

# DRL project update

Cartesian/polar duplicated coordinates  
experiment

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Andrea Pierré

January 21, 2025

# Outline

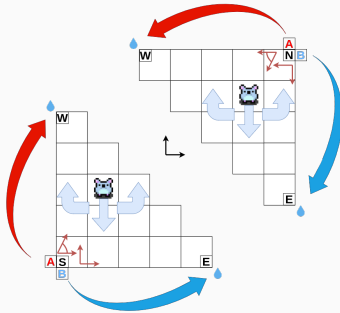
1. Current status
2. How to get insights at what the network learn?

# Outline

1. Current status

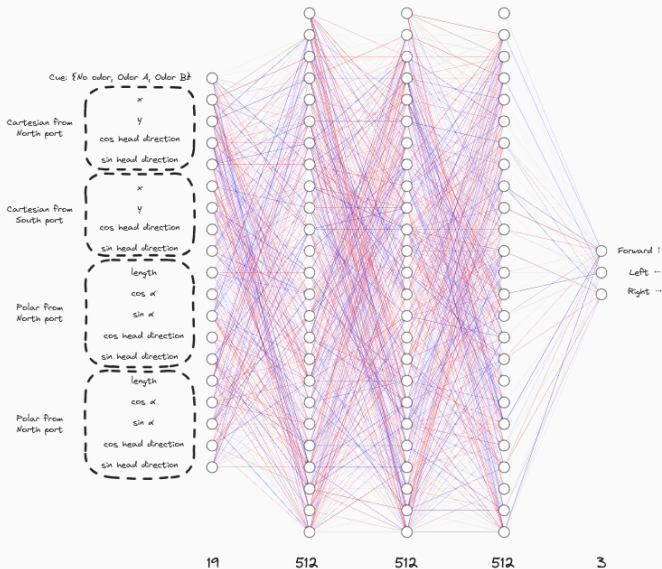
2. How to get insights at what the network learn?

# Current status



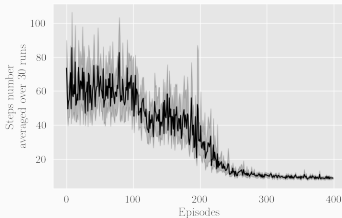
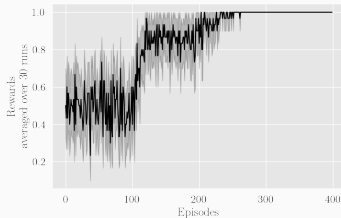
- Environment rewrite: done
- Training: ~4.5 hours to train 30 agents on both tasks on Oscar
- Analysis: WIP

# State space & network architecture

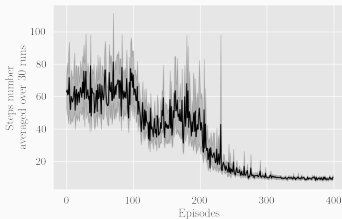
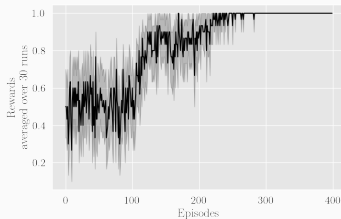


# Training

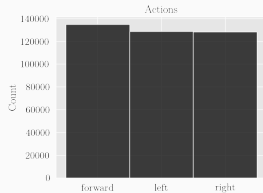
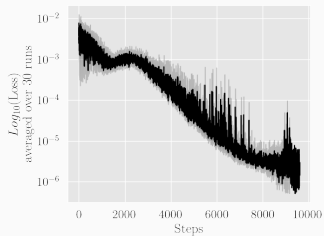
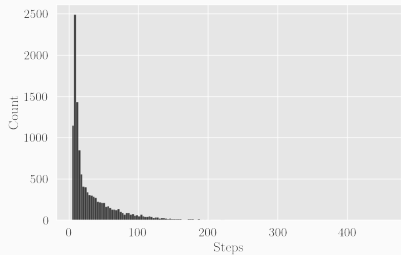
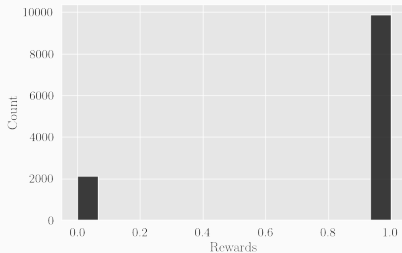
## East/West



