

Evolution of cooperation among individuals with limited payoff memory

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Abstract

1 Introduction

One of the most important applications of evolutionary game theory is the evolution of cooperation. Why is it that some individuals choose to help others, increasing their payoff, at the expense of decreasing one's own? In evolutionary game theory, individuals are not required to be rational, instead they adapt strategies based on mutation and exploration. Strategies are more likely to spread if they have a high fitness either because the individuals who adopt them have more offspring, or because they are imitated more often [1]. The fitness of a strategy is not constant but depends on the composition of the population. Individuals interact based on their strategies with other members of the population and the payoffs they yield are translated into fitness.

It is commonly assumed that individuals compute their fitness after interacting with a representative sample of the population, and remembering all the interactions they participated in [2]. Thus, they imply that individuals have a perfect memory. However, when modelling how individuals make decisions in each turn they are assumed to have very limited memory. To be precise, most of the works in the literature focus on naive subjects who can only choose from a restricted set of strategies [3], or who do not remember anything beyond the outcome of the very last round [4]. Note that there are a few notable exceptions [5, 6]. Thus, the perfect memory assumption is not only unrealistic but it also creates this curious inconsistency.

This has led us to question the robustness of our understanding of cooperation. In this work we explore whether cooperation can evolve if individuals compute their fitness based on a minimum of social information. Though we are not the first to question the assumptions of estimating fitness [7], we are the first to explore the effect of payoff memory.

We first consider two extreme scenarios, the classical scenario of the expected payoffs and the alternative scenario where individuals update their strategies only based on the very last payoff they obtained. We observe that individuals with limited memory tend to adopt less generous strategies and they achieve less cooperation than in the classical scenario. We obtain similar results when we consider that individuals

update their strategies based on more social information. More specifically, up to the last two payoffs they obtained when interacting with up to two different members of the population.

The remainder of the paper is organized as follows. In section 2 we describe the model. In section 3 we presents the results of the simulations. Finally, section 4 we outline the main conclusions.

2 Model Setup

We consider a population of N players ¹ (N is even) where mutations are sufficiently rare. Thus, at any point in time there are at most two different strategies present in the population; a *resident* strategy and a *mutant* strategy. We assume a pairwise process where strategies spread because they are imitated more often.

Each step of the evolutionary process consists of two stages, a game stage and an updating stage. In the game stage each individual is randomly matched with some other individual in the population to interact for a number of turns, where subsequent turns occur with a fixed probability δ . At each turn they can choose to either cooperate (C) or to defect (D), and thus, at each turn the possible outcomes are CC , CD , DC and DD . The payoffs depend on the outcome. If both cooperate they receive the reward payoff R , whereas if both defect they receive the punishment payoff P . If one cooperates but the other defects, the defector receives the temptation to defect, T , whereas the cooperator receives the sucker's payoff, S . We denote the payoffs of an individual as $\mathcal{U} = (R, S, T, P)$.

We assume herein that individuals use *reactive strategies* to make decisions in each turn. Reactive strategies are a set of memory-one strategies that only take into account the previous action of the opponent. They can be written explicitly as a vector $\in \mathbb{R}_3$, more specifically, a reactive strategy s is given by $s = (y, p, q)$ where y is the probability that the strategy opens with a cooperation and p, q are the probabilities that the strategy cooperates given that the opponent cooperated and defected equivalently.

In the updating stage, two players are randomly drawn from the population, a 'learner' and a 'role model'. Given that the learner's payoff $u_L \in \mathcal{U}$ and that the role model's payoff $u_{RM} \in \mathcal{U}$, we assume the learner adopts the role model's strategy based on the Fermi distribution function,

$$\rho(u_L, u_{RM}) = \frac{1}{1 + \exp^{-\beta(u_{RM} - u_L)}}. \quad (1)$$

where $\beta \geq 0$ is the relative influence of the payoffs on adopting the strategy of the other. We refer to β as the intensity of selection.

This basic evolutionary step is repeated until either the mutant strategy goes extinct, or until it fixes in the population. If the mutant fixes in the population then the mutant strategy becomes the new resident strategy. After either outcome we introduce a new mutant strategy uniformly chosen from all reactive strategies at random, and we set the number of mutants to 1. This process of mutation and fixation/extinction is then

¹The terms "player" and "individual" are used interchangeably here.

iterated many times.

The perfect memory assumption occurs at the updating stage. The learner and the role model are assumed to interact with a representative sample of the population, and they remember all interactions they participate in. Thus, their updating payoffs are based on the mean payoff they achieved over all the interactions. These payoffs are referred to as the expected payoffs. We will compare the expected payoffs to payoffs that are calculated when the role model and learner do not remember all of their interactions. In order to account for the effect of these different methods, we explore the cooperation rate within the resident population over multiple generations. More details on our methodology are found in Appendix A.

3 Results

3.1 Updating payoffs based on the last round with another member of the population

In this section we explore the case where the updating payoffs are based on the last round payoff achieved against another member of the population. We compare this to the classical scenario of the expected payoffs. We assume that each pair of players interacts in a donation game. The donation game is a special case of the prisoner’s dilemma. Each player can choose to cooperate by providing a benefit b to the other player at their cost c , with $0 < c < b$. Thus, the payoffs of a one round interact are $T = b$, $R = b - c$, $S = -c$, $P = 0$.

Figure 1 shows simulations results for the described process of section 2. Figure 1 depicts the evolving conditional cooperation probabilities p and q . The discount factor δ is comparably high, thus the opening move y is a transient effect and has no effect on the outcome. The left panel corresponds to the standard scenario considered in the literature. It considers players who use expected payoffs to update their strategies. The right panel shows the scenario considered herein, in which players update their strategies based on their last round’s payoff. The top panels assume a benefit b of 3, whereas the bottom assume a benefit of 10.

The figure suggests that when updating is based on expected payoffs, players tend to be more generous and more cooperative. The q -values of the resident strategies are on average higher in the case of the expected payoffs. The players will occasionally forgive a defection more often if their fitness depends on interacting with every member of the population. On the other hand, when social interactions are limited they are less forgiving. The average cooperation rate for each simulation is calculated as the the average cooperation rate within the resident population. In the case of the expected payoffs, regardless the value of benefit, the average cooperation rate is strictly higher than that of the last round payoffs. The difference based the two methods is statistically significant, and the dissimilarity is even more obvious for a high value of b . More specifically, the average cooperation of resident strategies drops from 97% to 57%.

We further explore the effect of the benefit. Figure 2 suggests that expected payoffs always yield a higher cooperation rate. We observe that the cooperation rate increases as the value of the benefit gets higher. In comparison, for the limited memory payoffs, the cooperation rate remains unchanged, at approximately 50%.

