MINISTRY OF SCIENCE AND HIGHER EDUCATION OF THE RUSSIAN FEDERATION FEDERAL STATE AUTONOMOUS EDUCATIONAL INSTITUTION OF HIGHER EDUCATION "NOVOSIBIRSK NATIONAL RESEARCH UNIVERSITY STATE UNIVERSITY" (NOVOSIBIRSK STATE UNIVERSITY, NSU)

09.03.01 - Informatics and Computer Engineering
Focus (profile): Software Engineering and Computer Science

"Arkanoid"

Digital platforms project

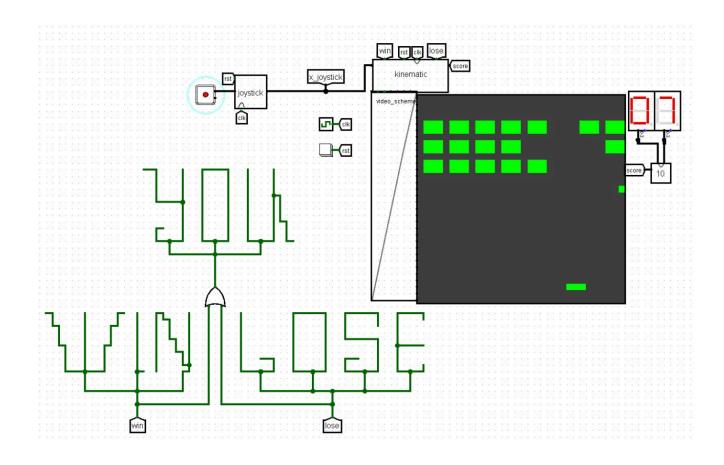
Anisimov Kirill Lebedev Nikolay Romankin Daniil

Contents

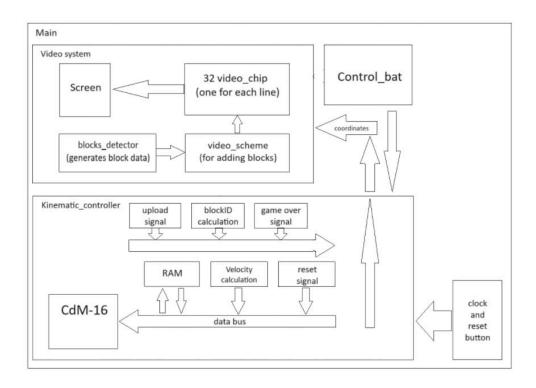
	Introduction	2
1.	Hardware	3
	1.1 Video system	3
	1.1.1 Video_chip	4
	1.1.2 Video_scheme	4
	1.2 Blocks_detector	(
	1.3 Block_paint	ϵ
	1.4 Block_ID calculation	7
	1.5 Bat_control	8
	1.6 Kinematic_controller	Ģ
2.	Cdm-16 software	10
3.	Interaction between software and hardware	19
4.	User manual	19
	Conclusion	20

Introduction

Arkanoid is a classic arcade game in which the player controls a platform, hitting a ball and destroying blocks on the screen. The goal is to clear all the blocks from the field without letting the ball fall. The game ends when a player reaches 72 points (win) or when the ball reaches the bottom of the screen (lose). Our version of Arkanoid is a simplified variant of the original game. It offers one block placement option and one difficulty level. Additionally, the game provides different ball bounce settings and angles. To play, we have used a video display with a resolution of 32 x 32 pixels and a kinematic controller chip to move the bat and ball on the display.



