# **Spring Boot Note**

this repository is some notes about Spring Boot MVC AutoConfiguration

train.txt/test.txt

#### 要求:

- 出租车id必须为5位,比如"14276",我原本的出租车id为"2012000002",改为"00002"即可
- **出发网格坐标**格式为"69.0--/-14.0", 作者没有描述清楚
- 出发方向"abcdefghi",全部规定为e
- 出发时间本数据集可以满足
- 预计寻客时间不清楚怎样算
- 网格变化没有表述清楚, 我设置随机值
- 目标网格id需要进行分类,类别数不得超过2823

```
## 数据样例
```

```
|出租车id|出发网格坐标|出发方向|出发时间|预计寻客时间|网格变化|目标网格id|
|:--:|:--:|:--:|:--:|
|14276|69.0-14.0|d|9.6|1050s|-7.0x2.0y|1677|
|80862|15.0-29.0|a|17.4|6s|0.0x0.0y|2378|
|41136|47.0--44.0|e|0.6|943s|-7.0x-2.0y|2607|
|80345|41.0-38.0|h|1.0|1124s|12.0x-13.0y|253|
|66746|49.0--14.0|b|23.0|354s|0.0x9.0y|2790|
|12195|39.0-33.0|d|12.8|1571s|-2.0x2.0y|2731|
```

# 二、如何处理:

## 1、预处理:

输入: train.txt/test.txt

输出: in\_array, target\_array, test\_in\_array, test\_target\_array, n\_status

• in\_array: 为每一个训练数据编号

```
|出租车id|出发网格坐标|出发方向|出发时间|预计寻客时间|网格变化|
|:--:|:--:|:--:|:--:|
|1|4|7|10|13|16|
|2|5|8|11|14|17|
|3|6|9|12|15|18|
```

• target\_array: 对训练数据目标网格id分类后产生的数组

• test\_in\_array: 为每一个测试数据编号

```
|出租车id|出发网格坐标|出发方向|出发时间|预计寻客时间|网格变化|
|:--:|:--:|:--:|:--:|
|1|4|7|10|13|16|
|2|5|8|11|14|17|
|3|6|9|12|15|18|
```