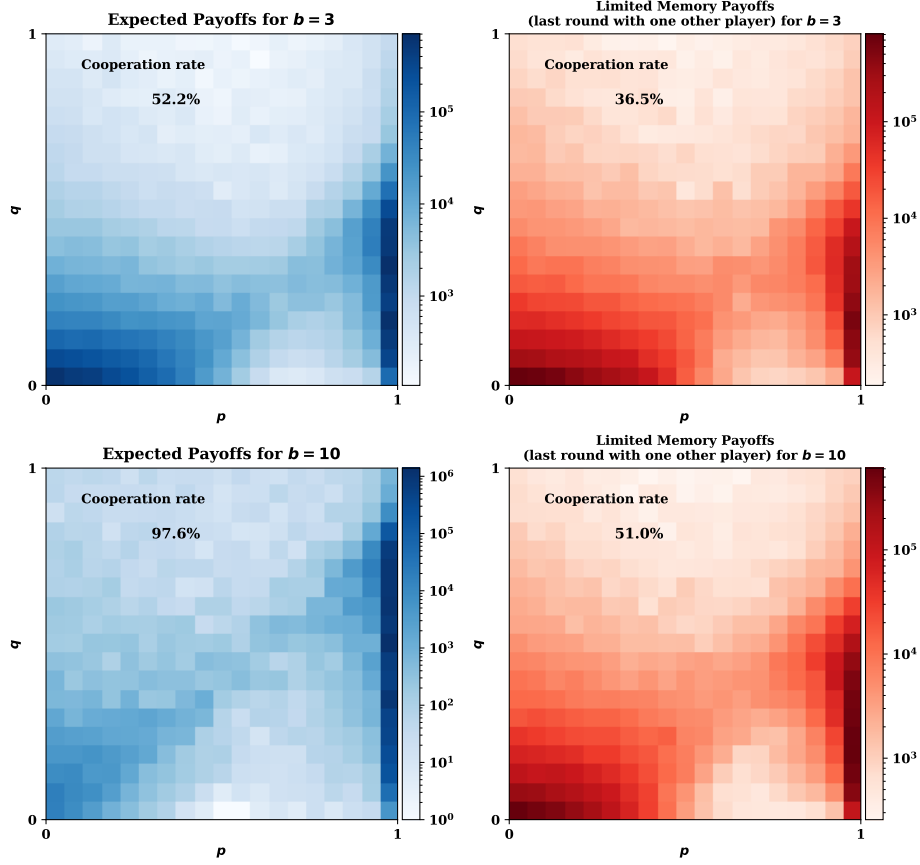


Figure 1: Evolutionary dynamics under expected payoffs and last round with one interaction payoffs. We have run two simulations of the evolutionary process described in section 2 for $T = 10^7$ time steps. For each time step, we have recorded the current resident population (y, p, q) . Since simulations are run for a relatively high continuation probability of $\delta = 0.999$, we do not report the players' initial cooperation probability y . The graphs show how often the resident population chooses each combination (p, q) of conditional cooperation probabilities in the subsequent rounds. **(A)** If players update based on their expected payoffs, the resident population typically applies a strategy for which $p \approx 1$ and $q \leq 1 - c/b = 0.9$. **(B)** When players update their strategies based on their realized payoffs in the last round, there are two different predominant behaviors. The resident population either consists of defectors (with $p \approx q \approx 0$) or of conditional cooperators. In the latter case, the maximum level of q consistent with stable cooperation is somewhat smaller compared to the expected-payoff setting, $q < 0.5$. The cooperation rate within the resident population (averaged over all games and over all time steps) is close to 100%. Parameters: $N = 100$, $c = 1$, $\beta = 1$, $\delta = 0.999$.

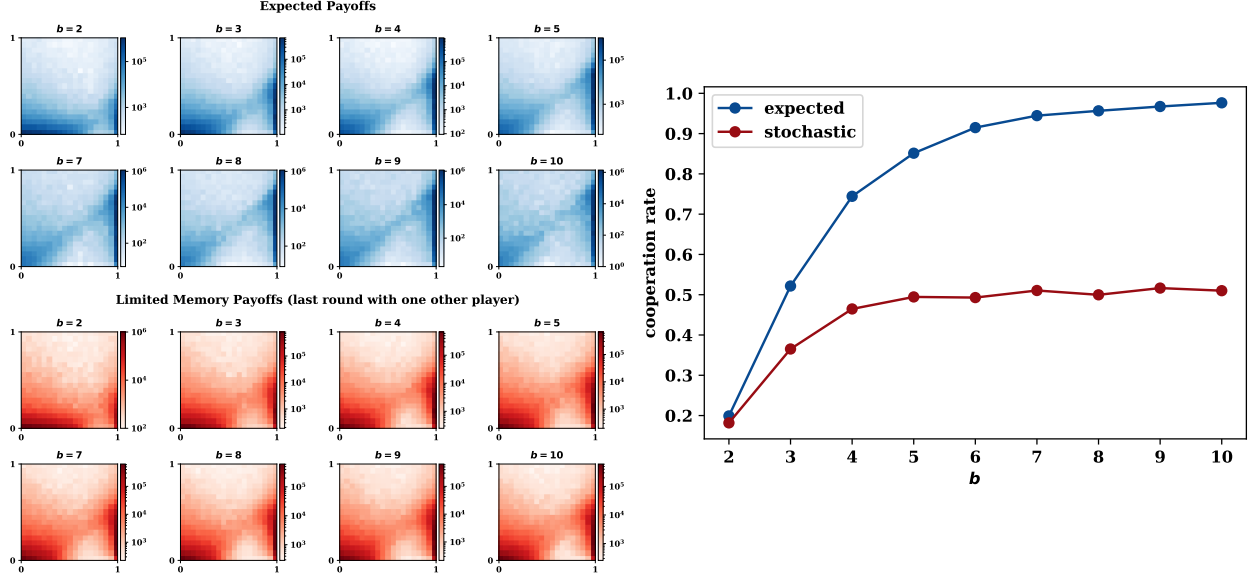


Figure 2: The evolution of cooperation for different benefit values. We vary the benefit of defection b . In all cases, expected payoffs appear to overestimate the average cooperation rate the population achieves. (A) the probabilities p, q for resident population over 10^7 time steps for each benefit value. (B) The cooperation rate within the resident population (averaged over all games and over all time steps) over the benefit. Unless explicitly varied, the parameters of the simulation are $N = 100$, $c = 1$, $\beta = 1$, $\delta = 0.99$. Simulations are run for $T = 5 \times 10^6$ time steps for each parameter combination.

We also investigate the effect of the strength of selection. Figure 3 illustrates results for various runs of the evolutionary process. For weak selection, $\beta < 1$, we observe that the two methods yield the same result, however, as β increases there is variation in the evolving populations. In the case of expected payoffs the resident populations become more and more cooperative as β increases, whereas in the case of limited memory payoffs, the resident populations become less cooperative.

