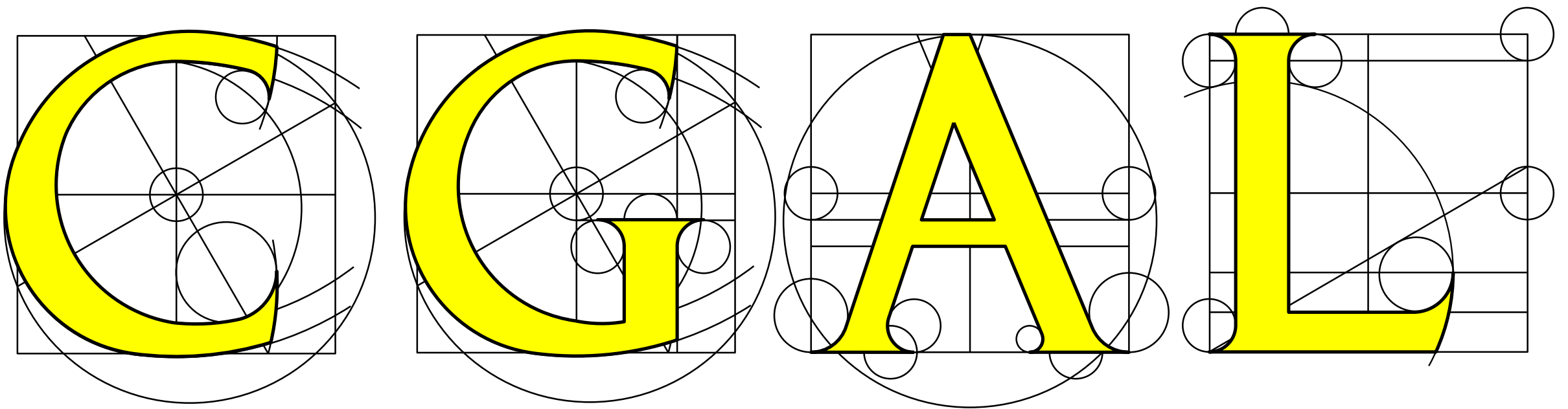


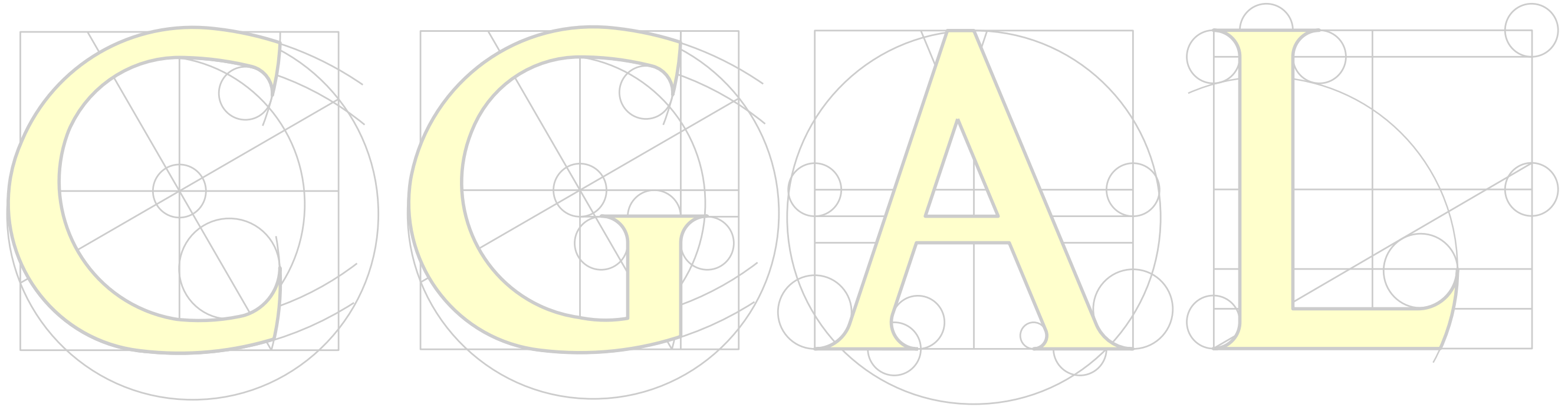
# A VERY SHORT INTRODUCTION TO



The Computational Geometry Algorithms Library

Michael Hoffmann <[hoffmann@inf.ethz.ch](mailto:hoffmann@inf.ethz.ch)>

(Based on work by Pierre Alliez, Andreas Fabri, Efi Fogel, Lutz Kettner, Sylvain Pion, Monique Teillaud, Mariette Yvinec, and probably many others.)

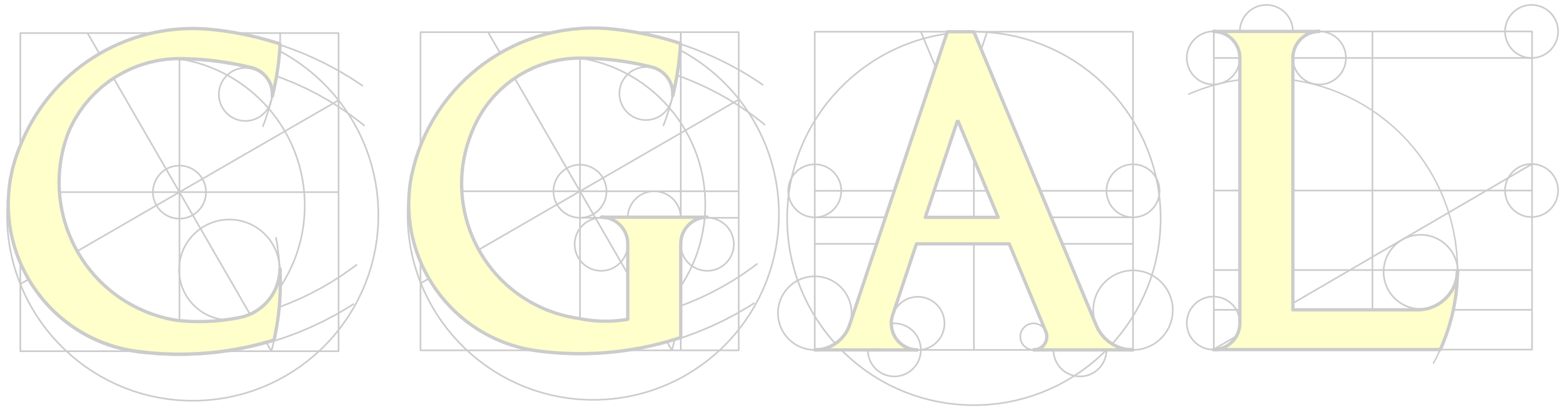


I: The CGAL Project

II: Exact Geometric Computing

III: Basic Programming using a CGAL Kernel

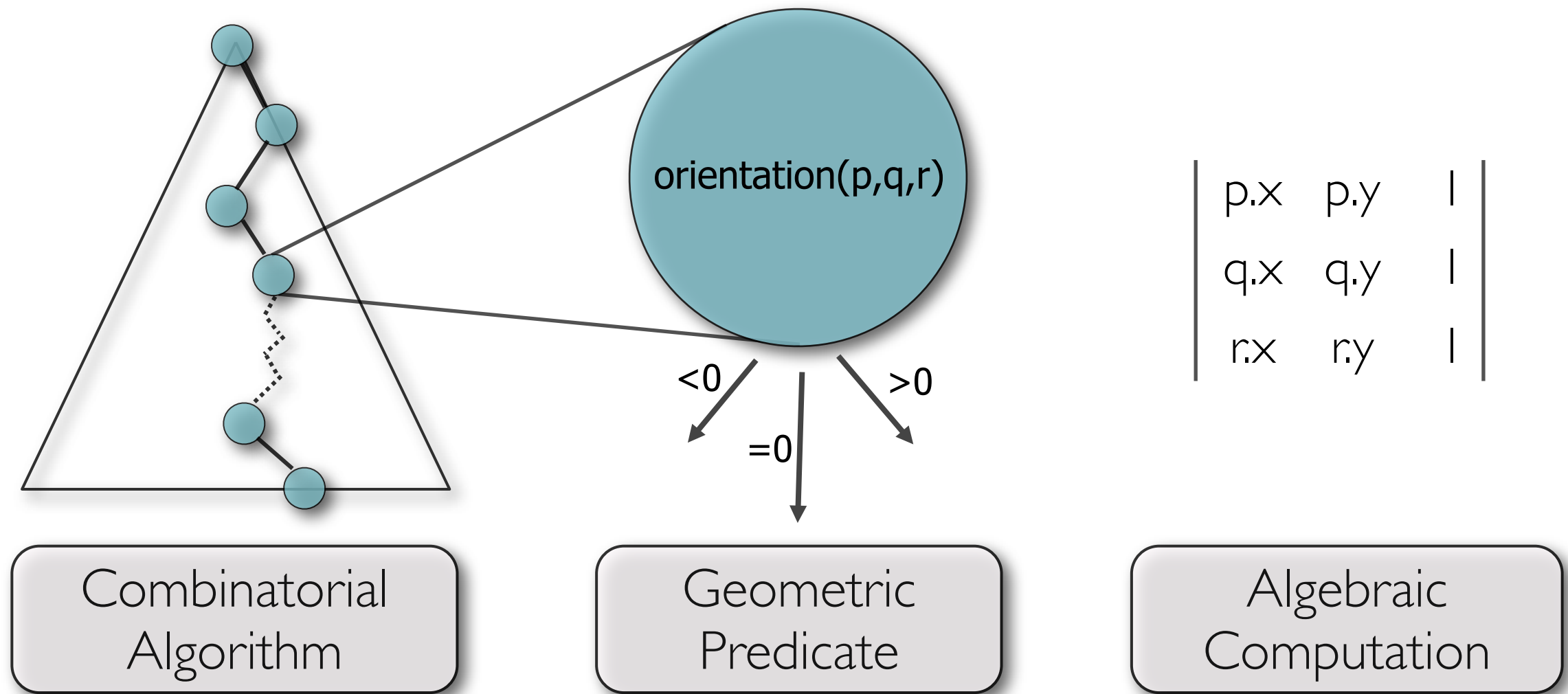
IV: Practical Information



## PART II:

# Exact Geometric Computing

# LAYERS OF GEOMETRIC ALGORITHMS



Control flow depends on non-trivial algebraic computations.  
How to do these efficiently and consistently?  
(Tough, no universally applicable solution...)