• test\_target\_array: 对测试数据目标网格id分类后产生的数组

• n status:编号数量

### 2、嵌入并预测

• 训练过程:

```
2570/2570 [============ ] - 1s 518us/step - loss: 7.9458 - acc:
3.8911e-04 - val_loss: 7.9453 - val_acc: 0.0000e+00
Epoch 2/50
0.0023 - val_loss: 7.9450 - val_acc: 0.0000e+00
Epoch 3/50
0.0070 - val_loss: 7.9446 - val_acc: 0.0000e+00
Epoch 4/50
2570/2570 [============ ] - 1s 407us/step - loss: 7.9347 - acc:
0.0237 - val_loss: 7.9442 - val_acc: 0.0000e+00
2570/2570 [============ ] - 1s 401us/step - loss: 7.9296 - acc:
0.0595 - val_loss: 7.9437 - val_acc: 0.0000e+00
Epoch 6/50
2570/2570 [============ ] - 1s 398us/step - loss: 7.9238 - acc:
0.0977 - val_loss: 7.9430 - val_acc: 0.0000e+00
Epoch 7/50
2570/2570 [============= ] - 1s 395us/step - loss: 7.9168 - acc:
0.1533 - val_loss: 7.9423 - val_acc: 0.0000e+00
Epoch 8/50
2570/2570 [============ ] - 1s 393us/step - loss: 7.9088 - acc:
0.2175 - val_loss: 7.9413 - val_acc: 0.0000e+00
Epoch 9/50
0.2580 - val_loss: 7.9402 - val_acc: 0.0000e+00
Epoch 10/50
2570/2570 [============] - 1s 392us/step - loss: 7.8893 - acc:
0.2786 - val_loss: 7.9389 - val_acc: 0.0000e+00
Epoch 11/50
2570/2570 [============== ] - 1s 395us/step - loss: 7.8772 - acc:
0.2798 - val_loss: 7.9373 - val_acc: 0.0000e+00
Epoch 12/50
2570/2570 [============ ] - 1s 392us/step - loss: 7.8640 - acc:
0.2981 - val_loss: 7.9355 - val_acc: 0.0000e+00
Epoch 13/50
2570/2570 [============ ] - 1s 394us/step - loss: 7.8483 - acc:
0.3148 - val_loss: 7.9336 - val_acc: 0.0000e+00
Epoch 14/50
2570/2570 [============== ] - 1s 398us/step - loss: 7.8321 - acc:
0.3113 - val_loss: 7.9314 - val_acc: 0.0000e+00
Epoch 15/50
```

```
2570/2570 [============ ] - 1s 400us/step - loss: 7.8132 - acc:
0.3257 - val_loss: 7.9290 - val_acc: 0.0000e+00
0.3331 - val_loss: 7.9264 - val_acc: 0.0000e+00
Epoch 17/50
2570/2570 [=========== ] - 1s 393us/step - loss: 7.7695 - acc:
0.3518 - val_loss: 7.9236 - val_acc: 0.0000e+00
Epoch 18/50
0.3533 - val_loss: 7.9207 - val_acc: 0.0000e+00
Epoch 19/50
2570/2570 [============ ] - 1s 392us/step - loss: 7.7186 - acc:
0.3533 - val_loss: 7.9176 - val_acc: 0.0000e+00
Epoch 20/50
0.3658 - val_loss: 7.9143 - val_acc: 0.0000e+00
2570/2570 [============= ] - 1s 399us/step - loss: 7.6578 - acc:
0.3599 - val_loss: 7.9112 - val_acc: 0.0000e+00
Epoch 22/50
2570/2570 [============ ] - 1s 396us/step - loss: 7.6253 - acc:
0.3556 - val_loss: 7.9083 - val_acc: 0.0000e+00
Epoch 23/50
0.3669 - val_loss: 7.9056 - val_acc: 0.0000e+00
Epoch 24/50
2570/2570 [============= ] - 1s 404us/step - loss: 7.5505 - acc:
0.3864 - val_loss: 7.9034 - val_acc: 0.0010
Epoch 25/50
0.3875 - val_loss: 7.9014 - val_acc: 0.0010
Epoch 26/50
0.3930 - val_loss: 7.8996 - val_acc: 0.0010
2570/2570 [============ ] - 1s 569us/step - loss: 7.4213 - acc:
0.4148 - val_loss: 7.8981 - val_acc: 0.0010
Epoch 28/50
2570/2570 [============ ] - 1s 406us/step - loss: 7.3736 - acc:
0.4245 - val_loss: 7.8966 - val_acc: 0.0010
Epoch 29/50
0.4385 - val_loss: 7.8952 - val_acc: 0.0010
Epoch 30/50
0.4642 - val_loss: 7.8938 - val_acc: 0.0010
Epoch 31/50
2570/2570 [============ ] - 1s 398us/step - loss: 7.2095 - acc:
0.4981 - val_loss: 7.8928 - val_acc: 0.0000e+00
Epoch 32/50
0.5304 - val_loss: 7.8920 - val_acc: 0.0010
Epoch 33/50
2570/2570 [============ ] - 1s 393us/step - loss: 7.0790 - acc:
0.5689 - val_loss: 7.8912 - val_acc: 0.0010
Epoch 34/50
```

```
0.6008 - val_loss: 7.8904 - val_acc: 0.0010
Epoch 35/50
0.6533 - val_loss: 7.8898 - val_acc: 0.0010
Epoch 36/50
2570/2570 [============ ] - 1s 399us/step - loss: 6.8581 - acc:
0.6938 - val_loss: 7.8895 - val_acc: 0.0010
Epoch 37/50
0.7241 - val_loss: 7.8892 - val_acc: 0.0010
Epoch 38/50
0.7720 - val_loss: 7.8892 - val_acc: 0.0000e+00
Epoch 39/50
0.8132 - val_loss: 7.8893 - val_acc: 0.0010
Epoch 40/50
2570/2570 [============= ] - 1s 396us/step - loss: 6.4874 - acc:
0.8502 - val_loss: 7.8898 - val_acc: 0.0000e+00
Epoch 41/50
2570/2570 [============ ] - 1s 397us/step - loss: 6.3876 - acc:
0.8786 - val_loss: 7.8904 - val_acc: 0.0000e+00
Epoch 42/50
0.9019 - val_loss: 7.8913 - val_acc: 0.0000e+00
Epoch 43/50
0.9152 - val_loss: 7.8928 - val_acc: 0.0000e+00
Epoch 44/50
0.9350 - val_loss: 7.8948 - val_acc: 0.0000e+00
Epoch 45/50
2570/2570 [============ ] - 1s 394us/step - loss: 5.9031 - acc:
0.9537 - val_loss: 7.8972 - val_acc: 0.0010
2570/2570 [============ ] - 1s 392us/step - loss: 5.7697 - acc:
0.9615 - val_loss: 7.9002 - val_acc: 0.0010
Epoch 47/50
2570/2570 [===========] - 1s 394us/step - loss: 5.6253 - acc:
0.9626 - val_loss: 7.9038 - val_acc: 0.0010
Epoch 48/50
0.9700 - val_loss: 7.9078 - val_acc: 0.0010
Epoch 49/50
2570/2570 [============= ] - 1s 397us/step - loss: 5.3287 - acc:
0.9747 - val_loss: 7.9122 - val_acc: 0.0010
Epoch 50/50
2570/2570 [============ ] - 1s 399us/step - loss: 5.1745 - acc:
0.9817 - val_loss: 7.9167 - val_acc: 0.0000e+00
```