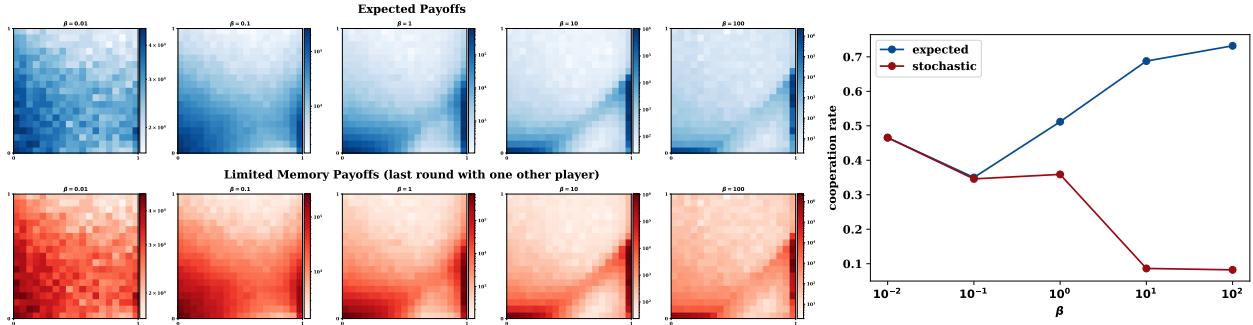


Figure 3: The evolution of cooperation for different selection strength values. We vary the selection strength β . In all cases, stochastic payoff evaluation tends to reduce the evolving cooperation rates. (A) the probabilities p, q for resident population over 10^7 time steps for each β value. (B) The cooperation rate within the resident population (averaged over all games and over all time steps) over β . Unless explicitly varied, the parameters of the simulation are $N = 100$, $b = 3$, $c = 1$, $\beta = 1$, $\delta = 0.99$. Simulations are run for $T = 5 \times 10^6$ time steps for each parameter combination.

3.2 Effect of updating payoffs in different social dilemmas

In the previous subsection we gained insights into the effects of the updating payoffs, and into how parameters such as the benefit and the strength of selection can intensify them. We investigated these effects by using the donation game. In order to broaden our understanding of the updating payoffs on different forms of possible human interactions, we extend our approach to other 2×2 symmetric games. More specifically, we apply our analysis to the four different classes of games given by Table 1. We compare the results of the evolutionary process described in section 2 when the updating payoffs are based on the expected payoffs, and on the last round payoffs for all the four possible classes of games. The results of the simulations are given in Figures 4 and 5 respectively.

	social dilemmas	preference ordering
(iii)	harmony	$R > T > S > P$
(i)	stag hunt	$R > T > P > S$
(iv)	prisoner dilemma	$T > R > P > S$
(ii)	snowdrift	$T > R > S > P$

Table 1: Social dilemmas and payoffs’ constraints. The various social dilemmas we explore in this work. Results for cases (i) - (iv) are presented in section 3.2 and results for case (v) are presented in section 3.1.

In Figure 4 each sub figure represents a run of evolutionary process for a different set of values the payoffs of an individual, \mathcal{U} . Without loss of generality we set $R = 1$ and $P = 0$ [8, 9], and we vary the values of the temptation T (across the x -axis) and of the risk of cooperating S (across the y -axis). There are four classes of games as presented in Table 1. Starting at the upper left corner and proceeding clockwise correspond to the harmony game, the snowdrift, the prisoner’s dilemma and the stag hunt.

The harmony game represents a situation without tensions where it is in the best interest of both players to cooperate. This is confirmed by our simulations Figure 4. In the several experiments of the harmony game the resident population applies a strategy for which $p \approx 1$ and $q \approx 1$.

The snowdrift game describes a situation similar to the prisoner’s dilemma where cooperation results in a benefit to the opposing player but entailing a cost to the cooperator. Compared to the prisoner’s dilemma, individuals obtain immediate direct benefits from the cooperative acts. The story of the snowdrift game usually goes as follow: two drivers are trapped on either side of a snowdrift and have the options of staying in the car or removing the snowdrift. Letting the opponent do all the work is the best option but if the other player stays in the car it is better to shove. In the end cooperation leads to the cooperated drive to get home, even though they had to endure the work, thus $S > P$. In the snowdrift game more cooperation emerges compared to the prisoner’s dilemma. Defection is never a resident strategy and for the shame values of

temptation the overall q – values are higher. It can be seen that the p – values are lower as individuals have free room to defect after receiving a cooperation.

The last class of games corresponds to the stag hunt game. In the stag hunt game both players benefit for mutual cooperation and defection, however, $R > P$ and thus the resident strategies with the highest fitness are the cooperative ones. The results are similar to the cases of the harmony game.

The results for the last round payoffs are fairly similar with the patterns begging the same. It can be seen from Figure 5 that the results are move variation. We have discussed the expected behaviour for each social dilemma. We now want to account the difference in the cooperation rate given the two updating payoffs. The cooperation rates for each of the case of the social dilemmas we have used are given in Figure 6.

So far we have explored the difference between the expected payoffs and the last round payoffs. In order to explore further the effect of limited memory we allow individuals to remember more. We consider the cases where individuals remember up two interactions, and up to the last two rounds. In total we present results for three more cases. These are the cases of the last round two rounds with another member of the population, last round with two members of the population, and last round two rounds with two members of the population.

Similarly to the previous examples we have run the evolutionary process for a large number of step for each of the social dilemmas. The results remain the same. The behavior over the different games remains the same. We note that now there is more noise in the evolved populations. Due to space the figures have been moved to the Appendix, however, the cooperating rates for each of the cases are given in Figure 7.

4 Conclusions

A Model Setup

Consider a population of N individuals where N is even. At any point in time there are at most two different strategies in present in the population. More specifically, a mutant strategy played by k individuals and a resident strategy played by $N - k$ individuals. We assume a pairwise process in which strategies spread because they are imitated more often. Each step of the evolutionary process consists of two stages; a game stage and an update stage.

