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1 Common

1 Setup

- 1. Terminal: font Monospace 12
- Gedit: Oblivion, font Monospace 12, auto indent, display line numbers, tab 4, highlight matching brackets, highlight current line, F9 (side panel)
- 3. /.bashrc: export CXXFLAGS='-Wall -Wshadow -Wextra Wconversion -Wno-unused-result -Wno-deprecated-declarations O2 -std=gnu++11 -g -DLOCAL'
- 4. for i in {A.K}; do mkdir \$i; cp main.cpp \$i/\$i.cpp; done

2 Template

```
#include <bits/stdc++.h>
using namespace std;
#define pb push_back
#define mp make pair
#define fst first
#define snd second
\#define sz(x) (int) ((x).size())
#define forn(i, n) for (int i = 0; i < (n); ++i)
#define fornr(i, n) for (int i = (n) - 1; i \ge 0; --i)
#define forab(i, a, b) for (int i = (a); i < (b); ++i)
#define all(c) (c).begin(), (c).end()
using ll = long long;
using vi = vector < int >;
using pii = pair<int, int>;
#define FNAME ""
int main() {
#ifdef LOCAL
 ^Ifreopen(FNAME".in", "r", stdin);
^^Ifreopen(FNAME".out", "w", stdout);
#endif
^{^{\hat{}}}Icin.tie(0);
^{\smallfrown} {\rm Iios\_base::sync\_with\_stdio(0)};
^ ^ I
^{^{\smallfrown}}Ireturn 0;
```

3 Stress

stress.sh:

```
\label{eq:continuous_problem} \begin{split} \#!/\text{bin/bash} \\ &\text{for } ((i=0;;i++)); \text{ do } \\ & \smallfrown I./\text{gen } \$i > \text{in } || \text{ exit } \\ & \smallfrown I./\text{main } < \text{in } > \text{out } 1 \;|| \text{ exit } \\ & \smallfrown \land I./\text{st upid } < \text{in } > \text{out } 2 \;|| \text{ exit } \\ & \smallfrown \land \text{Idiff out } 1 \text{ out } 2 \;|| \text{ exit } \\ & \smallfrown \land \text{Iecho } \$i \text{ OK } \\ & \text{done} \end{split}
```

4 Java

Java template:

```
import java.io.BufferedReader;
  import java.io.FileNotFoundException;
  import java.io.FileReader;
  import java.io.IOException;
  import java.io.InputStreamReader;
  import java.io.PrintWriter;
import java.util.*;
  public class Main {
                          ^IFastScanner in:
        ^ ^ IPrintWriter out;
  ^^Ivoid solve() {
  ^{^{\hat{}}}I^{^{\hat{}}}Iint a = in.nextInt();
  ^{\hat{}}I^{\hat{}}I int b = in.nextInt();
  {\hat{\ }}{\hat{\  }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\
^{^{\smallfrown}}I
  ^^Ivoid run() {
  ^^I^^Itry {
  \begin{center} $\hat{\ \ } \hat{\ 
  ^{\hat{I}^{\hat{I}}}I^{\hat{I}} = \text{new PrintWriter}(\text{"output.txt"});
  ^{\hat{}}I^{\hat{}}I^{\hat{}}I^{\hat{}}Isolve();
^^I^^I^^Iout.flush();
^^I^^I^^Iout.close();
  {^\smallfrown} {^\smallfrown} I{^\smallfrown} I \} \ catch \ (FileNotFoundException \ e) \ \{
     ^ ^ I ^ ^ I }
  ^{\smallfrown} I \}
  ^{\smallfrown}\, I
  ^^Iclass FastScanner {
  {\hat{\ }}{\hat{\  }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\  }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\  }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{
  ^{^{\hat{}}I^{^{\hat{}}}I^{^{\hat{}}}}Ipublic FastScanner() {
  ^{\hat{I}^{\hat{I}}} I ^{\hat{I}^{\hat{I}}} I new BufferedReader(new
     \hookrightarrow InputStreamReader(System.in));
  ^^I^^Ipublic FastScanner(String s) {
  {}^\smallfrown\tilde{I}{}^\smallfrown {}^\smallfrown\tilde{I}{}^\smallfrown {}^\smallfrown Itry\ \{
  {^\smallfrown}I^\smallfrown I^\smallfrown I^\smallfrown I^\smallfrown Ibr = \text{new BufferedReader}(\text{new FileReader}(s));}
  \begin{center} $\hat{\ } \hat{\ } 
  {}^\smallfrown {}^\smallfrown I {}^\smallfrown {}^\smallfrown I \}
  ^{^{\smallfrown}}I^{^{\smallfrown}}IString\ nextToken()\ \{
  ^^I^^I^^Iwhile (st == null || !st.hasMoreElements()) {
  {\color{red} \smallfrown} {\color{blue} \Gamma} {\color{bl
  {\color{blue} {\color{blue} \cap I } {\color{blue} \cap
  ^^I^^I^^I^^I} catch (IOException e) {
  {^\smallfrown} I {^\smallfrown} I {^\smallfrown} I {^\smallfrown} I {^\smallfrown} I {^\smallfrown} Ie.printStackTrace();
  {}^\smallfrown {}^\smallfrown I {}^\smallfrown
  ~ ~ I ~ ~ I ~ ~ I }
  ^^I^^I^^Ireturn st.nextToken();
  {}^\smallfrown {}^\smallfrown I {}^\smallfrown {}^\smallfrown I \}
  ^^I^^Iint nextInt() {
  {\hat{\ }}{\hat{\  }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\ }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\  }}{\hat{\
  {\,{}^\smallfrown}{\,{}^\smallfrown} I {\,{}^\smallfrown} {\,{}^\smallfrown} I \big\}
  ^^I^^Ilong nextLong() {
  {\hat{\ }}{}^{\hat{\ }}I{}^{\hat{\ }}I{}^{\hat{\ }}I{}^{\hat{\ }}Ireturn\ Long.parseLong(nextToken());
  ^{\land} I ^{\land} I
  ^^I^^Idouble nextDouble() {
  {\hat{\ }}{}^{\hat{\ }}I^{\hat{\ }}I^{\hat{\ }}Ireturn\ Double.\underline{parseDouble}(nextToken());
  \land \land I \land \land I
  {}_{\smile} {}_{\smile} I {}_{\smile} {}_{\smile} I
```

```
^{^{\hat{}}}I^{^{\hat{}}}I () {
   {}^{\smallfrown} I {}^{\smallfrown} I {}^{\smallfrown} I {}^{\smallfrown} I t \, ry \; \{
   {^{\smallfrown}I^{\smallfrown}I^{\smallfrown}I^{\smallfrown}Ireturn}\ (char)\ (br.read());
   \begin{cal}{l} \^{\ } \^{\ } \^{\ } I \^{\ } \^{\ } I \^{\ } \^{\ } I \end{cal} $(IO\,Ex\,ception\,\,e)$ \ \{ \end{cal}
      ^{^{1}}I^{^{1}}I^{^{1}}I^{^{1}}Ie.printStackTrace();
   ^^I^^I^^Ireturn 0;
^{^{\wedge}}I^{^{\wedge}}I
   ^^I^^I
{^{\smallfrown}}I{^{\smallfrown}}\operatorname{IString\ nextLine}()\ \{
   {\color{red} {\color{gray} \widehat{I}}} {\color{gray} {\gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\gar} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray
^^I^^I^^I^^Ireturn br.readLine();
   ^{\hat{I}^{\hat{I}}} catch (IOException e) {
   {^{\smallfrown}}I{^{\smallfrown}}I{^{\smallfrown}}I{^{\smallfrown}}Ie.printStackTrace();
   {\,{}^\smallfrown}{\,{}^\smallfrown} I{\,{}^\smallfrown}{\,{}^\smallfrown} I{\,{}^\smallfrown}{\,{}^\smallfrown} I \big\}
   ^^I^^Ireturn "";
{\color{red} {\color{gray} {\ent} {\color{gray} {\color{gray} {\gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\color{gray} {\color{ga
^{\smallfrown \cap I}\}
   ^^Ipublic static void main(String[] args) {
{^{\smallfrown}}{^{\smallfrown}}I{^{\smallfrown}}{^{\smallfrown}}Inew\ \underline{Main}().\underline{run}();
^\smallfrown ^\smallfrown I\}
```

