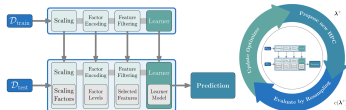


# Introduction to Machine Learning

## Hyperparameter Tuning - Pipelines and AutoML

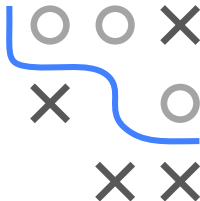
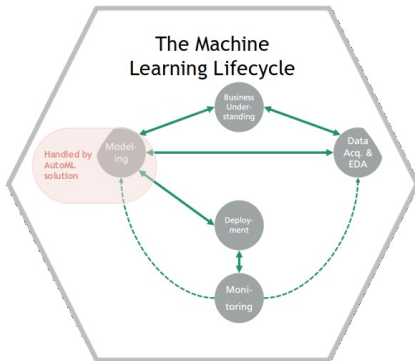


### Learning goals

- Pipelines as connected steps of learnable operations
- Sequential pipeline
- Pipelines and DAGs

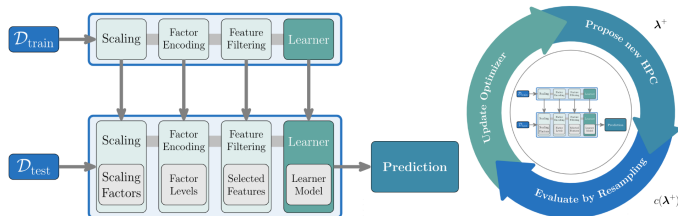
## CASE FOR AUTOML

- More and more tasks are approached via data driven methods.
- Data scientists often rely on trial-and-error.
- The process is especially tedious for similar, recurring tasks.
- Not the entire machine learning lifecycle can be automated.



# PIPELINES AND AUTOML

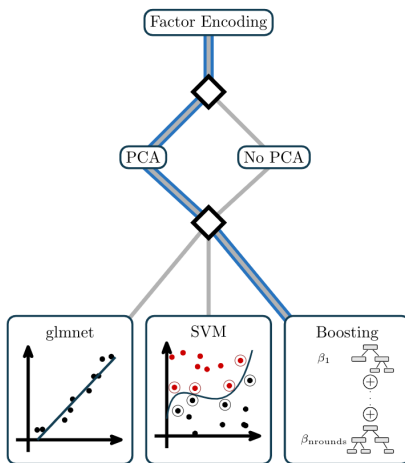
- ML typically has several data transformation steps before model fit
- If steps are in succession, data flows through sequential pipeline
- NB: Each node has a train and predict step and learns params
- And usually has HPs



**Pipelines are required to embed full model building into CV to avoid overfitting and biased evaluation!**

# PIPELINES AND AUTOML

- Further flexibility by representing pipeline as DAG
- Single source accepts  $\mathcal{D}_{\text{train}}$ , single sink returns predictions
- Each node represents a preprocessing operation, a learner, a postprocessing operation or controls data flow
- Can be used to implement ensembles, operator selection, ...



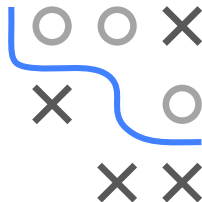
# PIPELINES AND AUTOML

- HPs of pipeline are the joint set of all HPs of its contained nodes:

$$\tilde{\Lambda} = \tilde{\Lambda}_{\text{op},1} \times \cdots \times \tilde{\Lambda}_{\text{op},k} \times \tilde{\Lambda}_{\mathcal{I}}$$

- HP space of a DAG is more complex:  
Depending on branching / selection  
different nodes and HPs are active  
→ **hierarchical search space**

| Search Space $\tilde{\Lambda}$ |      |                       |        |
|--------------------------------|------|-----------------------|--------|
| Name                           | Type | Bounds/Values         | Trafo  |
| encoding                       | C    | one-hot, impact       |        |
| ◇ pca                          | C    | PCA, no PCA           |        |
| ◇ learner                      | C    | glmnet, SVM, Boosting |        |
| if learner = glmnet            |      |                       |        |
| s                              | R    | $[-12, 12]$           | $2^x$  |
| alpha                          | R    | $[0, 1]$              | –      |
| if learner = SVM               |      |                       |        |
| cost                           | R    | $[-12, 12]$           | $2^x$  |
| gamma                          | R    | $[-12, 12]$           | $2^x$  |
| if learner = Boosting          |      |                       |        |
| eta                            | R    | $[-4, 0]$             | $10^x$ |
| nrounds                        | I    | $\{1, \dots, 5000\}$  | –      |
| max_depth                      | I    | $\{1, \dots, 20\}$    | –      |



A graph that includes many preprocessing steps and learner types can be flexible enough to work on a large number of data sets

**Combining such graph with an efficient tuner is key in AutoML**

# AUTOML – CHALLENGES

- Most efficient approach?
- How to integrate human a-priori knowledge?
- How can we best (computationally) transfer “experience” into AutoML? Warmstarts, learned search spaces, etc.
- Multi-Objective goals, including model interpretability
- AutoML as a process is too much of a black-box, hurts adoption.