#### • 预测结果:

```
[[ 3.64165717e-05 2.74343794e-04
                              4.14482405e-04 ..., 3.78384830e-05
   4.19457101e-05 4.13001580e-05]
[ 3.27585985e-05 2.59199296e-04
                              3.99807584e-04 ..., 3.12815464e-05
   3.27650960e-05 3.39298749e-05]
[ 4.90684688e-05 3.99563200e-04
                              2.82602821e-04 ..., 4.46101440e-05
   4.80465133e-05 4.82552787e-05]
[ 3.68002620e-05 2.34481893e-04
                              5.22579183e-04 ..., 3.41883351e-05
   3.53059768e-05 3.54943259e-05]
3.96053256e-05 4.09918248e-05]
[ 4.50075604e-05 2.86251132e-04 1.95218134e-04 ..., 4.85109158e-05
   3.53059768e-05 3.54943259e-05]
```

• 从预测结果中选100个出现次数最多的值:

```
target_classes = [np.argmax(class_list) for class_list in prob]
print(Counter(target_classes).most_common(100))
```

## 二、输出:

输出两个结果:

## 1、一个hdf5文件:

作用: 用来储存每个周期该模型的信息

存储操作:

```
model = embedding_mlp(n_status)
checkpoint = ModelCheckpoint('models/weigts.{epoch:02d}-{val_acc:.2f}.hdf5',
monitor='val_acc', verbose=0,save_best_only=True, mode='auto')
```