2 Big numbers

5 Big Int

```
const int BASE LEN = 9;
const int NUM LEN = 50000 / BASE LEN + 2; // LEN <=
\hookrightarrow NUM LEN * BASE LEN
const int BASE = pow(10, BASE LEN);
const ll INF = 8e18, ADD = INF / BASE;
struct num {
 ll~a[NUM\_LEN];
 int len; // always > 0
 inline const ll& operator [] ( int i ) const { return a[i]; }
 inline ll& operator [] ( int i ) { return a[i]; }
 num& operator = (const num &x) { // copy
  len = x.len;
  memcpy(a, x.a, sizeof(a[0]) * len);
  return *this;
 num(const num \&x) {*this = x;} // copy
 num() \{ len = 1, a[0] = 0; \} // 0
 num( ll x ) { // x
  len = 0:
  while (!len || x) {
    assert(len < NUM LEN); // to catch overflow
    a[len++] = x \% BASE, x /= BASE;
 num& cor() {
  while (a[len - 1] >= BASE) {
    assert(len < NUM_LEN); // to catch overflow
    if (a[len - 1] >= 2 * BASE)
     a[len] = a[len - 1] / BASE, a[len - 1] \% = BASE;
     a[len] = 1, a[len - 1] -= BASE;
    len++;
  while (len > 1 && !a[len - 1])
  return *this;
```

```
}
_{\mathrm{int}}\ \mathrm{length}()\ \{
 if (!len)
   return 0;
 int x = a[len - 1], res = 0;
 assert(x);
 while (x || !res)
  x /= 10, res++;
 return res + (len - 1) * BASE LEN;
void out() const {
 int i = len - 1;
 printf("%d", (int)a[i--]);
 while (i >= 0)
   printf("%0*d", BASE LEN, (int)a[i--]);
 puts("");
void init( const char *s ) {
 int sn = strlen(s);
 while (sn && s[sn - 1] <= 32)
   sn--;
 len = (sn + BASE LEN - 1) / BASE LEN;
 memset(a, 0, sizeof(a[0]) * len);
 forn(i, sn) {
   ll \&r = a[(sn - i - 1) / BASE LEN];
   r = r * 10 + (s[i] - 0);
}
bool read() {
 static const int L = NUM LEN * BASE LEN + 1;
 static char s[L];
 if (!fgets(s, L, stdin))
   return 0;
 assert(!s[L - 2]);
 init(s):
 return 1;
void mul2() {
 forn(i, len)
   a[i] <<= 1;
 forn(i, len - 1)
   \mathrm{if}\ (a[i]>=\mathrm{BASE})
    a[i + 1]++, a[i] -= BASE;
 cor();
}
void div2() {
 for (int i = len - 1; i >= 0; i--) {
   if (i && (a[i] & 1))
    a[i - 1] += BASE;
   a[i]>>=1;
 }
 cor();
static ll cmp( ll *a, ll *b, int n ) {
 while (n--)
   if (a[n] := b[n])
    return a[n] - b[n];
 return 0;
int cmp( const num &b ) const {
 if (len != b.len)
   return len - b.len;
 for (int i = len - 1; i >= 0; i--)
```

```
\mathrm{if}\ (a[i] \mathrel{\mathop:}= b[i])
      return a[i] - b[i];
   return 0;
 }
 bool zero() {
  return len == 1 && |a[0]|;
 /** c = this/b, this %= b */
 num &div( num b, num &c ) {
  c.len = len - b.len;
   for (int i = c.len; i >= 0; i--) {
    int k = (1.0L * a[len - 1] * BASE + (len >= 2 ? a[len - 2] : 0)) /
     \rightarrow (1.0L * b[b.len - 1] * BASE + (b.len >= 2 ? b[b.len - 2] + 1:
     \rightarrow 0));
    c[i] = 0;
    if (k > 0) {
      c[i] += k;
      forn(j, b.len)
       a[i + j] = (ll)b[j] * k;
      forn(j, b.len)
        if (a[i + j] < 0) {
         ll k = (-a[i + j] + BASE - 1) / BASE;
         a[i + j] += k * BASE, a[i + j + 1] -= k;
        }
    if (i)
      len--, a[len - 1] += a[len] * BASE, a[len] = 0;
    else if (cmp(a, b.a, b.len) >= 0) {
      c[0]++;
      forn(j, b.len)
        if ((a[j] -= b[j]) < 0)
         a[j] += BASE, a[j + 1]--;
   if (c.len < 0)
    c[c.len = 0] = 0;
   forn(i, c.len)
    if (c[i] >= BASE)
      c[i\,+\,1]\,+=\,c[i]\,\,/\,\,BASE,\,c[i]\,\,\%=\,BASE;
   c.len += (!c.len || c[c.len]);
   return cor();
};
num& operator += ( num &a, const num &b ) {
 while (a.len < b.len)
   \mathbf{a}[\mathbf{a}.\mathbf{len}++]\,=\,0;
 forn(i, b.len)
  a[i] += b[i];
 forn(i, a.len - 1)
   \mathrm{if}\ (a[\mathrm{i}] >= \mathrm{BASE})
    a[i] = BASE, a[i + 1] ++;
 return a.cor();
num\& operator = (num \&a, const num \&b) 
 while (a.len < b.len)
   a[a.len++] = 0;
 forn(i, b.len)
  a[i] -= b[i];
 forn(i, a.len - 1)
   if (a[i] < 0)
    a[i] += BASE, a[i + 1]--;
 assert(a[a.len - 1] >= 0); // a >= b
 return a.cor();
num& operator *= ( num &a, int k ) {
 if (k == 1)
```

```
return a:
 if (k == 0) {
  a.len = 0;
  return a;
 forn(i, a.len)
  a[i] *= k;
 forn(i, a.len - 1)
  if (a[i] >= BASE)
    a[i + 1] += a[i] / BASE, a[i] \% = BASE;
 return a.cor();
num& operator /= ( num &a, int k ) {
 if (k == 1)
  return a;
 assert(k != 0);
 for (int i = a.len - 1; i > 0; i--)
  a[i - 1] += (ll)(a[i] \% k) * BASE, a[i] /= k;
 a[0] /= k;
 return a.cor();
num& mul(const num &a, const num &b, num &x) {
 assert(a.len + b.len - 1 \le NUM LEN);
 memset(x.a, 0, sizeof(x[0]) * (a.len + b.len - 1));
 forn(i, a.len)
  forn(j, b.len)
    if ((x[i + j] += a[i] * b[j]) >= INF)
      x[i + j + 1] += ADD, x[i + j] -= INF;
 x.len = a.len + b.len - 1;
 forn(i, x.len - 1)
  if (x[i] >= BASE)
   x[i + 1] += x[i] / BASE, x[i] \% = BASE;
 return x.cor();
bool operator == ( const num &a, const num &b ) { return a.cmp(b)
\Rightarrow ==0; \}
bool operator != ( const num &a, const num &b ) { return a.cmp(b)
\hookrightarrow != 0; }
bool operator < ( const num &a, const num &b ) { return a.cmp(b) <
bool operator > (const num &a, const num &b) { return a.cmp(b) >
\hookrightarrow 0; }
bool operator <= ( const num &a, const num &b ) { return a.cmp(b)
\leftrightarrow \langle = 0; \}
bool operator >= ( const num &a, const num &b ) { return a.cmp(b)
\Rightarrow >= 0; }
num\& add(const num \&a, const num \&b, num \&c) \{c = a; c += b;
\hookrightarrow return c; }
num & sub( const num &a, const num &b, num &c) { c = a; c = b;
\hookrightarrow return c; }
num& mul(const num &a, int k, num &c)
                                                  \{ c = a; c *= k; 
\hookrightarrow return c; }
num& div(const num &a, int k, num &c)
                                                 \{c = a; c \neq k; return \}
num& operator *= ( num &a, const num &b ) {
 static num tmp;
 mul(a, b, tmp);
 return a = tmp;
num operator ^ ( const num &a, int k ) {
 num res(1);
 forn(i, k)
  res *= a;
 return res;
```

```
const \ Num \ z = a[i+j+k] * rt[j+k];
num& gcd binary( num &a, num &b ) {
                                                                                   a[i + j + k] = a[i + j] - z;
 int cnt = 0:
                                                                                   a[i + j] += z;
 while (!a.zero() && !b.zero()) {
                                                                             }
   while (!(b[0] \& 1) \& \& !(a[0] \& 1))
    cnt++, a.div2(), b.div2();
   while (!(b[0] \& 1))
                                                                             void fftInv(Num *a, int n) {
    b.div2();
                                                                              fft(a, n):
   while (!(a[0] \& 1))
                                                                              reverse(a + 1, a + n);
                                                                              forn\ (i,\ n)
    a.div2();
   if (a.cmp(b) < 0)
                                                                                a[i] /= n;
    b = a;
   else
                                                                             void doubleFft(Num *a, Num *fa, Num *fb, int n) { // only if you
    a = b;

→ need it

                                                                              fft(a, n);
 if (a.zero())
  std::swap(a, b);
                                                                              const int n1 = n - 1;
 while (cnt)
                                                                              forn (i, n) {
                                                                                const\ Num\ \&z0\ =\ a[i],\ \&z1\ =\ a[(n\ \text{-}\ i)\ \&\ n1];
  a.mul2(), cnt--;
                                                                                fa[i] = Num(z0.real() + z1.real(), z0.imag() - z1.imag()) * 0.5;
 return a;
                                                                                fb[i] = Num(z0.imag() + z1.imag(), z1.real() - z0.real()) * 0.5;
                                                                              }
                                                                             }
num& gcd( num &a, num &b ) {
 static num tmp;
 return b.zero() ? a : gcd(b, a.div(b, tmp));
                                                                             Num tmp[MAX N];
                                                                             template < class T
                                                                             void mult(T *a, T *b, T *r, int n) { // n = 2^k
                                                                              forn (i, n)
   FFT
                                                                                tmp[i] = Num((dbl) a[i], (dbl) b[i]);
                                                                              fft(tmp, n);
int rev[MAX N];
                                                                               const int n1 = n - 1;
                                                                               const Num c = Num(0, -0.25 / n);
//typedef complex<dbl> Num;
                                                                               fornr (i, n / 2 + 1) {
struct Num {
                                                                                const int j = (n - i) \& n1;
 dbl x, y;
                                                                                const Num z0 = sqr(tmp[i]), z1 = sqr(tmp[j]);
 Num() {}
                                                                                tmp[i] = (z1 - conj(z0)) * c;
 Num(dbl _x, dbl _y): x(_x), y(_y) \{\}
                                                                                tmp[j] = (z0 - conj(z1)) * c;
 inline dbl real() const { return x; }
 inline dbl imag() const { return y; }
                                                                              fft(tmp, n);
 inline Num operator+(const Num &B) const { return Num(x + B.x,
                                                                              forn (i, n)
  \hookrightarrow y + B.y); }
                                                                                r[i] = (T) round(tmp[i].real());
 inline Num operator-(const Num &B) const { return Num(x - B.x, y
 → - B.y); }
 inline Num operator*(dbl k) const { return Num(x * k, y * k); }
                                                                             void init() { // don 't forget to init
 inline Num operator*(const Num &B) const { return Num(x * B.x -
                                                                              forn(i, MAX N)
 \rightarrow y * B.y, x * B.y + y * B.x); }
                                                                                rev[i] = (rev[i >> 1] >> 1) + ((i \& 1) << (LOG - 1));
 inline void operator+=(const Num &B) { x += B.x, y += B.y; }
 inline void operator/=(dbl k) { x /= k, y /= k; } inline void operator*=(const Num &B) { *this = *this * B; }
                                                                               rt[1] = Num(1, 0);
                                                                              for (int k = 1, p = 2; k < LOG; k++, p *= 2) {
                                                                                \stackrel{\cdot}{\rm const} \ {\rm Num} \ x(\cos({\rm PI} \ / \ p), \ \sin({\rm PI} \ / \ p));
                                                                                forab (i, p / 2, p)
Num rt[MAX N];
                                                                                  rt[2\ *\ i] = rt[i],\, rt[2\ *\ i\ +\ 1] = rt[i]\ *\ x;
inline Num sqr(const Num &x) { return x * x; }
inline Num conj(const Num &x) { return Num(x.real(), -x.imag()); }
inline int get N(int n) {
                                                                                 FFT by mod and FFT with digits up to 10<sup>6</sup>
 int k = 1;
                                                                             Num\ ta[MAX\_N],\ tb[MAX\_N],\ tf[MAX\_N],\ tg[MAX\_N];
 while(k < n)
  k <<= 1;
                                                                             const int HALF = 15;
 return k:
                                                                             void mult(int *a, int *b, int *r, int n, int mod) {
void fft(Num *a, int n) {
                                                                              int tw = (1 << HALF) - 1;
 assert(rev[1]); // don 't forget to init
                                                                              forn (i, n) {
 int q = MAX N / n;
                                                                                int x = int(a[i] \% mod);
 forn (i, n)
                                                                                ta[i] = Num(x \& tw, x >> HALF);
  if (i < rev[i] / q)
    swap(a[i], a[rev[i] / q]);
                                                                              forn (i, n) {
                                                                                int x = int(b[i] \% mod);
 for (int k = 1; k < n; k <<= 1)
   for (int i = 0; i < n; i += 2 * k)
                                                                                tb[i] = Num(x \& tw, x >> HALF);
    forn (j, k) {
```

```
fft(ta, n), fft(tb, n);
 forn (i, n) {
   int j = (n - i) & (n - 1);
   Num\ a1 = (ta[i] + conj(ta[j])) * Num(0.5, 0);
   Num a2 = (ta[i] - conj(ta[j])) * Num(0, -0.5);
   Num b1 = (tb[i] + conj(tb[j])) * Num(0.5 / n, 0);
   Num b2 = (tb[i] - conj(tb[j])) * Num(0, -0.5 / n);
   tf[j] = \, a1 \, * \, b1 \, + \, a2 \, * \, b2 \, * \, Num(0, \, 1);
   tg[j] = a1 * b2 + a2 * b1;
 fft(tf, n), fft(tg, n);
 forn (i, n) {
   ll aa = ll(tf[i].x + 0.5);
   ll\ bb = ll(tg[i].x + 0.5);
   ll\ cc=\ ll(tf[i].y\ +\ 0.5);
   r[i] = int((aa + ((bb \ \% \ mod) << HALF) + ((cc \ \% \ mod) << (2 \ *
   \hookrightarrow HALF))) % mod);
int tc[MAX_N], td[MAX_N];
const int MOD1 = 1.5e9, MOD2 = MOD1 + 1;
void multLL(int *a, int *b, ll *r, int n){
 mult(a, b, tc, n, MOD1), mult(a, b, td, n, MOD2);
 forn(i, n)
   r[i] = tc[i] + (td[i] - tc[i] + (ll)MOD2) * MOD1 \% \ MOD2 * MOD1;
```

3 Data Structures

8 Centroid Decomposition

```
vi g[MAX_N];
int d[MAX_N], par[MAX_N], centroid;
//d par -
int find(int v, int p, int total) {
 int size = 1, ok = 1;
 for (int to: g[v])
   if (d[to] == -1 \&\& to != p) {
    int s = find(to, v, total);
    if (s > total / 2) ok = 0;
    size += s;
 if (ok && size > total / 2) centroid = v;
 return size:
void calcInComponent(int v, int p, int level) {
  // do something
 for (int to:g[v])
   if (d[to] == -1 \&\& to != p)
     calcInComponent(to, v, level);
//\text{fill}(d, d + n, -1)
//decompose(0, -1, 0)
void decompose(int root, int parent, int level) {
 find(root, -1, find(root, -1, INF));
 int c = centroid;
 par[c] = parent, d[c] = level;
 calcInComponent(centroid, -1, level);
 for (int to : g[c])
   if (d[to] == -1)
     decompose(to, c, level + 1);
}
```

