

# Topology Presentation Notes

Nilay Tripathi

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## 1 Metric Space Preliminaries

- Sequences and Cauchy sequences

- A sequence converges to a point  $x_0 \in X$  if

$$\forall \varepsilon > 0, \exists N_\varepsilon \in \mathbb{N} : n \geq N_\varepsilon \implies d(x_n, x) < \varepsilon$$

- A sequence is Cauchy if

$$\forall \varepsilon > 0, \exists N_\varepsilon \in \mathbb{N} : m, n \geq N_\varepsilon \implies d(x_n, x_m) < \varepsilon$$

- Every convergent sequence is Cauchy. PROOF: use triangle inequality with  $\varepsilon/2$  argument.

- Complete metric space: every Cauchy sequence in  $X$  converges to a limit in  $X$ .

- The metric space  $\mathbb{Q}$  is not complete. PROOF: consider the sequence of rational approximations to any irrational number.
- Discrete spaces are complete. PROOF: every Cauchy sequence is eventually constant.
- Briefly comment about equivalent formulas of completeness in  $\mathbb{R}$  (i.e. least upper bound property, montone convergence property, etc.). Cauchy completeness is the most general definition and works in all metric spaces.

### 1.1 Function Space

We define the **function space**,  $C[a, b]$ , to be all continuous functions from  $[a, b]$  to  $\mathbb{R}$ . That is

$$C[a, b] = \{f : [a, b] \rightarrow \mathbb{R} \mid f \text{ is continuous}\}$$

We define a metric on the function space as follows: for  $f, g \in C[a, b]$

$$d(f, g) = \max_{t \in [a, b]} |f(t) - g(t)|$$

- The metric is well defined (i.e. is finite). PROOF:  $f - g$  is continuous and  $[a, b]$  is compact. EVT implies existence of a maximum (and minimum)

## 2 Vector Space Preliminaries

- A vector space  $V$  over a field  $\mathbb{F}$  has two operations: vector addition and scalar multiplication where
  - Vector addition is an abelian group
  - Scalar multiplication satisfies:  $1v = v$ ,  $a(bv) = (ab)v$ , and two distributive laws: scalar multiplication distributes over vector addition and field addition.

- Linearly independent sets: a (finite) set  $V$  is linearly independent if for scalars  $c_i$  and vectors  $v_i$

$$c_1v_1 + c_2v_2 + \cdots + c_nv_n = 0 \implies c_1 = c_2 = \cdots = c_n = 0$$

Infinite sets are linearly independent if all of its finite subsets are L.I.

- If  $V$  is a V.S. over  $\mathbb{F}$  and  $S \subseteq V$  is finite, then  $\text{span } S$  is defined as

$$\text{span } S = \{c_1v_1 + \cdots + c_nv_n : c_i \in \mathbb{F}, v_i \in S\}$$

The span of an infinite set is the union of the span of all its finite subsets.

- If  $E \subseteq X$  is a subspace, then a set  $S$  is a spanning set if  $\text{span } S = E$ .
- A basis is a linearly independent generating set.
  - It is the smallest generating set and the largest L.I. set (in a f.d. V.S.)
  - Every vector has a unique representation in a basis
  - The dimension of a V.S. is the size of its basis (either finite or infinite)
  - Every V.S. has a basis. For f.d. spaces, all bases have the same size

## 2.1 Function Spaces

We turn the function space  $C[a, b]$  into a vector space over  $\mathbb{R}$ . For  $f, g \in C[a, b]$  and  $\alpha \in \mathbb{R}$ , define

$$\begin{aligned}(f + g)(t) &= f(t) + g(t) \\ (\alpha f)(t) &= \alpha f(t)\end{aligned}$$

The additive identity is the zero function. It is also an infinite dimensional V.S.

## 2.2 Linear Maps

Linear maps preserve linear combos. So  $T : X \rightarrow Y$  is linear if

$$T(c_1v_1 + c_2v_2 + \cdots + c_nv_n) = c_1Tv_1 + c_2Tv_2 + \cdots + c_nTv_n$$

Notably, linear maps send the identity of  $X$  to the identity of  $Y$  (i.e.  $T0 = 0$ )

- The differentiation operator on  $C[a, b]$ ,  $Df = f'$ , is linear. PROOF: derivative rules from calculus.

## 3 Normed Spaces

- A norm on a V.S.  $V$  generalizes the length of a vector. It satisfies these axioms
  1.  $\|x\| \geq 0$  with  $\|x\| = 0 \iff x = 0$
  2.  $\|\alpha x\| = |\alpha|\|x\|$  (norm only depends on direction)
  3.  $\|x + y\| \leq \|x\| + \|y\|$  (satisfies triangle inequality)

We use the word “norm” to mean both the value  $\|x\|$  and the function  $x \mapsto \|x\|$ .