# ARITHMETIC

All operations beyond  $+$  and  $-$  are computed using limited precision floating point arithmetic.

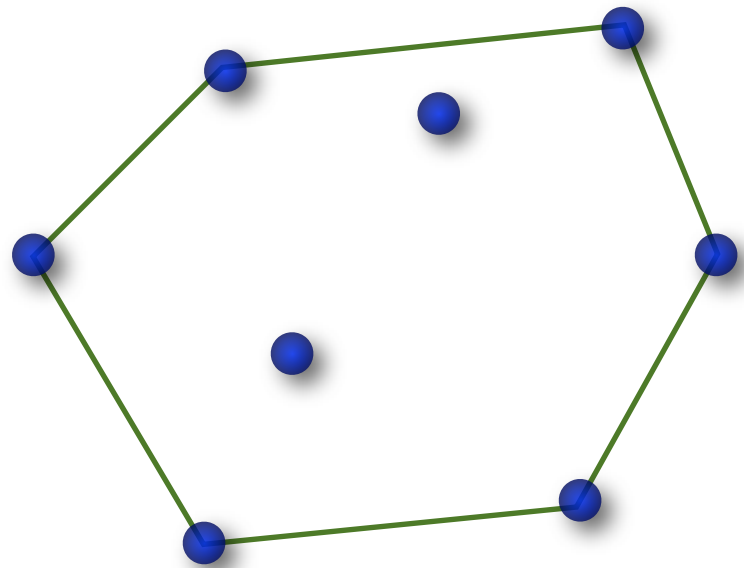
Integer multiplication and division are usually slower, often considerably. And the precision is limited regardless...

➔ Results may be **incorrect** due to roundoff.

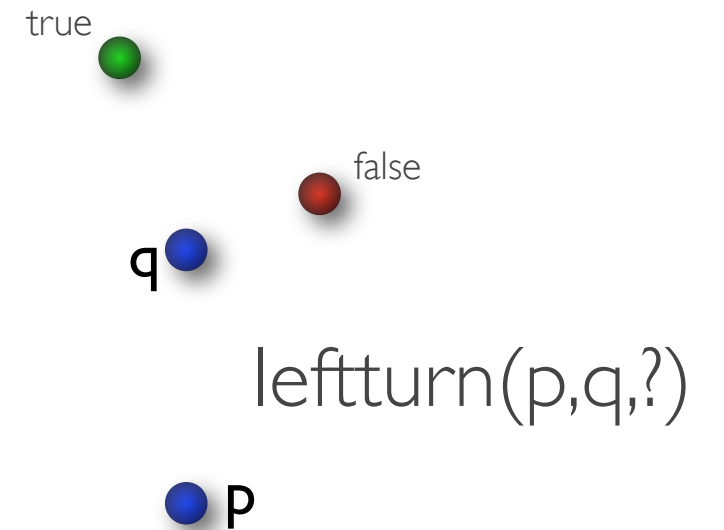
Difference to numeric computing:  
Results are interpreted combinatorially: yes or no.

Incorrect results often lead to a **complete failure** rather than to a reasonable approximation.

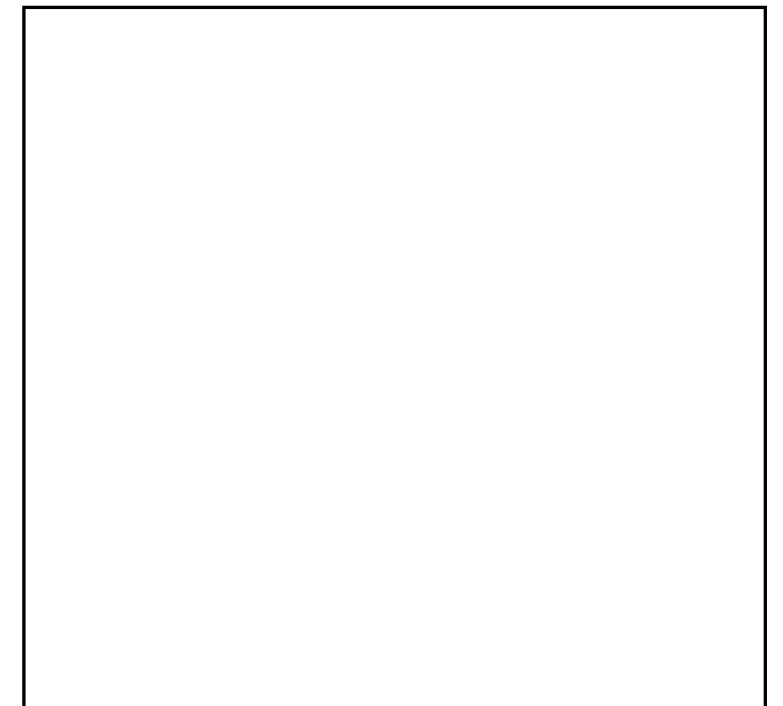
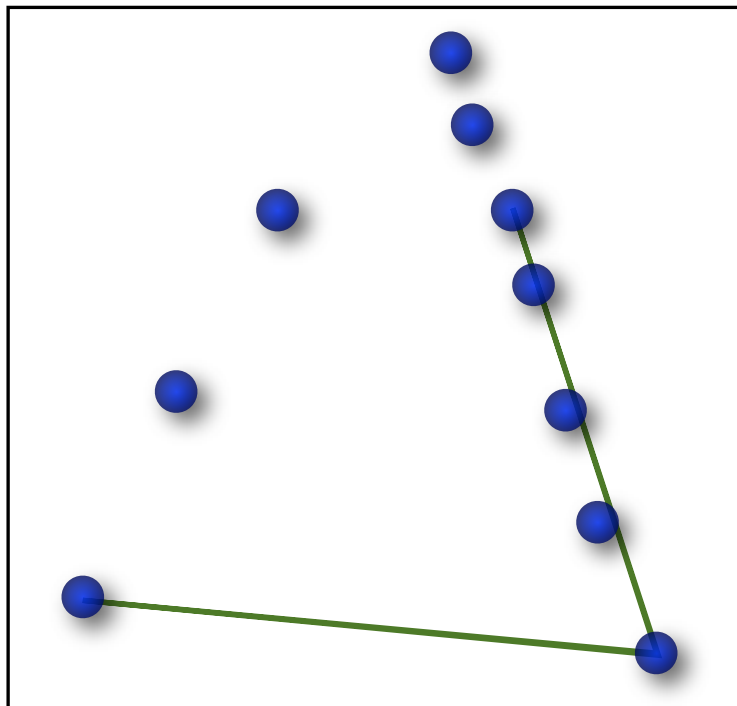
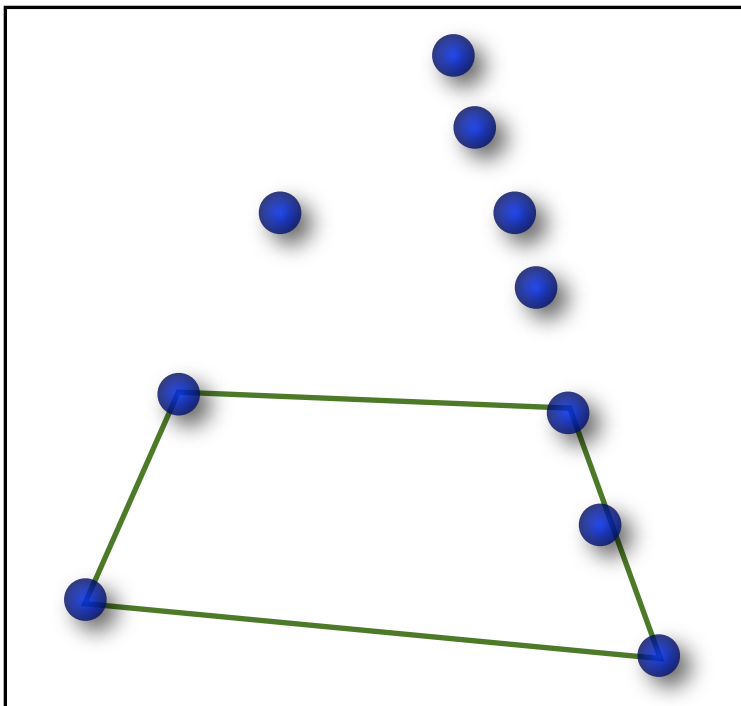
# CONVEX HULL



Based on  
orientation test.