9 Convex Hull Trick

```
struct Line {
 int k. b:
 Line() {}
 Line(int k, int b): k(k), b(b) {}
 ll get(int x) \{ return b + k * 1 ll * x; \}
 bool operator < (const Line &l) const { return k < l.k; } // >
// , (a,b) (a,c)
inline bool check(Line a, Line b, Line c) {
 return (a.b - b.b) * 111 * (c.k - a.k) < (a.b - c.b) * 111 * (b.k - a.k);
struct Convex {
 vector<Line> st;
 inline void add(Line l) {
   while (\mathbf{sz}(\mathbf{st}) >= 2 \&\& !\mathbf{check}(\mathbf{st}[\mathbf{sz}(\mathbf{st}) - 2], \ \mathbf{st}[\mathbf{sz}(\mathbf{st}) - 1], \ l))
     st.pop_back();
   st.pb(l);
  int get(int x) {
   int l = 0, r = sz(st);
   while (r - l > 1) {
     int m = (1 + r) / 2; // >
     if \ (st[m-1].get(x) < st[m].get(x)) \\
      l = m;
     else
      r = m;
   }
   return 1;
  Convex() {}
  Convex(vector<Line> &lines) {
   st.clear();
   for(Line &l: lines)
     add(l);
  Convex(Line line) { st.pb(line); }
  Convex(const Convex &a, const Convex &b) {
   vector<Line> lines;
   lines.resize(sz(a.st) + sz(b.st));
   merge(all(a.st), all(b.st), lines.begin());
   st.clear();
   for(Line &l: lines)
     add(1);
};
10
     DSU
int pr[MAX_N];
int get(int v) {
 return v == pr[v] ? v : pr[v] = get(pr[v]);
bool unite(int v, int u) {
 v = get(v), u = get(u);
 \quad \text{if } (v == u) \ \text{return } 0; \\
 pr[u] = v;
 return 1;
void init(int n) {
 forn (i, n) pr[i] = i;
```

Fenwick Tree int t[MAX_N]; int get(int ind) { int res = 0; for (; ind >= 0; ind &= (ind + 1), ind--) res += t[ind];return res; void add(int ind, int n, int val) { for (; ind < n; ind |= (ind + 1)) t[ind] += val;int sum(int l, int r) $\{ // [l, r) \}$ return get(r-1) - get(l-1); Hash Table 12using H = ll; $\label{eq:const_int_HT_SIZE} \mbox{const_int} \ \mbox{HT_SIZE} = 1 << 20, \mbox{HT_AND} = \mbox{HT_SIZE} - 1,$ $\begin{array}{lll} \hookrightarrow & \text{HT_SIZE_ADD} = & \text{HT_SIZE} \ / \ 100; \\ \text{H ht[HT_SIZE} + & \text{HT_SIZE_ADD]}; \end{array}$ int data[HT_SIZE + HT_SIZE_ADD]; int get(const H &hash){ int k = ((ll) hash) & HT AND;while (ht[k] && ht[k] != hash) ++k;return k; void insert(const H & hash, int x){ int k = get(hash); if (!ht[k]) ht[k] = hash, data[k] = x;bool count(const H &hash, int x){ int k = get(hash);return ht[k] != 0;Heavy Light Decomposition vi g[MAX_N]; $\begin{array}{ll} & \text{int size}[MAX_N], \ comp[MAX_N], \ num[MAX_N], \ top[MAX_N], \\ & \rightarrow \quad pr[MAX_N], \ tin[MAX_N], \ tout[MAX_N]; \end{array}$ vi t[MAX_N], toPush[MAX_N], lst[MAX_N]; int curPath = 0, curTime = 0;void pushST(int path, int v, int vl, int vr) { if (toPush[path][v] != -1) { if (vl != vr - 1) forn (j, 2)toPush[path][2 * v + j] = toPush[path][v];t[path][v] = toPush[path][v];toPush[path][v] = -1;int getST(int path, int v, int vl, int vr, int ind) { pushST(path, v, vl, vr); if (vl == vr - 1)

return t[path][v];

if (ind >= vm)

int vm = (vl + vr) / 2;

return getST(path, 2 * v + 1, vm, vr, ind);

return getST(path, 2 * v, vl, vm, ind);

```
void setST(int path, int v, int vl, int vr, int l, int r, int val) {
 if (vl >= l && vr <= r) {
   toPush[path][v] = val;
   pushST(path, v, vl, vr);
   return;
 pushST(path, v, vl, vr);
 if (vl >= r || l >= vr)
  return;
 int vm = (vl + vr) / 2;
 \mathtt{setST}(\mathtt{path},\ 2\ *\ v,\ vl,\ vm,\ l,\ r,\ val);
 setST(path, 2 * v + 1, vm, vr, l, r, val);
 t[path][v] = \min(t[path][2 * v], \, t[path][2 * v + 1]);
bool isUpper(int v, int u) {
 \operatorname{return} \ \operatorname{tin}[v] <= \operatorname{tin}[u] \ \&\& \ \operatorname{tout}[v] >= \operatorname{tout}[u];
int getHLD(int v) {
 return getST(comp[v], 1, 0, sz(t[comp[v]]) / 2, num[v]);
int setHLD(int v, int u, int val) {
 int ans = 0, w = 0;
 forn (i, 2) {
   while (!isUpper(w = top[comp[v]], u))
     setST(comp[v], 1, 0, sz(t[comp[v]]) / 2, 0, num[v] + 1, val), v =
     \rightarrow pr[w];
   swap(v, u);
 setST(comp[v], 1, 0, sz(t[comp[v]]) / 2, min(num[v], num[u]),
  \rightarrow max(num[v], num[u]) + 1, val);
 return ans;
void dfs(int v, int p) {
 tin[v] = curTime++;
 size[v] = 1;
 pr[v] = p;
 for (int u : g[v])
  if (u != p) {
    dfs(u, v);
     size[v] += size[u];
 tout[v] = curTime++;
void build(int v) {
 if (v == 0 \mid \mid size[v] * 2 < size[pr[v]])
  top[curPath] = v, \ comp[v] = curPath, \ num[v] = 0, \ curPath++;
   comp[v] = comp[pr[v]], num[v] = num[pr[v]] + 1;
 lst[comp[v]].pb(v);
 for (int u : g[v])
   if (u \vdash pr[v])
     build(u);
void initHLD() {
 dfs(0, 0);
 build(0);
 forn (i, curPath) {
   int curSize = 1;
   while (curSize < sz(lst[i]))
    curSize *= 2;
   t[i].resize(curSize * 2);
   toPush[i] = vi(curSize * 2, -1);\\
   //initialize t[i]
```

```
SPb HSE (Labutin, Podguzov, Bogomolov)
                                                                               Team reference document. Page 8 of 24
                                                                              return \ get(x_2, y_2) - get(x_1 - 1, y_2) - get(x_2, y_1 - 1) + \\
                                                                               \hookrightarrow \quad get(x\_1 \ \hbox{-}\ 1,\ y\_1 \ \hbox{-}\ 1);
      Next Greater in Segment Tree
                                                                             // Adds val to corresponding rectangle
                                                                             inline void add(int x_1, int y_1, int x_2, int y_2, ll val) {
int t[4 * MAX N], tSize = 1;
                                                                              add(x_1, y_1, val);
                                                                              if \ (y\_2 \, < \, m) \ add(x\_1, \, y\_2 \, + \, 1, \, \text{-val}); \\
      pos x
                                                                              if (x_2 < n) add(x_2 + 1, y_1, -val);
int nextGreaterX(int v, int l, int r, int pos, int x) {
                                                                              if (x_2 < n \&\& y_2 < m) add(x_2 + 1, y_2 + 1, val);
 if (r \le pos + 1 || t[v] \le x) return INF;
 if (v >= tSize) return v - tSize;
 int ans = nextGreaterX(2 * v, l, (l + r) / 2, pos, x);
 if (ans == INF)
                                                                                  Dynamic Programming
                                                                             4
  ans = nextGreaterX(2 * v + 1, (l + r) / 2, r, pos, x);
 return ans:
                                                                                   LIS
                                                                             17
                                                                             int longestIncreasingSubsequence(vi a) {
                                                                              int n = sz(a);
      Sparse Table
15
                                                                              vi d(n + 1, INF);
                                                                              d[0] = -INF;
int st[MAX N][MAX LOG];
                                                                              forn (i, n)
int lg[MAX_N];
                                                                               *upper\_bound(all(d), a[i]) = a[i];
                                                                              form (i, n + 1) if (d[i] != INF) return i;
int get(int l, int r) \{ // [l, r)
                                                                              return 0;
 int curLog = lg[r - l];
 return \ min(st[l][curLog], \ st[r - (1 << curLog)][curLog]); \\
                                                                             18 DP tree
void initSparseTable(int *a, int n) {
                                                                             int dp[MAX_N][MAX_N], a[MAX_N];
                                                                             vi g[MAX N];
 forab (i, 2, n + 1) lg[i] = lg[i / 2] + 1;
 forn (i, n) st[i][0] = a[i];
                                                                             int dfs(int v, int n) {
 forn\ (j,\ lg[n])
                                                                              forn (i, n + 1)
  forn (i, n - (1 << (j + 1)) + 1)
                                                                                dp[v][i] = \text{-INF}; \\
    st[i][j+1] = min(st[i][j], st[i+(1 << j)][j]);
                                                                              dp[v][1] = a[v];
                                                                              int curSz = 1;
                                                                              for (int to : g[v]) {
     Fenwick Tree 2D
                                                                               int toSz = dfs(to, n);
                                                                                for (int i = curSz; i >= 1; i--)
ll a[4][MAX N][MAX N];
                                                                                 fornr (j, toSz + 1)
int n, m;
                                                                                   dp[v][i+j] = max(dp[v][i+j],\, dp[v][i] + \, dp[to][j]);
                                                                                curSz += toSz;
inline int f(int x) { return x & ^{\sim}(x - 1); }
                                                                              }
                                                                              return curSz;
inline void add(int k, int x, int y, ll val) {
 for (; x \le n; x += f(x))
   for \; ( \underset{}{\textbf{int}} \; j = y; \, j <= m; \, j \mathrel{+}= f(j) )
                                                                                   Masks tricks
    a[k][x][j] += val;
                                                                             int dp[(1 \ll MAX MASK)][MAX MASK];
inline ll get(int k, int x, int y) {
                                                                             void calcDP(int n) {
 ll s = 0;
                                                                              forn(mask, 1 << n) {
 for (; x > 0; x -= f(x))
                                                                                dp[mask][n] = 1;
   for (int j = y; j > 0; j = f(j))
                                                                                fornr(i, n) {
    s += a[k][x][j];
                                                                                 dp[mask][i] = dp[mask][i + 1];
 return s;
                                                                                 if ((1 << i) & mask)
                                                                                   dp[mask][i] += dp[mask ^ (1 << i)][i + 1];
inline ll get(int x, int y) {
                                                                              }
 return ll(x + 1) * (y + 1) * get(0, x, y) - (y + 1) * get(1, x, y)
                                                                             }
    -(x + 1) * get(2, x, y) + get(3, x, y);
                                                                             5
                                                                                   Flows
inline void add(int x, int y, ll val) {
 add(0, x, y, val);
                                                                             20 Utilities
 add(1, x, y, val * x);
 add(2, x, y, val * y);
                                                                             vi g[MAX_N];
 add(3, x, y, val * x * y);
                                                                             // for directed unweighted graph
                                                                             struct Edge {
inline ll get(int x_1, int y_1, int x_2, int y_2) {
                                                                              int v, u, c, f;
```

```
Edge() {}
                                                                                   q[tail++] = s;
 Edge(int v, int u, int c): v(v), u(u), c(c), f(0) {}
                                                                                   \mathbf{d}[\mathbf{s}] = 0;
                                                                                   while (tail - head > 0) {
                                                                                    int v = q[head++];
                                                                                     for (int edge : g[v]) {
vector{<}Edge{>}\ edges;
                                                                                      auto \&e = edges[edge];
inline void addFlow(int e, int flow) {
                                                                                      if \ (d[e.u] > d[v] + 1 \ \&\& \ e.c \text{-} \ e.f >= curPush) \\
  edges[e] f += flow, edges[e ^ 1] f -= flow;
                                                                                        d[e.u] \, = \, d[v] \, + \, 1, \, q[tail + +] \, = \, e.u;
inline void addEdge(int v, int u, int c) {
                                                                                   return d[t] != INF;
 g[v].pb(sz(edges)), edges.pb(Edge(v, u, c));
 g[u].pb(sz(edges)), edges.pb(Edge(u, v, 0)); // for undirected 0 should
                                                                                  int dinic(int n, int s, int t) {
                                                                                   int ansFlow = 0;
                                                                                   // Without scaling
                                                                                   while (bfs(n, s, t, 1))
21
      Ford-Fulkerson
                                                                                    ansFlow \mathrel{+}= dfs(s,\,INF,\,1,\,t);
                                                                                   // With scaling
int used[MAX_N], pr[MAX_N];
                                                                                   fornr (j, INF LOG)
int curTime = 1;
                                                                                     while (bfs(n, s, t, 1 \ll j))
                                                                                      ansFlow += dfs(s, INF, 1 << j, t);
int dfs(int v, int can, int toPush, int t) {
                                                                                   return ansFlow;
 if (v == t) return can;
 used[v] = curTime;
 for (int edge : g[v]) {
   auto &e = edges[edge];
                                                                                  23
                                                                                        Hungarian
   if (used[e.u] != curTime \&\& e.c - e.f >= toPush) {
                                                                                 const int INF = 1e9:
    int flow = dfs(e.u, min(can, e.c - e.f), toPush, t);
     if (flow > 0)
                                                                                 int a[MAX N][MAX N];
      addFlow(edge, flow), pr[e.u] = edge;
      return flow;
                                                                                  // \min = \text{sum of a}[pa[i], i]
                                                                                  // you may optimize speed by about 15%, just change all vectors to
   }

→ static arrays

                                                                                 vi Hungarian(int n) {
 return 0;
                                                                                   vi pa(n + 1, -1), row(n + 1, 0), col(n + 1, 0), la(n + 1);
                                                                                   forn (k, n) {
                                                                                     vi u(n + 1, 0), d(n + 1, INF);
int fordFulkerson(int s, int t) {
                                                                                     pa[n] = k;
                                                                                     int l = n, x;
 int ansFlow = 0, flow = 0;
                                                                                     while ((x = pa[l]) != -1) {
  // Without scaling
 while ((flow = dfs(s, INF, 1, t)) > 0)
                                                                                      u[l] = 1;
   ansFlow += flow, curTime++;
                                                                                      int minn = INF, tmp, 10 = 1;
  // With scaling
                                                                                      forn (j, n)
 fornr (i, INF LOG)
                                                                                        if (!u[j]) {
   for (curTime++; (flow = dfs(s, INF, (1 << i), t)) > 0; curTime++)
                                                                                          if ((tmp = a[x][j] + row[x] + col[j]) < d[j])
                                                                                           d[j]=tmp,\,la[j]=l0;\\
     ansFlow += flow:
                                                                                          if (d[j] < minn)
 return ansFlow;
}
                                                                                            minn = d[j], l = j;
                                                                                      forn (j, n + 1)
      Dinic
                                                                                        if (u[i])
                                                                                          col[j] += minn, row[pa[j]] -= minn;
int pr[MAX N], d[MAX N], q[MAX N], first[MAX N];
                                                                                        else
                                                                                          d[j] = minn;
int dfs(int v, int can, int toPush, int t) {
 if (v == t) return can;
                                                                                     while (l != n)
 int sum = 0;
                                                                                      pa[l] = pa[la[l]], l = la[l];
 for (; first[v] < (int) g[v].size(); first[v]++) \{
   auto \&e = edges[g[v][first[v]]];
                                                                                   return pa;
   if (d[e.u] != d[v] + 1 || e.c - e.f < toPush) continue;
                                                                                  }
   int flow = dfs(e.u, min(can, e.c - e.f), toPush, t);
   addFlow(g[v][first[v]], flow);
   can -= flow, sum += flow;
                                                                                        Min Cost Max Flow
                                                                                  24
   if (!can)
                                                                                  const int MAX_M = 1e4;
   return sum;
                                                                                 \begin{array}{ll} & \text{int } \operatorname{pr}[MAX\_N], \operatorname{in}[MAX\_N], \operatorname{q}[MAX\_N * MAX\_M], \operatorname{used}[MAX\_N], \\ & \hookrightarrow & d[MAX\_N], \operatorname{pot}[MAX\_N]; \end{array}
  return sum;
                                                                                 vi g[MAX_N];
bool bfs(int n, int s, int t, int curPush) {
                                                                                 struct Edge {
                                                                                   \quad \quad \textbf{int} \ v, \ u, \ c, \ f, \ w;
 forn (i, n) d[i] = INF, first[i] = 0;
 int head = 0, tail = 0;
                                                                                   Edge() \{ \}
```

```
Edge(int \underline{v}, int \underline{u}, int \underline{c}, int \underline{w}): \underline{v}(\underline{v}), \underline{u}(\underline{u}), \underline{c}(\underline{c}), \underline{f}(0),
  \hookrightarrow w(_w) {}
};
vector<Edge> edges;
inline void addFlow(int e, int flow) {
 edges[e].f += flow, edges[e ^ 1].f -= flow;
inline void addEdge(int v, int u, int c, int w) {
 g[v].pb(sz(edges)), edges.pb(Edge(v, u, c, w));
 g[u].pb(sz(edges)), edges.pb(Edge(u, v, 0, -w));
int dijkstra(int n, int s, int t) {
 forn\ (i,\,n)\ used[i]=0,\,d[i]=INF;
 \mathbf{d}[\mathbf{s}] = 0;
 while (1) {
   int v = -1;
   forn (i, n)
     if (|used[i] \&\& (v == -1 || d[v] > d[i]))
      v = i;
   if (v == -1 || d[v] == INF) break;
   used[v] = 1;
   for (int edge : g[v]) {
     auto \&e = edges[edge];
     \  \  \, \mathbf{int} \,\, w \, = \, e.w \, + \, pot[v] \, \text{-} \, pot[e.u]; \\
     if (e.c > e.f \&\& d[e.u] > d[v] + w)
       d[e.u] = d[v] + w, pr[e.u] = edge;
   }
 if (d[t] == INF) return d[t];
 forn (i, n) pot[i] += d[i];
 return pot[t];
int fordBellman(int n, int s, int t) {
 forn (i, n) d[i] = INF;
 int head = 0, tail = 0;
 d[s] = 0, q[tail++] = s, in[s] = 1;
 while (tail - head > 0) {
   int \ v = q[head++];
   in[v] = 0;
   for (int edge : g[v]) {
     auto &e = edges[edge];
     if (e.c > e.f \&\& d[e.u] > d[v] + e.w) {
       d[e.u] = d[v] + e.w;
       pr[e.u] = edge;
       if (!in[e.u])
        in[e.u] = 1, q[tail++] = e.u;
   }
 }
 return d[t];
int minCostMaxFlow(int n, int s, int t) {
 int ansFlow = 0, ansCost = 0, dist;
 while ((dist = dijkstra(n, s, t)) != INF) {
   int curFlow = INF;
   for (int cur = t; cur != s; cur = edges[pr[cur]].v)
     curFlow = \min(curFlow,\,edges[pr[cur]].c - edges[pr[cur]].f);
   for (int cur = t; cur != s; cur = edges[pr[cur]].v)
     addFlow(pr[cur], curFlow);
   ansFlow += curFlow;
   ansCost += curFlow * dist;
 return ansCost;
```