In the game stage, each individual is randomly matched with some other individual in the population. Their interaction lasts for a number of turns which is not fixed but depends on the continuation probability δ . At each turn the individuals choose between cooperation (C) and defection (D). Thus, there are four possible outcomes in each turn CC, CD, DC and DD . If both players cooperate they receive the reward payoff R , whereas if both players defect they receive the punishment payoff P . If one cooperates but the other defects, the defector receives the temptation to defect, T , whereas the cooperator receives the sucker's payoff, S . Let $\mathcal{U} = \{R, S, T, P\}$ denote the set of feasible payoffs in each round, and let $\mathbf{u} = (R, S, T, P)$

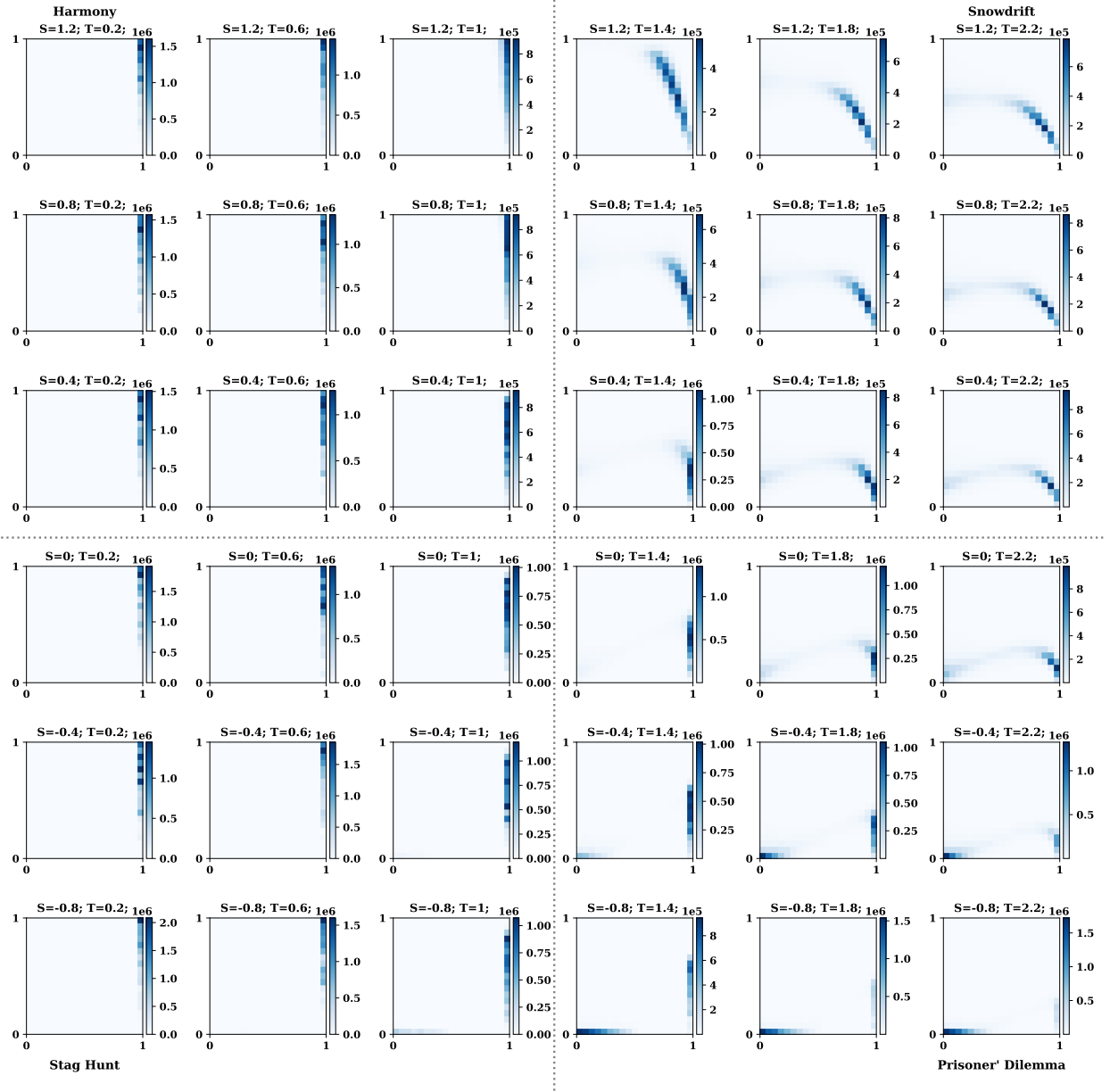


Figure 4: Evolutionary dynamics under expected payoffs for various social dilemmas. We have run several simulations of the evolutionary process described in section 2 for $T = 10^7$ time steps. The graphs show how often the resident population chooses each combination (p, q) of conditional cooperation probabilities in the subsequent rounds. We vary the temptation payoff $T \in \{-1, -0.6, -0.2, 0.2, 0.6, 1, 1.4, 1.8, 2.2, 2.6, 3\}$ across the x axis, and $S \in \{2, 1.6, 1.2, 0.8, 0.4, 0, -0.4, -0.8, -1.2, -1.6, -2\}$ across the y axis. Parameters: $N=100$, $c=1$, $\beta=1$, $\delta=0.999$.