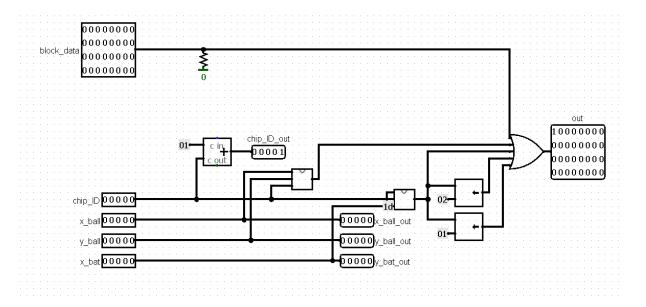
1 Hardware



1.1 Video system

The video system has a display with a resolution of 1024 pixels by 32. Each line of the display is composed of 32 individual pixels, and the lines are numbered sequentially from 0 to 31 on the left side of the screen. The pixels within each line are also numbered consecutively from the top of the screen to the bottom, beginning with 0 and ending at 31. The video chip and video scheme are located within the subsystem. This circuit is responsible for drawing one line at a time on the screen, following the specified numbering pattern.

1.1.1 Video chip

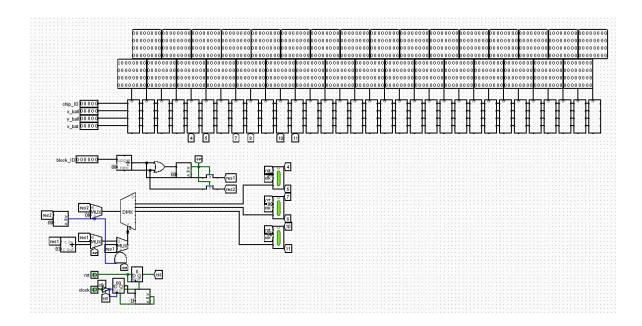


The circuit draws a line on the display. The input data includes the *chip_ID* from 0 to 31, the coordinates of the ball $(x_ball \text{ and } y_ball)$, the position of the right edge of the bat (x_bat) , and information about blocks in the line.

The *chip_ID* sends a signal indicating whether drawing or data transfer is required. The bat is displayed in chip 29 and the ball in the same chip as its y-coordinate. The rocket is created by combining three 32-bit values: the original value at the bat's location, and two additional values shifted left by 1 and 2 bits.

Output is transmitted as a string that will appear on the display, including the coordinates of the ball and bat $(x_ball_out, y_ball_out, x_bat_out)$ and a $chip_ID$ value incremented by 1.

1.1.2 Video scheme

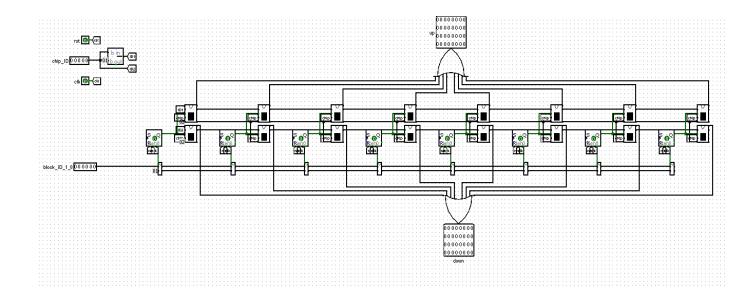


The circuit consists of 32 video chips and 3 detector block circuits. It establishes a connection between the video chips and the display, as well as converting the *block_ID* into a signal that removes the desired block from the display when the ball hits it.

The *block_ID* is a unique identifier for each block on the display, ranging from 1 to 32, from top left to bottom right. When the ID is divided by eight, the resulting remainder ranges from 1 to 8 and is fed into a specific detector block circuit based on the quotient. An 32-bit signal is sent to the input of the selected video chip.

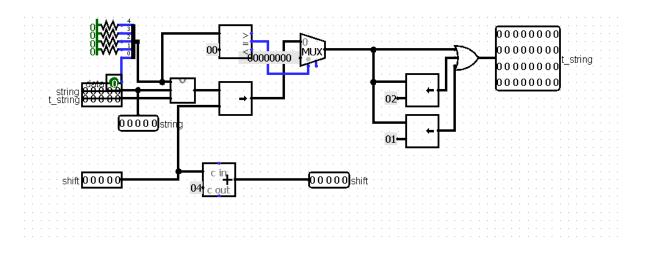
Input to the circuit includes the x-coordinate of the bat $(x_ball \text{ and } y_ball)$, *chip ID*, *block ID*, a *rst* signal (which will be described later), and a *clock* signal (provided by a clock generator).