Games

Retrograde Analysis

```
vi g[MAX N]; // reversed edges
int\ win[MAX\_N],\ lose[MAX\_N],\ used[MAX\_N],\ deg[MAX\_N];
void dfs(int v) {
 used[v] = 1;
 for (int u : g[v])
   if (!used[u]) {
    if (lose[v]) win[u] = 1;
    else if (-deg[u] == 0) lose[u] = 1;
    else continue;
    dfs(u);
  }
}
void retrogradeAnalysis(int n, vi initLose, vi initWin) {
 for (int v: initLose) lose[v] = 1;
 for (int v: initWin) win[v] = 1;
 forn (i, n)
  if (!used[i] && (win[i] || lose[i]))
    dfs(i);
```

7 Geometry

```
ClosestPoints (SweepLine)
#include "header.h"
const int N = 2e5;
struct Pnt {
 int x, y, i;
 bool operator <(const Pnt &p) const { return mp(y, i) < mp(p.y,
  \hookrightarrow p.i); }
ll d2 = 8e18, d = (ll) sqrt(d2) + 1;
Pnt p[N];
inline ll sqr(int x){
 return (LL)x * x;
inline void relax(const Pnt &a, const Pnt &b){
 ll tmp = sqr(a.x - b.x) + sqr(a.y - b.y);
 if (tmp < d2)
   d2 = tmp, d = (LL)(sqrt(d2) + 1 - 1e-9); // round up
inline bool xless(const Pnt &a, const Pnt &b){
 return a.x < b.x;
int main() {
 int n:
 scanf("%d", &n);
 forn(i, n)
  scanf("%d%d", &p[i].x, &p[i].y), p[i].i = i;
 sort(p, p + n, xless);
 set < Pnt > s;
 int l = 0;
   set < Pnt > :: iterator \ it \_r = s.lower\_bound(p[r]), \ it \_l = it \_r;
   for (; it _{r} := s.end() \&\& it _{r-} > y - p[r].y < d; ++it _r)
    relax(*it_r, p[r]);
```

struct Pnt{

dbl x,y;

 $Pnt():x(0),y(0)\{\}$

 $Pnt(dbl _x,dbl _y):x(_x),y(_y)\{\}$

```
while (it l = s.begin() \&\& p[r].y - (--it l)->y < d)
    relax(*it l, p[r]);
                                                                                   \hookrightarrow y+B.y); }
   s.insert(p[r]);
   while (l \le r \&\& p[r].x - p[l].x >= d)
                                                                                   \hookrightarrow y-B.y); }
    s.erase(p[l++]);
 printf("\%.9f \ n", sqrt(d2));
                                                                                   \rightarrow // LL
 return 0:
       ConvexHull
typedef vector<Pnt> vpnt;
inline bool by Angle (const Pnt &a, const Pnt &b) {
 dbl x = a \% b;
 return eq(x, 0) ? a.len2() < b.len2() : x < 0;
vpnt convexHull(vpnt p){
 int n = sz(p);
 assert(n > 0);
 swap(p[0], *min element(all(p)));
 forab(i, 1, n)
 \mathbf{p}[\mathbf{i}] = \mathbf{p}[\mathbf{i}] - \mathbf{p}[0];
 sort(p.begin() + 1, p.end(), byAngle);
      , (1) (2)
                                                                                      auto l = len();
 (1):
 int k = p.size() - 1;
 while(k > 0 \&\& eq((p[k-1]-p.back()) \% p.back(), 0))
                                                                                      auto l = len();
 reverse(pi.begin() + k, pi.end());*/
                                                                                      x/=l, y/=l;
 int rn = 0;
 vpnt r(n);
 r[rn\!+\!+]\,=\,p[0];
                                                                                      return Pnt(-y, x);
 forab(i, 1, n)
   Pnt q = p[i] + p[0];
   while(rn \geq 2 \&\& geq((r[rn - 1] - r[rn - 2]) \% (q - r[rn - 2]), 0)) //
   \rightarrow (2) ge
    --rn:
   r[rn\!+\!+]=q;
 }
                                                                                   inline void read(){
 r.resize(rn);
 return r;
                                                                                      x=\_x, y=\_y;
28
       GeometryBase
#include < bits/stdc++.h>
                                                                                };
using namespace std;
                                                                               struct Line{
typedef long long LL;
                                                                                   dbl a, b, c;
typedef long double LD;
typedef double dbl;
const dbl EPS = 1e-9;
const int PREC = 20;
inline bool eq(dbl a, dbl b) { return abs(a-b) <= EPS; }
inline bool gr(dbl a, dbl b) { return a>b+EPS; }
inline bool geq(dbl a, dbl b) { return a>=b-EPS; }
inline bool ls(dbl a, dbl b){ return a < b-EPS; }
inline bool leq(dbl a, dbl b) { return a <= b+EPS; }
```

```
inline Pnt operator +(const Pnt &B) const{ return Pnt(x+B.x,
inline Pnt operator - (const Pnt &B) const { return Pnt(x-B.x,
inline dbl operator *(const Pnt &B) const{ return x*B.x + y*B.y; }
inline dbl operator %(const Pnt &B) const { return x*B.y - y*B.x; }
inline Pnt operator *(dbl\ k) const{ return Pnt(x*k, y*k); }
inline Pnt operator /(dbl \ k) const{ return Pnt(x/k, y/k); }
inline Pnt operator -() const { return Pnt(-x, -y); }
inline void operator +=(const Pnt &B){ x+=B.x, y+=B.y; }
inline void operator -= (const Pnt &B) { x-=B.x, y-=B.y; }
inline void operator =(dbl k)\{x^*=k, y^*=k; \}
inline bool operator ==(const Pnt &B){ return abs(x-B.x)<=EPS
\rightarrow && abs(y-B.y)<=EPS; }
inline bool operator != (const Pnt &B){ return abs(x-B.x)>EPS ||
\hookrightarrow abs(y-B.y)>EPS; \hat{}
inline bool operator < (const Pnt &B) { return abs(x-B.x) <= EPS ?
\rightarrow y<B.y-EPS: x<B.x; }
inline dbl angle() const { return atan2(y, x); } // LD
inline dbl len2() const { return x*x+y*y; } // LL
inline dbl len() const{ return sqrt(x*x+y*y); } // LL, LD
inline Pnt getNorm() const{
   return Pnt(x/l, y/l);
inline void normalize(){
inline Pnt getRot90() const{ //counter-clockwise
inline Pnt getRot(dbl a) const{ // LD
   dbl si = sin(a), co = cos(a);
   return Pnt(x*co - y*si, x*si + y*co);
   int _x,_y;
scanf("%d%d",&_x,&_y);
inline void write() const {
   printf("%.*f %.*f ", PREC, (double)x, PREC, (double)y);
Line():a(0),b(0),c(0)\{\}
Line(dbl a, dbl b, dbl c):a(a),b(b),c(c)
Line(const Pnt &A, const Pnt &B){ // it normalizes (a,b),

→ important in d(), normalToP()

   Pnt n = (B-A).getRot90().getNorm();
   a = n.x, b = n.y, c = -(a*A.x + b*A.y);
inline dbl d(const Pnt &p) const{ return a*p.x + b*p.y + c; }
inline Pnt no() const {return Pnt(a, b);}
inline Pnt normalToP(const Pnt &p) const{ return Pnt(a,b) *
\rightarrow (a*p.x + b*p.y + c); }
```

inline void write() const{

```
\begin{array}{ll} & \operatorname{printf}("\%.*f~\%.*f~\%.*f~",~\operatorname{PREC},~(double)a,~\operatorname{PREC},~(double)b,\\ &\hookrightarrow&\operatorname{PREC},~(double)c);\\ &\}\\ \}; \end{array}
```

