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dsDEFDAT Robot program
EXTERNAL DECLARATIONS
; *
            Default dat Template for Kuka-Krc
           Created 14/08/2007 by Siemens PLM
;*
;* Study
                         : Njegovec diplomski
;* Program
                         : Robot program
;* Generation Date
                         : 09/03/2025 at 20:55:04
;* Robot
                         : KR120 R2700 2
;* User
                         : nnjegovec
;* Tecnomatix Software : Process Simulate Disconnected 16.1
                          : Kuka-Krc 4.38.2
; Positions (if any)
;# ----- START PATH : Op zavar -----
DECL E6POS XP1 HOME={X 839.48, Y 0.11, Z 698.66, A 180, B 0, C 180}
DECL FDAT FP1 HOME={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL PDAT PPPI HOME={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP1 20={X 0,Y 1515.55,Z 1516.16,A -90,B 64.498,C 180}
DECL FDAT FP1_20={TOOL_NO 1,BASE NO 0,IPO FRAME #BASE,POINT2[] " "}
DECL PDAT PPPT_20={VEL 100, ACC 100, APO_DIST 0, GEAR_JERK 50}
DECL E6POS XP1_25={X 0,Y 1699.98,Z 995.2,A 0,B 0,C-119.24}
DECL FDAT FP1_25={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL PDAT PPPI 25={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP1 30={X 0,Y 1893.84,Z 946,A 0,B 0,C -104.24}
DECL FDAT FP1 30={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL PDAT PPP1_30={VEL 100, ACC 100, APO_DIST 0, GEAR_JERK 50}
DECL E6POS XP1 40={X -15.86,Y 2305.14,Z 1006.23,A -0.084,B 0,C -105}
DECL FDAT FP1 40={TOOL NO 1,BASE NO 0,IPO FRAME #BASE,POINT2[] " "}
DECL PDAT PPPT_40={VEL 100, ACC 100, APO_DIST 0, GEAR_JERK 50}
DECL E6POS XP1
                _45={X 284.14,Y 2304.7,Z 1006.23,A -0.084,B 0,C -105}
DECL FDAT FP1 45={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL LDAT LLP1_45={VEL_0.1,ACC 100,APO_DIST 0,APO_FAC 0,AXIS_VEL 100,AXIS_ACC 100,ORI_TYP
#VAR, CIRC TYP #BASE, JERK FAC 50, GEAR JERK 50, EXAX IGN 0}
DECL E6POS XP1 50=\{X 284.\overline{0}3, Y 2227.42, \overline{Z} 1026.94, A -0.084, B 0, C -105\}
DECL FDAT FP1_50={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL LDAT LLPT 50={VEL 0.1, ACC 100, APO_DIST 0, APO_FAC 0, AXIS_VEL 100, AXIS_ACC 100, ORI_TYP
#VAR, CIRC_TYP #BASE, JERK FAC 50, GEAR_JERK 50, EXAX_IGN 0}
DECL E6POS XP1_55={X 284.14,Y 2304.7,Z 1006.23,A -0.084,B 0,C -105}
DECL FDAT FP1 55={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL LDAT LLPI 55={VEL 0.1, ACC 100, APO DIST 0, APO FAC 0, AXIS VEL 100, AXIS ACC 100, ORI TYP
#VAR, CIRC TYP #BASE, JERK FAC 50, GEAR JERK 50, EXAX IGN 0}
DECL E6POS XP1 60=\{X-15.\overline{9}1,Y\ 2266.5,Z\ 1016.59,A-0.\overline{0}84,B\ 0,C-105\}
DECL FDAT FP1 60={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL LDAT LLPI 60={VEL 0.1, ACC 100, APO DIST 0, APO FAC 0, AXIS VEL 100, AXIS ACC 100, ORI TYP
