
 } else {
   Pnt p = (x.p*y.r-y.p*x.r)/(y.r-x.r);
   forn(i,2) v.pb(mp(tangent(p,x,i),tangent(p,y,i)));
 return v;
}
vector<pair<Pnt,Pnt>> internal(const Circle &x, const Circle &y)
 return external({x.p,-x.r},y); }
vector<Pnt> line_line(const Line &1, const Line &m){
   dbl z = m.a * l.b - l.a * m.b;
  dbl x = m.c * 1.b - 1.c * m.b;
 dbl y = m.c * l.a - l.c * m.a;
    if(fabs(z) > EPS)
       return \{Pnt(-x/z, y/z)\};
    else if(fabs(x) > EPS || fabs(y) > EPS)
       return {}; // parallel lines
       return {Pnt(0, 0), Pnt(0, 0)}; // same lines
vector<Pnt> circle_line(const Circle &c, const Line &l){
    dbl d = 1.d(c.p);
    if(fabs(d) > c.r + EPS)
        return {};
    if(fabs(fabs(d) / c.r - 1) < EPS) {
       return {c.p - 1.no() * d};
    } else {
       dbl s = sqrt(fabs(sqr(c.r) - sqr(d)));
       return {c.p - 1.no() * d + 1.no().getRot90() * s,
            c.p - 1.no() * d - 1.no().getRot90() * s};
    }
vector<Pnt> circle_circle(const Circle &x, const Circle &y) {
  dbl d = (x.p-y.p).len(), a = x.r, b = y.r;
```

if (eq(d, 0)) { assert(a != b); return {}; }

```
dbl C = (a*a+d*d-b*b)/(2*a*d);
  if (abs(C) > 1+EPS) return {};
  dbl S = sqrt(max(1-C*C,(dbl)0)); Pnt tmp = (y.p-x.p)/d*x.r;
  if (eq(S, 0)) return {x.p+tmp.bmul(Pnt(C,0))};
  \texttt{return } \{ \texttt{x.p+tmp.bmul(Pnt(C,S)),x.p+tmp.bmul(Pnt(C,-S))} \}; \\
dbl circle_isect_area(const Circle &x, const Circle &y) {
 dbl d = (x.p-y.p).len(), a = x.r, b = y.r; if (a < b)
\rightarrow swap(a,b);
  if (geq(d, a+b)) return 0;
  if (leq(d, a-b)) return PI*b*b;
  dbl ca = acos((a*a+d*d-b*b)/(2*a*d)), cb =
\rightarrow acos((b*b+d*d-a*a)/(2*b*d)):
  return (ca*a*a-0.5*a*a*sin(ca*2))+(cb*b*b-0.5*b*b*sin(cb*2));
}
// Squared distance between point p and segment [a..b]
dbl dist2(Pnt p, Pnt a, Pnt b){
    if ((p - a) * (b - a) < 0) return (p - a).len2();
    if ((p - b) * (a - b) < 0) return (p - b).len2();
    dbl d = fabs((p - a) \% (b - a));
    return d * d / (b - a).len2();
}
31 GeometrySimple
int sign(dbl a) { return (a > EPS) - (a < -EPS); }</pre>
// Checks, if point is inside the segment
inline bool inSeg(const Pnt &p, const Pnt &a, const Pnt &b) {
    return eq((p - a) % (p - b), 0) && leq((p - a) * (p - b), 0);
}
// Checks, if two intervals (segments without ends) intersect AND
→ do not lie on the same line
inline bool subIntr(const Pnt &a, const Pnt &b, const Pnt &c,
return
            sign((b - a) \% (c - a)) * sign((b - a) \% (d - a)) ==
   -1 &&
            sign((d - c) \% (a - c)) * sign((d - c) \% (b - c)) ==
    -1;
}
// Checks, if two segments (ends are included) has an intersection
inline bool checkSegInter(const Pnt &a, const Pnt &b, const Pnt
\texttt{return inSeg(c, a, b)} \ | \ | \ \texttt{inSeg(d, a, b)} \ | \ | \ \texttt{inSeg(a, c, d)} \ | \ |
   inSeg(b, c, d) || subIntr(a, b, c, d);
}
inline dbl area(vector<Pnt> p){
    dbl s = 0;
    int n = sz(p);
    p.pb(p[0]);
    forn(i, n)
        s += p[i + 1] \% p[i];
    p.pop_back();
    return abs(s) / 2;
// Check if point p is inside polygon <n, q[]>
int containsSlow(Pnt p, Pnt *z, int n){
    int cnt = 0;
    forn(j, n){
        Pnt a = z[j], b = z[(j + 1) \% n];
        if (inSeg(p, a, b))
            return -1; // border
        if (min(a.y, b.y) - EPS \le p.y \&\& p.y \le max(a.y, b.y) -

→ EPS)

            cnt += (p.x < a.x + (p.y - a.y) * (b.x - a.x) / (b.y
   - a.y));
    }
    return cnt & 1; // O = outside, 1 = inside
}
```

//for convex polygon

//assume polygon is counterclockwise-ordered

forn(i, cntVar) {

if (comp[2 * i] == comp[2 * i + 1]) return false;

dfsInit(u, v, e.snd);

}

```
bool containsFast(Pnt p, Pnt *z, int n) {
                                                                         if (comp[2 * i] < comp[2 * i + 1]) val[2 * i + 1] = 1;
    Pnt o = z[0];
                                                                         else val[2 * i] = 1;
    if(gr((p - o) \% (z[1] - o), 0) || ls((p - o) \% (z[n - 1] -
\rightarrow o), 0))
                                                                      return true;
                                                                    }
       return 0:
    int 1 = 0, r = n - 1;
    while(r - 1 > 1){
                                                                     33 Bridges
        int m = (1 + r) / 2;
        if(gr((p - o) \% (z[m] - o), 0))
                                                                     int up[N], tIn[N], timer;
           r = m;
                                                                     vector<vi> comps;
        else
                                                                     vi st;
            1 = m:
    }
                                                                    struct Edge {
   return leq((p - z[1]) % (z[r] - z[1]), 0);
                                                                       int to, id;
                                                                       Edge(int _to, int _id) : to(_to), id(_id) {}
// Checks, if point "p" is in the triangle "abc" IFF triangle in
                                                                     vector<Edge> g[N];
inline int isInTr(const Pnt &p, const Pnt &a, const Pnt &b, const
→ Pnt &c){
                                                                    void newComp(int size = 0) {
   return
                                                                       comps.emplace_back(); // new empty
            gr((b - a) % (p - a), 0) &&
                                                                       while (sz(st) > size) {
            gr((c - b) % (p - b), 0) &&
                                                                         comps.back().pb(st.back());
            gr((a - c) \% (p - c), 0);
                                                                         st.pop_back();
}
                                                                      }
                                                                    }
8
     Graphs
                                                                     void findBridges(int v, int parentEdge = -1) {
                                                                      if (up[v]) // visited
                                                                        return;
    2-SAT
32
                                                                       up[v] = tIn[v] = ++timer;
// VAR - 2 * vars
                                                                       st.pb(v);
                                                                       for (Edge e : g[v]) {
int cntVar = 0, val[VAR], usedSat[VAR], comp[VAR];
                                                                        if (e.id == parentEdge)
vi topsortSat:
                                                                           continue:
                                                                         int u = e.to;
vi g[VAR], rg[VAR];
                                                                        if (!tIn[u]) {
inline int newVar() {
                                                                          int size = sz(st);
                                                                          findBridges(u, e.id);
 cntVar++:
                                                                          if (up[u] > tIn[v])
 return (cntVar - 1) * 2;
                                                                             newComp(size);
inline int Not(int v) { return v ^ 1; }
                                                                         up[v] = min(up[v], up[u]);
                                                                      }
inline void Implies(int v1, int v2) { g[v1].pb(v2),
\rightarrow rg[v2].pb(v1); }
                                                                     // after find_bridges newComp() for root
inline void Or(int v1, int v2) { Implies(Not(v1), v2),
                                                                    void run(int n) {
                                                                      forn (i, n)
if (!up[i]) {
                                                                          findBridges(i);
inline void Nand(int v1, int v2) { Or(Not(v1), Not(v2)); }
                                                                           newComp();
inline void setTrue(int v) { Implies(Not(v), v); }
                                                                    }
void dfs1(int v) {
 usedSat[v] = 1:
                                                                     34 Cactus
  for (int to : g[v])
                                                                     int used[N]:
    if (!usedSat[to]) dfs1(to);
  topsortSat.pb(v);
                                                                     struct Edge {
                                                                       11 1;
void dfs2(int v, int c) {
                                                                        Edge() {}
 comp[v] = c;
                                                                        Edge(int _1): 1(_1) {}
  for (int to : rg[v])
                                                                    };
    if (!comp[to]) dfs2(to, c);
                                                                     vector<pair<int, Edge>> g[N], rev[N], path;
                                                                    pair<int, Edge> pr[N];
int getVal(int v) { return val[v]; }
                                                                    void dfsInit(int v, int p, Edge prE) {
// cntVar
                                                                      used[v] = 1;
bool solveSat() {
                                                                       pr[v] = mp(p, prE);
  forn(i, 2 * cntVar) usedSat[i] = 0;
                                                                      for (auto e : g[v]) {
  forn(i, 2 * cntVar)
                                                                        int u = e.fst;
                                                                        if (u == p)
   if (!usedSat[i]) dfs1(i);
  reverse(all(topsortSat));
                                                                           continue;
  int c = 0;
                                                                        if (used[u] == 1)
  for (int v : topsortSat)
                                                                          rev[u].pb(mp(v, e.snd));
    if (!comp[v]) dfs2(v, ++c);
                                                                         else if (used[u] != 2)
```