1.2 Block_detector



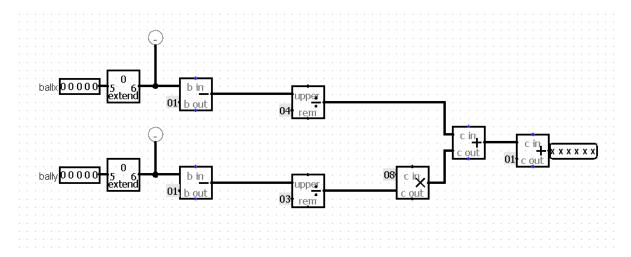
The circuit is responsible for generating the data required to draw blocks. The inputs to the circuit are the *rst*, *clock*, *chip_ID*, and *block_ID*. Based on the *block_ID*, it determines which S trigger should send a signal to erase the block (asynchronously load zero). Using two **block_paint** schemes for each of the eight CP triggers, the block is then drawn in the desired location.

1.3 Block_paint



In this circuit, data for drawing blocks is generated. The input consists of the *data* (trigger CP value), a *string*, and *t_string* for comparison, as well as a *shift* parameter (determining how much the line should be shifted to the right to draw the block at the desired position). If the *data* is zero, a string of 32 zeroes is sent to the *t_string* output. The *shift* value is increased by 4 and passed to the next **block paint** block.

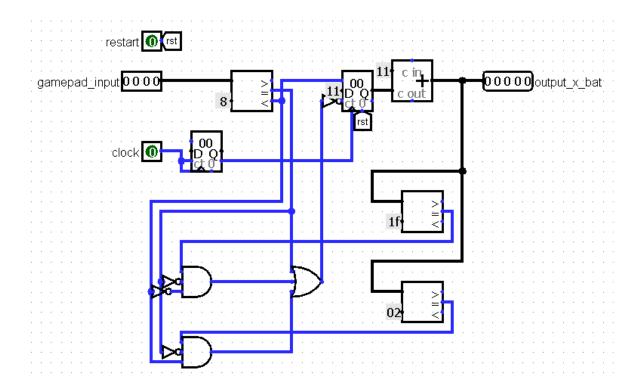
1.4 Block_ID calculation



In this scheme, the block ID is calculated using the formula

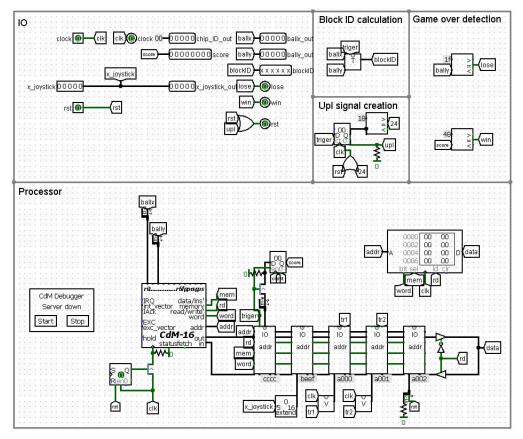
$$((bally - 1) // 3) * 8 + ((ballx - 1) // 4) +1$$

1.5 Bat control



The circuit is responsible for translating the input value from the joystick into the x-coordinate of the rightmost pixel of the bat (output_x_bat), which ranges from 2 to 31. The input is a number (gamepad_input), which can range from 1 to 16. If this number is less than 8, the coordinate will be decreased by 1; if it is greater than or equal to 8, it will be increased by 1. If the number is equal to 8, nothing will happen. Additionally, restrictions have been implemented to prevent the bat from moving to the left of the screen when moving right, and to prevent it from hitting the right side of the screen when moving left. An artificial delay in the rate at which the bat's coordinates change has been implemented due to the addition of an extra counter, which is controlled by the clock frequency.

1.6 Kinematic_controller



In this scheme, interaction with the processor takes place, the <code>block_ID</code> is calculated and a signal indicating victory or defeat is generated. The CDM-16 processor in the Von Neumann configuration was selected for its ability to handle a large number of memory locations and accelerate command execution. This allowed for the implementation of all collision detection and resolution functionality within the device.