#VAR,CIRC_TYP #BASE, JERK_FAC 50, GEAR_JERK 50, EXAX_IGN 0}
DECL E6POS XP1_70={X 0,Y 2107.08,Z 891.89,A 0,B 0,C -104.24}

DECL FDAT FP1_70={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}

DECL PDAT PPP1_70={VEL 100,ACC 100,APO_DIST 0,GEAR_JERK 50}
DECL E6POS XP1\overline{80}={X -15.93,Y 2253.38,\overline{Z} 813.05,A -\overline{0}.084,B 0,C -105}
DECL FDAT FP1 80={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL PDAT PPP1 80={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP1 85={X 284.07,Y 2252.93,Z 813.05,A -0.084,B 0,C -105}
DECL FDAT FP1_85={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL LDAT LLP1_85={VEL 0.1, ACC 100, APO_DIST 0, APO_FAC 0, AXIS_VEL 100, AXIS_ACC 100, ORI_TYP
#VAR, CIRC_TYP #BASE, JERK_FAC 50, GEAR_JERK 50, EXAX_IGN 0}
DECL E6POS XP1 90={X 284.01, Y 2214.3, Z 823.4, A -0.084, B 0, C -105}
DECL FDAT FP1 90={TOOL_NO 1, BASE_NO 0, IPO_FRAME #BASE, POINT2[] " "}
DECL LDAT LLPI 90={VEL 0.1, ACC 100, APO DIST 0, APO FAC 0, AXIS VEL 100, AXIS ACC 100, ORI TYP
#VAR, CIRC TYP #BASE, JERK FAC 50, GEAR JERK 50, EXAX IGN 0}
DECL E6POS XP1 95={X 284.\overline{0}7,Y 2252.93,\overline{Z} 813.05,A -0.\overline{0}84,B 0,C -105}
DECL FDAT FP1 95={TOOL NO 1,BASE NO 0,IPO FRAME #BASE,POINT2[] " "}
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DECL PDAT PPP1 95={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP1 100={X -15.99,Y 2214.74,Z 823.4,A -0.084,B 0,C -105}
DECL FDAT FP1 100={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL LDAT LLP1_100={VEL 0.1,ACC 100,APO_DIST 0,APO_FAC 0,AXIS_VEL 100,AXIS_ACC
100,ORI_TYP #VAR,CIRC_TYP #BASE, JERK_FAC 50, GEAR_JERK 50, EXAX_IGN 0}
DECL E6POS XP1_110={X 0,Y 1515.55,Z 1516.16,A -90,B 64.498,C 180}
DECL FDAT FP1 110={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL PDAT PPPI 110={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP1 120={X -0.11,Y 639.48,Z 698.66,A -90,B 0,C 180}
DECL FDAT FP1_120={TOOL_NO 1,BASE NO 0,IPO FRAME #BASE,POINT2[] " "}
DECL PDAT PPPI 120={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
;# ----- START PATH : Op brusenje kapica -----
DECL E6POS XP2 HOME=\{X 839.48, Y 0.11, \overline{Z} 698.66, A 180, B 0, C 180\}
DECL FDAT FP2 HOME={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL PDAT PPP2 HOME={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP2 10={X 1057.95, Y -242.69, Z 663.51, A 90, B 0, C 180}
DECL FDAT FP2_10={TOOL_NO 1,BASE NO 0,IPO FRAME #BASE,POINT2[] " "}
DECL PDAT PPP2_10={VEL 100, ACC 100, APO_DIST 0, GEAR_JERK 50}
DECL E6POS XP2_20={X 1057.95,Y -242.69,Z 1103.51,A 90,B 0,C 180}

DECL FDAT FP2_20={TOOL NO 1,BASE NO 0,IPO FRAME #BASE,POINT2[] " "}