29 GeometryInterTangent

```
void buildTangent(Pnt p1, dbl r1, Pnt p2, dbl r2, Line &l) { // r1, r2
     = radius with sign
   Pnt\ p=\ p2\ \text{-}\ p1;
   l.c = r1;
   dbl c2 = p.len2(), c1 = sqrt(c2 - sqr(r2));
   \begin{array}{l} l.a = \left( -p.x * (r1 - r2) + p.y * c1 \right) / c2; \\ l.b = \left( -p.y * (r1 - r2) - p.x * c1 \right) / c2; \end{array}
   l.c -= l.no() * p1;
   assert(eq(l.d(p1), r1));
   assert(eq(l.d(p2), r2));
struct Circle {
   Pnt p;
   dbl r;
vector<Pnt> v; // to store intersection
// Intersection of two lines
int line line(const Line &l, const Line &m){
   dbl z = m.a * l.b - l.a * m.b,
          x = m.c * l.b - l.c * m.b,
          y = m.c * l.a - l.c * m.a;
   if(fabs(z) > EPS){
       v.pb(Pnt(-x/z, y/z));
      return 1:
   else if(fabs(x) > EPS || fabs(y) > EPS)
      return 0; // parallel lines
      return 2; // same lines
// Intersection of Circle and line
void circle_line(const Circle &c, const Line &l){
   dbl d = l.d(c.p);
   if(fabs(d) > c.r + EPS)
      return:
   if(fabs(fabs(d) / c.r - 1) < EPS)
      v.pb(c.p - l.no() * d);
       dbl \ s = sqrt(fabs(sqr(c.r) - sqr(d)));
       v.pb(c.p - l.no() * d + l.no().getRot90() * s);
       v.pb(c.p - l.no() * d - l.no().getRot90() * s);
   }
}
// Intersection of two circles
void circle circle(const Circle &a, const Circle &b){
   circle line(a, Line((b.p - a.p) * 2, a.p.len2() - b.p.len2() + sqr(b.r) -
    \hookrightarrow sqr(a.r)));
// Squared distance between point p and segment [a..b]
dbl dist2(Pnt p, Pnt a, Pnt b){
   if ((p - a) * (b - a) < 0) return (p - a).len2();
   if ((p - b) * (a - b) < 0) return (p - b).len2();
   dbl \ d = fabs((p - a) \% (b - a));
   return d * d / (b - a).len2();
}
```

30 GeometrySimple

```
int sign(dbl a) \{ return (a > EPS) - (a < -EPS); \}
// Checks, if point is inside the segment
inline bool inSeg(const Pnt &p, const Pnt &a, const Pnt &b) {
   \text{return eq}((p - a) \ \% \ (p - b), \ 0) \ \&\& \ leq((p - a) \ * \ (p - b), \ 0);
// Checks, if two intervals (segments without ends) intersect AND do

→ not lie on the same line

inline bool subIntr(const Pnt &a, const Pnt &b, const Pnt &c, const
\hookrightarrow Pnt &d){
   return
          sign((b - a) \% (c - a)) * sign((b - a) \% (d - a)) == -1 \&\&
          sign((d - c) \% (a - c)) * sign((d - c) \% (b - c)) == -1;
}
// Checks, if two segments (ends are included) has an intersection
inline bool checkSegInter(const Pnt &a, const Pnt &b, const Pnt &c,
return inSeg(c, a, b) || inSeg(d, a, b) || inSeg(a, c, d) || inSeg(b, c, d)
   \rightarrow || subIntr(a, b, c, d);
inline dbl area(vector<Pnt>p){
   dbl s = 0;
   int n = sz(p);
   p.pb(p[0]);
   forn(i, n)
      s += p[i + 1] \% p[i];
   p.pop\_back();
   return abs(s) / 2;
// Check if point p is inside polygon <n, q[]>
int contains slow(Pnt p, Pnt *z, int n){
   int cnt = 0;
   forn(j, n){
      Pnt a = z[j], b = z[(j + 1) \% n];
      if\ (inSeg(p,\,a,\,b))
         return -1; // border
      if (\min(a.y, b.y) - EPS \le p.y \&\& p.y < \max(a.y, b.y) - EPS)
          cnt += (p.x < a.x + (p.y - a.y) * (b.x - a.x) / (b.y - a.y));
   return cnt & 1; // 0 = outside, 1 = inside
}
//for convex polygon
//assume polygon is counterclockwise-ordered
bool contains fast(Pnt p, Pnt *z, int n) {
   Pnt \mathbf{o} = \mathbf{z}[0];
   if(gr((p-o)\% (z[1]-o), 0) || ls((p-o)\% (z[n-1]-o), 0))
      return 0;
   \quad \text{int } l=0, \ r=n-1;
   while(r - l > 1){
      int m = (l + r) / 2;
      if(gr((p - o) \% (z[m] - o), 0))
         r = m;
      else
         l = m;
   return leq((p - z[l]) % (z[r] - z[l]), 0);
}
// Checks, if point "i" is in the triangle "abc" IFF triangle in CCW
→ order
inline int isInTr(int i, int a, int b, int c){
   return
          gr((p[b] - p[a]) \% (p[i] - p[a]), 0) \&\&
```

