

# **Effects of the Velo drift on the mass distributions**

# General remarks and settings

- The goal is to estimate the size of the impact of VELO movements on the reconstructed mass distributions
- Tested on both **Tx** and **Ry** for the VELO C-side: effect of Ry proved to be negligible
- Tests run over the full set of B0->D\* $\pi$  MC samples from  
`/eos/lhcb/user/l/lohenry/ClusterBias/DigiSamples_clusterFix`
  - The samples include the cluster bias fix
- Alignment degrees of freedom: **Tx** and **Rz**
- Alignables: **LongModules**
- Lagrange constraints:
  - Tx, Rz and Sxz (shear of x vs z) are constrained to 0 across the whole SciFi
  - The average Tx of the modules in the last layer (T3X2) is also constrained to be 0
- Running using the new **Alignment/master** and the new PrKalman filter

# Data selection

Well reconstructed primary vertices with a threshold on the number of reconstructed tracks to reduce combinatorics

```
def VPPPrimaryVertices(input_pvs):
    from PyConf.Algorithms import VertexListRefiner
    selected_pvs = VertexListRefiner(
        name='VertexListRefinerVPPPrimaryVertices',
        MaxChi2PerDoF=5,
        MinNumTracks=15,
        MaxNumTracks=50,
        MinNumLongTracks=0,
        InputLocation=input_pvs).OutputLocation
    return selected_pvs
```

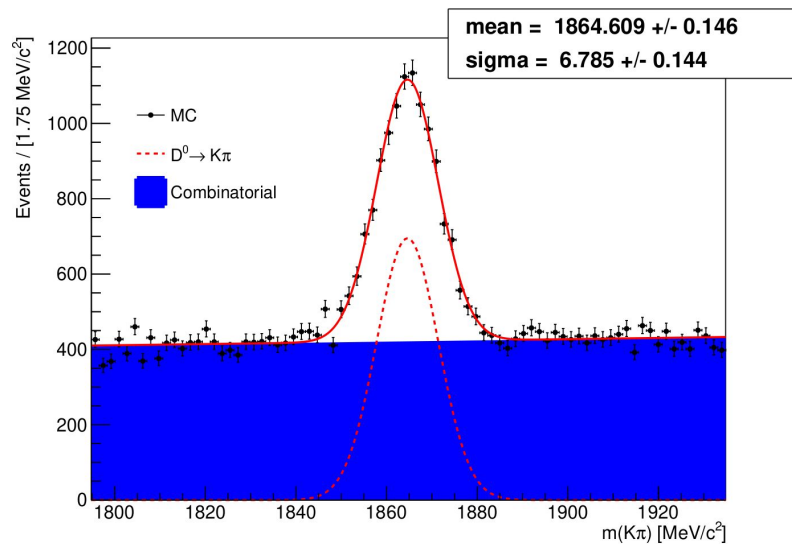
- A further set of cuts looking for  $D0 \rightarrow K\pi$  candidates are applied to the selected tracks and vertices
  - The selection of candidates is aligned with the HLT1 D0 line

Using only well reconstructed long tracks

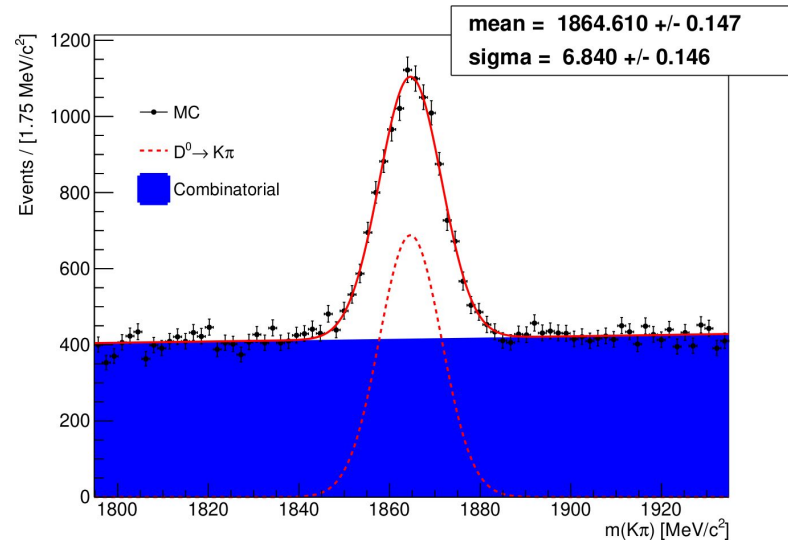
```
def GoodLongTracks(input_tracks):
    myTrackSelector = TrackSelector(
        TrackTypes=["Long"],
        MinPCut=5000,
        MaxPCut=200000,
        MinPtCut=200,
        MaxNTHoles=1,
        MaxChi2Cut=5,
        MaxChi2PerDoFMatch=5,
        MaxChi2PerDoFVelo=5,
        MaxChi2PerDoFDownstream=5)
    selected_tracks = TrackListRefiner(
        name='TrackListRefinerGoodLongTracks',
        inputLocation=input_tracks,
        Selector=myTrackSelector).outputLocation
    return selected_tracks
```