Possible results with an unreliable orientation test:



# STRAIGHT LINES ?

$$\text{Orientation}(p, q, r) = \begin{vmatrix} p.x & p.y & 1 \\ q.x & q.y & 1 \\ r.x & r.y & 1 \end{vmatrix} = (q.x - p.x)(r.y - p.y) - (q.y - p.y)(r.x - p.x)$$

$$p = (0.5 + x \cdot u, 0.5 + y \cdot u)$$

$$q = (12, 12)$$

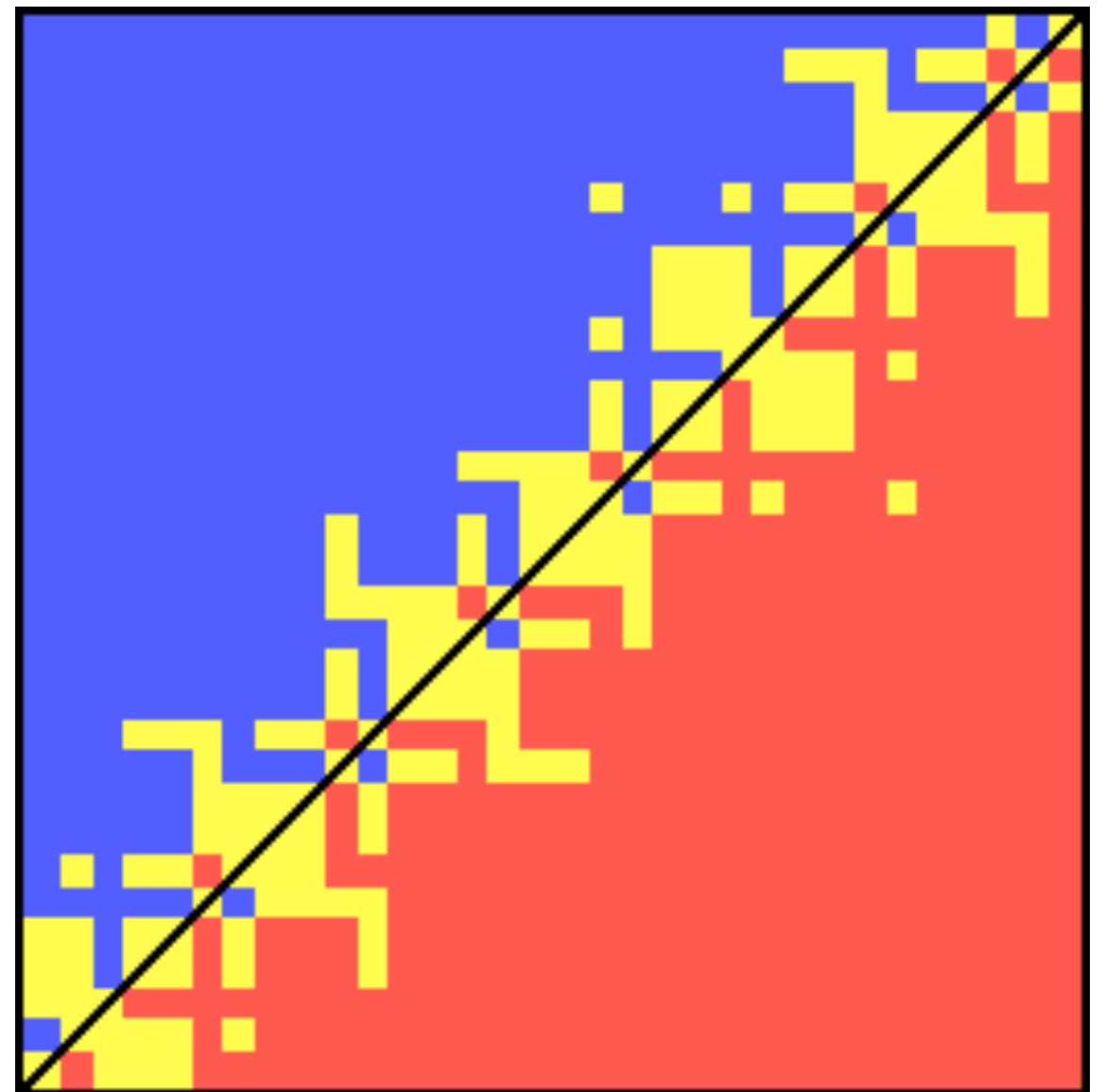
$$r = (24, 24)$$

$$0 \leq x, y < 256, u = 2^{-53}$$

256x256 pixel image

**red**: <0, **yellow**: =0, **blue**: >0

evaluated with **double**



# STRAIGHT LINES ?

$$\text{Orientation}(p, q, r) = \begin{vmatrix} p.x & p.y & 1 \\ q.x & q.y & 1 \\ r.x & r.y & 1 \end{vmatrix} = (q.x - p.x)(r.y - p.y) - (q.y - p.y)(r.x - p.x)$$

$$p = (0.5 + x \cdot u, 0.5 + y \cdot u)$$

$$q = (8.800000000000000000000007, \\ 8.800000000000000000000007)$$

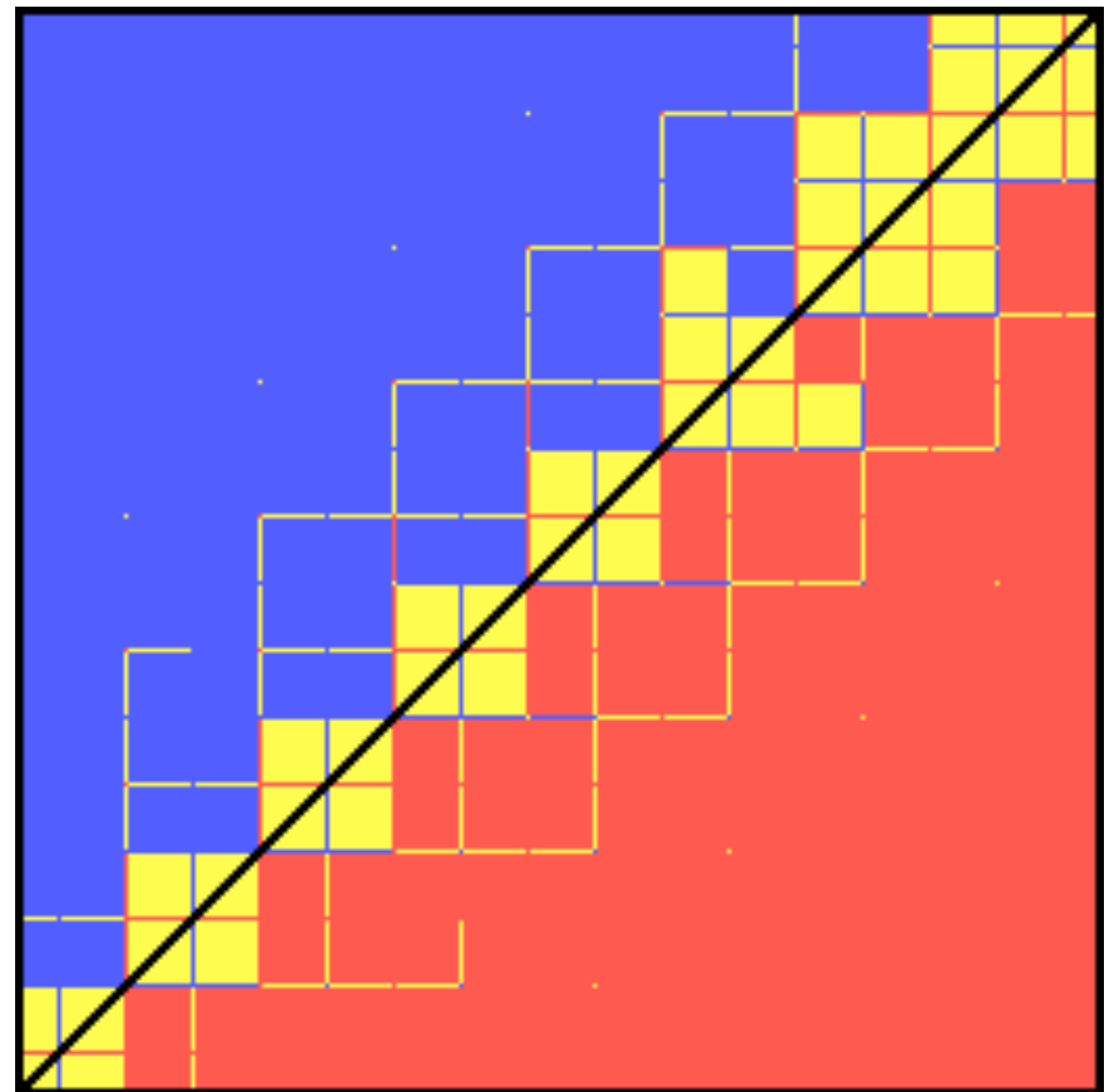
$$r = (12.1, 12.1)$$

$$0 \leq x, y < 256, u = 2^{-53}$$

256x256 pixel image

**red**: <0, **yellow**: =0, **blue**: >0

evaluated with **double**





# STRAIGHT LINES ?

$$\text{Orientation}(p, q, r) = \begin{vmatrix} p.x & p.y & 1 \\ q.x & q.y & 1 \\ r.x & r.y & 1 \end{vmatrix} = (q.x - p.x)(r.y - p.y) - (q.y - p.y)(r.x - p.x)$$

$$p = (0.5000000000000000002531 + x \cdot u, \\ 0.5000000000000000001710 + y \cdot u)$$