ModelCheckpoint的源码:

```
class ModelCheckpoint(Callback):
   """Save the model after every epoch.
    `filepath` can contain named formatting options,
   which will be filled the value of `epoch` and
   keys in `logs` (passed in `on_epoch_end`).
   For example: if `filepath` is `weights.{epoch:02d}-{val_loss:.2f}.hdf5`,
   then the model checkpoints will be saved with the epoch number and
   the validation loss in the filename.
   # Arguments
       filepath: string, path to save the model file.
       monitor: quantity to monitor.
       verbose: verbosity mode, 0 or 1.
       save_best_only: if `save_best_only=True`,
            the latest best model according to
            the quantity monitored will not be overwritten.
       mode: one of {auto, min, max}.
           If `save_best_only=True`, the decision
```

```
to overwrite the current save file is made
        based on either the maximization or the
        minimization of the monitored quantity. For `val_acc`,
        this should be `max`, for `val_loss` this should
        be `min`, etc. In `auto` mode, the direction is
        automatically inferred from the name of the monitored quantity.
    save_weights_only: if True, then only the model's weights will be
        saved (`model.save_weights(filepath)`), else the full model
        is saved (`model.save(filepath)`).
    period: Interval (number of epochs) between checkpoints.
.....
def __init__(self, filepath, monitor='val_loss', verbose=0,
             save_best_only=False, save_weights_only=False,
             mode='auto', period=1):
    super(ModelCheckpoint, self).__init__()
    self.monitor = monitor
    self.verbose = verbose
    self.filepath = filepath
    self.save_best_only = save_best_only
    self.save_weights_only = save_weights_only
    self.period = period
    self.epochs_since_last_save = 0
    if mode not in ['auto', 'min', 'max']:
        warnings.warn('ModelCheckpoint mode %s is unknown, '
                      'fallback to auto mode.' % (mode),
                      RuntimeWarning)
        mode = 'auto'
    if mode == 'min':
        self.monitor_op = np.less
        self.best = np.Inf
    elif mode == 'max':
        self.monitor_op = np.greater
        self.best = -np.Inf
    else:
        if 'acc' in self.monitor or self.monitor.startswith('fmeasure'):
            self.monitor_op = np.greater
            self.best = -np.Inf
            self.monitor_op = np.less
            self.best = np.Inf
def on_epoch_end(self, epoch, logs=None):
    logs = logs or {}
    self.epochs_since_last_save += 1
    if self.epochs_since_last_save >= self.period:
        self.epochs_since_last_save = 0
        filepath = self.filepath.format(epoch=epoch + 1, **logs)
        if self.save_best_only:
            current = logs.get(self.monitor)
            if current is None:
                warnings.warn('Can save best model only with %s available, '
                              'skipping.' % (self.monitor), RuntimeWarning)
            else:
                if self.monitor_op(current, self.best):
                    if self.verbose > 0:
```

```
print('\nEpoch %05d: %s improved from %0.5f to
%0.5f,'
                                   ' saving model to %s'
                                  % (epoch + 1, self.monitor, self.best,
                                      current, filepath))
                        self.best = current
                        if self.save_weights_only:
                            self.model.save_weights(filepath, overwrite=True)
                             self.model.save(filepath, overwrite=True)
                    else:
                        if self.verbose > 0:
                            print('\nEpoch %05d: %s did not improve' %
                                   (epoch + 1, self.monitor))
            else:
                if self.verbose > 0:
                    print('\nEpoch %05d: saving model to %s' % (epoch + 1,
filepath))
                if self.save_weights_only:
                    self.model.save_weights(filepath, overwrite=True)
                else:
                    self.model.save(filepath, overwrite=True)
```

#### 2、如上所示, k个元素的二元组

(目的地类, 出现次数)

```
[(2298, 14), (1085, 8), (1200, 8), (2260, 8), (1751, 8), (2055, 7), (920, 7), (484, 7), (831, 7), (887, 7), (2149, 6), (2297, 6), (2338, 6), (2426, 6), (600, 6), (2158, 6), (426, 5), (438, 5), (663, 5), (1800, 5), (167, 5), (934, 5), (2050, 4), (2566, 4), (1125, 4), (1130, 4), (2159, 4), (1168, 4), (2303, 4), (286, 4), (299, 4), (2434, 4), (1490, 4), (255, 4), (544, 4), (2139, 4), (548, 4), (756, 4), (1799, 4), (1842, 4), (1852, 4), (868, 4), (2048, 3), (1033, 3), (2077, 3), (68, 3), (2118, 3), (83, 3), (86, 3), (1171, 3), (2196, 3), (1223, 3), (1197, 3), (2223, 3), (1403, 3), (1262, 3), (2291, 3), (2319, 3), (273, 3), (292, 3), (294, 3), (295, 3), (363, 3), (2443, 3), (2444, 3), (1496, 3), (2524, 3), (1503, 3), (480, 3), (496, 3), (2554, 3), (516, 3), (358, 3), (526, 3), (1554, 3), (564, 3), (580, 3), (629, 3), (1668, 3), (1732, 3), (2340, 3), (1762, 3), (740, 3), (1781, 3), (1806, 3), (790, 3), (1873, 3), (1899, 3), (1948, 3), (1998, 3), (2020, 3), (2039, 3), (1016, 3), (2043, 3), (1028, 2), (13, 2), (1040, 2), (24, 2), (41, 2), (349, 2)]
```