# Sample fit results

**Tx = 0**

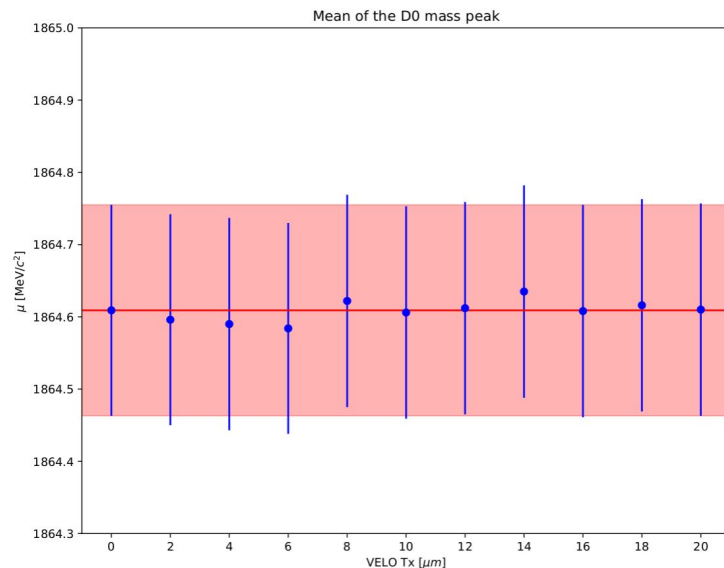


**Tx = 20 μm**

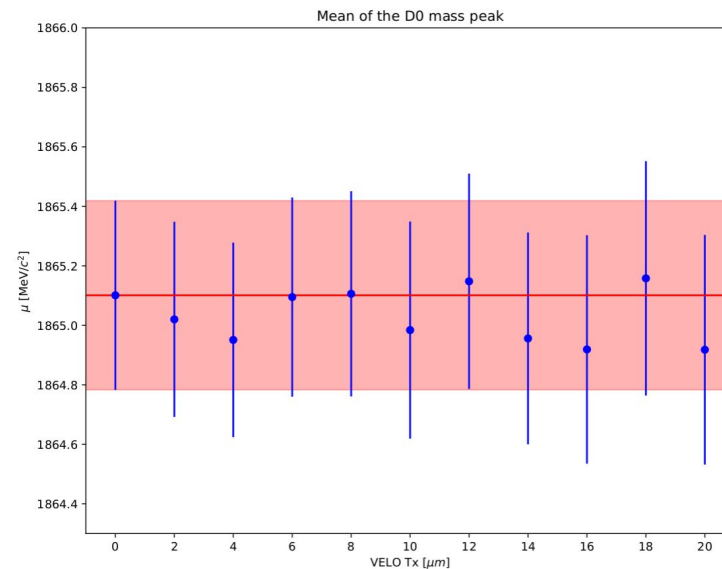


# Evolution of the mean

Tx in [0, 20]  $\mu\text{m}$



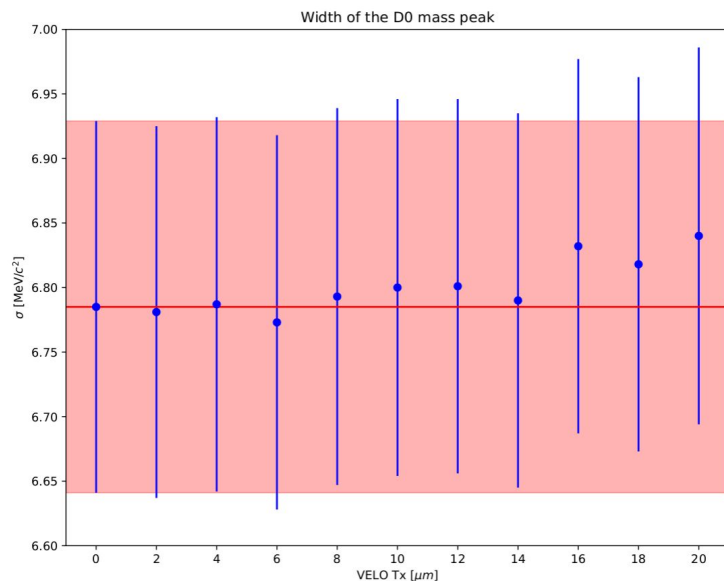
Tx in [0, 200]  $\mu\text{m}$



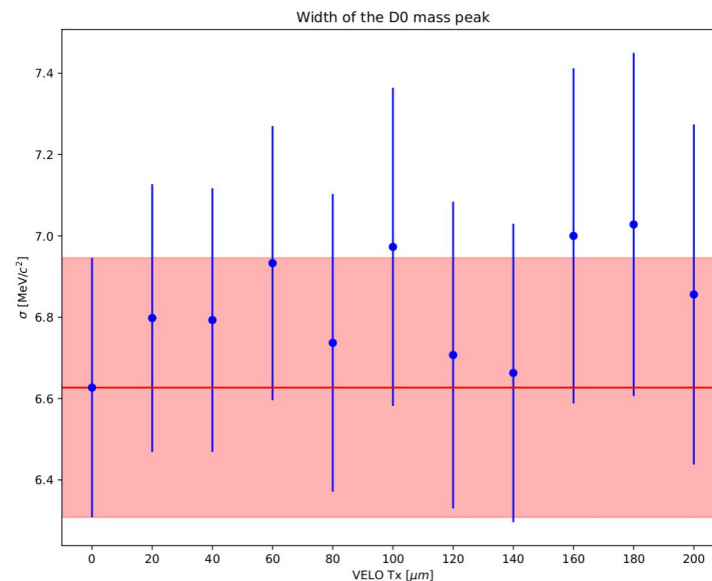
**Note:** Jobs run for the range [0, 200]  $\mu\text{m}$  have less statistics (8k events) to speed up testing