```
used[v] = 2;
void calc(int v) {
 used[v] = 1:
  for (auto e: rev[v]) {
     path.clear();
     int u = e.fst;
     while (u != v) {
        calc(u);
        path.pb(mp(u, pr[u].snd));
        u = pr[u].fst;
      // Calculate answer for cycle -- path and vertex v
   }
   for (auto e : g[v])
     if (!used[e.fst] && e.fst != pr[v].fst) {
      calc(e.fst);
       // Update answer for tree edges
```

35 Cut Points

```
bool used[M];
int tIn[N], timer, isCut[N], color[M], compCnt;
struct Edge {
 int to, id;
 Edge(int _to, int _id) : to(_to), id(_id) {}
vector<Edge> g[N];
int dfs(int v, int parent = -1) {
 tIn[v] = ++timer;
 int up = tIn[v], x = 0, y = (parent != -1);
 for (Edge p : g[v]) {
    int u = p.to, id = p.id;
   if (id != parent) {
      int t, size = sz(st);
      if (!used[id])
       used[id] = 1, st.push_back(id);
      if (!tIn[u]) { // not visited yet
       t = dfs(u, id);
       if (t >= tIn[v]) {
         ++x, ++compCnt;
          while (sz(st) != size) {
            color[st.back()] = compCnt;
            st.pop_back();
         }
       }
     } else
       t = tIn[u];
      up = min(up, t);
 if (x + y >= 2)
   isCut[v] = 1; // v is cut vertex
 return up;
```

36 Dominator Tree

```
sdom[co] = par[co] = bes[co] = co;
  for(auto y : adj[x]) {
   if (!label[y]) {
      dfs(y); child[label[x]].pb(label[y]); }
    radj[label[y]].pb(label[x]);
 }
}
void init(int root) {
  dfs(root);
  for(int i = co; i >= 1; i--) {
   for(auto j : radj[i]) sdom[i] = min(sdom[i], sdom[get(j)]);
   if (i > 1) sdomChild[sdom[i]].pb(i);
    for(auto j : sdomChild[i]) {
     int k = get(j);
      if (sdom[j] == sdom[k]) dom[j] = sdom[j];
      else dom[j] = k;
   for(auto j : child[i]) par[j] = i;
  forab(i,2,co+1) {
    if (dom[i] != sdom[i]) dom[i] = dom[dom[i]];
    ans[rlabel[dom[i]]].pb(rlabel[i]);
}
```

37 Eulerian Cycle

```
struct Edge {
  int to, used;
  Edge(): to(-1), used(0) {}
  Edge(int v): to(v), used(0) {}
};

vector<Edge> edges;
vi g[N], res, ptr;
// don't forget to clear ptr!

void dfs(int v) {
  for(; ptr[v] < sz(g[v]);) {
    int id = g[v][ptr[v]++];
    if (!edges[id].used {
      edges[id].used = edges[id ^ 1].used = 1;
      dfs(edges[id].to);
      res.pb(id); // edges
    }
}
res.pb(v); // res contains vertices
}</pre>
```

```
Euler Tour Tree
38
mt19937 rng(239);
struct Edge {
   Edge(int _v, int _u): v(_v), u(_u) {}
struct Node {
 Node *1, *r, *p;
  Edge e;
  int y, size;
 Node(Edge _e): 1(nullptr), r(nullptr), p(this), e(_e), y(rng()),
\hookrightarrow size(1) {}
inline int getSize(Node* root) { return root ? root->size : 0; }
inline void recalc(Node* root) { root->size = getSize(root->l) +

    getSize(root->r) + 1; }

set<pair<int, Node*>> edges[N];
Node* merge(Node *a, Node *b) {
  if (!a) return b;
  if (!b) return a;
  if (a->y < b->y) {
    a->r = merge(a->r, b);
```

if (a->r) a->r->p = a;

recalc(a);

Node *vN = makeRoot(v), *uN = makeRoot(u);

 $\label{eq:merge} merge(merge(vN, makeEdge(v, u)), uN), makeEdge(u, v));$

inline void link(int v, int u) {

```
return a:
  }
 b->1 = merge(a, b->1);
  if (b->1) b->1->p = b;
 recalc(b):
 return b;
void split(Node *root, Node *&a, Node *&b, int size) {
  if (!root) {
   a = b = nullptr;
   return;
 int lSize = getSize(root->1);
  if (lSize >= size) {
    split(root->1, a, root->1, size);
    if (root->1) root->1->p = root;
   b = root, b \rightarrow p = b;
  } else {
    split(root->r, root->r, b, size - 1Size - 1);
    if (root->r) root->r->p = root;
    a = root, a \rightarrow p = a;
   a->p = a;
  }
 recalc(root):
inline Node* rotate(Node* root, int k) {
 if (k == 0) return root;
  Node *1, *r;
  split(root, 1, r, k);
 return merge(r, 1);
inline pair<Node*, int> goUp(Node* root) {
 int pos = getSize(root->1);
  while (root->p != root)
   pos += (root->p->r == root ? getSize(root->p->l) + 1 : 0),

    root = root->p;

  return mp(root, pos);
inline Node* deleteFirst(Node* root) {
  split(root, a, root, 1);
  edges[a->e.v].erase(mp(a->e.u, a));
 return root;
inline Node* getNode(int v, int u) {
 return edges[v].lower_bound(mp(u, nullptr))->snd;
inline void cut(int v, int u) {
 auto pV = goUp(getNode(v, u));
  auto pU = goUp(getNode(u, v));
  int 1 = min(pV.snd, pU.snd), r = max(pV.snd, pU.snd);
 Node *a, *b, *c;
 split(pV.fst, a, b, 1);
  split(b, b, c, r - 1);
  deleteFirst(b);
  merge(a, deleteFirst(c));
inline pair<Node*, int> getRoot(int v) {
 return !sz(edges[v]) ? mp(nullptr, 0) :

→ goUp(edges[v].begin()->snd);

inline Node* makeRoot(int v) {
 auto root = getRoot(v);
 return rotate(root.fst, root.snd);
inline Node* makeEdge(int v, int u) {
  Node* e = new Node(Edge(v, u));
  edges[v].insert(mp(u, e));
  return e;
```