$$q = (17.30000000000000000001, \\ 17.30000000000000000001)$$

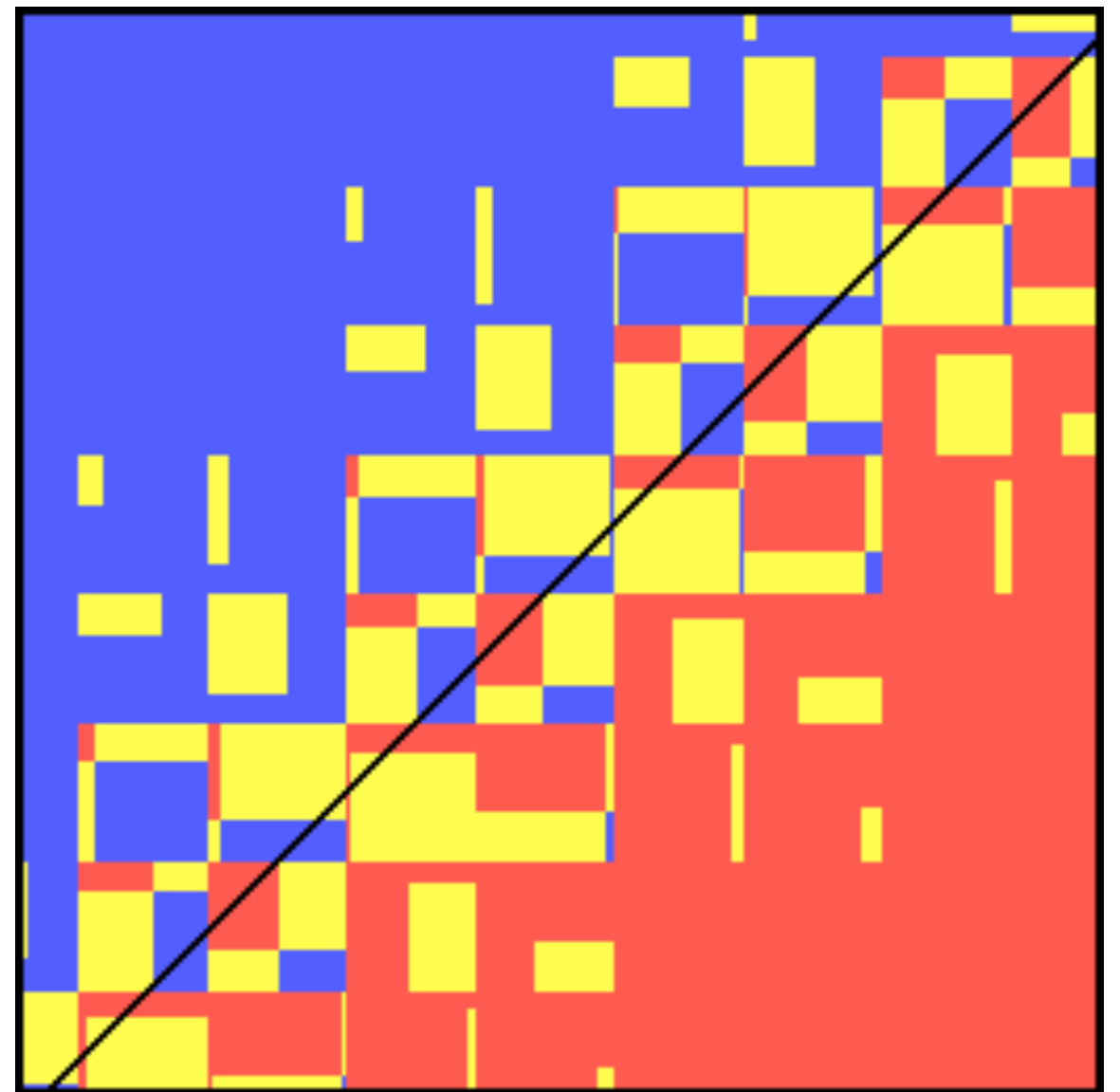
$$r = (24.000000000000000000500000, \\ 24.000000000000000000517765)$$

$$0 \leq x, y < 256, u = 2^{-53}$$

256x256 pixel image

**red**: <0, **yellow**: =0, **blue**: >0

evaluated with **ext double**



# HOW TO OBTAIN CORRECTNESS?

Several options:

▶ Hope things go fine  and fiddle around if not

Sometimes possible, often hard,  
always messy. Very problem-  
specific, no general machinery.

▶ Adapt algorithm to cope with imprecisions 

▶ Restrict input

Good in special cases, hard to impossible  
for general purpose implementations .  
Document and check properly!

▶ Use exact algebra

General approach. Easy to use.  
Can be very slow...

▶ Filtering: Check whether things go fine and use  
exact algebra only when needed.

General approach. Easy to use.  
Often quite efficient...

# FLOATING POINT NUMBERS

IEEE 754 double precision

+/-	exponent	mantissa
1 bit	11 bits	53 bits

0.1 is not exactly representable

Numbers  $\pm m \cdot 2^x$ ,  $0 \leq m < 2^{53}$ ,  $-1022 \leq x \leq 1023$ .

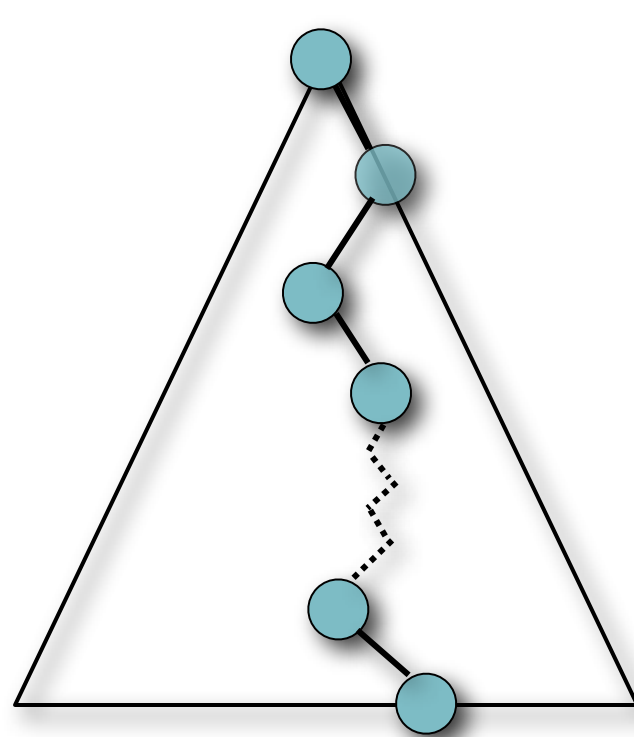
b bits	$\pm$	b bits	$\approx$	b+1 bits
b bits	$\cdot$	b bits	$\approx$	2b bits

$$(q.x-p.x)(r.y-p.y)-(q.y-p.y)(r.x-p.x)$$

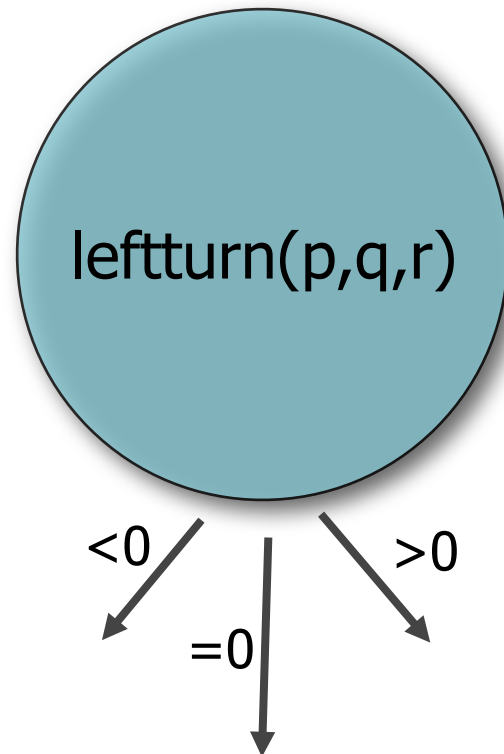


orientation test  $\approx 2b+3$  bits, can be done exactly for 25-bit integer coordinates.

# EXACT COMPUTATION



Combinatorial  
Algorithm

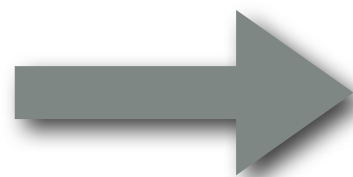


Geometric  
Predicate

$$\begin{vmatrix} p.x & p.y & 1 \\ q.x & q.y & 1 \\ r.x & r.y & 1 \end{vmatrix}$$

Algebraic  
Computation

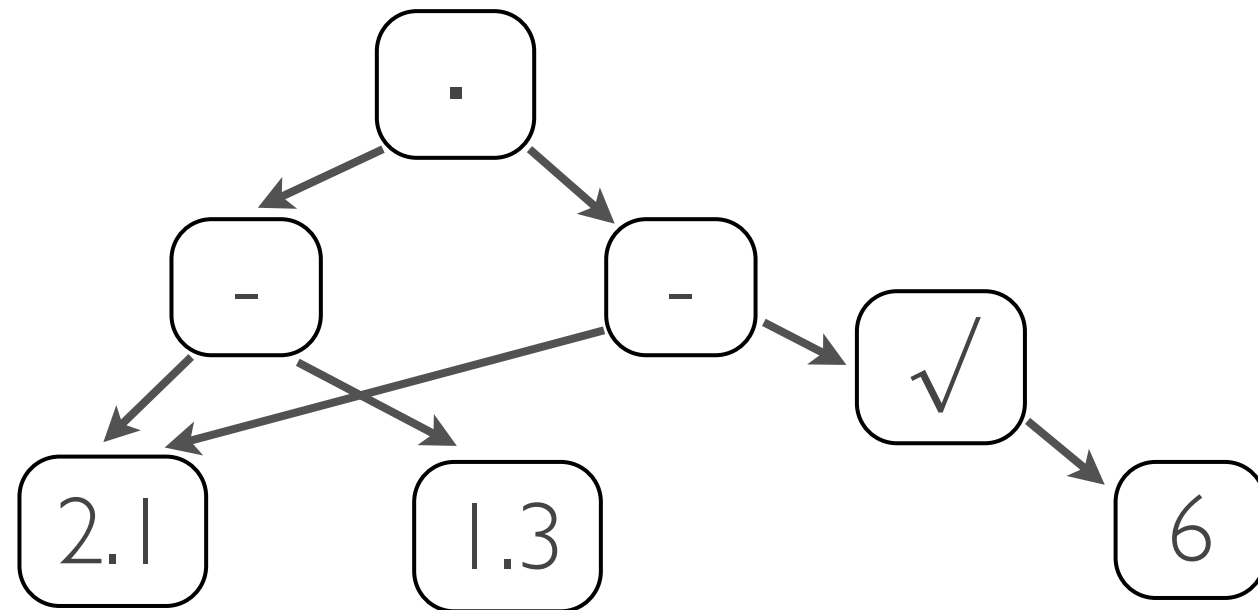
Ensure that the control flow in the algorithm is the same as if all algebraic computations were made exactly.



Correctness

# EXACT ALGEBRAIC COMPUTATION

$$(2.1 - 1.3)(2.1 - \sqrt{6})$$



- ▶ numbers represented as expression-dags
- ▶ arbitrary precision floating point data types (array of digits) to compute approximations
- ▶  $\text{sign}(x)$ : compute finer and finer approximations for  $x$ , until it becomes clear that  $x > 0$  or  $x < 0$ ;
- ▶ for any algebraic expression there is a *separation bound* that tells where to stop and conclude  $x = 0$ .

# FLOATING POINT FILTERS

Exact algebraic computation is expensive.