# Evolution of the width

Tx in [0, 20]  $\mu\text{m}$



Tx in [0, 200]  $\mu\text{m}$

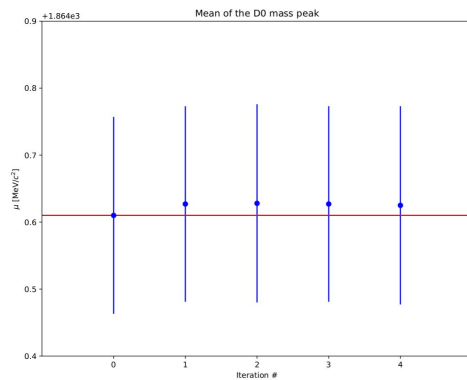


**Note:** Jobs run for the range [0, 200]  $\mu\text{m}$  have less statistics (8k events) to speed up testing

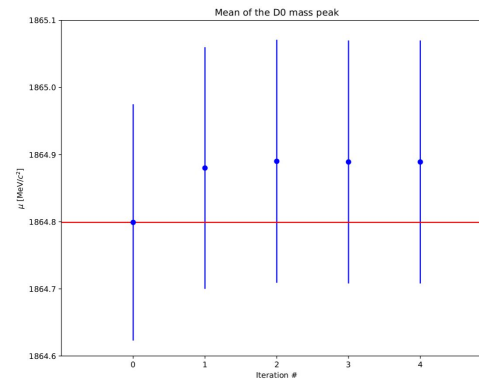
# Effect of the alignment algorithm

Mean

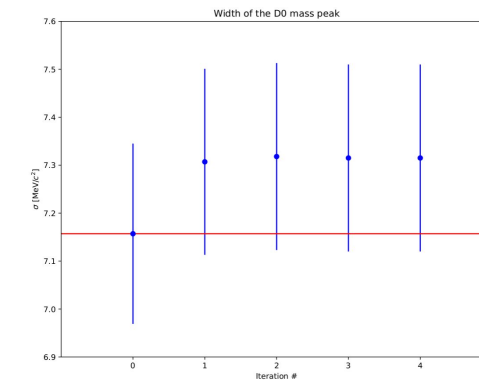
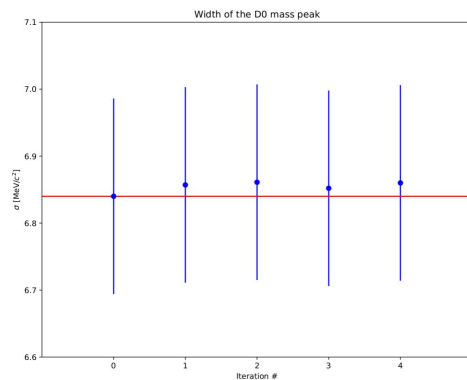
$T_x = 20 \mu\text{m}$



$T_x = 20 \mu\text{m}$

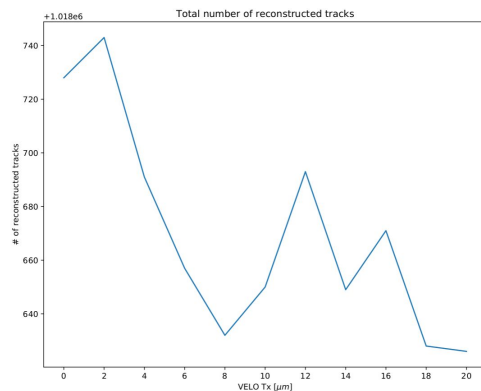


Width

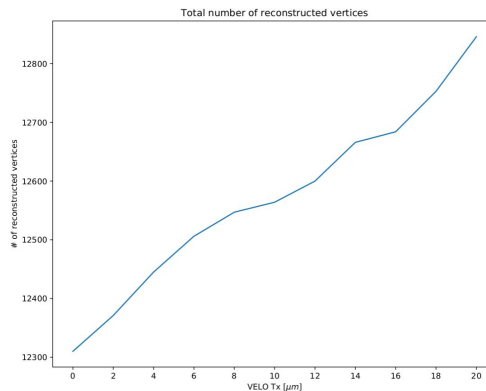


# Further checks

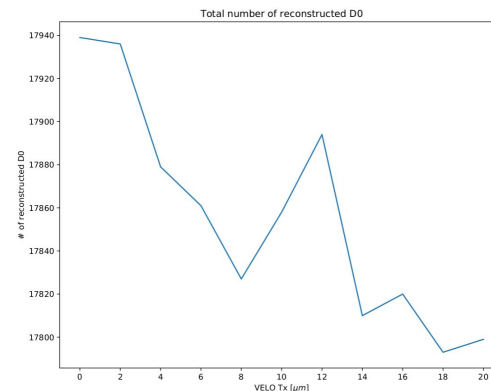
## # of tracks



## # of PVs



## # of D0 candidates



Larger number of PVs due to the appearance of **clone vertices** in the two VP halves when one of the halves is displaced



