# n-bits reactive strategies

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# 1 Introduction

In this work we explore reactive strategies in the infinitely repeated prisoner's dilemma. The prisoner's dilemma is a two person symmetric game that provides a simple model of cooperation. Each of the two players, p and q, simultaneously and independently decide to cooperate (C) or to defect (D). A player who cooperates pays a cost c>0 to provide a benefit b>c for the co-player. A cooperator either gets b-c (if the co-player also cooperates) or -c (if the co-player defects). Respectively, a defector either gets b (if the co-player cooperates) or 0 (if the co-player defects), and so, the payoffs of player p take the form,

cooperate defect cooperate 
$$\begin{pmatrix} b-c & -c \\ b & 0 \end{pmatrix}$$
 (1)

The transpose of (1) gives the payoffs of co-player q. We can also define each player's payoffs as vectors,

$$\mathbf{S}_p = (b-c, -c, b, 0)$$
 and  $\mathbf{S}_q = (b-c, b, -c, 0)$ . (2)

We denote the long-term payoffs of players p and q as  $\mathbf{s}_p$  and  $\mathbf{s}_q$ .

# 2 Model

At each round t of the repeated game, players p and q decide on an action  $a_t^p$ , and  $a_t^q \in \{C, D\}$  respectively (**Fig. 1a**). We assume that the players' decisions only depend on the outcome of the previous n rounds. An n-history for player p is a string  $h^p = (a_{-1}^p, \dots, a_{-n}^p) \in \{C, D\}^n$ . Here, an entry  $a_{-k}^p$  corresponds to player p's action k rounds ago. Let  $H^p$  denote the space of all n-histories of player p. Analogously, we define  $H^q$  as the set of n-histories  $h^q$  of player q. Sets  $H^p$  and  $H^q$  contain  $|H^p| = |H^q| = 2^n$  elements each. A pair  $h = (h^p, h^q)$  is called an n-history of the game. We use  $H = H^p \times H^q$  to denote the space of all such histories. This set contains  $|H| = 2^{2n}$  elements.

A memory-n strategy is a vector  $\mathbf{p} = (p_h)_{h \in H} \in [0,1]^{2n}$ . Each entry  $p_h$  corresponds to the player's cooperation probability in the next round, depending on the outcome of the previous n rounds.

On the other hand, an n-bit reactive strategy is a vector  $\hat{\mathbf{p}} = (\hat{p}_h)_{h \in H^q} \in [0,1]^{2n}$ . Each entry  $\hat{p}_h$  corresponds to the player's cooperation probability in the next round, depending on the co-player's action(s) of the

previous n rounds. Thus, n-bit reactive strategies only depend on the co-player's n-history (independent of the focal player's own actions during the past n rounds).

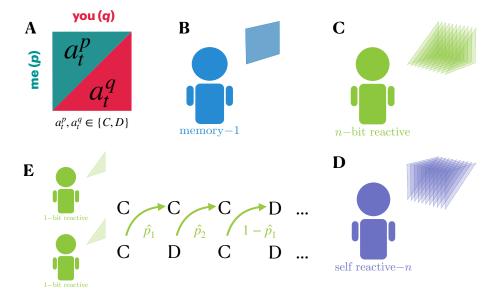


Figure 1: **Model. A.** At each turn t of the repeated game, players p and q decide on an action  $a_t^p$ ,  $a_t^q \in \{C, D\}$ , respectively. **B.** Memory–1 strategies are a set of very well studied strategies that use the actions of both player at round t-1 to decide on round t. In the graphical representation of memory-1 strategy we demonstrate this by using a single full shaded square. **C.** In this work we focus on reactive strategies, strategies that consider only the co-players actions  $h^q$ . This is demonstrated in the graphical representation by the shaded bottom half of the squares. **E.** Let the case of n=1, a 1-bit reactive strategy is a vector  $\hat{\mathbf{p}} = (\hat{p}_C, \hat{p}_D)$ .  $\hat{p}_C$  is the probability of cooperating given that the co-player cooperated and  $\hat{p}_D$  given that they defected. Consider a match between two 1-bit reactive strategies as shown in panel **E.** The top player (player  $\hat{p}$ ) cooperates with a probability  $\hat{p}_C$  in the second round since the co-player cooperated. The player defects in round 3 with a probability  $1-\hat{p}_C$  given that the co-player cooperated. **D.** Another strategies set that we consider is that of n-bit self reactive strategies. These are strategies that consider only their own previous n action.

We say  $h^q = (C, ..., C)$  is the full cooperation history. An n-bit reactive strategy  $\hat{\mathbf{p}}$  is called *agreeable* if it prescribes to cooperate with probability 1 after the full cooperation history.