```
39 Hamilton Cycle
// DP in O(n*2^n) for Ham cycle
vi g[MASK];
int adj[MASK], dp[1 << MASK];</pre>
vi hamiltonCycle(int n) {
 fill(dp, dp + (1 << n), 0);
  forn (v, n) {
   adj[v] = 0;
   for (int to : g[v])
      adj[v] |= (1 << to);
  dp[1] = 1;
 forn (mask, (1 << n))
   forn(v, n)
      if (mask & (1 << v) && dp[mask \hat{} (1 << v)] & adj[v])
        dp[mask] = (1 << v);
  vi ans:
  int mask = (1 << n) - 1, v;
  if (dp[mask] & adj[0]) {
   forab (i, 1, n)
     if ((1 << i) & (mask & adj[0]))
       v = i;
    ans.pb(v);
   mask ^= (1 << v);
    while(v) {
     forn(i, n)
        if ((dp[mask] & (1 << i)) && (adj[i] & (1 << v))) {
          v = i:
          break:
       }
      mask ^= (1 << v);
      ans.pb(v);
 }
 return ans;
}
40 Karp with cycle
int d[N][N], p[N][N];
vi g[N], ans;
struct Edge {
 int a, b, w;
  Edge(int _a, int _b, int _w): a(_a), b(_b), w(_w) {}
};
vector<Edge> edges;
void fordBellman(int s, int n) {
 forn (i, n + 1)
    forn (j, n + 1)
     d[i][j] = INF;
  d[0][s] = 0;
  forab (i, 1, n + 1)
   for (auto &e : edges)
      if (d[i-1][e.a] < INF && d[i][e.b] > d[i-1][e.a] + e.w)
        d[i][e.b] = d[i - 1][e.a] + e.w, p[i][e.b] = e.a;
}
ld karp(int n) {
 int s = n++;
 forn (i, n - 1)
    g[s].pb(sz(edges)), edges.pb(Edge(s, i, 0));
  fordBellman(s, n);
 ld ansValue = INF;
  int curV = -1, dist = -1;
 forn (v, n - 1)
    if (d[n][v] != INF) {
     ld curAns = -INF;
      int curPos = -1:
      forn(k, n)
```

```
if (curAns \le (d[n][v] - d[k][v]) * (ld) (1) / (n - k))
                                                                      void ae(int u, int v) {
          curAns = (d[n][v] - d[k][v]) * (ld) (1) / (n - k),
                                                                        adj[u].pb(v);
                                                                        adj[v].pb(u);

    curPos = k;

      if (ansValue > curAns)
        ansValue = curAns, dist = curPos, curV = v;
                                                                      queue<int> q;
 if (curV == -1) return ansValue;
                                                                      int par[SZ], vis[SZ], orig[SZ], aux[SZ];
  for (int iter = n; iter != dist; iter--)
   ans.pb(curV), curV = p[iter][curV];
                                                                      void augment(int u, int v) { // toggle edges on u-v path
                                                                        while (1) { // one more matched pair
 reverse(all(ans));
 return ansValue;
                                                                           int pv = par[v], nv = match[pv];
                                                                          match[v] = pv; match[pv] = v;
                                                                          v = nv; if (u == pv) return;
                                                                        }
    Kuhn's algorithm
// sz(LEFT) = n, sz(RIGHT) = m
                                                                      int lca(int u, int v) { // find LCA of supernodes in O(dist)
// numbered consequently
                                                                        static int t = 0;
int n, m, paired[2 * N], used[2 * N];
                                                                        for (++t;;swap(u,v)) {
vi g[N];
                                                                           if (!u) continue;
                                                                           if (aux[u] == t) return u; // found LCA
bool dfs(int v) {
                                                                          aux[u] = t; u = orig[par[match[u]]];
  if (used[v]) return false;
 used[v] = 1;
                                                                      }
 for (int to : g[v])
    if (paired[to] == -1 || dfs(paired[to])) {
     paired[to] = v, paired[v] = to;
                                                                      void blossom(int u, int v, int a) { // go other way
                                                                        for (; orig[u] != a; u = par[v]) { // around cycle
      return true;
                                                                          par[u] = v; v = match[u]; // treat u as if vis[u] = 1
   }
                                                                           if (vis[v] == 1) vis[v] = 0, q.push(v);
 return false;
                                                                           orig[u] = orig[v] = a; // merge into supernode
                                                                        }
int kuhn() {
 int ans = 0:
                                                                      bool bfs(int u) { // u is initially unmatched
  forn (i, n + m) paired[i] = -1;
 for (int run = 1; run;) {
                                                                        forn (i,N+1)
                                                                          par[i] = 0, vis[i] = -1, orig[i] = i;
   run = 0;
                                                                        q = queue<int>();
   fill(used, used + n + m, 0);
                                                                        vis[u] = 0;
   forn(i, n)
                                                                        q.push(u);
      if (!used[i] && paired[i] == -1 && dfs(i))
                                                                         while (sz(q)) { // each node is pushed to q at most once
        ans++, run = 1;
 }
                                                                          int v = q.front(); q.pop(); // 0 -> unmatched vertex
                                                                          for (int x : adj[v]) {
 return ans;
                                                                            if (vis[x] == -1) { // neither of x, match[x] visited
                                                                              vis[x] = 1; par[x] = v;
                                                                              if (!match[x])
// Start from unpaired vertex in Left part, go from Left anywhere,
                                                                                return augment(u,x),1;
// Max Independent -- A+, B-
                                                                              vis[match[x]] = 0;
                -- A-, B+
                                                                              q.push(match[x]);
// Min Cover
                                                                            } else if (vis[x] == 0 && orig[v] != orig[x]) {
                                                                              int a = lca(orig[v],orig[x]); // odd cycle
vi minCover, maxIndependent;
                                                                              blossom(x,v,a), blossom(v,x,a);
                                                                            } // contract O(n) times
void dfsCoverIndependent(int v) {
 if (used[v]) return;
                                                                          }
                                                                        }
 used[v] = 1;
 for (int to : g[v])
                                                                         return 0;
    if (!used[to])
      used[to] = 1, dfsCoverIndependent(paired[to]);
                                                                      int calc(int _N) { // rand matching -> constant improvement
                                                                        N = N;
                                                                        forn (i, N+1)
// Kuhn first!
                                                                          match[i] = aux[i] = 0;
void findCoverIndependent() {
                                                                         int ans = 0; vi V(N); iota(all(V),1); shuffle(all(V),rng); //
 fill(used, used + n + m, 0);
                                                                     \hookrightarrow find rand matching
  forn (i, n)
   if (paired[i] == -1)
                                                                        for (int x : V) {
     dfsCoverIndependent(i);
                                                                          if (!match[x]) {
                                                                            for (int y : adj[x]) {
  forn (i, n)
                                                                              if (!match[y]) {
    if (used[i]) maxIndependent.pb(i);
                                                                                match[x] = y, match[y] = x; ++ans;
    else minCover.pb(i);
                                                                                break;
  forab (i, n, n + m)
    if (used[i]) minCover.pb(i);
                                                                              }
                                                                            }
    else maxIndependent.pb(i);
                                                                          }
                                                                        }
                                                                        forab (i, 1, N+1)
42 Blossom algorithm
                                                                           if (!match[i] && bfs(i))
mt19937 rng(239017);
                                                                            ++ans:
                                                                         return ans:
```

}

};

```
template<int SZ> struct UnweightedMatch {
 int match[SZ], N;
 vi adj[SZ];
```

```
43 LCA
int tin[N], tout[N], up[N][LOG], curTime = 0;;
vi g[N];
void dfs(int v, int p) {
 up[v][0] = p;
 forn (i, LOG - 1)
   up[v][i + 1] = up[up[v][i]][i];
  tin[v] = curTime++;
 for (int u : g[v])
   if (u != p)
     dfs(u, v);
 tout[v] = curTime++;
int isUpper(int v, int u) {
 return tin[v] <= tin[u] && tout[v] >= tout[u];
int lca(int v, int u) {
 if (isUpper(u, v)) return u;
 fornr (i, LOG)
   if (!isUpper(up[u][i], v))
     u = up[u][i];
 return up[u][0];
void init() {
 dfs(0, 0);
    LCA offline (Tarjan)
vi g[N], q[N];
int pr[N], ancestor[N], used[N];
int get(int v) {
 return v == pr[v] ? v : pr[v] = get(pr[v]);
```