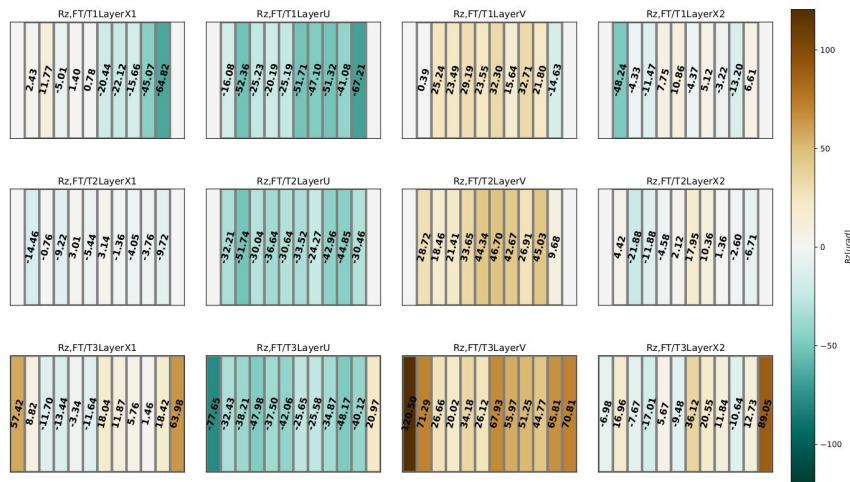
## **Test of alignment quality**

# Alignment settings

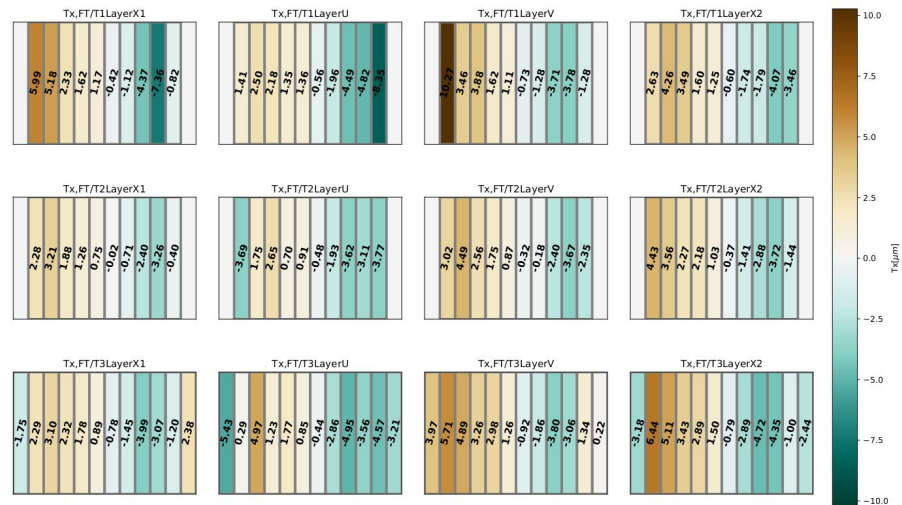
- Initially we wanted to check the impact of the UT on the general alignment algorithm with the new PrKalman filter
- Running over the full set of MC events from `/eos/lhcb/user/l/lohenry/ClusterBias/MinBias/ZehuaFix`
  - The sample includes the fix to remove the cluster bias
- Tests are run assuming a fully aligned detector and employing a D0 mass constrain
- Degrees of freedom: **Tx** and **Rz**
- Alignables: **LongModules**
- Lagrange constraints:
  - Tx, Rz and Sxz (shear of x vs z) are constrained to 0 across the whole SciFi
  - The average Tx of the modules in the last layer (T3X2) is also constrained to be 0

