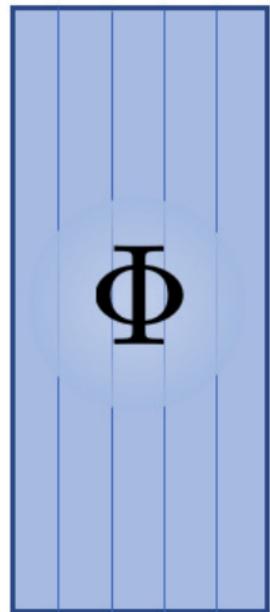
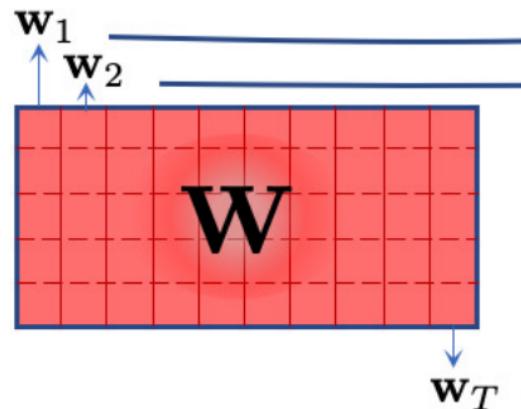


*parameter set*



*compositional  
vectors*



*task parameter  
vectors*

$$\begin{aligned}\theta_1 &= \Phi w_1 \\ \theta_2 &= \Phi w_2 \\ &\vdots \\ \theta_\tau &= \Phi w_\tau \\ &\vdots \\ \theta_T &= \Phi w_T\end{aligned}$$

$$\pi_{\theta_1}$$

$$\pi_{\theta_2}$$

$$\pi_{\theta_T}$$



**button press**



**door open**

⋮



**peg insert side**

$[\phi_1, \phi_2, \dots, \phi_K]$