DECL PDAT PPP2_20={VEL 100,ACC 100,APO DIST 0,GEAR_JERK 50}
DECL E6POS XP2 30={X 1057.95, Y -1022.69, Z 1103.51, A 90, B 22.5, C 180}
DECL FDAT FP2 30={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL PDAT PPP2 30={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP2 40={X 1177.95,Y -1887.38,Z 1445.49,A 90,B 67.5,C 180}
DECL FDAT FP2 40={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL PDAT PPPZ 40={VEL 100,ACC 100,APO DIST 0,GEAR JERK 50}
DECL E6POS XP2_50={X 1177.95,Y -1887.38,Z 825.49,A 0,B 90,C 90}
DECL E6POS XP2_50={X 1177.95,Y -1887.38,Z 825.49,A 0,B 90,C 90}
DECL FDAT FP2_50={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL PDAT PPP2 50={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
DECL E6POS XP2 60={X 1177.95, Y -1887.38, Z 625.49, A 0, B 90, C 90}
DECL FDAT FP2 60={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL LDAT LLP2 60={VEL 0.1, ACC 100, APO DIST 0, APO FAC 0, AXIS VEL 100, AXIS ACC 100, ORI TYP
#VAR, CIRC TYP #BASE, JERK FAC 50, GEAR JERK 50, EXAX IGN 0}
DECL E6POS XP2 70={X 1177.95,Y -1837.38,Z 625.49,A 0,B 90,C 90}
DECL FDAT FP2 70={TOOL NO 1,BASE NO 0,IPO FRAME #BASE,POINT2[] " "}
DECL LDAT LLP2 70={VEL 0.1, ACC 100, APO DIST 0, APO FAC 0, AXIS_VEL 100, AXIS_ACC 100, ORI_TYP #VAR, CIRC_TYP #BASE, JERK_FAC 50, GEAR_JERK 50, EXAX_IGN 0}
DECL E6POS XP2 80={X 1177.95, Y -1887.38, Z 625.49, A 0, B 90, C 90}
DECL FDAT FP2_80={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL LDAT LLP2 80={VEL 0.1, ACC 100, APO DIST 0, APO FAC 0, AXIS VEL 100, AXIS ACC 100, ORI TYP
#VAR, CIRC TYP #BASE, JERK FAC 50, GEAR JERK 50, EXAX IGN 0}
DECL E6POS XP2 90=\{X 1177.95, Y -1937.38, Z 625.49, A 0, B 90, C 90\}
DECL FDAT FP2_90={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL LDAT LLP2 90={VEL 0.1, ACC 100, APO DIST 0, APO_FAC 0, AXIS_VEL 100, AXIS_ACC 100, ORI_TYP
#VAR, CIRC TYP #BASE, JERK FAC 50, GEAR JERK 50, EXAX IGN 0}
DECL E6POS XP2_100={X 1177.95,Y -1887.38,Z 625.49,A 0,B 90,C 90}
DECL FDAT FP2 100={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL LDAT LLPZ 100={VEL 0.1, ACC 100, APO DIST 0, APO_FAC 0, AXIS_VEL 100, AXIS_ACC
100, ORI TYP #VAR, CIRC TYP #BASE, JERK FAC 50, GEAR JERK 50, EXAX IGN 0}
DECL E6POS XP2 110={X 1177.95,Y -1887.38,Z 825.49,A 0,B 90,C 90}
DECL FDAT FP2_110={TOOL_NO 1,BASE_NO 0,IPO_FRAME #BASE,POINT2[] " "}
DECL LDAT LLP2_110={VEL 0.1, ACC 100, APO_DIST 0, APO_FAC 0, AXIS_VEL 100, AXIS_ACC 100, ORI_TYP #VAR, CIRC_TYP #BASE, JERK_FAC 50, GEAR_JERK 50, EXAX_IGN 0}
DECL E6POS XP2_120={X 1177.95, Y -1887.38, Z 1445.49, A 90, B 67.5, C 180}
DECL FDAT FP2 120={TOOL NO 1, BASE NO 0, IPO FRAME #BASE, POINT2[] " "}
DECL PDAT PPP2 120={VEL 100, ACC 100, APO DIST 0, GEAR JERK 50}
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ENDDAT