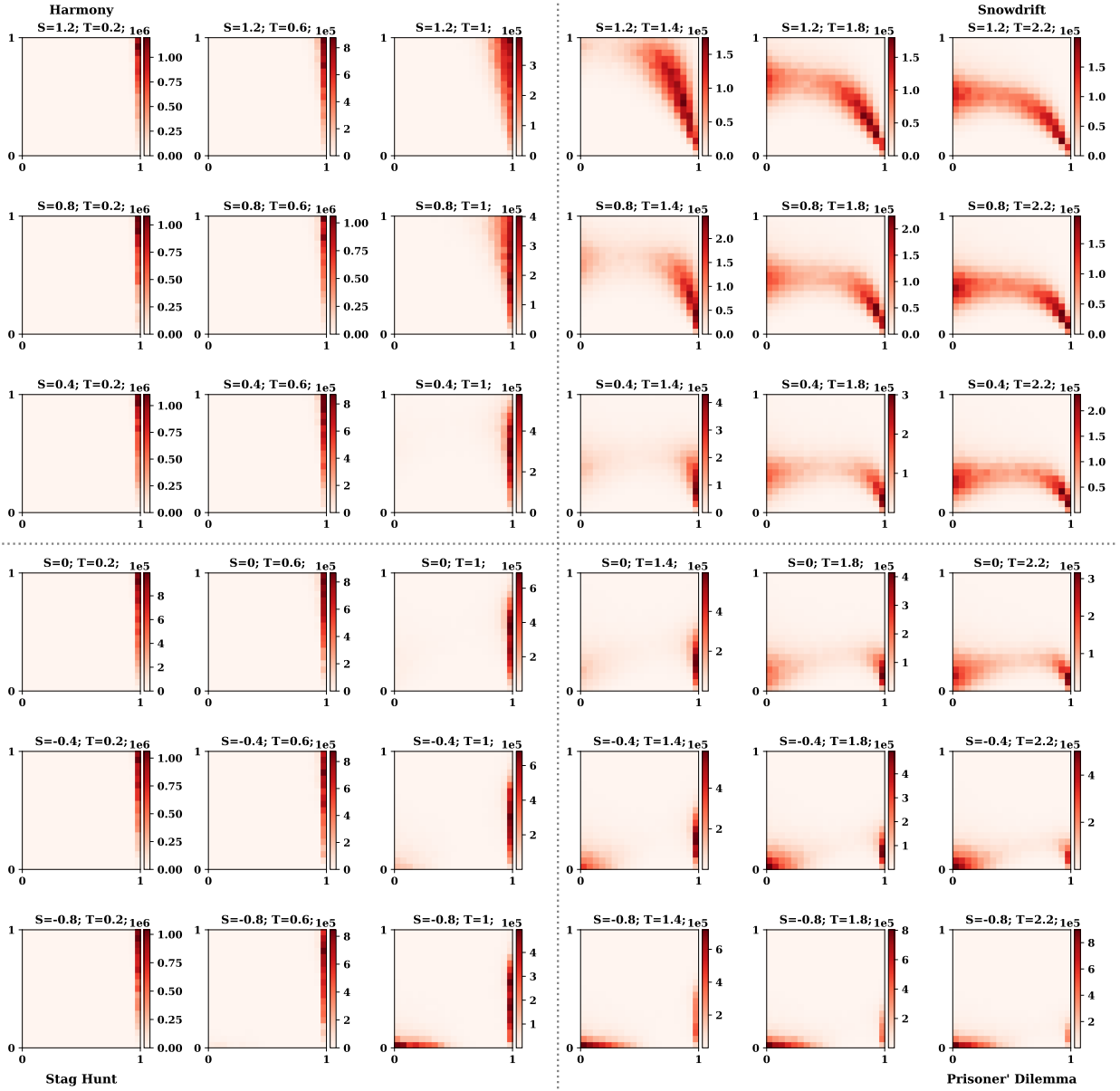


Figure 5: Evolutionary dynamics under last round payoffs for various social dilemmas. We have run several simulations of the evolutionary process described in section 2 for $T=10^7$ time steps. The graphs show how often the resident population chooses each combination (p, q) of conditional cooperation probabilities in the subsequent rounds. We vary the temptation payoff $T \in \{-1, -0.6, -0.2, 0.2, 0.6, 1, 1.4, 1.8, 2.2, 2.6, 3\}$ across the x axis, and $S \in \{2, 1.6, 1.2, 0.8, 0.4, 0, -0.4, -0.8, -1.2, -1.6, -2\}$ across the y axis. Parameters: $N=100$, $c=1$, $\beta=1$, $\delta=0.999$.

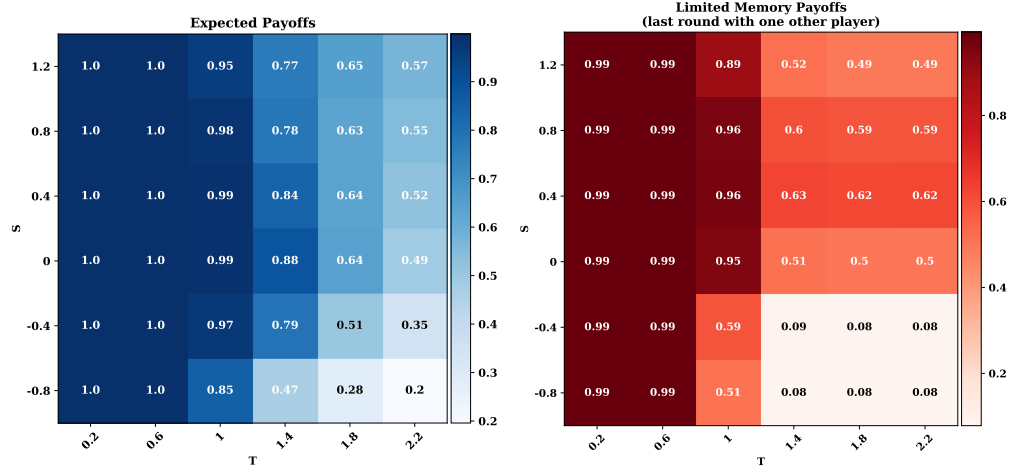


Figure 6: Cooperation rates over various social dilemmas. (A) If players update based on their expected payoffs. (B) If players update based on their last round payoffs.

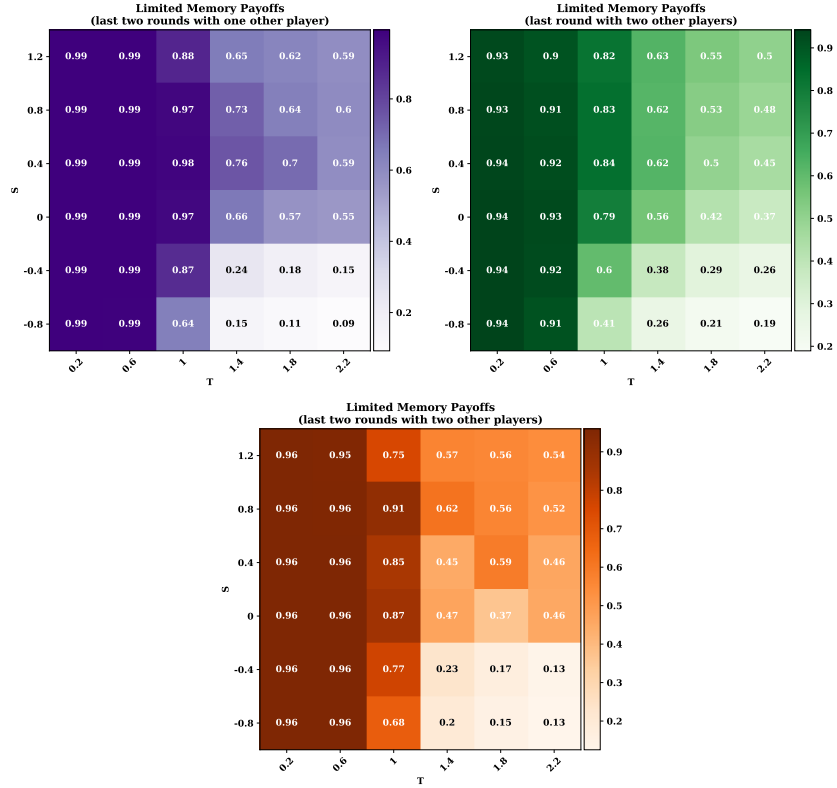


Figure 7: Cooperation rates over various social dilemmas for different limited memory payoffs. (A) If players update based on their last two rounds with another member of the population. (B) If players update based on their last round with two other members of the population. (C) If players update based on their last two rounds with two other members of the population.

be the corresponding payoff vector. The values of the payoffs are not only based on the prisoner's dilemma but all the symmetric 2×2 games, Table 1.

A further assumption of our model is that individuals make use of reactive strategies when they make decisions in each round. Reactive strategies are a set of strategies that take into account only the previous action of the opponent. A reactive strategy can be written explicitly as a vector,

$$s = (y, p, q)$$

where y is the probability that the strategy opens with a cooperation and p, q are the probabilities that the strategy cooperates given that the opponent cooperated and defected equivalently.