The entire assembler code for the game is stored in RAM (random access memory). To enhance the gameplay experience, a system for randomly generating velocities after each collision was implemented, making the trajectory of the ball unpredictable. The new velocity is calculated and communicated to the processor for processing.

2 Cdm-16 software

The CDM-16 assembler program performs several important functions, including:

- Calculating ball physics
- Storing the game score at the specified address (**0xccc**)
- Storing and updating block states
- Handling collisions
- Resetting the game state (reset signal stored at address **0xa002**)
- Reading the x-coordinate (5-bit) of the right pixel of the bat from the Logisim circuit at address **0xbeef** and random velocities stored at addresses **0xa000** and **0xa001**

In our program, we have a game field with a size of 256 x 256, and 8-bit values for coordinates and velocity, which range from 5 to 8 and are generated by a random number generator in Logisim. We use the most significant 5 bits of the coordinates for accurate display in Logisim.

All the blocks are stored in six arrays of zeros and ones, where each array corresponds to a specific Logisim display string (4, 5, 7, 8, 10, or 11).

```
# arrays of blocks, every array corresponds to logisim display string
bricks4: dc 0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,1,1,0,1,1,1,1,0,1,1,1,1,1,0,1,1,1,1,0,1,1,1,1,0,1,1,1,
```

We appended one zero to each array in order to facilitate the handling of collisions. The program begins by setting the initial values:

```
main>
26
     #we use:
28
     #r0 - x-coordinate
     #r1 - x-velocity
29
     #r2 - y-coordinate
30
31
           y-velocity
     #r3 -
32
     #r4,r5,r6 - for temporary calculations
     еi
     ldi r0,128 #x-coordinate
    ldi r1,0×a000 #random x-velocity
35
    ldb r1,r1
36
    ldi r2,224 #y-coordinate
    ldi r3,0×a001 #random y-velocity
    ldb r3,r3
39
     neg r3
40
```

Then, we initiate a while loop with a condition "while the y-coordinate is less than 248" (i.e., when the ball reaches the bottom).

```
41 while
42 | ldi r6,248 #comparing y-coordinate
43 | cmp r2,r6
44 v stays lt
```

After that, we verify for a reset signal, and if it is equal to 1, we reset the score to zero and proceed to the restart subroutine.

The restart subroutine is called when the level ends or when the player presses the reset button.

It sets the flags to different values to prevent re-entry into the subroutine on each new loop iteration, and the game ends at 72 points.

Then, we update the values in the block arrays to the starting values.

```
ldi r6,0
ldi r5, bricks4
ldi r4, bricks5 #rewriting the arrays of blocks
while
    cmp r6.8
stays lt
    ldi r3,0
    stb r5,r3
    stb r4,r3
    ldi r3,1
    add r5,2
    add r4,2
    stb r5,r3
    stb r4,r3
    add r5,2
    add r4,2
    stb r5,r3
    stb r4,r3
    add r5,2
    add r4,2
    stb r5,r3
    stb r4,r3
    add r5,2
    add r4,2
    inc r6
wend
```

We use the "reset" instruction to jump back to the beginning of the program.

```
1697 wend
1698 reset #reseting the programm
1699 rts
```

After checking for reset signals and score values, the physics calculation section begins.

We use r4 as a temporary register to precalculate the x-coordinate, and copy the value from r4 into the actual register r0 for accurate display of the ball. At this point, we read the random x-velocity from Logisim.