- Normed space  $\implies$  metric space
  - Define the metric as  $d(x, y) = \|x - y\|$

### 3.1 Examples

- The  $L^p$ -norms on  $\mathbb{R}^n$  are defined by

$$\|x\|_p = \left[ \sum_{i=1}^n |x_i|^p \right]^{1/p}$$

- The  $L^p$ -norm induces the  $L^p$ -metric on  $\mathbb{R}^n$ .
- If  $p = 2$ , this is the usual notion of length/distance on  $\mathbb{R}^2$ .
- Consider the function space  $C[a, b]$ . Define a norm on this space as

$$\|f\| = \max_{t \in [a, b]} |f(t)|$$

- Metric space  $\not\Rightarrow$  normed space: the discrete metric on  $\mathbb{R}$  is not induced by any norm.

### 3.2 Banach Spaces

A **Banach space** is any normed space where the norm induces a complete metric space.

- $\mathbb{R}^n$  is a Banach space (when we consider its usual Euclidean norm)
- The function space  $C[a, b]$  is a Banach space, under its usual metric.
- Not all normed spaces are Banach spaces.
  - Define a different norm on  $C[a, b]$  as:

$$\|f\| = \int_0^1 |f(t)| dt$$

The metric induced by the norm is

$$d(f, g) = \int_0^1 |f(t) - g(t)| dt$$

Under this metric  $C[a, b]$  is not a complete space.

## 4 Inner Product Spaces

An **inner product** satisfies the following axioms

1.  $\langle x + y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$
2.  $\langle \alpha x, y \rangle = \alpha \langle x, y \rangle$
3.  $\langle x, y \rangle = \overline{\langle y, x \rangle}$
4.  $\langle x, x \rangle \geq 0$  with  $\langle x, x \rangle = 0 \iff x = 0$

If the V.S. is over  $\mathbb{R}$ , axiom 3 becomes  $\langle x, y \rangle = \langle y, x \rangle$ .

- We have inner product space  $\implies$  normed space. A norm may be defined as

$$\|x\| = \sqrt{\langle x, x \rangle}$$

- However, the reverse implication is NOT true. EXAMPLE:  $L^p$ -norms when  $p \neq 2$ .

## 4.1 Examples

- The standard inner product on  $\mathbb{R}^n$  is

$$\langle x, y \rangle = \sum_{i=1}^n x_i y_i$$

It is better known as the dot product. It induces the Euclidean norm on  $\mathbb{R}^n$ .

- If  $X = \mathbb{C}^n$  instead, then the standard inner product becomes

$$\langle x, y \rangle = \sum_{i=1}^n x_i \overline{y_i}$$

## 4.2 Hilbert Space

A **Hilbert space** is an I.P.S. where the norm induced by the inner product induces a complete metric space.

- Hilbert space  $\implies$  Banach space
- Converse not true. EXAMPLE: the max norm on  $C[a, b]$  is not given by any inner product, so it cannot be a Hilbert space
- $\mathbb{R}^n$ , with the Euclidean norm/standard inner product is a Hilbert space.

## 5 Topological Vector Spaces

We now combine the notions of vector spaces and topological spaces. A **topological vector space** is a vector space with a topology such that

1. All one point sets are closed
2. The vector space operations  $+$  and  $\cdot$  are continuous

### 5.1 Continuous & Bounded Linear Map

- We say a linear map  $T : X \rightarrow Y$  is continuous at  $x_0 \in X$  if for every  $\varepsilon > 0$ , there is a  $\delta > 0$  such that

$$\|x - x_0\| < \delta \implies \|Tx - Tx_0\| < \varepsilon$$

If  $T$  is continuous at all points in  $X$ , then  $T$  is continuous.

- We say a linear map  $T : X \rightarrow Y$  is bounded if there exists  $M \in \mathbb{R}$  such that

$$\|Tx\| \leq M\|x\|$$

- We define the norm of an operator as follows

$$\|T\| = \sup_{\substack{x \in X \\ x \neq 0}} \frac{\|Tx\|}{\|x\|} = \sup_{\substack{x \in X \\ \|x\|=1}} \|Tx\|$$

This gives us that for any bounded operator:  $\|Tx\| \leq \|T\|\|x\|$ .

- The zero operator has norm 0. PROOF:

$$\frac{\|Tx\|}{\|x\|} = \frac{\|0\|}{\|x\|} = 0$$

- The identity operator has norm 1. PROOF:

$$\frac{\|Tx\|}{\|x\|} = \frac{\|x\|}{\|x\|} = 1$$

- The differentiation operator  $D(f) = f'$  is unbounded. PROOF: consider polynomials on  $[0, 1]$ . If  $x_n(t) = t^n$ , then

$$\|Tx_n\| = \|nt^{n-1}\| = n$$

## 5.2 Continuous $\iff$ Bounded

We prove the following result.