In the updating stage, two players are randomly drawn from the population, a 'learner' and a 'role model'. The learner adopts the role model's strategy based on the Fermi distribution function,

$$\rho(u_L, u_{RM}) = \frac{1}{1 + \exp^{-\beta(u_{RM} - u_L)}}. \quad (2)$$

where $u_L \in \mathcal{U}$ is the learner's payoff, $u_{RM} \in \mathcal{U}$ is the role model's payoff, and $\beta \geq 0$ is the intensity of selection.

We iterate this basic evolutionary step until either the mutant strategy goes extinct, or until it fixes in the population and becomes the new resident strategy. After either outcome, we set k to 1 and we introduce a new mutant strategy which is uniformly chosen from all reactive strategies at random. Instead of simulating each step of the evolutionary process, we estimate the probability that a newly introduced mutant fixes [10]. This is defined as the fixation probability of the mutant, and the standard form is the following,

$$\varphi = \frac{1}{1 + \sum_{i=1}^{N-1} \prod_k \frac{\lambda_k^-}{\lambda_k^+}}, \quad (3)$$

where λ_k^- , λ_k^+ are the probabilities that the number of mutants decreases and increases respectively.

This process of mutation and fixation/extinction is iterated many times. The evolutionary process is summarized by Algorithm 1.

The aim of this work is to explore the effect of updating memory on the cooperation rate of the evolved population. For this reason we consider two different approaches when estimating the payoffs at the updating stage. The two approaches we consider are those of (i) the expected and (ii) the limited memory payoffs.

Expected Payoffs

The expected payoffs are the conventional payoffs used in the updating stage [11]. They are defined as the mean payoff of an individual in a well-mixed population that engages in repeated games with all other

Algorithm 1: Evolutionary process

```
 $N \leftarrow$  population size;  
 $k \leftarrow 1$ ;  
resident  $\leftarrow (0, 0, 0)$ ;  
while  $step < \text{maximum number of steps}$  do  
  mutant  $\leftarrow$  random:  $\{\emptyset\} \rightarrow R^3$ ;  
  fixation probability  $\leftarrow \varphi$ ;  
  if  $\varphi > \text{random: } i \rightarrow [0, 1]$  then  
    | resident  $\leftarrow$  mutant;  
  end  
end
```

population members.

We first define the payoff of two reactive strategies at the game stage. Assume two reactive strategies $s_1 = (y_1, p_1, q_1)$ and $s_2 = (y_2, p_2, q_2)$. It is not necessary to simulate the play move by move, instead the play between the two strategies is defined a Markov matrix M ,

$$M = \begin{bmatrix} p_1 p_2 & p_1 (1 - p_2) & p_2 (1 - p_1) & (1 - p_1) (1 - p_2) \\ p_2 q_1 & q_1 (1 - p_2) & p_2 (1 - q_1) & (1 - p_2) (1 - q_1) \\ p_1 q_2 & p_1 (1 - q_2) & q_2 (1 - p_1) & (1 - p_1) (1 - q_2) \\ q_1 q_2 & q_1 (1 - q_2) & q_2 (1 - q_1) & (1 - q_1) (1 - q_2) \end{bmatrix}. \quad (4)$$

whose stationary vector \mathbf{v} , combined with the payoff u , yields the game stage outcome for each strategy, $\langle \mathbf{v}(s_1, s_2), \mathbf{u} \rangle$ [5].

In the updating stage the learner adopts the strategy of the role model based on their updating payoffs. Given that there are only two different types in the population at each time step we only need to define the expected payoff for a resident (π_R) and for a mutant (π_M). Assume the resident strategy $s_R = (y_R, p_R, q_R)$ and the mutant strategy $s_M = (y_M, p_M, q_M)$, the expected payoffs are give by,

$$\begin{aligned} \pi_R &= \frac{N-k-1}{N-1} \cdot \langle \mathbf{v}(s_R, s_R), \mathbf{u} \rangle + \frac{k}{N-1} \cdot \langle \mathbf{v}(s_R, s_M), \mathbf{u} \rangle, \\ \pi_M &= \frac{N-k}{N-1} \cdot \langle \mathbf{v}(s_M, s_R), \mathbf{u} \rangle + \frac{k-1}{N-1} \cdot \langle \mathbf{v}(s_M, s_M), \mathbf{u} \rangle. \end{aligned} \quad (5)$$

The number of mutant in the population increase if a learner resident adopts the strategy of a mutant role model, and decreases if a mutant learner adopts the strategy of a resident. The probabilities that the number of mutants decreases and increases, λ_k^- and λ_k^+ , are not explicitly define as,

$$\lambda_k^- = \rho(\pi_R, \pi_M)$$

$$\lambda_k^+ = \rho(\pi_M, \pi_R).$$

Limited memory payoffs

Initially, we discuss the case of the last round updating payoff. At the stage game we define the payoff of a reactive strategy in the last round, Proposition ??.

Proposition 1. *Consider a repeated prisoner's dilemma, with continuation probability δ , between players with reactive strategies $s_1 = (y_1, p_1, q_1)$ and $s_2 = (y_2, p_2, q_2)$ respectively. Then the probability that the s_1 player receives the payoff $u \in \mathcal{U}$ in the very last round of the game is given by $v_u(s_1, s_2)$, as given by Equation (6).*

$$\begin{aligned} v_R(s_1, s_2) &= (1-\delta) \frac{y_1 y_2}{1-\delta^2 r_1 r_2} + \delta \frac{\left(q_1 + r_1((1-\delta)y_2 + \delta q_2)\right) \left(q_2 + r_2((1-\delta)y_1 + \delta q_1)\right)}{(1-\delta r_1 r_2)(1-\delta^2 r_1 r_2)} \times R, \\ v_S(s_1, s_2) &= (1-\delta) \frac{y_1 \bar{y}_2}{1-\delta^2 r_1 r_2} + \delta \frac{\left(q_1 + r_1((1-\delta)y_2 + \delta q_2)\right) \left(\bar{q}_2 + \bar{r}_2((1-\delta)y_1 + \delta p_1)\right)}{(1-\delta r_1 r_2)(1-\delta^2 r_1 r_2)} \times S, \\ v_T(s_1, s_2) &= (1-\delta) \frac{\bar{y}_1 y_2}{1-\delta^2 r_1 r_2} + \delta \frac{\left(\bar{q}_1 + \bar{r}_1((1-\delta)y_2 + \delta p_2)\right) \left(q_2 + r_2((1-\delta)y_1 + \delta q_1)\right)}{(1-\delta r_1 r_2)(1-\delta^2 r_1 r_2)} \times T, \\ v_P(s_1, s_2) &= (1-\delta) \frac{\bar{y}_1 \bar{y}_2}{1-\delta^2 r_1 r_2} + \delta \frac{\left(\bar{q}_1 + \bar{r}_1((1-\delta)y_2 + \delta p_2)\right) \left(\bar{q}_2 + \bar{r}_2((1-\delta)y_1 + \delta p_1)\right)}{(1-\delta r_1 r_2)(1-\delta^2 r_1 r_2)} \times P. \end{aligned} \tag{6}$$

In these expressions, we have used the notation $r_i := p_i - q_i$, $\bar{y}_i = 1 - y_i$, $\bar{q}_i := 1 - q_i$, and $\bar{r}_i := \bar{p}_i - \bar{q}_i = -r_i$ for $i \in \{1, 2\}$.