gr((p[c] - p[b]) % (p[i] - p[b]), 0) &&

```
gr((p[a] - p[c]) \% (p[i] - p[c]), 0);
}
      Halfplanes Intersection
const int \max n = (int)4e5 + 9;
const dbl eps = 1e-12;
dbl sqr(dbl x) \{ return x * x; \}
struct pnt{
 LL operator * ( pnt p ) { return (LL)x * p.y - (LL)y * p.x; }
 LL operator ^ (pnt p) { return (LL)x * p.x + (LL)y * p.y; }
 pnt ort() { return pnt(-y, x); }
 dbl ang() \{ return atan2(y, x); \}
 LL d2() { return x * x + y * y; }
pnt st, v, p[maxn];
int n, sp, ss[maxn], ind[maxn], no[maxn], cnt[maxn], k = 0, a[maxn],
\hookrightarrow b[maxn];
dbl ang[maxn];
pnt Norm(int k) \{ return (p[a[k]] - p[b[k]]).ort(); \}
void AddPlane( int i, int j ){
 a[k] = i, b[k] = j, ind[k] = k;
 ang[k] = Norm(k).ang();
bool angLess(int i, int j) { return ang[i] < ang[j];}
void Unique()
 int i = 0, k2 = 0;
 while (i < k)
   int ma = ind[i], st = i;
   pnt no = Norm(ma);
   for (i++; i < k \&\& fabs(ang[ind[st]] - ang[ind[i]]) < eps; i++)
    if ((no \hat{p}[a[ma]]) < (no \hat{p}[a[ind[i]]]))
     ma = ind[i];
   ind[k2++] = ma;
 k = k2;
dbl xx, yy, tmp;
#define BUILD(a1, b1, c1, i) \
 dbl a1 = Norm(i).x;
 dbl b1 = Norm(i).y;
 tmp = sqrt(a1 * a1 + b1 * b1); \setminus
 a1 /= tmp, b1 /= tmp; \setminus
 dbl c1 = -(a1 * p[a[i]].x + b1 * p[a[i]].y);
\mathbf{void} \ \mathbf{FindPoint}(\ \mathbf{int}\ \mathbf{i},\ \mathbf{int}\ \mathbf{j},\ \mathbf{dbl}\ \mathbf{step} = 0.0\ ) \{
 BUILD(a1, b1, c1, i);
 BUILD(a2, b2, c2, j);
 xx = -(c1 * b2 - c2 * b1) / (a1 * b2 - a2 * b1);
 yy = (c1 * a2 - c2 * a1) / (a1 * b2 - a2 * b1);
 dbl no = sqrt(sqr(a1 + a2) + sqr(b1 + b2));
 xx += (a1 + a2) * step / no;
 yy += (b1 + b2) * step / no;
void TryShiftPoint( int i, int j, dbl step )
```

```
FindPoint(i, j, step);
 forn(i, k){
  BUILD(a1,\ b1,\ c1,\ ind[i]);
   if (a1 * xx + b1 * yy + c1 < eps)
    return;
 puts("Possible");
 printf("%.20lf %.20lf\n", (double)xx, (double)yy);
 exit(0);
void PushPlaneIntoStack( int i )
 while (sp >= 2 \&\& ang[i] - ang[ss[sp - 2]] + eps < M PI){
   FindPoint(i, ss[sp - 2]);
   BUILD(a1, b1, c1, ss[sp - 1]);
   if ((a1 * xx + b1 * yy + c1) < -eps)
   sp--;
 ss[sp{++}]\,=\,i;
int main()
 scanf("%d", &n);
 forn(i, n)
  scanf("%d%d", &p[i].x, &p[i].y);
 \mathbf{p}[\mathbf{n}] = \mathbf{p}[0];
 // Find set of planes
 forn(i, sp)
   AddPlane(max(ss[i],\,ss[i+1]),\,min(ss[i],\,ss[i+1]));
 forn(i, n - 1)
   AddPlane(i + 1, i);
 sort(ind, ind + k, angLess);
 int old K = k;
 Unique();
 forn(i, oldK)
  no[i] = i;
 forn(i, k){
   int j = oldK + i, \, x = ind[i];
   ang[j] = ang[x] + 2 * M_PI;
   a[j] = a[x];
   b[j] = b[x];
   ind[i+k]=j,\,no[j]=x;\\
 sp = 0;
 forn(i, 2 * k)
  PushPlaneIntoStack(ind[i]);
 forn(t, sp)
   if (++cnt[no[ss[t]]] > 1){
    TryShiftPoint(ss[t], ss[t - 1], 1e-5);
    break;
 return 0;
```

```
Graphs
32
      2-SAT
// MAXVAR - 2 * vars
int cntVar = 0, val[MAXVAR], usedSat[MAXVAR], comp[MAXVAR];
vi topsortSat;
vi g[MAXVAR], rg[MAXVAR];
inline int newVar() {
 cntVar++;
 return (cntVar - 1) * 2;
inline int Not(int v) { return v ^ 1; }
inline void Implies(int v1, int v2) { g[v1].pb(v2), rg[v2].pb(v1); }
inline void Or(int v1, int v2) { Implies(Not(v1), v2), Implies(Not(v2),
\rightarrow v1); }
inline void Nand(int v1, int v2) { Or(Not(v1), Not(v2)); }
inline void setTrue(int v) { Implies(Not(v), v); }
void dfs1(int v) {
 usedSat[v] = 1;
 for (int to : g[v])
   if (!usedSat[to]) dfs1(to);
 topsortSat.pb(v);
void dfs2(int v, int c) {
 comp[v] = c;
 for (int to : rg[v])
   if (!comp[to]) dfs2(to, c);
int getVal(int v) { return val[v]; }
// cntVar
bool solveSat() {
 \begin{array}{l} forn(i,\; 2\; *\; cntVar)\; usedSat[i] \; = \; 0; \\ forn(i,\; 2\; *\; cntVar) \end{array}
  if (!usedSat[i]) dfs1(i);
 reverse(all(topsortSat));
 int c = 0;
 for (int v : topsortSat)
  if (!comp[v]) dfs2(v, ++c);
 forn(i, cntVar) {
   if (comp[2 * i] == comp[2 * i + 1]) return false;
   if (comp[2 * i] < comp[2 * i + 1]) val[2 * i + 1] = 1;
   else val[2 * i] = 1;
 return true;
      Bridges
33
int up[MAX_N], tIn[MAX_N], timer;
vector<vi> comps;
vi st;
struct Edge {
 int to, id;
 Edge(int \_to, int \_id) : to(\_to), id(\_id) \{\}
vector < Edge > g[MAX_N];
void newComp(int size = 0) {
```

```
comps.emplace_back(); //
 while (sz(st) > size) {
   comps.back().pb(st.back());
   st.pop back();
void findBridges(int v, int parentEdge = -1) {
 if (up[v]) /
   return;
 up[v] = tIn[v] = ++timer;
 st.pb(v);
 for (Edge e : g[v]) {
   if (e.id == parentEdge)
    continue;
   int u = e.to;
   if (!tIn[u]) {
    int size = sz(st);
    find Bridges(u,\ e.id);
    if (up[u] > tIn[v])
      newComp(size);
   up[v] = min(up[v], up[u]);
// find bridges newComp()
void run(int n) {
 forn (i, n)
   if (!up[i]) {
    findBridges(i);
    newComp();
}
34
      Cut Points
bool used[MAX M];
int tIn[MAX_N], timer, isCut[MAX_N], color[MAX_M], compCnt;
struct Edge {
 int to, id;
 Edge(int to, int id): to( to), id( id) {}
vector<Edge> g[MAX N];
int dfs(int v, int parent = -1) {
 tIn[v] = ++timer;
 \quad \text{int } up = tIn[v], \, x = 0, \, y = (parent \mathrel{\mathop:}= \text{-}1);
 for (Edge p : g[v]) {
   int u = p.to, id = p.id;
   if (id != parent) {
    int t, size = sz(st);
    if (!used[id])
      used[id] = 1, st.push_back(id);
    if (!tIn[u]) { // not visited yet
      t = dfs(u, id);
      \mathrm{if}\ (t\,>=\,t\,\mathrm{In}[v])\ \{
        ++x, ++compCnt;
        while (sz(st) != size) {
         color[st.back()] = compCnt;
          st.pop back();
    } else
      t = tIn[u];
    up = \min(up,\,t);
 }
```

```
if (x + y > = 2)
                                                                                return:
   isCut[v] = 1; // v is cut vertex
                                                                              int lSize = getSize(root->l);
 return up;
                                                                              if (lSize >= size) {
                                                                                split(root->l, a, root->l, size);
                                                                                if (root->l) root->l->p = root;
      Eulerian Cycle
35
                                                                                b = root, b->p = b;
                                                                              } else {
struct Edge {
                                                                                split(root->r, root->r, b, size - lSize - 1);
 int to, used;
                                                                                if (root->r) root->r->p = root;
 Edge(): to(-1), used(0) \{\}
                                                                                a=root,\,a\text{-}\!>\!p=a;
 Edge(int v): to(v), used(0) \{\}
                                                                               a->p=a;
                                                                              recalc(root);
vector<Edge> edges;
vi g[MAX N], res, ptr;
// ptr
                                                                             inline Node* rotate(Node* root, int k) {
                                                                              if (k == 0) return root;
void dfs(int v) {
                                                                              Node *l, *r;
 for(; ptr[v] < sz(g[v]);)  {
                                                                              split(root, l, r, k);
   \quad \quad \mathbf{int} \ id = g[v][ptr[v] + +];
                                                                              return merge(r, l);
   if (!edges[id].used) {
    edges[id].used = edges[id ^ 1].used = 1;
    dfs(edges[id].to);
                                                                             inline pair < Node*, int > goUp(Node* root) {
    res.pb(id); //
                                                                              int pos = getSize(root->l);
                                                                              while (root->p!= root)
                                                                                pos += (root->p->r == root ? getSize(root->p->l) + 1:0), root
 res.pb(v); // res
                                                                                \Rightarrow = root->p:
                                                                              return mp(root, pos);
      Euler Tour Tree
                                                                             {\tt inline\ Node*\ deleteFirst(Node*\ root)\ \{}
mt19937 rng(239);
                                                                              split(root, a, root, 1);
struct Edge {
                                                                              edges[a->e.v].erase(mp(a->e.u, a));
  int v, u;
                                                                              return root;
  Edge(int v, int u): v(v), u(u) 
                                                                             inline Node* getNode(int v, int u) {
struct Node {
                                                                              return edges[v].lower_bound(mp(u, nullptr))->snd;
 Node *l, *r, *p;
 Edge e;
 int y, size;
                                                                             inline void cut(int v, int u) {
 Node(Edge e): l(nullptr), r(nullptr), p(this), e(e), y(rng()), size(1)
                                                                              auto pV = goUp(getNode(v, u));
                                                                              auto pU = goUp(getNode(u, v));
};
                                                                              int l = \min(pV.snd, pU.snd), r = \max(pV.snd, pU.snd);
                                                                              Node *a, *b, *c;
inline int getSize(Node* root) { return root ? root->size : 0; }
                                                                              split(pV.fst, a, b, l);
                                                                              split(b, b, c, r - l);
inline void recalc(Node* root) { root->size = getSize(root->l) +
                                                                              deleteFirst(b);
\rightarrow getSize(root->r) + 1; }
                                                                              merge(a, deleteFirst(c));
set<pair<int, Node*>> edges[MAX N];
                                                                            in line \ pair {<} Node^*, \ int {>} \ getRoot(int \ v) \ \{
Node* merge(Node *a, Node *b) {
                                                                              return !sz(edges[v]) ? mp(nullptr, 0) : goUp(edges[v].begin()->snd);
 if (!a) return b;
 if (!b) return a;
 if (a->y < b->y) {
                                                                            inline Node* makeRoot(int v) {
  a->r = merge(a->r, b);
                                                                              auto root = getRoot(v);
   if (a->r) a->r->p = a;
                                                                              return rotate(root.fst, root.snd);
   recalc(a);
   return a:
                                                                             inline Node* makeEdge(int v, int u) {
 b->l = merge(a, b->l);
                                                                              Node* e = new Node(Edge(v, u));
 if (b->l) b->l->p = b;
                                                                              edges[v].insert(mp(u, e));
 recalc(b);
                                                                              return e:
 return b;
                                                                             inline void link(int v, int u) {
void split(Node *root, Node *&a, Node *&b, int size) {
                                                                              Node \ ^*vN = makeRoot(v), \ ^*uN = makeRoot(u);
 if (!root) {
                                                                              merge(merge(vN,\,makeEdge(v,\,u)),\,uN),\,makeEdge(u,\,v));
   a\,=\,b\,=\,\mathrm{nullpt}\,\mathrm{r};
```

```
forn (v, n - 1)
}
                                                                              if (d[n][v] := INF) {
                                                                               ld\ curAns = -INF;
37
     Hamilton Cycle
                                                                               int curPos = -1;
                                                                               forn(k, n)
// - n*2^n
                                                                                 if (curAns \le (d[n][v] - d[k][v]) * (ld) (1) / (n - k))
vi g[MAX_MASK];
                                                                                  cur Ans = (d[n][v] - d[k][v]) * (ld) (1) / (n - k), \ cur Pos = k;
int adj[MAX_MASK], dp[1 << MAX_MASK];
                                                                               if (ansValue > curAns)
                                                                                 ansValue = curAns, dist = curPos, curV = v;
vi hamiltonCycle(int n) {
 fill(dp, dp + (1 << n), 0);
                                                                            if (curV == -1) return ans Value;
 forn (v, n) {
                                                                            for (int iter = n; iter != dist; iter--)
   adj[v] = 0;
                                                                             ans.pb(curV), curV = p[iter][curV];
   \quad \text{for (int to}:g[v])
                                                                            reverse(all(ans));
    adj[v] = (1 << to);
                                                                            return ansValue;
 dp[1] = 1;
 forn (mask, (1 << n))
  forn(v, n)
                                                                                Kuhn's algorithm
    if (mask & (1 << v) && dp[mask ^ (1 << v)] & adj[v])
      dp[mask] = (1 << v);
                                                                              - n , - m
 vi ans;
 int mask = (1 << n) - 1, v;
                                                                          int n, m, paired[2 * MAX_N], used[2 * MAX_N];
 if (dp[mask] \& adj[0]) \{
                                                                          vi g[MAX N];
  forab (i, 1, n)
    if ((1 << i) \& (mask \& adj[0]))
                                                                           bool dfs(int v) {
     v = i:
                                                                            if (used[v]) return false;
   ans.pb(v);
                                                                            used[v] = 1;
   mask \hat{} = (1 << v);
                                                                            for (int to : g[v])
   while(v) {
                                                                             if (paired[to] == -1 \mid | dfs(paired[to])) {
    forn(i, n)
                                                                               paired[to] = v, paired[v] = to;
      if ((dp[mask] & (1 << i)) & (adj[i] & (1 << v))) {
                                                                               return true:
       v=i;
                                                                             }
       break:
                                                                            return false;
     }
    mask \hat{} = (1 << v);
    ans.pb(v);
                                                                          int kuhn() {
                                                                            int ans = 0;
                                                                            forn (i, n + m) paired[i] = -1;
 return ans;
                                                                            for (int run = 1; run;) \{
                                                                              run = 0;
                                                                             fill(used, used + n + m, 0);
      Karp with cycle
                                                                             forn(i, n)
                                                                               if (!used[i] && paired[i] == -1 && dfs(i))
int d[MAX N][MAX N], p[MAX N][MAX N];
                                                                                 ans++, run = 1;
vi g[MAX_N], ans;
                                                                            return ans;
struct Edge {
 int a, b, w;
 Edge(int _a, int _b, int _w): a(_a), b(_b), w(_w) {}
                                                                           // Max -- A+, B-
                                                                           // Min -- A-, B+
vector<Edge> edges;
                                                                          vi minCover, maxIndependent;
void fordBellman(int s, int n) {
                                                                          void dfsCoverIndependent(int v) {
 forn (i, n + 1)
  forn (j, n + 1)
                                                                            if (used[v]) return;
    d[i][j]\,=\,INF;
                                                                            used[v]=1;\\
 \mathbf{d}[0][\mathbf{s}] = 0;
                                                                            for (int to:g[v])
 forab (i, 1, n + 1)
                                                                             if (!used[to])
                                                                               used[to] = 1, dfsCoverIndependent(paired[to]);
   for (auto &e: edges)
    if (d[i-1][e.a] < INF \&\& d[i][e.b] > d[i-1][e.a] + e.w)
      d[i][e.b] = d[i-1][e.a] + e.w, p[i][e.b] = e.a;
                                                                          void findCoverIndependent() {
ld karp(int n) {
                                                                            fill(used, used + n + m, 0);
                                                                            forn (i, n)
 int s = n++;
 forn (i, n - 1)
                                                                             if (paired[i] == -1)
   g[s].pb(sz(edges)), edges.pb(Edge(s, i, 0));
                                                                               dfsCoverIndependent(i);
 fordBellman(s, n);
                                                                            forn (i, n)
 ld ansValue = INF;
                                                                              if (used[i]) maxIndependent.pb(i);
 int curV = -1, dist = -1;
                                                                              else minCover.pb(i);
```