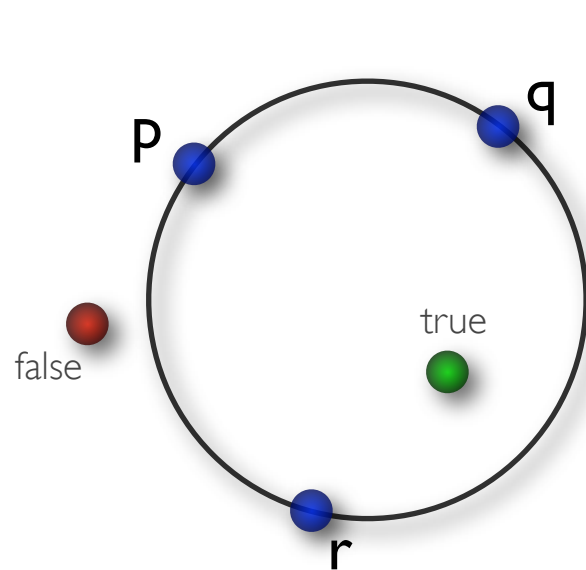
→ use when absolutely necessary only.

- ▶ maintain double approximation  $[l, h]$  using interval arithmetic (hardware support  $\Rightarrow$  fast)
- ▶ if  $0 \notin [l, h]$ , this is good enough to decide about sign.
- ▶ use exact machinery only if  $0 \in [l, h]$ .

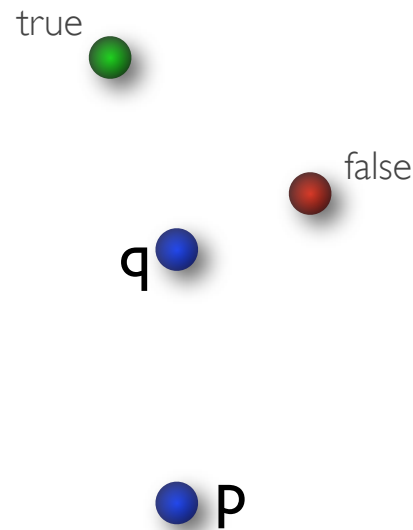
Minimal overhead as long as filter works.

In particular, if only predicates are used and no constructions.

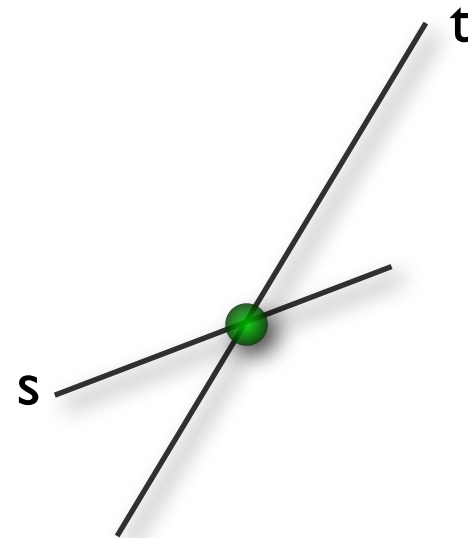
# GEOMETRIC OPERATIONS



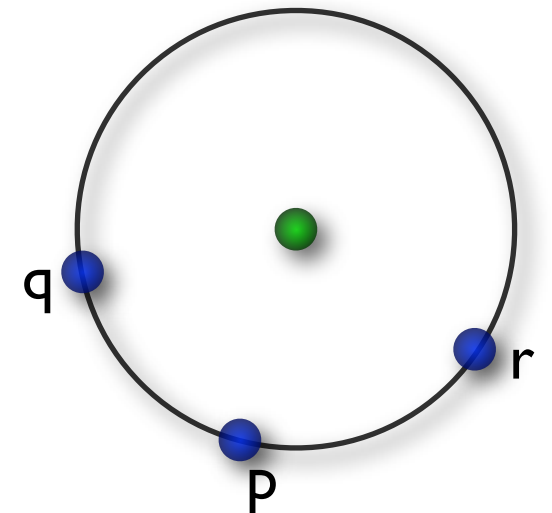
`incircle(p,q,r,?)`



`leftturn(p,q,?)`



`intersection(s,t)`



`circumcircle(p,q,r)`

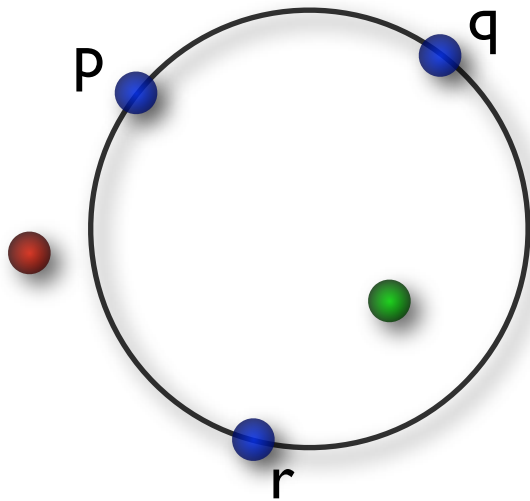
Predicates

Constructions

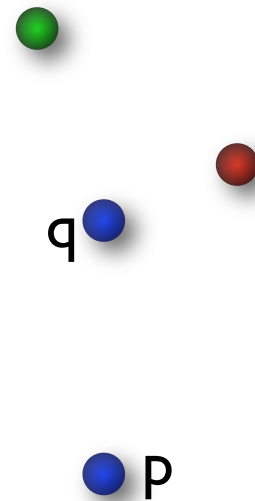


Do you need (exact) constructions?

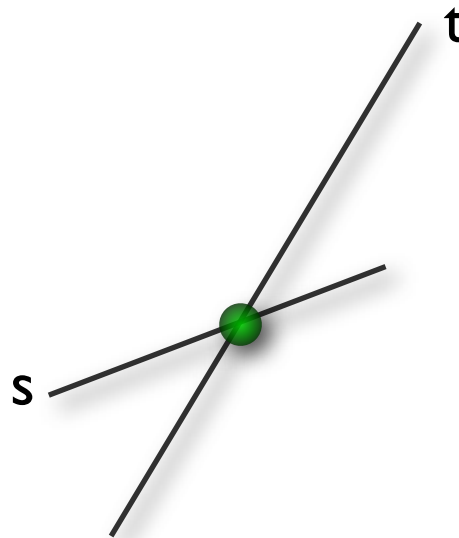
# GEOMETRIC OPERATIONS



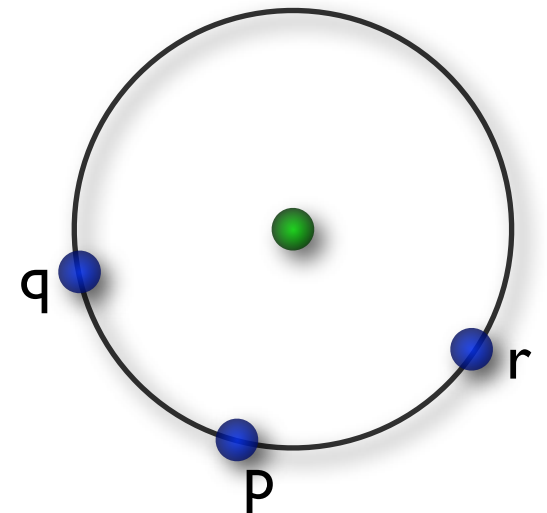
$\text{incircle}(p,q,r,?)$



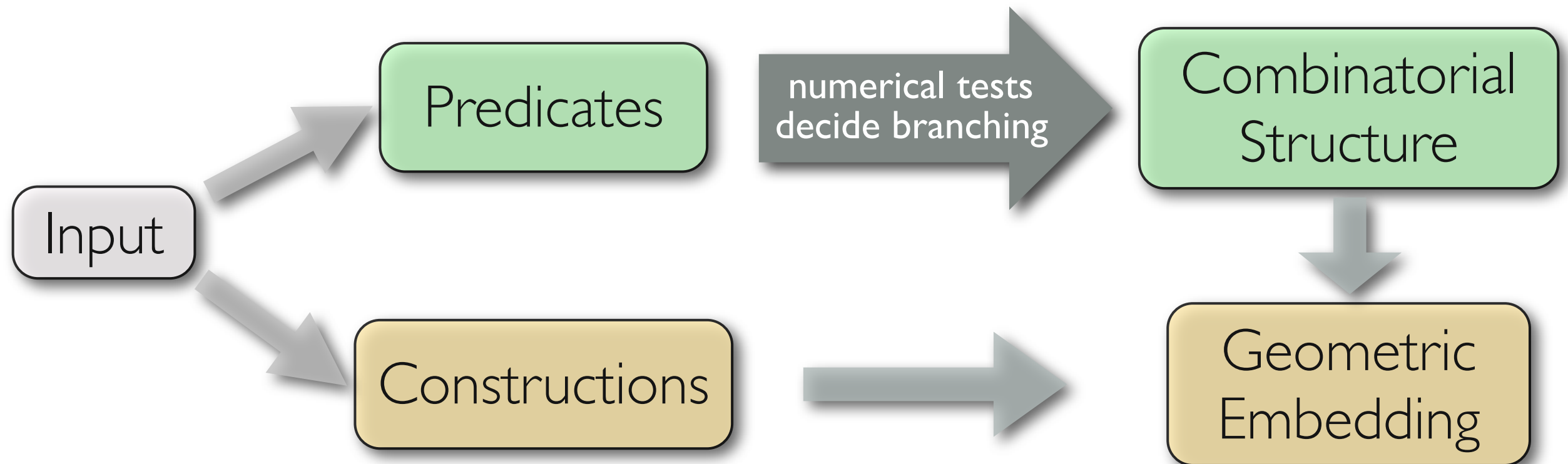
$\text{leftturn}(p,q,?)$



$\text{intersection}(s,t)$



$\text{circumcircle}(p,q,r)$

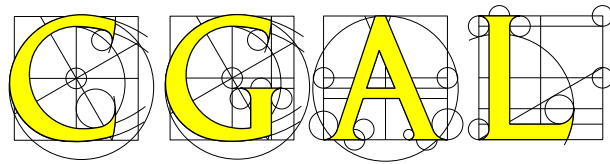
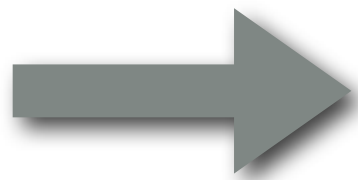




# FLEXIBILITY

Collection of geometric data types and operations.