Proof. Given a play between two reactive strategies with continuation probability δ . The outcome at turn t is given by,

$$(1-\delta) \mathbf{v}_0 \sum \delta^t M^{(t)}, \tag{7}$$

where \mathbf{v}_0 denotes the expected distribution of the four outcomes in the very first round, and $1-\delta$ the probability that the game ends. It can be shown that,

$$\begin{aligned}
(1 - \delta)\mathbf{v}_0 \sum \delta^t M^{(t)} &= (1 - \delta)(\mathbf{v}_0 + \delta\mathbf{v}_0 M + \delta^2\mathbf{v}_0 M^2 + \dots) \\
&= (1 - \delta)\mathbf{v}_0(1 + \delta M + \delta^2 M^2 + \dots) \text{ using standard formula for geometric series} \\
&= (1 - \delta)\mathbf{v}_0(I_4 - \delta M)^{-1}
\end{aligned}$$

where $(1 - \delta)\mathbf{v}_0(I_4 - \delta M)^{-1}$ is vector $\in R^4$ and it the probabilities for being in any of the outcomes CC, CD, DC, DD in the last round. Combining this with the payoff vector u and some algebraic manipulation we derive to the Equation 6. \square

In the updating stage we select a mutant and resident to be either the role model or the learner. Assume the selected mutant. Given that they can interact with only one other member of the population, they can interact either the selected resident, another resident or with another mutant. The same is true for the the selected resident. They can interact with the selected mutant, another resident, or another mutant. Thus, in each updating stage there are five possible combinations of pairs. These are illustrated by Figure 8.

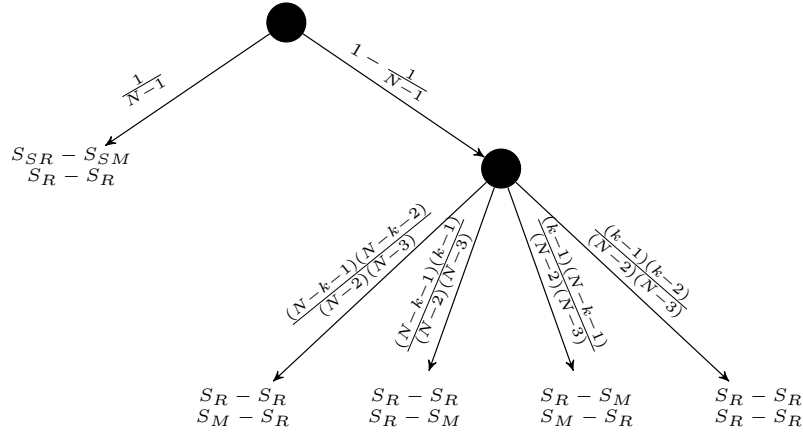


Figure 8: Possible pairings combination in the updating stage, given that individuals interact with only one other member in the population.. We distinguish between the selected resident and the rest of the residents and we do the same with the mutants. There is a probability that the selected resident interacts with the selected mutant.

The probability that the respective payoffs of the players are given by u_1 and u_2 can be calculated as

$$\begin{aligned}
x(u_1, u_2) = & \frac{1}{N-1} \cdot v_{u_1}(S_1, S_2) \cdot 1_{(u_1, u_2) \in \mathcal{U}_F^2} \\
& + \left(1 - \frac{1}{N-1}\right) \left[\frac{k-1}{N-2} \frac{k-2}{N-3} v_{u_1}(S_1, S_2) v_{u_2}(S_2, S_2) + \frac{k-1}{N-2} \frac{N-k-1}{N-3} v_{u_1}(S_1, S_2) v_{u_2}(S_2, S_1) \right. \\
& \left. + \frac{N-k-1}{N-2} \frac{k-1}{N-3} v_{u_1}(S_1, S_1) v_{u_2}(S_2, S_2) + \frac{N-k-1}{N-2} \frac{N-k-2}{N-3} v_{u_1}(S_1, S_1) v_{u_2}(S_2, S_1) \right]. \tag{8}
\end{aligned}$$

The first term on the right side corresponds to the case that the learner and the role model happened to be matched during the game stage, which happens with probability $1/(N-1)$. In that case, we note that only those payoff pairs can occur that are feasible in a direct interaction, $(u_1, u_2) \in \mathcal{U}_F^2 := \{(R, R), (S, T), (T, S), (P, P)\}$, as represented by the respective indicator function. Otherwise, if the learner and the role model did not interact directly, we need to distinguish four different cases, depending on whether the learner was matched with a resident or a mutant, and depending on whether the role model was matched with a resident or a mutant.

Given that $N-k$ players use the resident strategy $S_1 = (y_1, p_1, q_1)$ and that the remaining k players use the mutant strategy $S_2 = (y_2, p_2, q_2)$, the probability that the number of mutants increases by one in one step of the evolutionary process can be written as

$$\lambda_k^+ = \frac{N-k}{N} \cdot \frac{k}{N} \cdot \sum_{u_1, u_2 \in \mathcal{U}} x(u_1, u_2) \cdot \rho(u_1, u_2), \tag{9}$$

$$\lambda_k^- = \frac{N-k}{N} \cdot \frac{k}{N} \cdot \sum_{u_1, u_2 \in \mathcal{U}} x(u_1, u_2) \cdot \rho(u_2, u_1). \tag{10}$$

In this expression, $(N-k)/N$ is the probability that the randomly chosen learner is a resident, and k/N is the probability that the role model is a mutant. The sum corresponds to the total probability that the learner adopts the role model's strategy over all possible payoffs u_1 and u_2 that the two player may have received in their respective last rounds. We use $x(u_1, u_2)$ to denote the probability that the randomly chosen resident obtained a payoff of u_1 in the last round of his respective game, and that the mutant obtained a payoff of u_2 .

This framework can be extended to consider the case of where the payoffs correspond to the last n rounds payoff an individual achieved after interacting with m other individuals. For the case $n = 2$ the payoffs at the game stage are,

Proposition 2. *Assume a play between the reactive strategies s_1 and s_2 with a continuation probability δ . Then the probability of being in any of the sixteen outcomes $RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR$ on the last two rounds are given by,*

$$\mathbf{v}_{\mathbf{a}_1, \mathbf{a}_2} = (1 - \delta) m_{a_1, a_2} \delta^2 [\mathbf{v}_0 (I_4 - \delta M)^{-1}]_{a_1, a_2}, \quad \text{for } m_{a_1, a_2} \in M \text{ \& } a_1, a_2 \in \{R, S, T, P\} \quad (11)$$

Proposition 2 can be extended to the last n rounds.