We check for collisions with blocks by examining the y-coordinate. If the y-coordinate is equal to the block row coordinate, we load the address of the necessary array, extract the 5 most significant bits from the coordinate, and add this value to our address twice (because the values in the array are stored as 16-bit quantities, so we must advance two bytes). If the value at the resulting address is equal, a collision has occurred and we must update the score. Next, we need to determine whether the left or right pixel was struck in order to correctly update the memory values. We can do this by adding two to our address: if the value at this new address is 1, the left pixel has been struck; otherwise, the right pixel.

```
ldi r5, bricks11 #loading adress of necessary array
move r0,r4 #copying x-coordinate
shr r4 #taking 5 most significant bits from 8-bit value of x-coordinate
shr r4
shr r4
add r5,r4,r5 #adding x-coordinate to the adress of array
add r5,r4,r5
add r5,r4,r5
push r1
ld r5,r1
if
cmp r1, 1 #checking whether a collision occured
is eq # we need to know if this left or right pixel

push r5
ldi r6,0xcccc #updating the score, which is stored at 0xccc adress
ld r6,r5
inc r5
stb r6,r5
pop r5
add r5,2 # if we increase adress by 1 x-coordinate, and value by that adress equals 1
# we are adding 2 to r5 because we are working with 16-bit values
# it is left pixel, else it is right pixel

ld r5,r1

ld r5,r1

ld r5,r1

ld r5,r1

ld r6,0xccc #updating the score, which is stored at 0xccc adress
ld r6,r5
inc r5
stb r6,r5
pop r5
add r5,2 # if we increase adress by 1 x-coordinate, and value by that adress equals 1
# we are adding 2 to r5 because we are working with 16-bit values
# it is left pixel, else it is right pixel
```

We are updating memory values and adjusting random access speed.

```
sub r5,2
st r5,r1
add r5,2
st r5,r1
add r5,2
st r5,r1
ldi r5, bricks10 # updating values in adjacent row
add r5,r4,r5
add r5,r4,r5
st r5,r1
add r5,2
st r5,r1
add r5,2
st r5,r1
pop r1
ldi r6,0×a000 #loading random Vx
ldb r6,r6
    cmp r1,0
   neg r6
   move r6,r1
    move r6, r1
```

We are performing this procedure on other block arrays. Following that, we check for y-axis collisions. Wall collisions are checked in the same manner as with the x-axis.

We must check for collisions with the bat. First, we check the collision with the right pixel, then the middle, and finally the left (note: if the ball

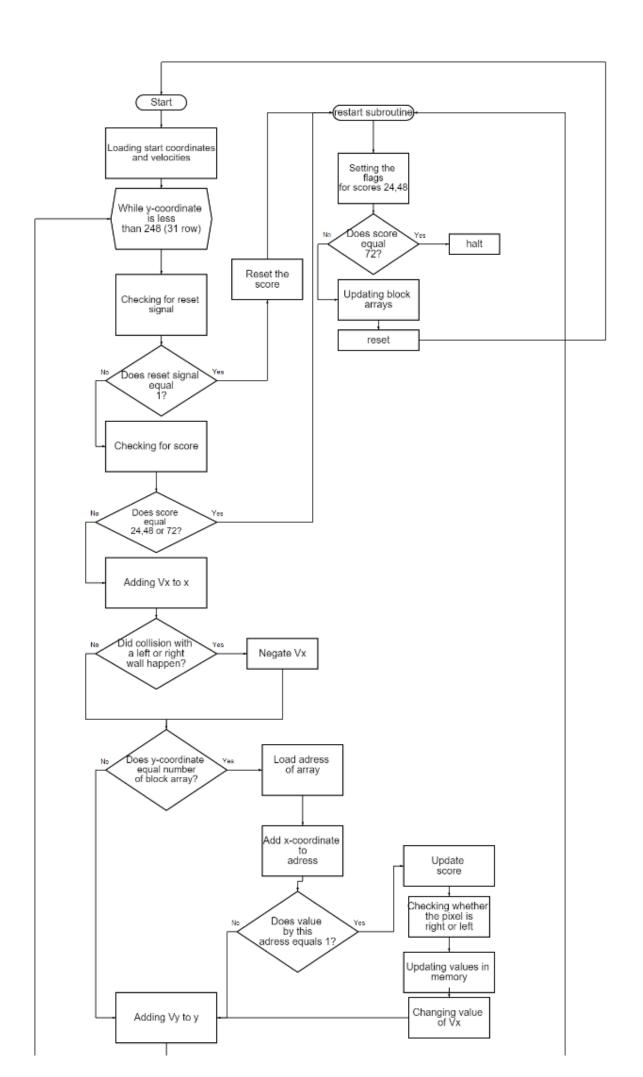
hits an edge pixel, the Vx and Vy values are negated; if the ball hits the middle pixel, only the Vy value is negated).

