Totally Integrated Automation Portal	

Robot_sekvenca [FB5]

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	#inicijalizacija MOVE			
	0 — EN — ENO — OUT1 —	#stepNum		
etwork 2: Automat	ika aktivna			
	"HMI_signals".			
	auto_mode		KRAJ ——-{ JMP }—— -	
etwork 4: S0 - hand	dshake			
	#stepNum varenje lint 0	MOVE EN ENO IN © OUT1 #stepNum	1	
etwork 5: S1 - Poče	etak robotske sekvence			
#stepNum == Int 1	%I4.1 "HMI_signals". "stol_final" strana_1_prisutni	%15.0 "KR120_R2700_ %18.6 2_at_HOME" "Zavar_gotov"	MOVE EN ENO IN № OUT1 —#stepNum	1
	"stol_home" strana_2_prisutni			

Totally Integrated Automation Portal		
Network 6: S2 - Izvrša	ivanje programa zavarivanja	
	#stepNum "pocetak_rada" MOVE	
	2	
Network 7: S3 - progr	am završen	
	%I5.1 "KR120_R2700_ #stepNum 2_programEnded" MOVE	
	Int EN ENO	
	3 U—IN d OUT1 — #stepNum	
Network 8: RADNJE	1	
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Network 9: Pokretani	e robotskog programa	
	"Sekvence_DB". KR120_R2700_	
	#stepNum 2_startProgram	
Network 10: Kraj		
	KRAJ	
	#nop	