```
vi g[N], q[N];
int pr[N], ancestor[N], used[N];

int get(int v) {
    return v == pr[v] ? v : pr[v] = get(pr[v]);
}

void unite(int v, int u, int anc) {
    v = get(v), u = get(u);
    pr[u] = v, ancestor[v] = anc;
}

void dfs(int v) {
    used[v] = 1;
    for (int u : g[v])
        if (!used[u])
            dfs(u), unite(v, u, v);
    for (int u : q[v])
        if (used[u])
            ancestor[get(u)]; // handle answer somehow
}

void init(int n) {
    forn (i, n) pr[i] = i, ancestor[i] = i;
    dfs(0);
}
```

45 2 Chinese

```
e[i] = \{-1, -1, -1, -1\};
            e[i] = *min_element(graph[i].begin(),
   graph[i].end());
   vector<vi> cycles;
    used[0] = -2;
   forn (s, n) {
       if (used[s] != -1)
           continue;
       int x = s;
        while (used[x] == -1) {
           used[x] = s;
            x = e[x].fr;
       }
       if (used[x] != s)
            continue:
        vi cycle = {x};
       for (int y = e[x].fr; y != x; y = e[y].fr)
            cycle.push_back(y), color[y] = x;
        cycles.push_back(cycle);
   }
    if (cycles.empty())
       return e:
    vector<vector<Edge>> next_graph(n);
   forn (s, n) \{
        for (const Edge& edge : graph[s]) {
            if (color[edge.fr] != color[s])
                next_graph[color[s]].push_back({
                    color[edge.fr], color[s], edge.w - e[s].w,
\hookrightarrow edge.id
                });
        }
   }
   vector<Edge> tree = work(next_graph);
    for (const auto& cycle : cycles) {
       int cl = color[cycle[0]];
       Edge next_out = tree[cl], out{};
       int from = -1;
       for (int v : cycle) {
            tree[v] = e[v];
            for (const Edge& edge : graph[v])
                if (edge.id == next_out.id)
                    from = v, out = edge;
        tree[from] = out;
   }
    return tree;
```

46 Matroid Intersection

```
struct Gmat { // graphic matroid
  int V = 0; vector<pii> ed; vi par;
  Gmat(vector<pii> _ed):ed(_ed) {
    map<int,int> m;
    for(auto &t : ed) m[t.fst] = m[t.snd] = 0;
    for(auto &t : m) t.snd = V++;
    for(auto &t : ed) t.fst = m[t.fst], t.snd = m[t.snd];
  int p(int v) {
   return par[v] == v ? v : par[v] = p(par[v]);
  bool unite(int v, int u) {
    v = p(v), u = p(u);
    if (v != u) { par[v] = u; return true; }
    return false;
  void clear() {
   par.resize(V);
    forn(i,V) par[i] = i;
  void ins(int i) { assert(unite(ed[i].fst,ed[i].snd)); }
  bool indep(int i) { return p(ed[i].fst) != p(ed[i].snd); }
}:
struct Cmat { // colorful matroid
  int C = 0; vi col; vi used;
  Cmat(vi \_col):col(\_col) \{for(auto t : col) C = max(C, t+1);\}
  void clear() { used.assign(C,0); }
```

int y = discreteLogarithm(power(g, k, mod), a, mod);

```
void ins(int i) { used[col[i]] = 1; }
  bool indep(int i) { return !used[col[i]]; }
template<class M1, class M2> struct MatroidIsect {
  int n; vi iset; M1 m1; M2 m2;
  bool augment() {
    vi pre(n+1,-1); queue<int> q({n});
    while (sz(q)) {
      int x = q.front(); q.pop();
      if (iset[x]) {
        m1.clear(); forn(i,n) if (iset[i] && i != x) m1.ins(i);
        forn(i,n) if (!iset[i] \&\& pre[i] == -1 \&\& m1.indep(i))
           pre[i] = x, q.push(i);
      } else {
        auto backE = [&]() { // back edge
          m2.clear();
          forn(c,2)forn(i,n)
\ \hookrightarrow \ \ \text{if}((x==i \mid | \texttt{iset}[i]) \&\&(\texttt{pre}[i]==-1)==c)\{
            if (!m2.indep(i))return c?pre[i]=x,q.push(i),i:-1;
             m2.ins(i); }
          return n:
        };
        for (int y; (y = backE()) != -1;) if (y == n) {
          for(; x != n; x = pre[x]) iset[x] = !iset[x];
           return 1: }
    }
    return 0;
  }
  {\tt MatroidIsect(int \_n, \ M1 \_m1, \ M2 \_m2):n(\_n), \ m1(\_m1), \ m2(\_m2) \ \{}
    iset.assign(n+1,0); iset[n] = 1;
    m1.clear(); m2.clear(); // greedily add to basis
    fornr(i,n) if (m1.indep(i) && m2.indep(i))
      iset[i] = 1, m1.ins(i), m2.ins(i);
    while (augment());
  }
};
```

9 Math

47 CRT (**KTO**)

```
vi crt(vi a, vi mod) {
  int n = sz(a);
  vi x(n);
  forn (i, n) {
    x[i] = a[i];
    forn (j, i) {
        x[i] = inverse(mod[j], mod[i]) * (x[i] - x[j]) % mod[i];
        if (x[i] < 0) x[i] += mod[i];
    }
  }
  return x;
}</pre>
```

48 Discrete Logarithm

```
// Returns x: a^x = b \pmod{mod} or -1, if no such x exists
int discreteLogarithm(int a, int b, int mod) {
 int sq = (int) sqrt(mod);
 int sq2 = mod / sq + (mod % sq ? 1 : 0);
 vector<pii> powers(sq2);
 forn (i, sq2)
   powers[i] = mp(power(a, (i + 1) * sq, mod), i + 1);
 sort(all(powers));
 forn (i, sq + 1) {
   int cur = power(a, i, mod);
   cur = mul(cur, b, mod);
   auto it = lower_bound(all(powers), mp(cur, 0));
   if (it != powers.end() && it->fst == cur)
     return it->snd * sq - i;
 }
 return -1;
```

49 Discrete Root

```
// Returns x: x \sim k = a \mod mod, mod is prime int discreteRoot(int a, int k, int mod) {
```

```
50 Eratosthenes
```

int g = primitiveRoot(mod);

return power(g, y, mod);

if (a == 0)

return 0;

```
vi eratosthenes(int n) {
 vi minDiv(n + 1, 0);
 minDiv[1] = 1;
 forab (i, 2, n + 1)
   if (minDiv[i] == 0)
     for (int j = i; j \le n; j += i)
       if (minDiv[j] == 0) minDiv[j] = i;
 return minDiv:
vi eratosthenesLinear(int n) {
 vi minDiv(n + 1, 0), primes;
 minDiv[1] = 1;
 forab (i, 2, n + 1) {
   if (minDiv[i] == 0)
     minDiv[i] = i, primes.pb(i);
   for (int j = 0; j < sz(primes) && primes[j] <= minDiv[i] && i
   * primes[j] <= n; j++)
     minDiv[i * primes[j]] = primes[j];
 }
 return minDiv;
```

51 Factorial

```
// Returns pair (rem, power), where rem = n! % mod,
// power = k: mod % | n!, mod is prime, O(mod log mod)
pii fact(int n, int mod) {
   int rem = 1, power = 0, nCopy = n;
   while (nCopy) nCopy /= mod, power += nCopy;
   while (n > 1) {
      rem = (rem * ((n / mod) % 2 ? -1 : 1) + mod) % mod;
      for (int i = 2; i <= n % mod; i++)
        rem = mul(rem, i, mod);
      n /= mod;
   }
   return mp(rem % mod, power);
}</pre>
```

52 Gauss

```
const double EPS = 1e-9;
int gauss(double **a, int n, int m) { // n is number of equations,