There is no single true way to do geometric computing.



offers different kernels to serve various needs

You have to choose the right one for your particular case.

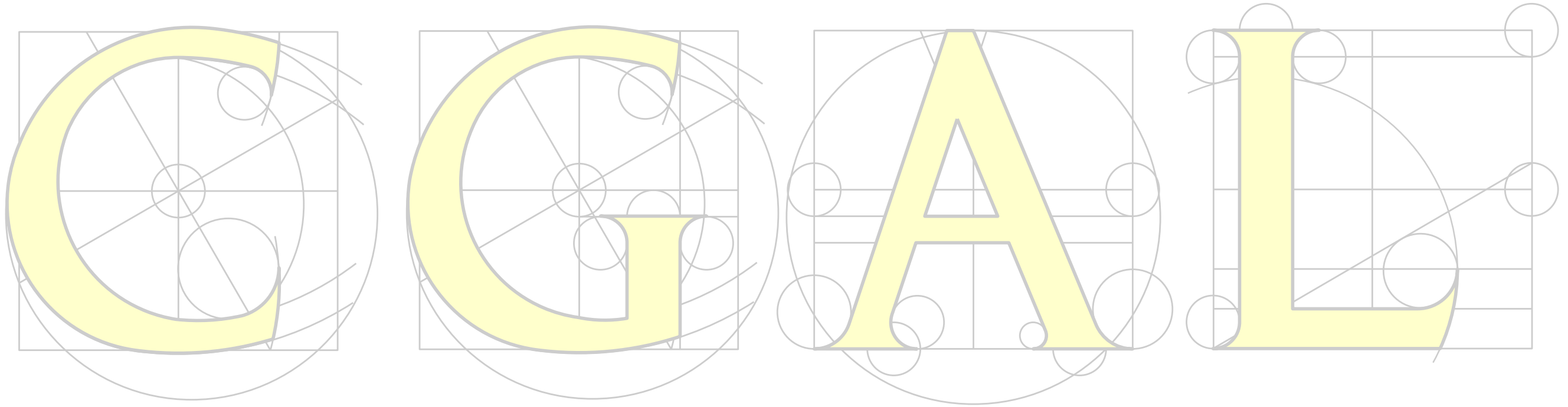
Predefined defaults:

All three compute predicates exactly using filters for efficiency.

- ▶ `CGAL::Exact_predicates_inexact_constructions_kernel`  
Constructions use `double`.
- ▶ `CGAL::Exact_predicates_exact_constructions_kernel`  
Constructions use an exact number type supporting `+, -, *, /`.
- ▶ `CGAL::Exact_predicates_exact_constructions_kernel_with_sqrt`  
Constructions use an exact number type supporting `+, -, *, /`, and roots.

fast

slow



## PART III:

### Basic Programming using a CGAL Kernel

# GOALS

For a geometric algorithm, you are able to pick an adequate CGAL kernel.



- ▶ Are non-trivial geometric constructions needed?
- ▶ Are exact roots needed?

You are able to do some basic geometric computations using CGAL.

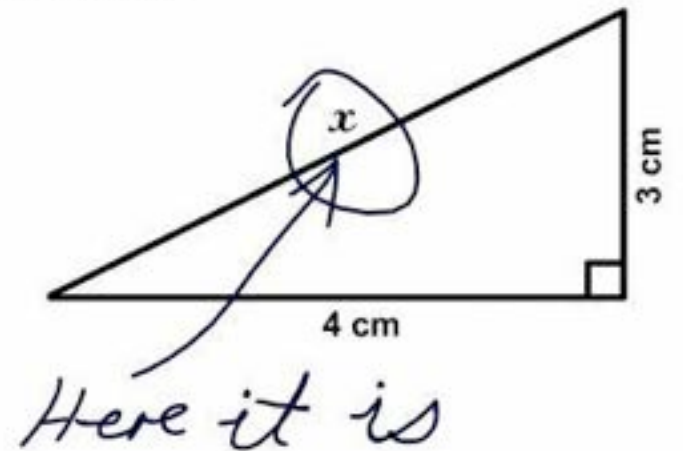
- ▶ 2D kernel objects
- ▶ Intersections
- ▶ Bounding Volumes



# PREREQUISITES

You know basic Euclidean geometry (e.g., distance/area/volume, angles, Pythagoras, ...) and can apply this knowledge to describe and analyze problems, to design models and algorithms.

3. Find  $x$ .



Ocular Trauma - by Wade Clarke ©2005

You know basic algorithmic techniques (e.g., D.P., binary search, sorting, line sweep...). ➔ You skillfully combine them with the geometric techniques discussed here.

# HELLO POINT

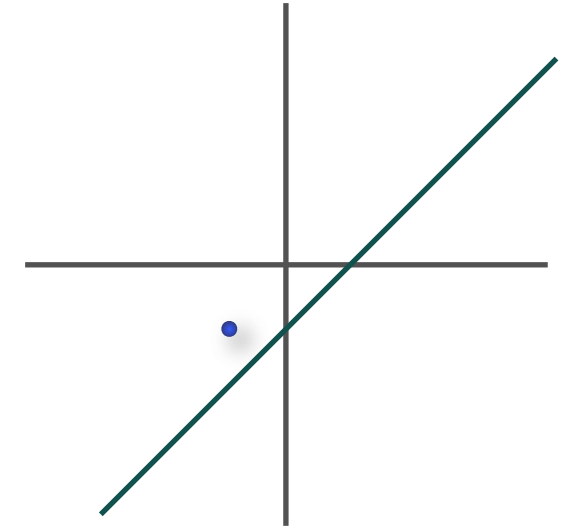
```
#include <CGAL/Exact_predicates_inexact_constructions_kernel.h>
#include <iostream>
```

```
typedef CGAL::Exact_predicates_inexact_constructions_kernel K;
```

```
int main()
{
    K::Point_2 p(2,1), q(1,0), r(-1,-1);
    K::Line_2 l(p,q);
    K::FT d = CGAL::squared_distance(r,l);
    std::cout << d << std::endl;
}
```

There is a bunch of hyperlinks here.  
Click me to get to the CGAL manual.

Does this code use  
constructions?  
YES!



Output: 0.5

FT = field type

The number type used for the  
underlying algebra. Supports all  
field operations, i.e., +-\*./.

Some (few) field types also support exact roots.

avoids square root computation

To obtain an approximation of the real distance, use

```
std::sqrt(CGAL::to_double(CGAL::squared_distance(r,l)))
```

This function must be defined for any field type.

Even if the field type supports exact square roots, in order to  
output it numerically you have to resort to an approximation...

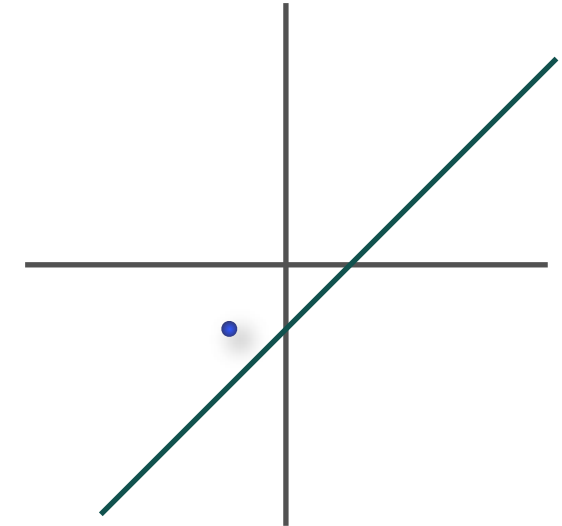
[https://moodle-app2.let.ethz.ch/pluginfile.php/163339/mod\\_folder/content/0/hello.cpp](https://moodle-app2.let.ethz.ch/pluginfile.php/163339/mod_folder/content/0/hello.cpp)

# HELLO POINT

```
#include <CGAL/Exact_predicates_inexact_constructions_kernel.h>
#include <iostream>

typedef CGAL::Exact_predicates_inexact_constructions_kernel K;

int main()
{
    K::Point_2 p(2,1), q(1,0), r(-1,-1);
    K::Line_2 l(p,q);
    K::FT d = CGAL::squared_distance(r,l);
    std::cout << d << std::endl;
}
```



For the small coordinates used here, things are probably fine. But in general...

this code is not safe!

Constructing a line from two points.  
Trivial?

Depends on representation of lines... equation => non-trivial construction

Constructing a point from Cartesian double coordinates. All default kernels can do this exactly, by just storing the coordinates.  
=> trivial construction, no problem

Also a non-trivial construction.  
(Squared distance may be considerably larger than input coordinates, which may lead to overflow.)

## CGAL::Line\_2<Kernel>

### Definition

An object  $l$  of the data type `Line_2<Kernel>` is a directed straight line in the two-dimensional Euclidean plane  $\mathbb{E}^2$ . It is defined by the set of points with Cartesian coordinates  $(x,y)$  that satisfy the equation  $l : ax + by + c = 0$

The line splits  $\mathbb{E}^2$  in a *positive* and a *negative* side. A point  $p$  with Cartesian coordinates  $(px, py)$  is on the positive side of  $l$ , iff  $apx + bpy + c > 0$ , it is on the negative side of  $l$ , iff  $apx + bpy + c < 0$ . The positive side is to the left of  $l$ .

Class

# HELLO POINT (EXACTLY)

```
#include <CGAL/Exact_predicates_exact_constructions_kernel_with_sqrt.h>
#include <iostream>
#include <iomanip>

typedef CGAL::Exact_predicates_exact_constructions_kernel_with_sqrt K;

int main()
{
    K::Point_2 p(2,1), q(1,0), r(-1,-1);
    K::Line_2 l(p,q);
    K::FT d = sqrt(CGAL::squared_distance(r,l));
    std::cout << CGAL::to_double(d) << std::endl;
    std::cout << std::setiosflags(std::ios::fixed) << std::setprecision(2)
    << CGAL::to_double(d) << std::endl;
}
```

Set precision (number of digits after the decimal point) for floating point number output. Round to nearest, but tie-breaking is not well defined!