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SPb HSE (Labutin, Podguzov, Bogomolov)

return minDiv;

dfs(0);

```
46 Factorial
// Returns pair (rem, deg), where rem = n! % mod,
 / deg = k: mod^k | n!, mod is prime, O(mod log mod)
pii fact(int n, int mod) {
 \dot{\text{int rem}} = 1,\, \deg = 0,\, n \text{Copy} = n;
 while (nCopy) nCopy /= mod, deg += nCopy;
 while (n > 1) {
   rem = (rem * ((n / mod) \% 2 ? -1 : 1) + mod) \% mod;
   for (int i = 2; i <= n \% \text{ mod}; i++)
    rem = (rem * 111 * i) \% mod;
   n /= mod;
 return mp(rem % mod, deg);
47
      Gauss
const double EPS = 1e-9;
int gauss(double **a, int n, int m) { // n is number of equations, m is
\hookrightarrow number of variables
 int row = 0, col = 0;
 vi par(m, -1);
 vector < double > ans(m, 0);
 for (col = 0; col < m \&\& row < n; col++) {
  int best = row:
   for (int i = row; i < n; i++)
    if (abs(a[i][col]) > abs(a[best][col]))
   if (abs(a[best][col]) < EPS) continue;
   par[col] = row;
   forn (i, m + 1) swap(a[row][i], a[best][i]);
   forn (i, n)
    if (i != row) {
      \label{eq:double_k} \begin{array}{l} \textbf{double} \ k = \ a[i][col] \ / \ a[row][col]; \end{array}
      for (int j = col; j \le m; j++)
        a[i][j] = k * a[row][j];
   row ++;
 int single = 1;
 forn (i, m)
   if (par[i] != -1) ans[i] = a[par[i]][m] / a[par[i]][i];
   else single = 0;
 forn (i, n) {
   double cur = 0;
   for (int j = 0; j < m; j++)
    \operatorname{cur} += \operatorname{ans}[j] * \operatorname{a}[i][j];
   \mathrm{if}\ (abs(cur\ \hbox{-}\ a[i][m]) > \mathrm{EPS})
    return 0:
 if (!single)
  return 2;
 return 1;
      Gauss binary
const int MAX = 1024;
int gaussBinary(vector<br/>bitset<MAX>> a, int n, int m) {
 int row = 0, col = 0;
 vi par(m, -1);
 for (col = 0; col < m \&\& row < n; col++) {
   int best = row;
   for (int i = row; i < n; i++)
    \quad \text{if } (a[i][col] > a[best][col]) \\
      best = i;
   if \ (a[best][col] == 0) \\
    continue;
   par[col] = row;
```

```
swap(a[row],\ a[best]);
   forn (i, n)
    if (i!= row && a[i][col])
        a[i] ^= a[row];
   row++;
  }
 vi ans(m, 0);
 forn (i, m)
   if (par[i] != -1)
    ans[i] \, = \, a[par[i]][n] \, \, / \, \, a[par[i]][i];
  bool ok = 1;
 forn (i, n) {
   int cur = 0;
   forn (j, m) cur ^= (ans[j] & a[i][j]);
   if (\operatorname{cur} != a[i][n]) \text{ ok} = 0;
 return ok:
49
       Gcd
int gcd(int a, int b) {
 return b ? gcd(b, a \% b) : a;
int gcd(int a, int b, int &x, int &y) {
 if (b == 0) {
  x = 1, y = 0;
   return a;
  }
 int g = gcd(b, a \% b, x, y), newX = y;
 y = x - a / b * y;
 x = newX;
 return g;
void diophant(int a, int b, int c, int &x, int &y) {
 int g = gcd(a, b, x, y);
 if (c \% g != 0) return;
 x *= c / g, y *= c / g;
 // next solutions: x += b / g, y -= a / g
int inverse(int a, int mod) { // Returns -1, if a and mod are not

→ coprime

 int x, y;
 int g = \gcd(a, \mod, x, y);
 return g == 1 ? (x \% mod + mod) \% mod : -1;
vi inverseForAll(int mod) {
 vi r(mod, 0);
 r[1] = 1;
 for (int i = 2; i < mod; i++)
   \mathbf{r}[\mathbf{i}] = (\bmod - \mathbf{r}[\bmod \% \mathbf{i}]) * (\bmod / \mathbf{i}) \% \mathbf{mod};
 return r;
50 Gray
int gray(int n) {
 return n \hat{} (n >> 1);
int revGray(int n) {
 int k = 0;
 for (; n; n >> = 1) k ^= n;
 return k;
```

```
Miller-Rabin Test
51
vector \langle int \rangle primes = \{2, 3, 5, 7, 11, 13, 17, 19, 23\};
bool isPrimeMillerRabin(ll n) {
 int k = 0:
 ll t = n - 1;
 while (t \% 2 == 0) k++, t /= 2;
 for (auto p : primes) {
   ll g = \underline{gcd}(n, (ll) p);
   if (g > 1 \&\& g < n) return 0;
   if (g == n) return 1;
   ll \ b = power(p, \ t, \ n), \ last = n \ \text{-} \ 1;
   bool was = 0;
   forn (i, k + 1) {
     if (b == 1 \&\& last != n - 1)
      return 0;
     if (b == 1) {
      was = 1;
      break;
     last = b, b = mul(b, b, n);
   if (!was) return 0;
 return 1;
52
      Phi
int phi(int n) {
 int result = n;
 for (int i = 2; i * i <= n; i++)
   if (n \% i == 0) {
     while (n \% i == 0) n /= i;
    result -= result / i;
 if (n > 1) result -= result / n;
 return result;
int inversePhi(int a, int mod) {
 return power(a, phi(mod) - 1, mod);
      Pollard
53
inline void pollardFoo(ll& x, ll mod) {
   = (mul(x, x, mod) + 1) \% mod;
vector<pair<ll, int>> factorize(ll n) {
 if (n == 1) return \{\};
 if (isPrimeMillerRabin(n)) return \{mp(n, 1)\};
 if (n <= 100) {
   vector < pair < ll, int >> ans;
   for (int i = 2; i * i <= n; i++)
    if (n \% i == 0) {
      int cnt = 0;
      while (n \% i == 0) n /= i, cnt++;
      ans.pb(mp(i, cnt));
   if (n != 1) ans.pb(mp(n, 1));
   sort(all(ans));
   return ans:
  while (1) {
   ll a = rand() \% n, b = a;
     pollardFoo(a, n), pollardFoo(b, n), pollardFoo(b, n);
    \begin{array}{l} ll~g = \_\_gcd(abs(a-b),~n);\\ if~(g \mathrel{\mathop:}= 1)~\{ \end{array}
```

```
if (g == n)
       break;
      auto ans1 = factorize(g);
      auto ans2 = factorize(n / g);
      vector{<}pair{<}ll,\ int{>}{>}\ ans;
      ans1.insert(ans1.end(), all(ans2));
      sort(all(ans1));
      for (auto np: ans1)
       if (sz(ans) == 0 || np.fst != ans.back().fst)
         ans.pb(np);
         ans.back().snd += np.snd;
      return ans;
  }
 }
 assert(0);
      Power And Mul
inline ll fix(ll a, ll mod) { // a in [0, 2 * mod)
 if (a >= mod) a -= mod;
 return a:
// \text{ Returns (a * b) \% mod, 0 } <= a < mod, 0 <= b < mod
ll mulSlow(ll a, ll b, ll mod) {
 if (!b) return 0;
 ll\ c = fix(mulSlow(a,\ b\ /\ 2,\ mod)\ *\ 2,\ mod);
 return b & 1 ? fix(c + a, mod) : c;
ll mul(ll a, ll b, ll mod) {
 ll q = (ld) a * b / mod;
 ll r = a * b - mod * q;
 while (r < 0) r += mod;
 while (r >= mod) r -= mod;
 return r;
int power(int a, int n, int mod) {
 if (!n) return 1;
 int b = power(a, n / 2, mod);
 b = (b * 111 * b) \% mod;
 return n & 1? (a * 111 * b) % mod: b;
ll powerLL(ll a, ll n, ll mod) {
 if (!n) return 1;
 ll b = power(a, n / 2, mod);
 b = mul(b, b, mod);
 return\ n\ \&\ 1\ ?\ mul(a,\,b,\,mod):b;
int powerFast(int a, int n, int mod) {
 int res = 1;
 while (n) {
  if (n & 1)
   res = (res * 111 * a) \% mod;
  a = (a * 111 * a) % mod;
  n /= 2;
 return res;
      Primitive Root
```

int primitiveRoot(int mod) { // Returns -1 if no primitive root exists

vi fact:

```
int ph = phi(mod);
                                                                              int go(int v, int c) {
                                                                                if (g[v], go[c] == -1) {
 int n = mod;
                                                                                 if (g[v].next[c] \mathrel{\mathop:}= -1) \ g[v].go[c] = g[v].next[c];
 for (int i = 2; i * i <= n; i++) {
   if (n % i == 0) {
                                                                                 else\ g[v].go[c] = !v\ ?\ 0: go(getLink(v),\ c);
    fact.pb(i);
    while (n % i == 0) n /= i;
                                                                                \mathtt{return}\ g[v].go[c];
 if (n > 1) fact.pb(n);
                                                                                    Prefix-function
 forab (i, 2, mod + 1) {
   bool ok = 1:
                                                                              vi prefix(const string &s) {
   for (int j = 0; j < sz(fact) && ok; j++)
                                                                               int n = sz(s);
    ok &= power(i, ph / fact[j], mod) != 1;
                                                                                vi pr(n);
   if (ok) return i;
                                                                                forab (i, 1, n + 1) {
 }
                                                                                 int j = pr[i-1];
 return -1;
                                                                                 while (j > 0 && s[i] != s[j]) j = pr[j - 1];
                                                                                 if (s[i] == s[j]) j++;
                                                                                 pr[i] = j;
                                                                                }
      Simpson
56
                                                                                return pr;
double f(double x) { return x; }
double simpson(double a, double b, int iterNumber) {
                                                                              59
                                                                                     Z-function
 double res = 0, h = (b - a) / iterNumber;
 forn (i, iterNumber + 1)
                                                                              vi z(const string & s) {
   res += f(a + h * i) * ((i == 0) || (i == iterNumber) ? 1 : ((i & 1))
                                                                                int n = sz(s);
   \Rightarrow == 0) ? 2 : 4);
                                                                                vi z(n);
 return res * h / 3;
                                                                                for (int i = 1, l = 0, r = 0; i < n; i++) {
                                                                                 if (i \le r) z[i] = min(r - i + 1, z[i - l]);
                                                                                 \text{while } (i+z[i] < n \text{ \&\& } s[z[i]] == s[i+z[i]]) \text{ } z[i]++;
                                                                                 if (i + z[i] - 1 > r) l = i, r = i + z[i] - 1;
       Strings
10
                                                                                }
                                                                                return z;
57
       Aho-Corasick
const int ALPHA = 26;
const int MAX N = 1e5;
                                                                                    Hashes
struct Node {
                                                                              const int P = 239017;
 int next[ALPHA], term; //
 int go[ALPHA], suf, p, pCh; /
                                                                              inline int add(int a, int b, int m) {
 Node(): term(0), suf(-1), p(-1) {
                                                                               a += b:
   fill(next, next + ALPHA, -1);
                                                                                return a >= m ? a - m : a;
   fill(go, go + ALPHA, -1);
};
                                                                              inline int sub(int a, int b, int m) {
                                                                               a = b:
Node g[MAX N];
                                                                                \mathtt{return}\ a\,<\,0\,\,?\,\,a\,+\,\,\textcolor{ret}{m}\,:a;
int last;
void add(const string &s) {
                                                                              const int MOD_X = 1e9 + 9, MOD_Y = 1e9 + 7;
 int now = 0;
 for(char x : s) {
                                                                              // using H = unsigned long long;
   if (g[now].next[x - 'a'] == -1) {
                                                                              struct H {
    g[now].next[x - 'a'] = ++last;
                                                                                int x, y;
    g[last].p = now, g[last].pCh = x;
                                                                                H(): x(0), y(0) \{ \}
                                                                                H(int _x): x(_x), y(_x) \{ \}
   now = g[now].next[x - 'a'];
                                                                                H(int _x, int _y): x(_x), y(_y) \{\}
                                                                                inline H operator+(const H& h) const { return H(add(x, h.x,
 g[now].term = 1;
                                                                                \rightarrow MOD_X), add(y, h.y, MOD_Y)); }
                                                                                inline H operator-(const H& h) const { return H(sub(x, h.x,
                                                                                \rightarrow MOD_X), sub(y, h.y, MOD_Y)); }
int go(int v, int c);
                                                                                inline H operator*(ll k) const { return H(int((x * k) \% MOD_X),
                                                                                \rightarrow int((y * k) % MOD Y)); }
int getLink(int v) {
                                                                                inline H operator*(const H& h) const{ return H(int((ll(x) * h.x) %
 if (g[v].suf == -1) {
                                                                                \rightarrow MOD X), int((ll(y) * h.y) % MOD Y)); }
   if (!v || !g[v].p) g[v].suf = 0;
                                                                                inline bool operator == (const H& h) const { return x == h.x && y
   else g[v].suf = go(getLink(g[v].p), g[v].pCh);
                                                                                \hookrightarrow == h.y; }
                                                                                inline bool operator!=(const H& h) const { return x != h.x || y !=
 return g[v].suf;
                                                                                \hookrightarrow h.y; }
                                                                                inline bool operator<(const H & h) const { return x < h.x \mid\mid (x ==
```