The strategy  $\mathbf{p}$  is called a partner strategy if it is agreeable and if expected payoffs satisfy

$$s_{\mathbf{q}} \ge b - c \qquad \Rightarrow \qquad s_{\mathbf{q}} = s_{\mathbf{p}} = b - c,$$
 (3)

Thus, if a player uses a partner strategy, both players can share the rewards fairly. However, if a co-player prefers an unfair approach, they will receive a reduced payoff as a consequence. Partner strategies, by definition, are best responses to themselves, making them Nash equilibria Hilbe et al. [2015]. We wish to characterise all partner n - bit reactive strategies of the repeated donation game.

# 3 Results

### 3.1 Sufficiency of self reactive strategies

To characterize all partner n-bit reactive strategies, one would usually need to check against all pure n-memory one strategies McAvoy and Nowak [2019]. However, we demonstrate that when player p employs an n-bit reactive strategy, it is sufficient to check only against n-bit self-reactive strategies. This finding aligns with the previous result by Press and Dyson Press and Dyson [2012].

More specifically, the result states that for any memory-n strategy used by player q, player ps' score is exactly the same as if q had played a specific self-reactive memory-n strategy.

A "maybe" example will consider the reactive  $\hat{\mathbf{p}} = (0,1)$  and the memory-1 strategy Pavlov or Win Stay Lose Shift  $\mathbf{p} = (1,0,0,1)$ .

## 3.2 2-bit partner strategies

For n=2,  $\hat{\mathbf{p}}=(\hat{p}_{CC},\hat{p}_{CD},\hat{p}_{DC},\hat{p}_{DD})$ , where  $\hat{p}_{CC}$  is the probability of cooperating in round t when the co-player cooperated in the last 2 rounds,  $\hat{p}_{CD}$  is the probability of cooperating given that the co-player cooperated in the second to last round and defected in the last, and so on. An agreeable 2-bit strategy is represented by the vector  $\hat{\mathbf{p}}=(1,\hat{p}_{CD},\hat{p}_{DC},\hat{p}_{DD})$ :

An agreeable 2-bit reactive strategy is a partner strategy if the entries of  $\hat{\mathbf{p}}$  satisfy:

$$\hat{p}_{DD} < 1 - \frac{c}{b} \quad and \quad \frac{\hat{p}_{CD} + \hat{p}_{DC}}{2} < 1 - \frac{c}{2b}.$$
 (4)

A special case of 2-bit reactive strategies is the 2-bit counting reactive strategies. These are strategies that respond to the action of the co-player, but they do not differentiate between when defection occurs, only if one or two defections occurred. Let  $r_i$  be the probability of cooperating given that the co-player cooperated i number of times in the last 2 turns.

Thus,  $r_2 = \hat{p}_1, r_1 = \hat{p}_2 = \hat{p}_3, r_0 = \hat{p}_4$  and  $\hat{\mathbf{p}} = (r_0, r_1, r_2 = 1)$ . Conditions (4) then become:

$$r_2 < 1 - \frac{c}{2b}$$
 and  $r_0 < 1 - \frac{c}{b}$ . (5)

#### 3.3 3-bit partner strategies

For n = 3,  $\hat{\mathbf{p}} = (\hat{p}_{CCC}, \hat{p}_{CCD}, \hat{p}_{CDC}, \hat{p}_{CDC}, \hat{p}_{DCD}, \hat{p}_{DCC}, \hat{p}_{DCD}, \hat{p}_{DDC}, \hat{p}_{DDD})$  where  $\hat{p}_{CCC}$  is the probability of cooperating in round t when the co-player cooperates in the last 3 rounds,  $\hat{p}_{CCD}$  is the probability of cooperating given that the co-player cooperated in the third and second to last rounds and defected in the last, etc. An agreeable 3-bit strategy is of the vector  $\hat{\mathbf{p}} = (1, \hat{p}_{CCD}, \hat{p}_{CDC}, \hat{p}_{CDD}, \hat{p}_{DCC}, \hat{p}_{DDD}, \hat{p}_{DDC}, \hat{p}_{DDD}, \hat{p}_{DDC}, \hat{p}_{DDD}, \hat{p}_{DDC}, \hat{p}_{DDD}, \hat{p}_{DDC}, \hat{p}_{DDD})$ .

An agreeable 3-bit reactive strategy is a partner strategy if the entries of  $\hat{\mathbf{p}}$  satisfy:

$$\hat{p}_{CCD} + \hat{p}_{CDC} + \hat{p}_{DCC} < 3 - \frac{c}{b} \qquad \hat{p}_{CDD} + \hat{p}_{DCD} + \hat{p}_{DDC} < 3 - \frac{2c}{b} \qquad \hat{p}_{DDD} < 1 - \frac{c}{b} \qquad (6)$$

$$\hat{p}_{CCD} + \hat{p}_{CDD} + \hat{p}_{DDC} + \hat{p}_{DCD} < 4 - \frac{2c}{b} \qquad \hat{p}_{CDC} + \hat{p}_{DCD} < 2 - \frac{c}{b} \qquad (7)$$