→ m is number of variables

 int row = 0, col = 0;
 vi par(m, -1);
 vector<double> ans(m, 0);
 for (col = 0; col < m && row < n; col++) {
   int best = row;
   for (int i = row; i < n; i++)
     if (abs(a[i][col]) > abs(a[best][col]))
       best = i;
   if (abs(a[best][col]) < EPS) continue;</pre>
   par[col] = row;
   forn (i, m + 1) swap(a[row][i], a[best][i]);
   forn (i, n)
     if (i != row) {
        double k = a[i][col] / a[row][col];
       for (int j = col; j <= m; j++)
          a[i][j] -= k * a[row][j];
     }
   row++;
 }
 int single = 1;
   if (par[i] != -1) ans[i] = a[par[i]][m] / a[par[i]][i];
    else single = 0;
 forn (i, n) \{
   double cur = 0;
   for (int j = 0; j < m; j++)
```

```
cur += ans[j] * a[i][j];
    if (abs(cur - a[i][m]) > EPS)
      return 0;
 if (!single)
   return 2;
  return 1;
     Gauss binary
const int MAX = 1024;
int gaussBinary(vector<bitset<MAX>> a, int n, int m) {
 int row = 0, col = 0;
  vi par(m, -1);
  for (col = 0; col < m && row < n; col++) {
    int best = row;
    for (int i = row; i < n; i++)</pre>
      if (a[i][col] > a[best][col])
       best = i;
    if (a[best][col] == 0)
      continue;
    par[col] = row;
    swap(a[row], a[best]);
    forn (i, n)
      if (i != row && a[i][col])
       a[i] ^= a[row];
  }
  vi ans(m, 0);
  forn (i, m)
    if (par[i] != -1)
      ans[i] = a[par[i]][n] / a[par[i]][i];
  bool ok = 1;
  forn (i, n) {
    int cur = 0;
    forn (j, m) cur ^= (ans[j] & a[i][j]);
    if (cur != a[i][n]) ok = 0;
  return ok:
54
    Gcd
int gcd(int a, int b) {
 return b ? gcd(b, a % b) : a;
int gcd(int a, int b, int &x, int &y) {
  if (b == 0) {
   x = 1, y = 0;
   return a;
 int g = gcd(b, a \% b, x, y), newX = y;
 y = x - a / b * y;
  x = newX:
  return g;
void diophant(int a, int b, int c, int &x, int &y) {
  int g = gcd(a, b, x, y);
  if (c % g != 0) return;
  x *= c / g, y *= c / g;
  // next solutions: x += b / g, y -= a / g
int inverse(int a, int mod) { // Returns -1, if a and mod are not
\hookrightarrow coprime
 int x, y;
  int g = gcd(a, mod, x, y);
  return g == 1 ? (x % mod + mod) % mod : -1;
vi inverseForAll(int mod) {
  vi r(mod, 0);
  r[1] = 1;
  for (int i = 2; i < mod; i++)
    r[i] = (mod - r[mod \% i]) * (mod / i) \% mod;
```

```
return r:
55 Gray
int gray(int n) {
 return n ^ (n >> 1);
int revGray(int n) {
 int k = 0;
 for (; n; n >>= 1) k ^= n;
  return k;
     Miller-Rabin Test
56
bool isPrimeMillerRabin(ull n) { // not ll!
  if (n < 2 | | n % 6 % 4 != 1)
   return n - 2 < 2;
  ull A[] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022};
           _builtin_ctzll(n - 1), d = n >> s;
  ull s =
 for (ull a : A) { // ^ count trailing zeroes
   ull p = power(a, d, n), i = s;
   while (p != 1 && p != n - 1 && a % n && i--)
     p = mul(p, p, n);
   if (p != n - 1 && i != s) return 0;
 }
 return 1:
57 Phi
int phi(int n) {
 int result = n;
  for (int i = 2; i * i <= n; i++)
   if (n % i == 0) {
     while (n \% i == 0) n /= i;
      result -= result / i;
  if (n > 1) result -= result / n;
  return result;
int inversePhi(int a, int mod) {
 return power(a, phi(mod) - 1, mod);
58 Pollard
ull pollard(ull n) { // return some nontrivial factor of n
  auto f = [n](ull x) \{ return mul(x, x, n) + 1; \};
  ull x = 0, y = 0, t = 30, prd = 2, i = 1, q;
  while (t++ \% 40 || __gcd(prd, n) == 1) { /// speedup: don't take
\hookrightarrow gcd every it
    if (x == y) x = ++i, y = f(x);
   if ((q = mul(prd, max(x, y) - min(x, y), n))) prd = q;
   x = f(x), y = f(f(y));
 }
 return __gcd(prd, n);
void factorize(ull n, map<ull,int>& cnt) {
 if (n == 1) return;
  if (isPrimeMillerRabin(n)) {
   ++cnt[n]:
   return;
 7
 ull u = pollard(n);
  factorize(u, cnt), factorize(n / u, cnt);
59 Power And Mul
template <tvpename T>
inline T add(T a, T b, T mod) {
 a += b;
  return a >= mod ? a - mod : a;
```

}

```
template <typename T>
inline T sub(T a, T b, T mod) {
 a -= b;
 return a < 0 ? a + mod : a;
template <typename T>
T mul(T a, T b, T mod) {
 return T((a * 111 * b) % mod);
template <>
11 mul<11>(11 a, 11 b, 11 mod) {
 11 q = 11((1d) a * b / mod);
 11 r = a * b - mod * q;
  while (r < 0) r += mod;
 while (r >= mod) r -= mod;
 return r;
template <typename T>
T power(T a, T n, T mod) {
 if (!n) return 1;
 T b = power(a, n / 2, mod);
 b = mul(b, b, mod);
 return n & 1 ? mul<T>(a, b, mod) : b;
int powerFast(int a, int n, int mod) {
  int res = 1;
  while (n) {
   if (n & 1)
    res = mul(res, a, mod);
    a = mul(a, a, mod);
   n /= 2;
 }
 return res;
```

60 Primitive Root

```
int primitiveRoot(int mod) { // Returns -1 if no primitive root
\hookrightarrow exists
 vi fact:
 int ph = phi(mod);
 int n = mod;
 for (int i = 2; i * i <= n; i++) {
   if (n % i == 0) {
     fact.pb(i);
      while (n \% i == 0) n /= i;
 }
 if (n > 1) fact.pb(n);
 forab (i, 2, mod + 1) {
   bool ok = 1;
   for (int j = 0; j < sz(fact) && ok; j++)
     ok &= power(i, ph / fact[j], mod) != 1;
   if (ok) return i;
 }
 return -1;
```

61 Simpson

62 Euclidean Burunduk-1

```
**
* Sergey Kopeliovich (burunduk30@gmail.com)
```

```
#include <iostream>
using namespace std;
// finds x:
     a+k*x \mod m --> min, 0 \le x \le r (0 \le a, k \le m, 0 \le r)
      +k costs pk, -m costs pm
     return r-x
//
int go(int a, int k, int m, int pk, int pm, int r) {
 if (!k) return r;
  if (a >= k) \{ // make a: 0 <= a < k \}
   int add = (m - a + k - 1) / k;
   if ((int64_t)add * pk + pm > r) return r;
   a += (int64_t)add * k - m, r -= add * pk + pm;
 int m1 = m \% k, pm1 = (m / k) * pk + pm;
 if (!m1) return r;
  int k1 = k \% m1, pk1 = (k / m1) * pm1 + pk;
 if (pm1 * (a / m1) > r) return r \% pm1;
  return go(a % m1, k1, m1, pk1, pm1, r - (a / m1) * pm1);
// finds x: a+k*x \mod m --> min, 0 <= a, k < m, 0 <= r
int go(int a, int k, int m, int r) {
 return r - go(a, k, m, 1, 0, r);
int main() {
  ios_base::sync_with_stdio(false), cin.tie(0);
 int a, k, m, r;
 while (cin >> a >> k >> m >> r) {
   int x = go(a, k, m, r);
   cout << ((int64_t)x * k + a) % m << ' ' << x << '\n';
}
```

63 Euclidean Burunduk-2