**Theorem 1.** *A linear operator  $T : X \rightarrow Y$ , between normed spaces is continuous iff it is bounded.*

*Proof.* Assume  $T$  is bounded. Then, we have  $\|T\| < \infty$ . Let  $\varepsilon > 0$  and  $x_0 \in X$  be arbitrary. Let

$$\delta = \frac{\varepsilon}{\|T\|}$$

and assume  $\|x - x_0\| < \delta$ . Then, we have

$$\begin{aligned}\|Tx - Tx_0\| &= \|T(x - x_0)\| \\ &\leq \|T\| \|x - x_0\| \\ &< \|T\| \cdot \frac{\varepsilon}{\|T\|} \\ &= \varepsilon\end{aligned}$$

Hence,  $T$  is continuous as it is continuous at all points.

Conversely, assume  $T$  is continuous. Then,  $T$  is continuous at  $x = 0$ . So, there is a  $\delta > 0$  such that

$$\|x\| < \delta \implies \|Tx\| < 1$$

Rewrite  $x$  as

$$x = \frac{2x\delta}{\|x\|} \cdot \frac{\|x\|}{2\delta}$$

So

$$\begin{aligned}Tx &= T\left(\frac{2x\delta}{\|x\|} \cdot \frac{\|x\|}{2\delta}\right) \\ &= \frac{2\|x\|}{\delta} T\left(\frac{x}{\|x\|} \cdot \frac{\delta}{2}\right)\end{aligned}$$

Put  $v = \frac{x}{\|x\|} \cdot \frac{\delta}{2}$  and note that

$$\|v\| = \frac{\delta}{2} \left\| \frac{x}{\|x\|} \right\| = \frac{\delta}{2} < \delta$$

So  $\|Tv\| < 1$ . Hence, we see that

$$\|Tx\| < \frac{2}{\delta} \|x\|$$

which shows that  $T$  is bounded. □

## 6 Closed Graph Theorem

### 6.1 Open Mapping Theorem

We state the open mapping theorem, and its corollary, the bounded inverse theorem.

- An open mapping sends open sets in the domain to open sets in the range i.e. the image of open sets is open
- Open Mapping Thrm: every surjective bounded linear operator between Banach spaces is an open mapping
  - IDEA OF PROOF: similar to the “neighborhood trick”: show that for an open set  $U$ , any point in  $T(U)$  contains an open set contained in  $T(U)$ .

- However, the details are complicated since we are in an arbitrary space
- Bounded Inverse Thrm: if  $T$  is a bijective, continuous linear operator, then  $T^{-1}$  is bounded.
  - IDEA OF PROOF: show  $T^{-1}$  is continuous. Indeed,  $T : X \rightarrow Y$  maps open sets to open sets. But this is roughly the same as the preimage of open sets in  $X$  being open under  $T^{-1}$ . Thus,  $T^{-1}$  is continuous and, therefore, bounded.

## 6.2 Norm On Product Space

If  $X, Y$  are Banach spaces, we define a norm on  $X \times Y$  as follows

$$\|(x, y)\| = \|x\| + \|y\|$$

We remark: there are other norms on the product space (e.g. the “max” norm), but the closed graph theorem will go through for all of them. I think this is the easiest one.

**Theorem 2.** *If  $X, Y$  are Banach spaces, then so is  $X \times Y$ .*

*Proof Sketch.* Let  $(z_n)$  be an arbitrary Cauchy sequence. W.T.S.  $(z_n)$  converges

- From definition of the product norm, we have  $(x_n)$  and  $(y_n)$  are Cauchy
- The two Cauchy sequences converge. Then,  $(z_n)$  converges to the ordered pair (limit of  $x_n$ , limit of  $y_n$ )
- To show this, use a  $\varepsilon/2$  argument.

□

## 6.3 Proof of Closed Graph Theorem

A linear operator  $T : X \rightarrow Y$  if the graph of  $T$

$$G_T = \{(x, Tx) : x \in X\}$$

is a closed set in  $X \times Y$ .

**Theorem 3** (Closed Graph Thrm). *Suppose  $T : D \rightarrow Y$  is a closed linear operator. Then,  $T$  is bounded if  $D$  is closed.*

*Proof Idea.* • Define a linear map  $P : G_T \rightarrow D$  as

$$P(x, Tx) = x$$

- $P$  is linear since

$$P(x + cy, T(x + cy)) = P(x + cy, Tx + cTy) = P[(x, Tx) + c(y, Ty)]$$

- $P$  is bounded since

$$\|P(x, Tx)\| = \|x\| \leq \|x\| + \|Tx\| = \|(x, Tx)\|$$

- $P$  is bijective.
- $G_T$  is a closed subset of  $X \times Y$ , a complete space  $\implies G_T$  is closed.
- Same argument shows  $D$  is a complete space.
- Invoke the bounded inverse theorem to get that  $P^{-1}$  is bounded.

- The proof is finished by noting that

$$\begin{aligned}\|Tx\| &\leq \|x\| + \|Tx\| \\ &= \|(x, Tx)\| \\ &= \|P^{-1}(x)\| \\ &\leq M\|x\|\end{aligned}$$

So  $T$  is bounded, as desired.

□