Proposition 3. Assume a play between the reactive strategies s_1 and s_2 with a continuation probability δ . Then the probability of being in any of the sixteen outcomes $RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR, RR$ on the last two rounds are given by,

$$\mathbf{v}_{\mathbf{a}_1, \mathbf{a}_2} = (1 - \delta) \prod m_{a_1, a_2} \delta^2 [\mathbf{v}_0 (I_4 - \delta M)^{-1}]_{a_1, a_2} \quad (12)$$

for $m_{a_1, a_2} \in M$ and $a_1, a_2 \in [1, 4]$.

Equation 8 can also be extended to include interactions with two other individuals. The possible pairings are illustrated by Figure ??.

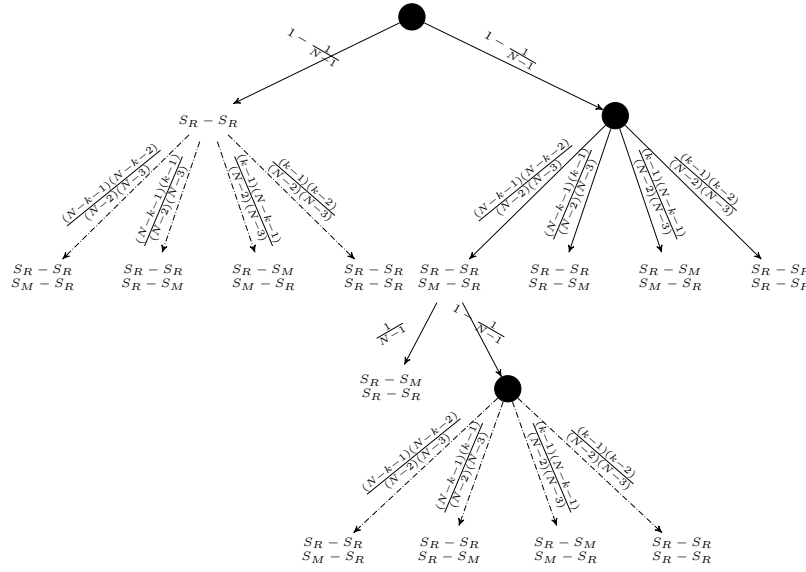


Figure 9: The tree

B Verifying analytical results with simulations

The analytical results presented in this work have been verified with simulations. More specifically the probabilities of Equation (6),

Proposition 2,

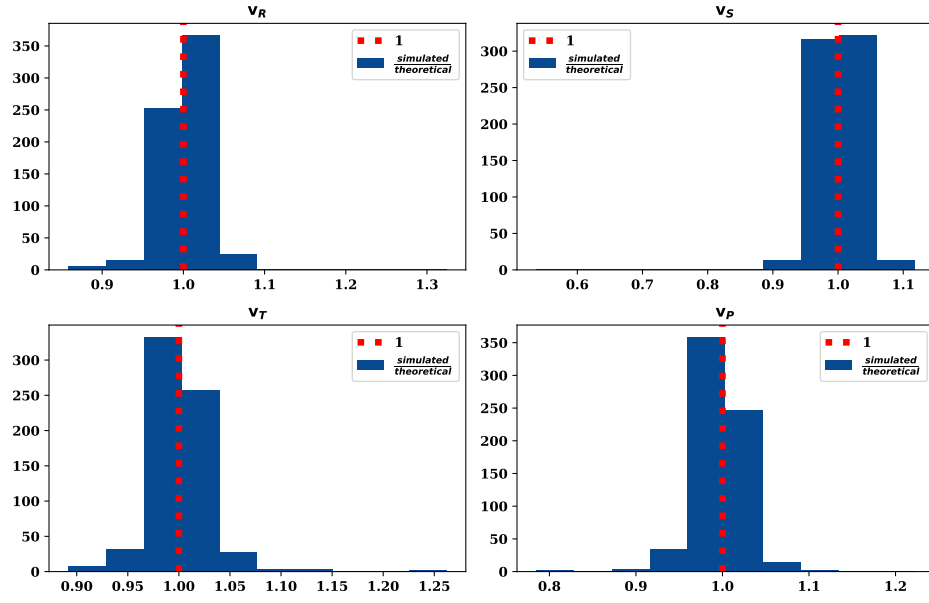


Figure 10

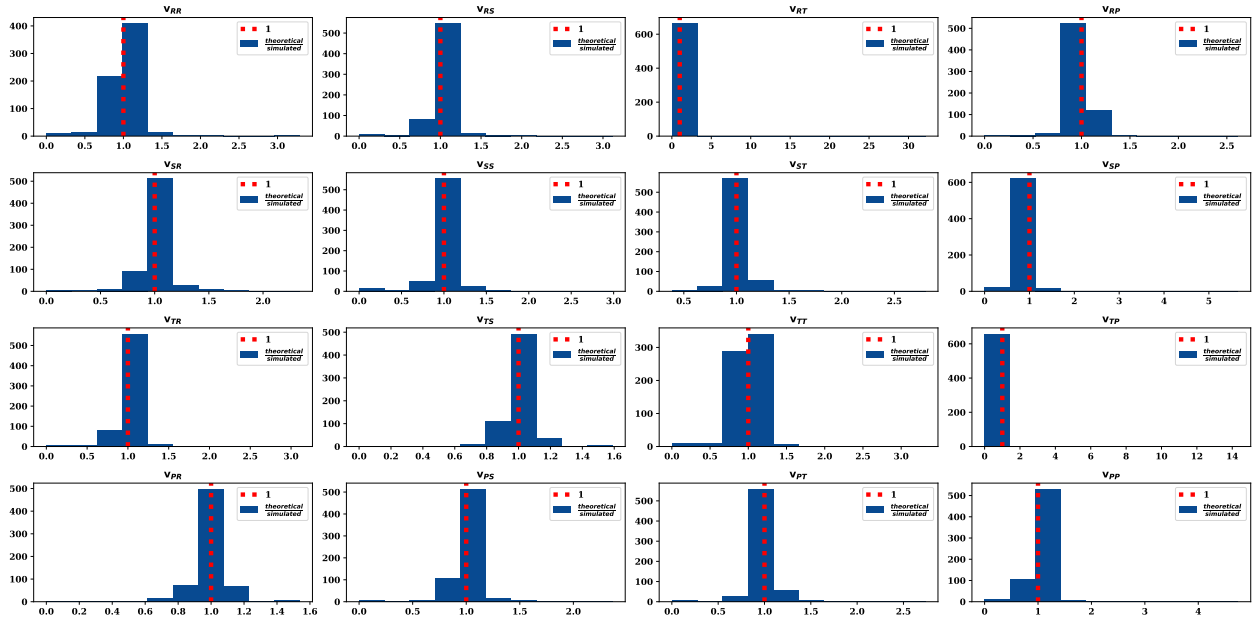


Figure 11

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