```
* Sergey Kopeliovich (burunduk30@gmail.com)
#include <iostream>
using namespace std;
// finds min x:
//
    a+k*x \mod m \setminus in [l..r]
      +k costs pk, -m costs pm
    l \ll r \ll a, first tries -m then +k
int go(int a, int k, int m, int pk, int pm, int l, int r) {
  int ans = 0, steps;
  while (1) {
    steps = (a - r + m - 1) / m;
    ans += steps * pm, a -= steps * m;
    if (1 <= a) return ans;</pre>
    if (!k) return -1;
    steps = (1 - a + k - 1) / k;
    ans += steps * pk, a += steps * k;
    if (a <= r) return ans;</pre>
    int m1 = m \% k, pm1 = (m / k) * pk + pm;
    if (!m1) return -1;
    int k1 = k \% m1, pk1 = (k / m1) * pm1 + pk;
    k = k1, m = m1, pk = pk1, pm = pm1; // recursion =)
}
int go(int a, int k, int m, int l, int r) {
 if (a < r)
    a += ((r - a) / m + 1) * m;
 return go(a, k, m, 1, 0, 1, r);
}
int main() {
  ios_base::sync_with_stdio(false), cin.tie(0);
  int a, k, m, l, r;
```

```
while (cin >> a >> k >> m >> 1 >> r)
    cout << go(a, k, m, 1, r) << '\n';
}</pre>
```

10 Strings

64 Aho-Corasick

```
struct Node {
  int next[ALPHA], term; //
  int go[ALPHA], suf, p, pCh; //
  Node(): term(0), suf(-1), p(-1) {
   fill(next, next + ALPHA, -1);
    fill(go, go + ALPHA, -1);
 }
Node g[N];
int last:
void add(const string &s) {
 int now = 0;
  for(char x : s) {
   if (g[now].next[x - 'a'] == -1) {
      g[now].next[x - 'a'] = ++last;
      g[last].p = now, g[last].pCh = x;
   now = g[now].next[x - 'a'];
 g[now].term = 1;
int go(int v, int c);
int getLink(int v) {
  if (g[v].suf == -1) {
   if (!v || !g[v].p) g[v].suf = 0;
    else g[v].suf = go(getLink(g[v].p), g[v].pCh);
 return g[v].suf;
int go(int v, int c) {
 if (g[v].go[c] == -1) {
   if (g[v].next[c] != -1) g[v].go[c] = g[v].next[c];
    else g[v].go[c] = !v ? 0 : go(getLink(v), c);
 return g[v].go[c];
```

65 Prefix-function

```
vi prefix(const string &s) {
  int n = sz(s);
  vi pr(n);
  forab (i, 1, n + 1) {
    int j = pr[i - 1];
    while (j > 0 && s[i] != s[j]) j = pr[j - 1];
    if (s[i] == s[j]) j++;
    pr[i] = j;
  }
  return pr;
}
```

66 Z-function

```
vi z(const string% s) {
   int n = sz(s);
   vi z(n);
   for (int i = 1, 1 = 0, r = 0; i < n; i++) {
      if (i <= r) z[i] = min(r - i + 1, z[i - 1]);
      while (i + z[i] < n && s[z[i]] == s[i + z[i]]) z[i]++;
      if (i + z[i] - 1 > r) 1 = i, r = i + z[i] - 1;
   }
   return z;
}
```

67 Hashes

```
#include "../math/PowerAndMul.cpp"
const int P = 239017, MOD_X = 1e9 + 7, MOD_Y = 1e9 + 9;
// using H = unsigned long long;
struct H {
 int x, y;
 H() = default;
  H(int _x): x(_x), y(_x) {}
 H(int _x, int _y): x(_x), y(_y) {}
 inline H operator+(const H& h) const { return H(add(x, h.x,

    MOD_X), add(y, h.y, MOD_Y)); }

 inline H operator-(const H& h) const { return H(sub(x, h.x,

    MOD_X), sub(y, h.y, MOD_Y)); }

 inline H operator*(const H& h) const { return H(mul(x, h.x,

    MOD_X), mul(y, h.y, MOD_Y)); }

 inline bool operator == (const H& h) const { return x == h.x && y
\hookrightarrow == h.y; }
};
H p[N], h[N];
inline H get(int 1, int r) { return h[r] - h[1] * p[r - 1]; }
void init(const string& s) {
 int n = sz(s);
  p[0] = 1;
 forn (i, n)
    h[i + 1] = h[i] * P + s[i], p[i + 1] = p[i] * P;
```

68 Manaker

```
void manaker(const string& s, int *z0, int *z1) {
 int n = sz(s);
  forn (t, 2) {
    int *z = t ? z1 : z0, 1 = -1, r = -1; // [l...r]
    forn (i, n - t) {
     int k = 0;
      if (r > i + t) {
       int j = 1 + (r - i - t);
        k = min(z[j], j - 1);
      while (i - k) = 0 \&\& i + k + t < n \&\& s[i - k] == s[i + k + t]
\hookrightarrow t])
       k++:
      z[i] = k;
      if (k && i + k + t > r)
        1 = i - k + 1, r = i + k + t - 1;
    }
  }
}
```

69 Palindromic Tree

```
struct Vertex {
  int suf, len, next[ALPHA];
  Vertex() { fill(next, next + ALPHA, 0); }
};
int vn, v;
Vertex t[N + 2];
int n, s[N];
int get(int i) { return i < 0 ? -1 : s[i]; }</pre>
void init() {
 t[0].len = -1, vn = 2, v = 0, n = 0;
}
void add(int ch) {
 s[n++] = ch;
  while (v != 0 && ch != get(n - t[v].len - 2))
    v = t[v].suf;
  int& r = t[v].next[ch];
  if (!r) {
   t[vn].len = t[v].len + 2;
    if (!v) t[vn].suf = 1;
    else {
```

```
SPb HSE (Bogomolov, Labutin, Podguzov)
      v = t[v].suf;
      while (v != 0 && ch != get(n - t[v].len - 2))
        v = t[v].suf;
      t[vn].suf = t[v].next[ch];
   r = vn++;
 }
  v = r;
     Suffix Array (+stable)
int sLen, num[N + 1], p[N], col[N], inv[N], lcp[N];
char s[N + 1];
inline int add(int a, int b) {
 a += b;
  return a >= sLen ? a - sLen : a;
inline int sub(int a, int b) {
 a -= b;
 return a < 0 ? a + sLen : a;
void buildArray(int n) {
  sLen = n;
  int ma = max(n, 256);
  forn (i, n)
    col[i] = s[i], p[i] = i;
  for (int k2 = 1; k2 / 2 < n; k2 *= 2) {
    int k = k2 / 2;
    memset(num, 0, sizeof(num));
    forn (i, n) num[col[i] + 1]++;
    forn (i, ma) num[i + 1] += num[i];
    forn (i. n)
     inv[num[col[sub(p[i], k)]]++] = sub(p[i], k);
    int cc = 0;
    forn (i, n) {
      bool flag = col[inv[i]] != col[inv[i - 1]];
     flag |= col[add(inv[i], k)] != col[add(inv[i - 1], k)];
      if (i && flag) cc++;
     num[inv[i]] = cc;
   forn (i, n) p[i] = inv[i], col[i] = num[i];
  memset(num, 0, sizeof(num));
  forn (i, n) num[col[i] + 1]++;
  forn (i, ma) num[i + 1] += num[i];
  forn (i, n) inv[num[col[i]]++] = i;
 forn (i, n) p[i] = inv[i];
  forn (i, n) inv[p[i]] = i;
void buildLCP(int n) {
  int len = 0:
  forn (ind, n){
    int i = inv[ind];
    len = max(0, len - 1);
    if (i != n - 1)
     while (len < n && s[add(p[i], len)] == s[add(p[i + 1], len)]
\rightarrow len)])
        len++;
    lcp[i] = len;
    if (i != n - 1 && p[i + 1] == n - 1) len = 0;
71 Suffix Automaton
struct Vx {
   int len, suf;
    int next[ALPHA];
    Vx() {}
    Vx(int 1, int s): len(1), suf(s) {}
};
```