Output:  
0.707107  
0.71

Compute squareroot (here: exactly).

Round to some **double** nearby.  
(There is no easy way to output the exact internal representation.)

**Problem:** No guarantee on precision and rounding.

Output floating point numbers in fixed point notation from now on.  
`std::resetiosflags(std::ios::fixed)` switches back to default behaviour.

# HELLO POINT (EVEN MORE EXACTLY)

```
#include <CGAL/Exact_predicates_exact_constructions_kernel_with_sqrt.h>
#include <iostream>
#include <cmath> ← for std::floor(...)

typedef CGAL::Exact_predicates_exact_constructions_kernel_with_sqrt K;

double floor_to_double(const K::FT& x)
{
    double a = std::floor(CGAL::to_double(x)); ← Compute approximation of the
    while (a > x) a -= 1;                       closest integer ≤ x.
    while (a+1 <= x) a += 1;                     (Usually, this is pretty good. But we
    return a;                                    cannot be sure that it is always...)
}

int main()
{
    K::Point_2 p(2,1), q(1,0), r(-1,-1);
    K::Line_2 l(p,q);
    K::FT d = sqrt(CGAL::squared_distance(r,l)); ← Compare to the exact
    std::cout << floor_to_double(d) << std::endl;    value to be sure.
}                                                    (This assumes that x is somewhere within the range
                                                    of double, which will be the case in all our problems.)

                                                    Compute squareroot exactly.
```

Output:

0

We need a precise specification for all output, in order to compare on the judge.

This is the recommended way to round down to an integer.

(The symmetric function `ceil_to_double(...)` to round up should be an easy exercise...)

[https://moodle-app2.let.ethz.ch/pluginfile.php/163339/mod\\_folder/content/0/hello-really-exact.cpp](https://moodle-app2.let.ethz.ch/pluginfile.php/163339/mod_folder/content/0/hello-really-exact.cpp)



# TWO KERNELS IN ONE PROGRAM

```
#include <CGAL/Exact_predicates_inexact_constructions_kernel.h>
#include <CGAL/Exact_predicates_exact_constructions_kernel.h>
#include <iostream>
#include <stdexcept>
```

```
typedef CGAL::Exact_predicates_inexact_constructions_kernel IK;
typedef CGAL::Exact_predicates_exact_constructions_kernel EK;
```

```
int main()
```

```
{
```

```
    IK::Point_2 p(2,1), q(1,0), r(-1,-1);
```

```
    // do something that needs predicates only, e.g., ...
```

```
    std::cout << (CGAL::left_turn(p, q, r) ? "y" : "n") << "\n";
```

```
    // now we use non-trivial constructions...
```

```
    EK::Point_2 ep(p.x(), p.y()), eq(q.x(), q.y()), er(r.x(), r.y());
```

```
    EK::Circle_2 c(ep, eq, er);
```

```
    if (!c.has_on_boundary(ep))
```

```
        throw std::runtime_error("ep not on c");
```

```
}
```

This works because the coordinates of `IK::Point_2` are actually `double`.

It would not work the other way round, because the coordinates of `EK::Point_2` are of some elaborate number type.

We cannot just write `c(p, q, r)` because these are `IK::Point_2` and there is no general conversion between points from different kernels.

Output:

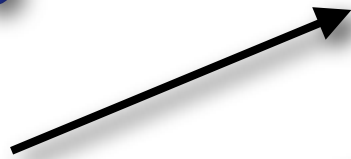
n

# 2D (LINEAR) KERNEL

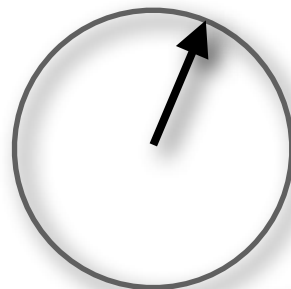
► Point\_2



► Vector\_2



► Direction\_2



► Line\_2

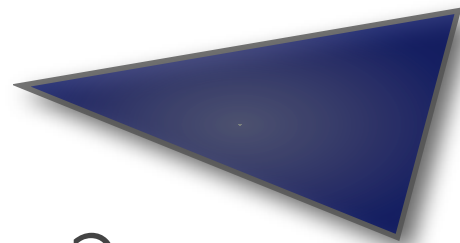
► Ray\_2



► Segment\_2

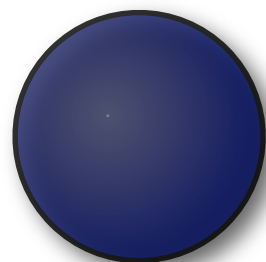


► Triangle\_2



► Iso\_rectangle\_2

► Circle\_2



Follow the links to see the manual.

# 2D KERNEL FUNCTIONALITY

See the  Manual: <http://www.cgal.org>

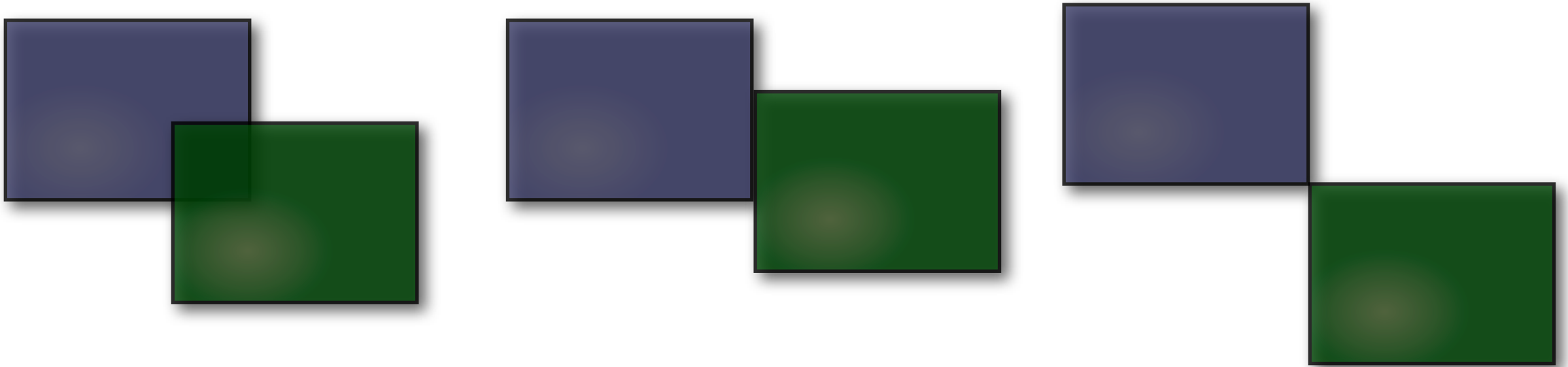
Most manual chapters have two parts:

- ▶ User Manual: general introduction and examples.
- ▶ Reference Manual: complete list of functionality.

Often one deals with several different interacting types and has to jump back and forth.

=> html is very convenient

# INTERSECTIONS



Problem: We do not know the return type.

```
K::Iso_rectangle_2 r1 = ... ;  
K::Iso_rectangle_2 r2 = ... ;  
??? i = CGAL::intersection(r1, r2);
```

Solution: Use a generic wrapper class (based on boost::variant).  
Test whether it contains an object of type T using boost::get<T>.

# INTERSECTIONS

```
#include <CGAL/Exact_predicates_exact_constructions_kernel.h>
```

```
#include <iostream>
```

```
#include <stdexcept>
```

```
typedef CGAL::Exact_predicates_exact_constructions_kernel K;
```

```
typedef K::Point_2 P;
```

```
typedef K::Segment_2 S;
```

```
int main()
```

```
{
```

```
    P p[] = { P(0,0), P(2,0), P(1,0), P(3,0), P(.5,1), P(.5,-1) };
```

```
    S s[] = { S(p[0],p[1]), S(p[2],p[3]), S(p[4],p[5]) };
```

```
    for (int i = 0; i < 3; ++i)
```

```
        for (int j = i+1; j < 3; ++j)
```

```
            if (CGAL::do_intersect(s[i],s[j])) {
```

```
                auto o = CGAL::intersection(s[i],s[j]);
```

```
                if (const P* op = boost::get<P>(&*o))
```

```
                    std::cout << "point: " << *op << "\n";
```

```
                else if (const S* os = boost::get<S>(&*o))
```

```
                    std::cout << "segment: " << os->source() << " "
```

```
                        << os->target() << "\n";
```

```
                else // how could this be? -> error
```

```
                    throw std::runtime_error("strange segment intersection");
```

```
            } else
```

```
                std::cout << "no intersection\n";
```

```
}
```

The actual type is `std::result_of<K::Intersect_2(S,S)>::type`

Needs `#include <type_traits>`

Test for intersection (predicate)

Construct intersection (construction :-)

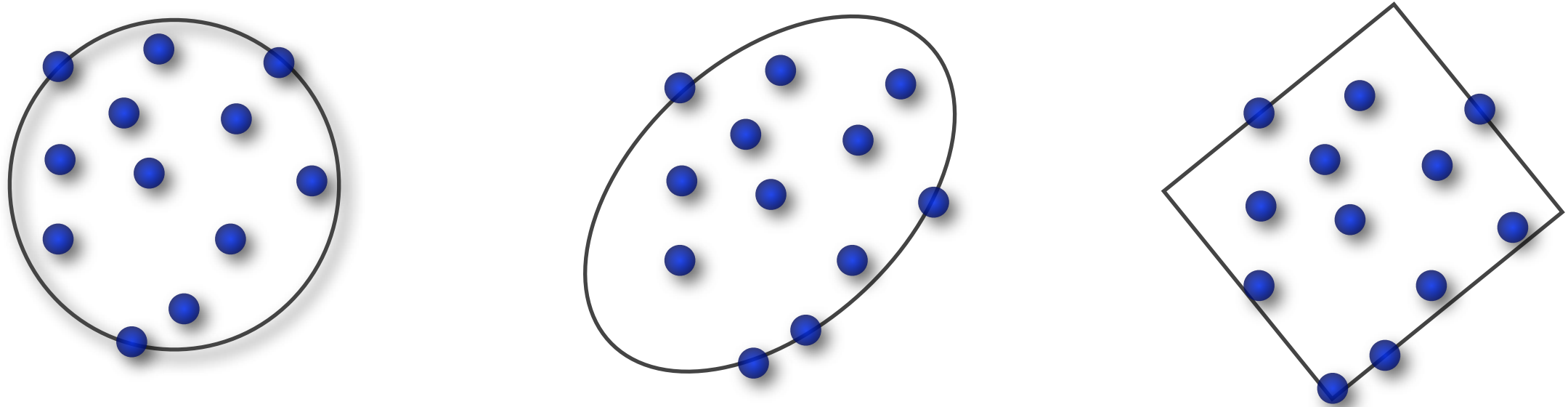
Cast fails (`=0`) if `o` is not of type `P`.