# Tests with UT

Rz

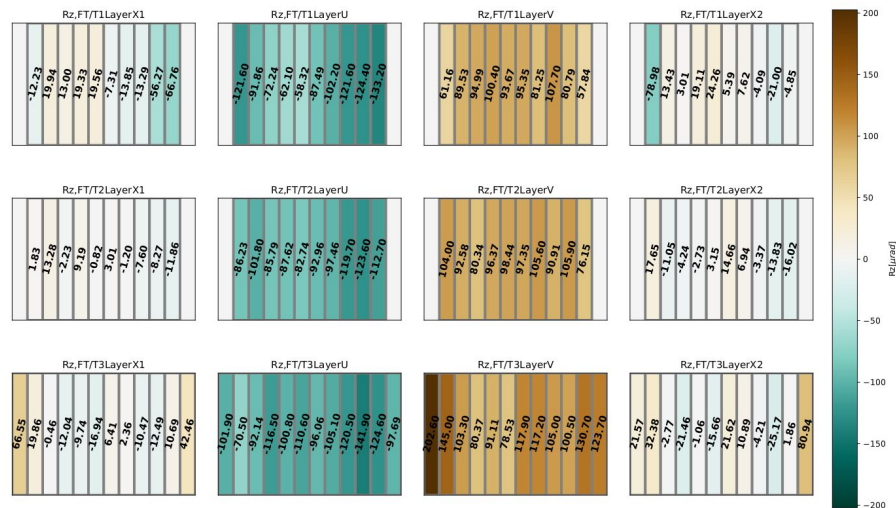


Tx

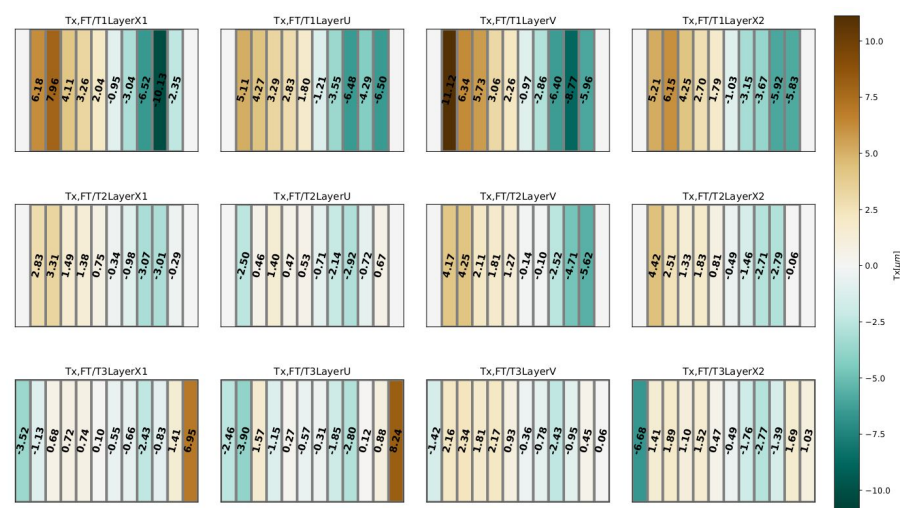


# Tests without UT

Rz



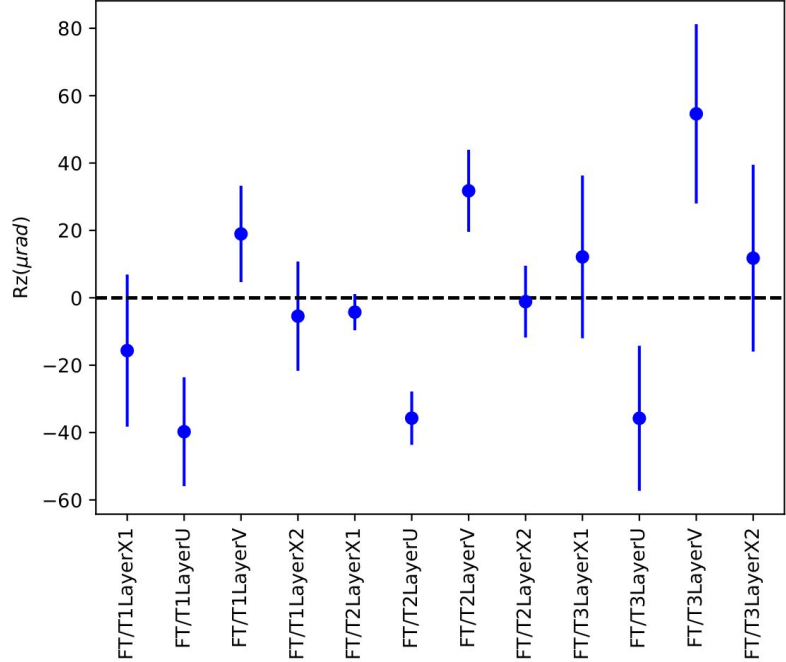
Tx



# Rz across SciFi layers

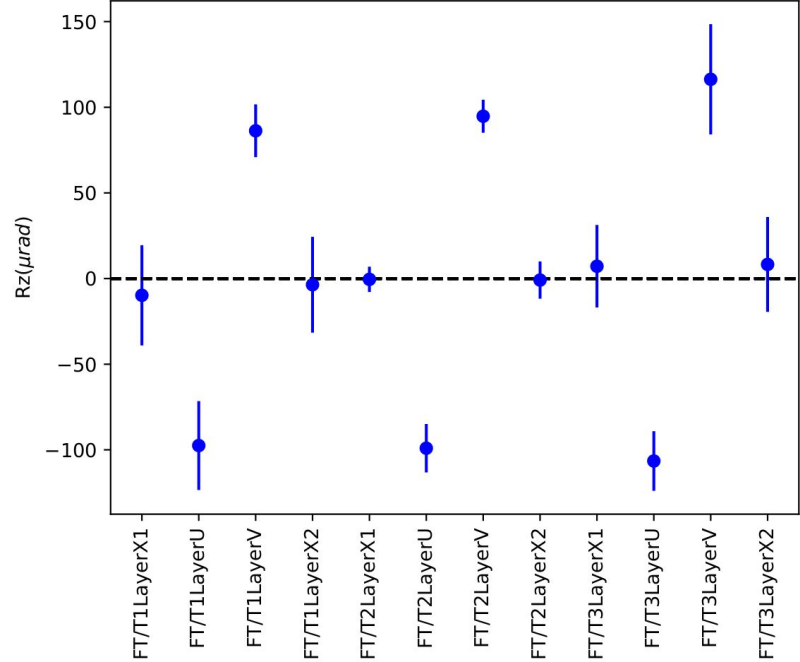