```
struct SA {
```

```
static const int V = 2 * LEN;
    int last, vcnt;
    Vx v[V];
   SA() { vcnt = 1, last = newV(0, 0); } // root = vertex with
   int newV(int len, int suf){
        v[vcnt] = Vx(len, suf);
        return vcnt++;
    int add(char ch) {
        int p = last, c = ch - 'a';
        last = newV(v[last].len + 1, 0);
        while (p && !v[p].next[c]) // added p &&
            v[p].next[c] = last, p = v[p].suf;
        if (!p)
           v[last].suf = 1;
        else {
            int q = v[p].next[c];
            if (v[q].len == v[p].len + 1) v[last].suf = q;
                int r = newV(v[p].len + 1, v[q].suf);
                v[last].suf = v[q].suf = r;
                memcpy(v[r].next, v[q].next, sizeof(v[r].next));
                while (p \&\& v[p].next[c] == q)
                    v[p].next[c] = r, p = v[p].suf;
            }
       }
        return last;
   }
};
```

72 Suffix Tree

```
char S[N]:
int L;
struct Node:
struct Pos:
typedef Node *pNode;
typedef map<char,pNode> mapt;
struct Node{
  pNode P, link;
  int L. R:
  mapt next;
  Node(): P(NULL), link(this), L(0), R(0) {}
  Node(pNode P_, int L_, int R_): P(P_), link(NULL), L(L_), R(R_)
 inline int elen() const { return R - L; }
 inline pNode addEdge(int L_, int R_) { return next[S[L_]] = new
\,\hookrightarrow\,\,\text{Node(this, L\_, R\_); }\}
};
struct Pos{
 pNode V;
  int up;
  Pos(): V(NULL), up(0) {}
  Pos(pNode V_, int up_): V(V_), up(up_) {}
  pNode splitEdge() const {
   if(!up)
     return V;
    int L_ = V->L, M = V->R - up;
    pNode P = V->P, n = new Node(P, L_, M);
    P->next[S[L_]] = n;
    n->next[S[M]] = V;
    V->P = n, V->L = M;
    return n;
  Pos nextChar(char c) const {
    if(up)
      return S[V->R - up] == c ? Pos(V, up - 1) : Pos();
    else{
      mapt::iterator it = V->next.find(c);
      return it == V->next.end() ? Pos() : Pos(it->snd,
\rightarrow it->snd->elen() - 1);
    }
```

```
Pos goDown(pNode V, int L_, int R_) {
  if(L == R)
    return Pos(V, 0);
  while (1) {
    V = V - \text{next}[S[L_]];
    L_ += V->elen();
    if(L_ >= R_)
      return Pos(V, L_ - R_);
inline pNode calcLink(pNode &V) {
  if (!V->link)
    V->link = goDown(V->P->link, V->L + !V->P->P,
\hookrightarrow V->R).splitEdge();
 return V->link;
Pos addChar(Pos P, int k) {
  while(1) {
    Pos p = P.nextChar(S[k]);
    if (p.V)
     return p;
    pNode n = P.splitEdge();
    n->addEdge(k, LEN);
    if (!n->P)
     return Pos(n, 0);
    P = Pos(calcLink(n), 0);
}
pNode Root:
void make_tree(){
  Root = new Node();
  Pos P(Root, 0);
  forn (i, L)
    P = addChar(P, i);
```

11 C++ Tricks

73 Fast allocation

```
const int MEM = 100 << 20;
static char buf[MEM];
inline void* operator new(size_t n) {
   static size_t i = sizeof buf;
   assert(n < i);
   return (void*) &buf[i -= n];
}
inline void operator delete(void*) {}
inline void* operator new[](size_t) { assert(0); }
inline void operator delete[](void*) { assert(0); }</pre>
```

74 Hash of pair

75 Ordered Set

```
assert(s.order_of_key(3) == 1 && s.order_of_key(4) == 2 && 

→ *s.find_by_order(0) == 1);
```

76 Hash Map

77 Fast I/O

template <class T>

```
const int BUF SIZE = 4096;
char buf[BUF_SIZE];
int bufLen = 0, pos = 0;
inline int getChar() {
  if (pos == bufLen) {
   pos = 0, bufLen = (int) fread(buf, 1, BUF_SIZE, stdin);
   if (!bufLen)
     return -1:
 return buf[pos++];;
inline int readChar() {
 int c = getChar();
 while (c !=-1 \&\& c <= 32)
   c = getChar();
 return c:
template <class T>
inline T readInt() {
 int s = 1, c = readChar();
 T x = 0;
 if (c == '-')
   s = -1, c = getChar();
 while ('0' <= c && c <= '9')
   x = x * 10 + c - '0', c = getChar();
 return s == 1 ? x : -x;
inline void readWord(char *s) {
 int c = readChar();
  while (c > 32)
   *s++ = (char) c, c = getChar();
  *s = 0;
}
int writePos = 0;
char writeBuf[BUF_SIZE];
inline void flush() {
  if (writePos)
    fwrite(writeBuf, 1, writePos, stdout), writePos = 0;
inline void writeChar(int x) {
 if (writePos == BUF_SIZE)
   flush():
  writeBuf[writePos++] = (char) x;
```

```
inline void writeInt(T x, char after = '\0') {
    if (x < 0)
        writeChar('-'), x = -x;

    char s[24];
    int n = 0;
    while (x || !n)
        s[n++] = '0' + x % 10, x /= 10;
    while (n--)
        writeChar(s[n]);
    if (after)
        writeChar(after);
}

inline void writeWord(const char *s) {
    while (*s)
        writeChar(*s++);
}</pre>
```

12 Notes

78 Работа с деревьями

Приемы для работы с деревьями:

- 1. Двоичные подъемы
- 2. Поддеревья как отрезки Эйлерова обхода
- 3. Вертикальные пути в Эйлеровом обходе (на ребрах вниз +k, на ребрах вверх -k).
- 4. Храним в вершине значение функции на пути от корня до нее, дальше LCA. **82**
- 5. Спуск с DFS, поддерживаем ДО на пути до текущей вершины.
- 6. Heavy-light decomposition
- 7. Centroid decomposition
- 8. Корневая по запросам
- 9. Тяжелые/легкие вершины
- 10. DFS \rightarrow дерево блоков, размеры $\in [K..2K]$
- 11. У вершины не более $O(\sqrt{N})$ разных поддеревьев
- 12. Сумма размеров поддеревьев без тяжелого ребенка $O(n \log n)$
- 13. Сумма глубин поддеревьев без глубокого ребенка O(n)

79 Маски

Считаем динамику по маскам за $O(2^n \cdot n)$ f[mask] = sum по submask g[submask].

dp[mask][i] — значение динамики для маски mask, если младшие i бит в ней зафиксированы (то есть мы не можем удалять оттуда).

Ответ в dp[mask][0].

dp[mask][len] = g[mask]. Если i-ый бит 0, то dp[mask][i] = dp[mask][i+1], иначе $dp[mask][i] = dp[mask][i+1] + dp[mask^{(1)} < i)[i+1]$.

Старший бит: предподсчет.

Младший бит: $x \& \sim (-x)$

Чтобы по степени двойки получить логарифм, можно воспользоваться тем, что все степени двойки имеют разный остаток по модулю 67.