Output:

```
segment: 1 0 2 0
point: 0.5 0
no intersection
```

[https://moodle-app2.let.ethz.ch/pluginfile.php/163339/mod\\_folder/content/0/intersect.cpp](https://moodle-app2.let.ethz.ch/pluginfile.php/163339/mod_folder/content/0/intersect.cpp)

# BOUNDING VOLUMES



Problem: Given  $n$  points in  $\mathbb{R}^2$ , what is their minimum enclosing ... ?

- ▶ Circle
- ▶ Ellipse
- ▶ (Circular) annulus
- ▶ Rectangle
- ▶ Parallelogram
- ▶ Strip



Can be computed in expected linear time.



Can be computed in linear time once the convex hull is known.

# MINIMUM ENCLOSING CIRCLE

```
#include <CGAL/Exact_predicates_exact_constructions_kernel.h>
#include <CGAL/Min_circle_2.h>
#include <CGAL/Min_circle_2_traits_2.h>
#include <iostream>
```

Many data structures and algorithms have their own traits concept. It defines the geometric primitives needed.

```
// typedefs
typedef CGAL::Exact_predicates_exact_constructions_kernel K;
typedef CGAL::Min_circle_2_traits_2<K> Traits;
typedef CGAL::Min_circle_2<Traits> Min_circle;
```

Separate: Combinatorial algorithm  $\Leftrightarrow$  geometry

```
int main()
{
```

```
    const int n = 100;
    K::Point_2 P[n];
```

Build from a range of points.

Attention! Constructions are used inside...

```
    for (int i = 0; i < n; ++i)
        P[i] = K::Point_2((i % 2 == 0 ? i : -i), 0);
    // (0,0), (-1,0), (2,0), (-3,0), ...
```

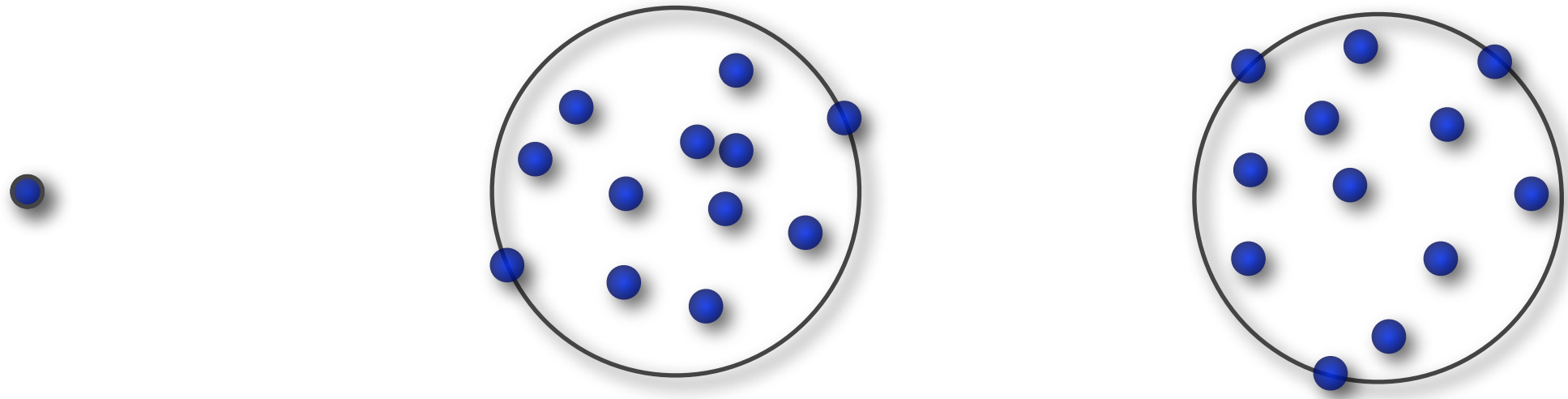
Randomize input order? Generally a good idea, unless input is known to be random, anyway.

```
    Min_circle mc(P, P+n, true);
    Traits::Circle c = mc.circle();
    std::cout << c.center() << " " << c.squared_radius() << std::endl;
}
```

Construct and return the circle.

Output:  
-0.5 0 9702.25

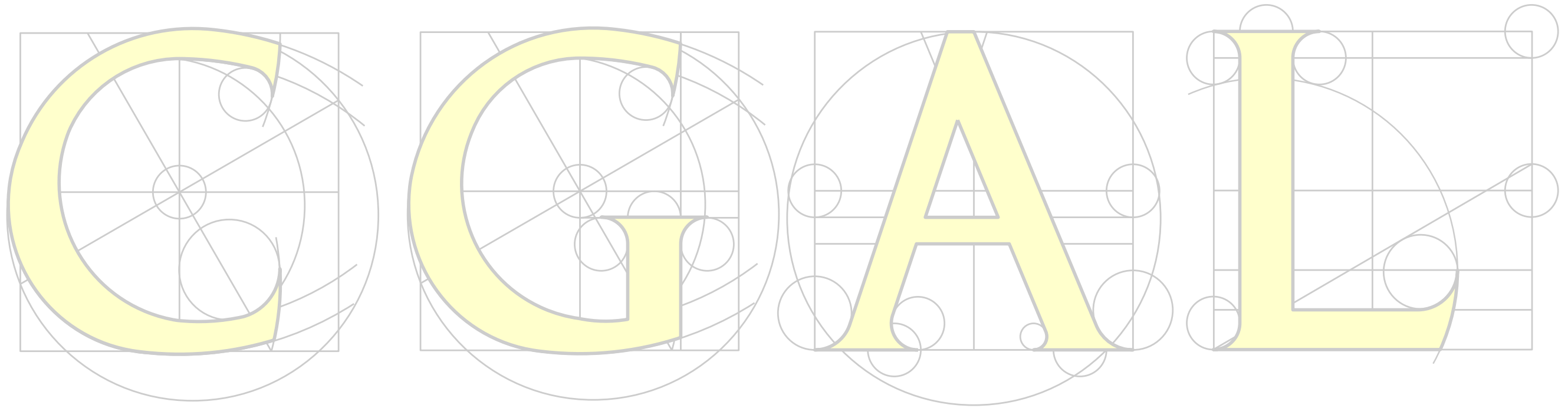
# MINIMUM ENCLOSING CIRCLE



The minimum enclosing circle for a set of  $n \geq 1$  points in  $\mathbb{R}^2$  is determined ... by at most three points on its boundary.

These so-called support points can be obtained using corresponding member functions and iterators of `CGAL::Min_circle_2`.





## PART IV:

### Practical Information

# INTEGER IO

```
#include <CGAL/Exact_predicates_exact_constructions_kernel.h>
#include <iostream>

typedef CGAL::Exact_predicates_exact_constructions_kernel K;
...
// this is nicer ... (and usually ok for the inexact_constructions kernel)
K::Point_2 p;
std::cin >> p;
...
// this is faster ... assuming the input fits in a double
double x, y;
std::cin >> x >> y;
K::Point_2 p(x, y);
...
// this is even faster ... assuming the input fits in an int
int x, y;
std::cin >> x >> y;
K::Point_2 p(x, y);
```

# IO PERFORMANCE

- ▶ If possible, read as an **int**
- ▶ else read as a **long**

32bit on the judge

64bit on the judge

Typical for 64-bit computers,  
but not universally true....

## Sanity check

```
#include <limits>
```

```
if (std::numeric_limits<int>::max() < 33554432.0)  
    throw std::range_error("max(int) < 2^(25)");
```

double literal for  $2^{25}$

# USING

Best start in a new directory, name source file s.t. it ends with `.cpp`.

Run **`cgal_create_cmake_script`** in this directory.

**`cmake .`** ← Note the dot  
(current directory)!

This creates a makefile with rules and targets for every `.cpp` file.  
You can then build your program using **`make`**

You have to re-run `cgal_create_cmake_script` whenever you add a new application/`.cpp` file.

No need to re-run `cmake` because that's done by `make` automatically.

As a default, makefiles are created in release mode. If you want to debug, run `cmake -DCMAKE_BUILD_TYPE=Debug .`

To go back to release mode, run `cmake -DCMAKE_BUILD_TYPE=Release .`

If you want to see the actual compiler and linker calls, run `cmake -DCMAKE_VERBOSE_MAKEFILE=ON .`

If you want to install CGAL on your private computer:

- Check/install prerequisites first: compiler, cmake, boost, gmp, mpfr, (qt)
- Install cgal (on the judge we run CGAL-4.6.2)  
[https://judge.inf.ethz.ch/doc/cgal/doc\\_html/Manual/installation.html](https://judge.inf.ethz.ch/doc/cgal/doc_html/Manual/installation.html)
- Or download CGAL packages of your distribution if they exist (don't forget cgal-devel).

## That's it!

For more, see...

# VIRTUALBOX IMAGE

<http://www.ti.inf.ethz.ch/ew/lehre/Algolab/algolab.ova>

Instructions (in German, sorry):

[http://lec.inf.ethz.ch/ifmp/2015/setup\\_vb.html](http://lec.inf.ethz.ch/ifmp/2015/setup_vb.html)

If you want to use C++11 features, add

```
set(CMAKE_CXX_FLAGS "${CMAKE_CXX_FLAGS} -std=c++11")
```

somewhere in the CMakeLists.txt file.

# HTTP://WWW.CGAL.ORG

