

KDOM Project

PART B:Q1

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Given information:

Write a computer program (in Matlab/Octave or Geogebra) which accepts the following inputs:

- (a) Pitch circle of the gear
- (b) Pressure angle of the teeth
- (c) Number of gear teeth

Using **AGMA**(American Gears Manufacturer's Association) standards and the data input above, generate the complete geometry of the gear (in the form of a figure showing all the teeth).

For Bonus Credit: Correct the Mechanica logo (for the gear tooth profile).

Equation of Involute:

$$r=R\sqrt{1+\theta^2}$$

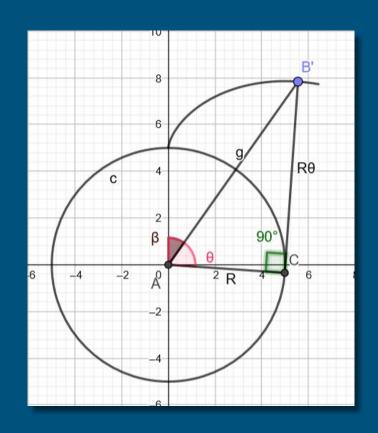
$$y=R\sqrt{1+\theta^2}cos(\beta)$$

$$x=R\sqrt{1+\theta^2}sin(\beta)$$
 where ,

$$\beta = \theta - tan^{-1}(\theta)$$

Geogebra Link for the involute profile:

https://www.geogebra.org/classic/yuggbq6v



When Radius of dedendum circle is greater than Radius of base circle:

 Calculate the angular distances where the distance of a point on the involute from the center becomes:

$$\circ$$
 Rd = α

$$\circ$$
 Rp = β

$$\circ$$
 Ra = γ

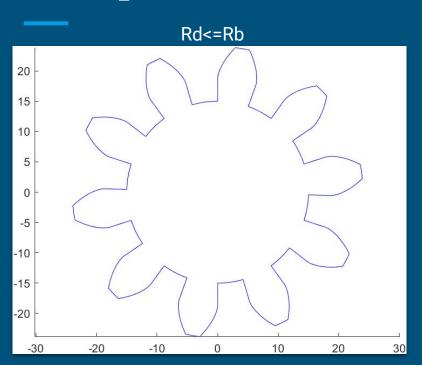
Between alpha and beta, draw a circular arc of radius Rd, then between beta and gamma, draw part of involute curve that begins from Rb at an angular distance of 0

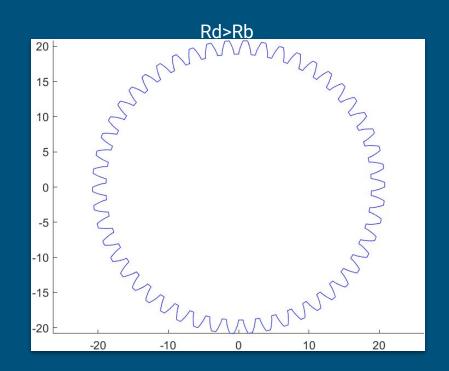
- The return path of the tooth should have an involute of circle with radius Rb with a different starting point
- This starting point will be at an angular distance ct (angle subtended by the circular thickness) + 2 x beta
- Using this information, we can repeat the same process for the return part also.

When Radius of dedendum circle is lesser than Radius of base circle:

- In this case, we need to draw an involute of base circle from angular distance of 0 to gamma.
- In addition to this we have to radially extend the starting point of the involute to the base circle.

Gear profile:





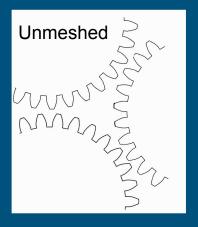
Matlab code link:

https://drive.google.com/file/d/1g64d 541lgo uMtvQGWh1mD4Bp2OgO60/view?usp=sharing

Correcting the Mechanica logo:







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(using gear generated by Matlab code, 30 teeth)