```
for (int mask = 0; mask < (1 << n); mask++)
^^Isubmask : for (int s = mask; s; s = (s - 1) & mask)
^^Isupmask : for (int s = mask; s < (1 << n); s = (s + 1) | mask)</pre>
```

80 Гранди

Теорема Шпрага-Гранди: берем mex всех значений функции Гранди по состояниям, в которые можем перейти из данного.

Если сумма независимых игр, то значение функции Гранди равно хог значений функций Гранди по всем играм.

Бывает полезно вывести первые п значений и поискать закономерность.

Часто сводится к xor по чему-нибудь.

81 Потоки

Потоки:

Name	Asympthotic
Ford-Fulkerson	$O(f \cdot E)$
Ford-Fulkerson with scaling	$O(\log f \cdot E^2)$
Edmonds-Karp	$O(V \cdot E^2)$
Dinic	$O(V^2 \cdot E)$
Dinic with scaling	$O(V \cdot E \cdot \log C)$
Dinic on bipartite graph	$O(E\sqrt{V})$
Dinic on unit network	$O(E\sqrt{E})$

L—R потоки:

Есть граф с недостатками или избытками в каждой вершине. Создаем фиктивные исток и сток (из истока все ребра в избытки, из недостатков все ребра в сток).

Теперь пусть у нас есть L-R граф, для каждого ребра $e\ (v \to u)$ известны L_e и R_e . Добавим в v избыток L_e , в u недостаток L_e , а пропускную способность сделаем R_e-L_e .

Получили решение задачи о LR-циркуляции.

Если у нас обычный граф с истоком и стоком, то добавляем бесконечное ребро из стока в сток и ищем циркуляцию.

Таким образом нашли удовлетворяющий условиям LR-поток. Если хотим максимальный поток, то на остаточной сети запускаем поиск максимального потока.

В новом графе в прямую сторону пропускная способность равна R_e-f_e , в обратную f_e-L_e .

MinCostCirculation:

Пока есть цикл отрицательного веса, запускаем алгоритм Карпа и пускаем максимальный поток по найденному циклу.

82 ДП

Табличка с оптимизациями для динамики:

Name	Original recurrence	From
	Sufficient Condition	То
CHT1	$dp[i] = \min_{j < i} dp[j] + b[j] \cdot a[i]$	$O(n^2)$
	$ b[j] \geqslant b[j+1] \mid a[i] \leqslant a[i+1]$	O(n)
CHT2	$dp[i][j] = \min_{k < j} dp[i-1][k] + b[k] \cdot a[j]$	$O(kn^2)$
	$b[k] \geqslant b[k+1] \mid\mid a[j] \leqslant a[j+1]$	O(kn)
D&C	$dp[i][j] = \min_{k < j} dp[i-1][k] + c[k][j]$	$O(kn^2)$
	$p[i,j] \leqslant p[i,j+1]$	$O(kn\log n)$
Knuth	$dp[i][j] = \min_{i < k < j} dp[i][k] + dp[k][j] + c[i][j]$	$O(n^3)$
	$p[i, j-1] \leqslant p[i, j] \leqslant p[i+1, j]$	$O(n^2)$
IOI	$f_n(k)$ — best for fixed k	$O(k^{(2)}n)$
	f_n — convex, add penalty $\lambda \cdot k$	$O(n \log C)$

83 Комбинаторика

Биномиальные коэффициенты:

Теорема Люка для биномиальных коэффициентов: Хотим посчитать C_n^k , разложим в р-ичной системе счисления, $n=(n_0,n_1,\dots), k=(k_0,k_1,\dots).$ $ans=C_{n_0}^{k_0}\cdot C_{n_1}^{k_1}\cdot\dots$

Способы вычисления C_n^k :

$$\label{eq:continuous} \begin{split} 1. & \ C_n^k = C_{n-1}^k + C_{n-1}^{k-1} \\ & \ \text{precalc: } O(n^2) \text{, query: } O(1). \end{split}$$

2. $C_n^k = \frac{n!}{k!(n-k)!}$, предподсчитываем факториалы precale: $O(n\log n)$, query: $O(\log n)$

3. Теорема Люка

precalc: $O(p \log p)$, query: O(log p).

4.
$$C_n^k = C_n^{k-1} \cdot \frac{n-k+1}{k}$$

5. $C_n^k = \frac{n!}{k!(n-k)!}$, для каждого факториала считаем степень вхождения и остаток

precalc: $O(p \log p)$, query: O(log p)

$$C_n^{\frac{n}{2}} = \frac{2^n}{\sqrt{\frac{\pi n}{2}}}$$

84 Делители

• $\leq 20: d(12) = 6$

• $\leq 50 : d(48) = 10$

• $\leq 100 : d(60) = 12$

• $\leq 1000 : d(840) = 32$

 \bullet < 10⁴ : $d(9\ 240) = 64$

• $\leq 10^5 : d(83\ 160) = 128$

 \bullet < 10⁶ : d(720720) = 240

 $\bullet \le 10^7 : d(8\,648\,640) = 338$

 $\bullet \le 10^8 : d(91891800) = 768$

 \bullet < 10⁹ : $d(931\ 170\ 240) = 1344$

 $\bullet \le 10^{11} : d(97772875200) = 4032$

 $\bullet \ \leq 10^{12} : d(963\ 761\ 198\ 400) = 6720$

 \bullet < 10¹⁵ : $d(866\ 421\ 317\ 361\ 600) = 15360$

 $\bullet \ \leq 10^{18} : d(897\ 612\ 484\ 786\ 617\ 600) = 103680$

85 Числа Белла

i	B_i	i	B_i
0	1	12	4,213,597
1	1	13	27,644,437
2	2	14	190,899,322
3	5	15	1,382,958,545
4	15	16	10,480,142,147
5	52	17	82,864,869,804
6	203	18	682,076,806,159
7	877	19	5,832,742,205,057
8	4,140	20	51,724,158,235,372
9	21,147	21	474,869,816,156,751
10	115,975	22	4,506,715,738,447,323
11	678,570	23	44,152,005,855,084,346

86 Разбиения

Число неупорядоченных разбиений n на положительные слагаемые.

$$\begin{split} p(0) &= 1, \ p(n) = \sum_{k \in \mathbb{Z} \backslash \{0\}} (-1)^{k+1} p(n-k(3k-1)/2) \\ & p(n) \sim 0.145/n \cdot \exp(2.56\sqrt{n}) \\ & \frac{n}{p(n)} \begin{vmatrix} 0.1 & 2.3 & 4.5 & 6.7 & 8.9 & 20.50 & 100 \\ \hline 1.1 & 2.3 & 5.7 & 11.15 & 22.30 & 627 \sim 2e5 \sim 2e8 \\ \end{matrix} \end{split}$$

87 Матричные игры

Пишем матрицу стратегий $A_{i,j}$ это выигрыш первого и проигрыш второго, i стратегия 1-го. Седловая точка есть для несмешанной стратегии если $\max_i \min A_{i,*} = \min_i \max A_{*,j}$. Иначе:

$$f(x) = sum(x_i) \to max, \ Ans = 1/f(x)$$

$$Ax \le 1_n, \ x_i \ge 0$$

Для 2×2 , p первый игрок, q — второй:

$$p^* = \left(\frac{a_{22} - a_{21}}{a_{22} - a_{12} + a_{11} - a_{21}}; \frac{a_{11} - a_{12}}{a_{22} - a_{12} + a_{11} - a_{21}}\right)$$
$$q^* = \left(\frac{a_{22} - a_{12}}{a_{22} - a_{12} + a_{11} - a_{21}}; \frac{a_{11} - a_{21}}{a_{22} - a_{12} + a_{11} - a_{21}}\right)$$
$$Ans = \frac{a_{22}a_{11} - a_{12}a_{21}}{a_{11} + a_{22} - a_{12} - a_{21}}$$

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88 Mixed

- ullet Формула Пика: S = Inside + Edge/2 1
- Теорема Люка: $0 \le n, m \in \mathbb{Z}, p$ простое. $n = n_k p^k + ... + n_1 p + n_0$ и $m = m_k p^k + ... + m_1 p + m_0$. Тогда $\binom{n}{m} \equiv \prod_{i=0}^k \binom{n_i}{m_i} \pmod{p}$.
- Лемма Бернсайда: |X/G| число орбит G. $X^g = \{x \in X | gx = x\}$

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

89 Ideas

- Generic: binary search, ternary search, sort, dp, meet-in-the-middle, divide&conquer, greedy, sqrt-decomposition, matroids, Gauss, FFT, suffix array, suffix automaton, DSU;
- Graphs: build graph, add vertices / edges, 2-SAT, flows / cut, matching, Hall's theorem, topsort, HLD, centroid decomposition, MST, Euler cycle, Binary lifting, LCA;
- Tricks: consider the process from the end / from the middle, try any one, draw on 2D plane, simplify the problem / consider special case / consider more general case, simplify solution, prefix sums, differences of adjacent elements, consider min/max, analyze why a straightforward solution doesn't work, check limitations, consider contribution of separate element, small answer, different solutions for different limitations, consider complement set, maintain sum / sum of squares, convex function, store O(1) top candidates, inversions, inclusion-exclusion formula, bounding box, angle sort, Grundy function, Eucklid, Mo's algorithm, iterate over divisors, matrix exponentiation;