 \hookrightarrow h.x && y < h.y); }

```
explicit inline operator ll() const { return ll(x) * MOD_Y + y + 1; }
                                                                                     \mathbf{v} = \mathbf{r}:
  \rightarrow // > 0
};
                                                                                           Suffix Array (+stable)
                                                                                    63
H deg[MAX_N], h[MAX_N];
                                                                                    int sLen, num[MAX N + 1];
inline H get(int l, int r) { return h[r] - h[l] * deg[r - l]; }
                                                                                    \frac{\text{char s}[\text{MAX}_{\text{N}} + 1];}{\text{char s}[\text{MAX}_{\text{N}} + 1];}
                                                                                    int \ p[MAX\_N], \ col[MAX\_N], \ inv[MAX\_N], \ lcp[MAX\_N];
void init(const string& s) {
 int n = sz(s);
                                                                                    inline int mod(int x) {
 \deg[0] = 1;
                                                                                     return (x + sLen) % sLen;
 forn (i, n)
   h[i + 1] = h[i] * P + s[i], deg[i + 1] = deg[i] * P;
                                                                                    void buildArray(int n) {
                                                                                      sLen = n;
                                                                                      int ma = max(n, 256);
61
       Manaker
                                                                                      forn (i, n)
void manaker(const string& s, int *z0, int *z1) {
                                                                                       col[i] = s[i], p[i] = i;
 int n = sz(s);
                                                                                      for (int k2 = 1; k2 / 2 < n; k2 *= 2) {
 forn (t, 2) {
   int *z = t ? z1 : z0, l = -1, r = -1; // [l..r]
                                                                                       int k = k2 / 2;
   forn \ (i,\ n\ \text{-}\ t)\ \{
                                                                                        memset(num, 0, sizeof(num));
    int k = 0;
                                                                                       forn (i, n) num[col[i] + 1]++;
                                                                                       forn (i, ma) num[i + 1] += num[i];
     if (r > i + t) {
      int j = l + (r - i - t);
                                                                                         inv[num[col[mod(p[i]-k)]]++] = mod(p[i]-k);
      k = \min(z[j], j - l);
                                                                                        int cc = 0;
     while (i - k) = 0 \&\& i + k + t < n \&\& s[i - k] == s[i + k + t]
                                                                                       forn (i, n) {
                                                                                         bool add = col[inv[i]] != col[inv[i - 1]];
     z[i] = k;
                                                                                         add \models col[mod(inv[i] + k)] \models col[mod(inv[i - 1] + k)];
     if (k \&\& i + k + t > r)
                                                                                         if (i && add) cc++;
      l = i - k + 1, r = i + k + t - 1;
                                                                                         num[inv[i]] = cc;
                                                                                       forn (i, n) p[i] = inv[i], col[i] = num[i];
}
                                                                                      memset(num, 0, sizeof(num));
      Palindromic Tree
                                                                                      forn (i, n) num[col[i] + 1]++;
                                                                                      forn (i, ma) num[i + 1] += num[i];
const int ALPHA = 26;
                                                                                      forn\ (i,\ n)\ inv[num[col[i]]++]=i;
                                                                                     forn (i, n) p[i] = inv[i];
struct Vertex {
                                                                                      forn\ (i,\ n)\ inv[p[i]] = i;
 int suf, len, next[ALPHA];
  Vertex() { fill(next, next + ALPHA, 0); }
};
                                                                                    void buildLCP(int n) {
                                                                                     int len = 0:
int vn, v;
                                                                                      forn (ind, n){
Vertex \ t[MAX\_N + 2];
                                                                                       int i = inv[ind];
int n, s[MAX N];
                                                                                        len = max(0, len - 1);
                                                                                       if (i!= n - 1)
int get(int i) { return i < 0 ? -1 : s[i]; }
                                                                                         while (\operatorname{len} < \operatorname{n} \&\& \operatorname{s}[\operatorname{mod}(\operatorname{p}[i] + \operatorname{len})] == \operatorname{s}[\operatorname{mod}(\operatorname{p}[i+1] + \operatorname{len})])
                                                                                           len++;
void init() {
                                                                                       lcp[i] = len;
 t[0].len = -1, vn = 2, v = 0, n = 0;
                                                                                       if (i != n - 1 \&\& p[i + 1] == n - 1) len = 0;
                                                                                    }
void add(int ch) {
 s[n++]=ch;
 while (v != 0 \&\& ch != get(n - t[v].len - 2))
                                                                                    64 Suffix Automaton
   v = t[v].suf;
                                                                                    struct Vx {
 int \& r = t[v].next[ch];
                                                                                        static const int AL = 26;
   t[vn].len = t[v].len + 2;
                                                                                       int len. suf:
   if (!v) t[vn].suf = 1;
                                                                                        int next[AL];
   else {
                                                                                        Vx() \{ \}
                                                                                        V_X(int | l, int | s): len(l), suf(s) {}
    v = t[v].suf;
    while (v != 0 \&\& ch != get(n - t[v].len - 2))
                                                                                    };
      v = t[v].suf;
     t[vn].suf = t[v].next[ch];
                                                                                       static const int MAX_LEN = 1e5 + 100, MAX_V = 2*
   }
   \mathbf{r}=\mathbf{v}\mathbf{n}++;
                                                                                        \hookrightarrow MAX LEN;
                                                                                       int last, vcnt;
```

};

```
if(up)
   Vx \ v[MAX \ V];
                                                                               return S[V->R-up]==c? Pos(V,up-1):Pos();
   SA() { vcnt = 1, last = newV(0, 0); } // root = vertex with number
                                                                               mapt::iterator\ it=V->next.find(c);
   int newV(int len, int suf){
                                                                               return it == V-> next.end() ? Pos()
     v[vent] = Vx(len, suf);
                                                                                    Pos(it->snd,it->snd->elen()-1);
      return vcnt++;
                                                                            }
                                                                           };
   int add(char ch) {
      int p = last, c = ch - 'a';
      last = newV(v[last].len + 1, 0);
                                                                           Pos go down(pNode V,int L,int R){
      while (p \&\& !v[p].next[c]) // added p \&\&
                                                                            if(L==R)
                                                                              return Pos(V,0);
         v[p].next[c] = last, p = v[p].suf;
                                                                            while(1){
      if (!p)
         v[last].suf = 1;
                                                                              V=V->next[S[L]];
                                                                              L+=V->elen();
      else {
                                                                              if(L>=R)
         \quad \text{int } q = v[p].next[c]; \\
                                                                                return Pos(V,L-R);
         if (v[q].len == v[p].len + 1) v[last].suf = q;
            int r = newV(v[p].len + 1, v[q].suf);
            v[last].suf = v[q].suf = r; \\
            memcpy(v[r].next, v[q].next, sizeof(v[r].next));
                                                                           inline pNode calc link(pNode &V){
                                                                            if(!V->link)
            while (p \&\& v[p].next[c] == q)
               v[p].next[c] = r, p = v[p].suf;
                                                                              \rightarrow >R).split edge();
      }
                                                                            \operatorname{return} V-> \operatorname{link};
      return last;
                                                                           Pos add_char(Pos P,int k){
                                                                            while(1){
                                                                              Pos p=P.next char(S[k]);
      Suffix Tree
65
                                                                              if(p.V)
                                                                               return p;
const int MAX L=1e5+10;
                                                                              pNode n=P.split edge();
char S[MAX_L];
                                                                              n\text{-}\!>\!add\_edge(k,\!MAX\_L);
int L;
                                                                              if(!n->P)
                                                                               return Pos(n,0);
struct Node;
                                                                              P = Pos(calc\_link(n), 0);
struct Pos:
                                                                            }
typedef Node *pNode;
                                                                           }
typedef map<char,pNode> mapt;
                                                                           pNode Root;
struct Node{
                                                                           void make tree(){
 pNode P,link;
                                                                            Root=new Node();
 int L,R;
                                                                            Pos P(Root,0);
 mapt next;
                                                                            forn(i,L)
                                                                              P = add char(P,i);
 Node():P(NULL),link(this),L(0),R(0){}
 Node(pNode\ P, int\ L, int\ R) : P(P), link(NULL), L(L), R(R) \{\}
 inline int elen() const{return R-L;}
 inline pNode add edge(int L,int R){return next[S[L]]=new
     Node(this,L,R);
                                                                           11
                                                                                  C++ Tricks
};
struct Pos{
                                                                           66
                                                                                 Fast allocation
 pNode V;
 int up;
 Pos():V(NULL),up(0)\{\}
                                                                           const int MAX MEM = 1e8;
 Pos(pNode V, int up): V(V), up(up) \{\}
                                                                           int mpos = 0;
 pNode split edge() const {
                                                                           char mem[MAX MEM];
                                                                           inline void^* operator new(size\_t n) {
   if (!up)
                                                                            char *res = mem + mpos;
    return V:
   _{\text{int }}L\!\!=\!V\!\!-\!\!>\!\!L,\;M\!\!=\!\!V\!\!-\!\!>\!\!R\!\!-\!\!up;
                                                                            mpos += n;
   pNode P=V->P, n=new Node(P,L,M);
                                                                            assert(mpos <= MAX MEM);
   P->next[S[L]]=n;
                                                                            return (void*) res;
   n->next[S[M]]=V;
   V\text{-}{>}P\text{=}n,\;V\text{-}{>}L\text{=}M;
                                                                           inline void operator delete(void*) {}
   return n;
                                                                           inline void* operator new[](size_t) { assert(0); }
 Pos next_char(char c) const{
                                                                           inline void operator delete[](void*) { assert(0); }
```

x = x * 10 + c - 0', c = getChar();

return x;

template < class T>

inline T readInt() {

 $\operatorname{int} s = 1, c = \operatorname{readChar}();$

}

template <class T> inline void writeInt(T x) {

 $\mathbf{s}[\mathbf{n} + +] = \phantom{\mathbf{b}}^{\dagger} \mathbf{0}^{\dagger} + \mathbf{x} \hspace{0.1cm}\% \hspace{0.1cm} \mathbf{10}, \hspace{0.1cm} \mathbf{x} \hspace{0.1cm} / = \hspace{0.1cm} \mathbf{10};$

if (x < 0)

char s[24]; int n = 0:

while (x || !n)

putchar('-'), x = -x;

```
T x = 0;
 if (c == '-')
  s = -1, c = getChar();
 while ('0' <= c \&\& c <= '9')
  x = x * 10 + c - '0', c = getChar();
 return \mathbf{s} == 1 ? \mathbf{x} : -\mathbf{x};
inline double readDouble() {
 int s = 1, c = readChar();
 double x = 0;
 if (c == '-')
  s = -1, c = getChar();
 while (0' <= c \&\& c <= 9')
 x = x * 10 + c - 0', c = getChar();
 if (c == '.') {
  c = getChar();
   double coef = 1;
   while ('0' <= c \&\& c <= '9')
    x += (c - '0') * (coef *= 1e-1), c = getChar();
 return \mathbf{s} == 1 ? \mathbf{x} : -\mathbf{x};
}
inline void readWord(char *s) {
 int c = readChar();
 while (c > 32)
   *s++ = c, c = getChar();
  *s = 0;
}
inline bool readLine(char *s) {
 int c = getChar();
 while (c != '\n' && c != -1)
   *s++ = c, c = getChar();
 *s = 0;
 return c != -1;
int writePos = 0;
char writeBuf[BUF SIZE];
inline void writeChar(int x) {
 if (writePos == BUF SIZE)
   fwrite(writeBuf, 1, BUF SIZE, stdout), writePos = 0;
 writeBuf[writePos++] = x;
}
inline void flush() {
 if (writePos)
   fwrite(writeBuf, 1, writePos, stdout), writePos = 0;
template <class T>
inline void writeInt(T x, int outputLen) {
 if (x < 0)
   writeChar('-'), x = -x;
 char s[24];
 int n = 0:
 while (x || !n)
  s[n++] = '0' + x \% 10, x /= 10;
 while (n < outputLen)
   s[n++] = "0";
 while (n--)
   writeChar(s[n]);
template < class \ T >
inline void writeUInt(T x, int outputLen) {
```

```
char\ s[24];
 int n = 0;
 while (x || !n)
  s[n++] = "0" + char(x \% 10), x /= 10;
 while (n < outputLen)
  s[n++] = 0;
 while (n--)
  writeChar(s[n]);
inline void writeWord(const char *s) {
 while (*s)
  writeChar(*s++);
inline void writeDouble(double x, int outputLen) {
 if (x < 0)
  writeChar('-'), x = -x;
 int t = (int) x;
 writeUInt(t), x = t;
 writeChar('');
 for (int i = outputLen - 1; i > 0; i--) {
  x *= 10;
  t = std::min(9, (int) x);
  writeChar('0' + t), x = t;
 }
 x *= 10;
 t = std::min(9, (int)(x + 0.5));
 writeChar('0' + t);
```