## With UT

Modules grouped per layer



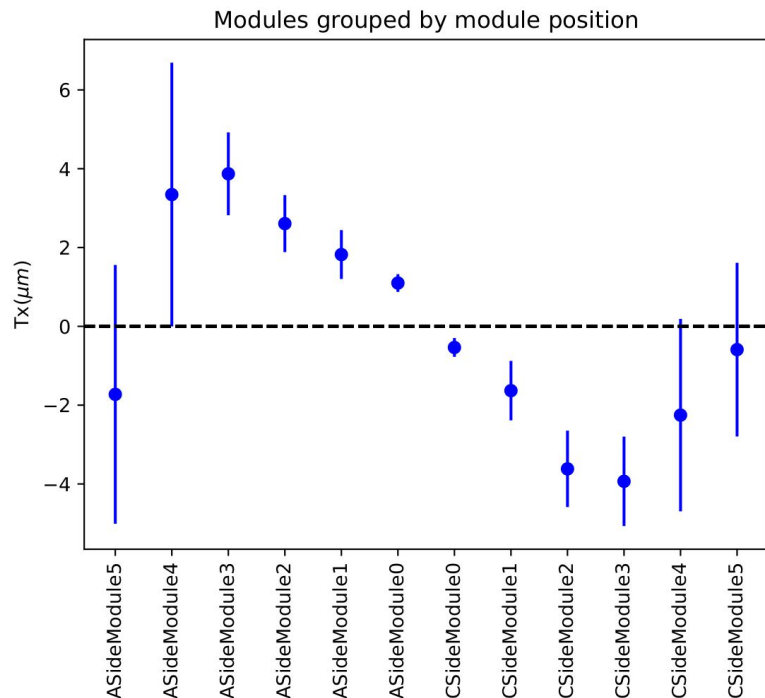
## Without UT

Modules grouped per layer

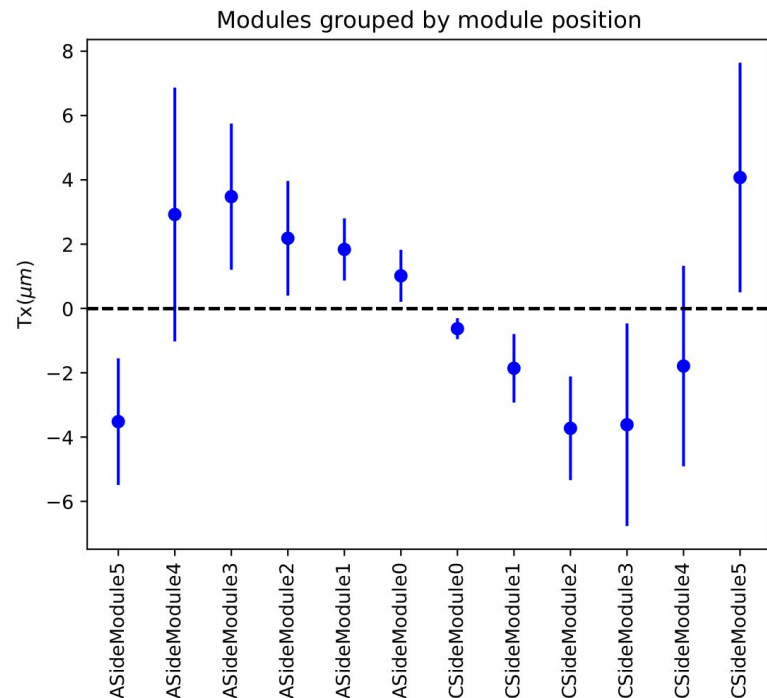


# Tx across SciFi module positions

## With UT



## Without UT



# On going work

- Null tests so far are run using the DetDesc detector geometry. I'm currently re-running them using DD4Hep to check for the presence of bugs
- I am looking into possible biases present in the reconstruction sequence that could explain these results