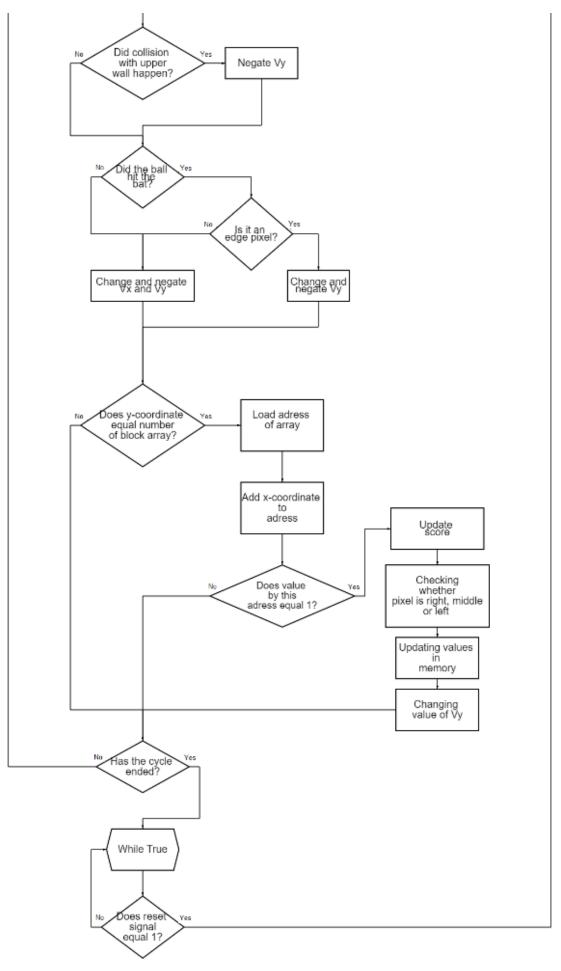
```
753
754
755
755
756
757
758
759
760
761
762
763
764
765
765
765
766
767
768
769
768
769
```

We use the same algorithm for processing collisions in both horizontal and vertical directions, with the exception of additional verification for the middle pixel. If the value at the current address is 0, we assume that it is the right pixel. However, if the value is not 0, we move two pixels backward and check the value at the new address. If it is 0, it is the left pixel; otherwise, it is considered the middle pixel.

If the ball reaches the 31st row, the cycle ends. We then start a new "while true" loop and wait for a reset signal.

```
1572 | wend |
1573 | ldi r6,2 |
1574 | while |
1575 | cmp r6,2 #starting infinite loop |
1576 | stays eq |
1577 | ldi r5,0×a002 |
1578 | ldb r5,r5 |
1579 | if |
1580 | cmp r5,1 |
1581 | is eq |
1582 | ldi r6,0×cccc # if reset signal equals 1 - jump to restart subroutine |
1583 | ldi r5,0 |
1584 | st r6,r5 |
1585 | jsr restart |
1586 | fi |
1587 | wend |
1588 | halt |
1589
```





3 Interaction between software and hardware

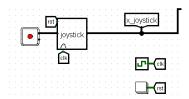
From Hardware:

- Random values of ball speed modules Vx, Vy
- *Reset* signal (restarts the program)
- Coordinate of the right pixel of the joystick

From Software:

- ball x and y coordinates
- game score

4 User manual



The game starts by clicking on the first (reset) button. To control the bat, a joystick is used. The joystick moves by clicking on the mouse. If the player wishes to generate blocks again, they should click on the *rst* (reset) button. If they wish to restart the game from the beginning, they should hold down the *rst* (reset) button.

Conclusion

For our team, the project work has been very interesting. We have gained a significant amount of experience through working in a collaborative environment, writing assembly code, designing chips, and creating documentation.