A special case of 3-bit reactive strategies are the 3-bit counting reactive strategies. Let  $r_i$  be the probability of cooperating given that the co-player cooperated i number of times in the last 3 turns. So,  $r_3 = \hat{p}_{CCC}$ ,  $r_2 = \hat{p}_{CCD} = \hat{p}_{DCC}$ ,  $r_1 = \hat{p}_{CDD} = \hat{p}_{DCD} = \hat{p}_{DCD}$ ,  $r_0 = \hat{p}_{CCC}$  and  $\hat{\mathbf{p}} = (r_0, r_1, r_2, r_3 = 1)$ . Then, conditions (6), the conditions for being a partner strategy become:

$$r_2 < 1 - \frac{c}{3b}$$
,  $r_1 < 1 - \frac{2c}{3b}$  and  $r_0 < 1 - \frac{c}{b}$ . (8)

# 3.4 n-bit counting partner strategies

In the case of counting reactive strategies, we observe a pattern in the conditions they must satisfy to be partner strategies. We show that for an n-bit counting reactive strategy to be a partner strategy, the strategy's entries must satisfy the conditions:

$$r_{n} = 1$$

$$r_{n-1} \le 1 - \frac{(n-1)}{n} \times \frac{c}{b}$$

$$r_{n-2} \le 1 - \frac{(n-2)}{n} \times \frac{c}{b}$$

$$\vdots$$

$$r_{0} \le 1 - \frac{c}{b}$$

## 3.5 Evolutionary Dynamics

# 4 Discussion

# References

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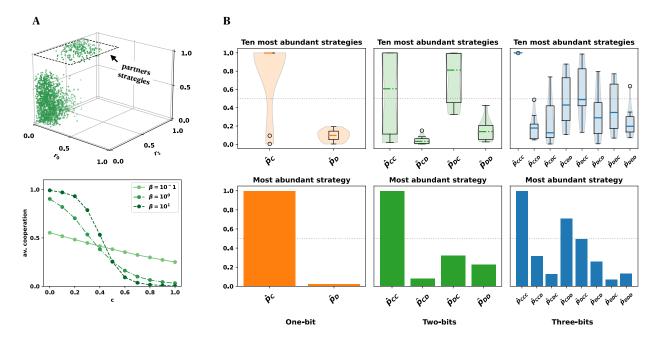


Figure 2: **Evolving strategies for** n=1, n=2 **and** n=3. In the previous sections we have characterized partners strategies for two and three bit reactive cases, and we have also discussed the case of counting reactive strategies. Here we want to assess whether partner strategies are strategies that evolve, thus are beneficial to adopt in an evolutionary setting. We ran simulations based on Imhof and Nowak. For a single run of the evolutionary process, we record the cooperating probabilities of the resident at each elementary time step. **A. Counting two-bit reactive strategies**. In the top panel we show the most abundant strategies of the evolutionary process when the population can use any counting two-bit reactive strategy  $(r_0, r_1, r_2)$ . The abundant strategies are the residents that were fixed for the most time steps. The most abundant strategies fall within the region of the partner strategies. In the bottom panel we look at the evolving cooperation rate closer. The average cooperation is calculated by considering the cooperation rate within the resident population. For a given  $\beta$  value we vary the cost  $c \in [0,1]$  whilst we have fixed b=1. Three curves are shown, these are for different values of selection strength,  $\beta \in 10^-1, 10^0, 10^1$ . **B. One, two, three bits.** We ran 10 independent simulations for each set of strategies and recorded the most abundant strategy for each run. The abundant strategy is the resident that was fixed for the most time steps. For the simulations we used b=1 and c=.5. For n equal to 1 and 2,  $T=10^7$  and for n=3 then  $T=2\times 10^7$ .

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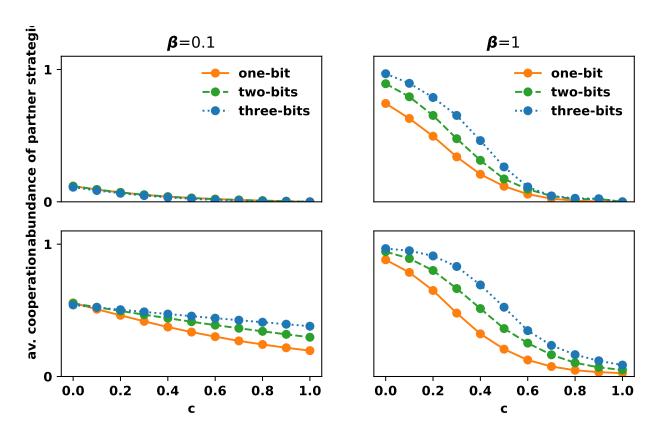


Figure 3: Abundance of partner strategies. We ran simulations based on Imhof and Nowak, varying the cost (c) and strength of selection  $(\beta)$ . The cooperation benefit (b) is fixed at a value of 1. The results demonstrate that partner strategies evolve notably under strong selection  $(\beta = 1)$  and lower cost conditions. Furthermore, the abundance of partner strategies is consistently higher when individuals have access to greater memory. The bottom panel displays how these partner strategies lead to increased levels of cooperation.