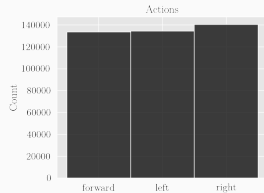
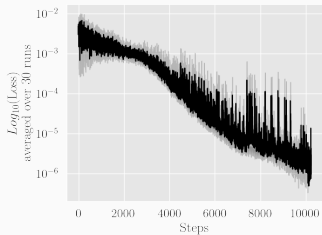
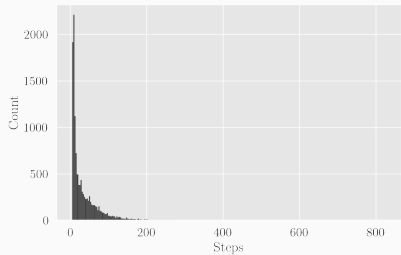
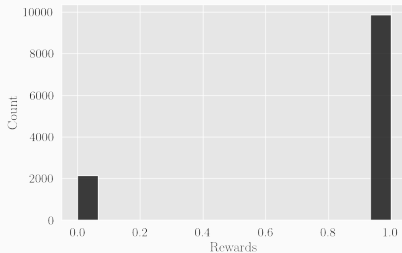
## Left/Right



# Training checks - East/West

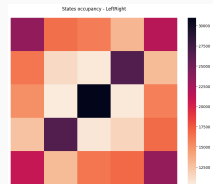
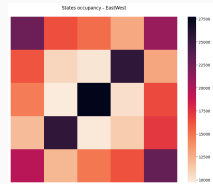
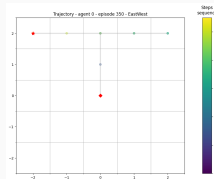
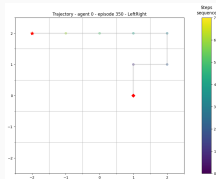
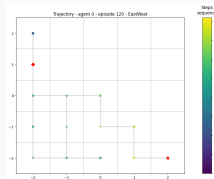
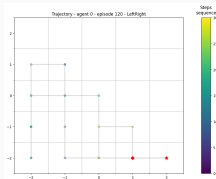
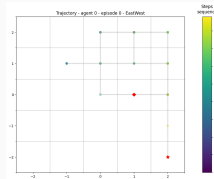
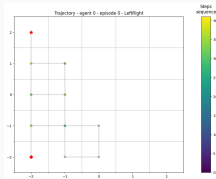


# Training checks - Left/Right





# Agent behavior

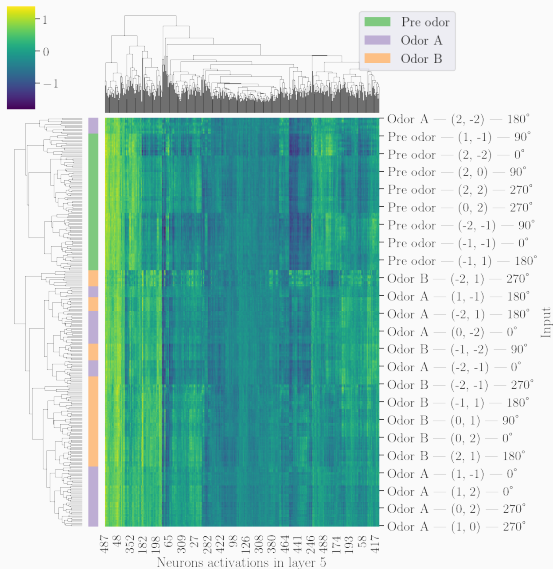


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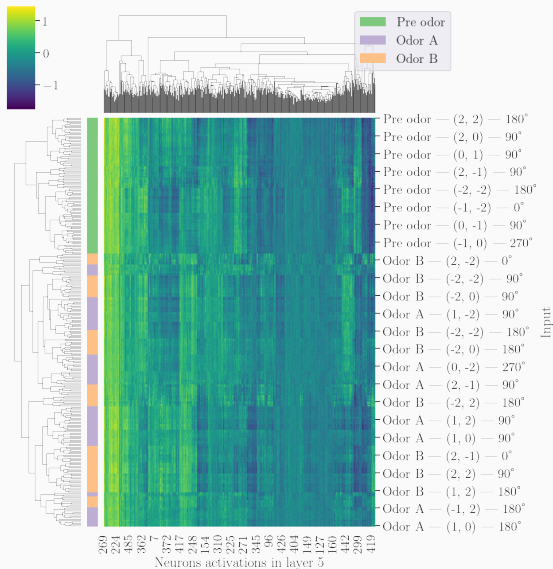
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# Activations learned - East/West



# Activations learned - Left/Right



# Use the behavior as proxy

- Silence the Cartesian/polar part of the input on a trained agent and look at how the agent behaves (x4 experiments)
- Expectation:
  - Left/right task
  - East/west task
- Any other approach we could use?

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  - Left/right task:
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    - With the polar inputs silenced → the agent struggle to solve the task
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# Neural representations?

## 2. How the constraints of the task impact the representations learned?

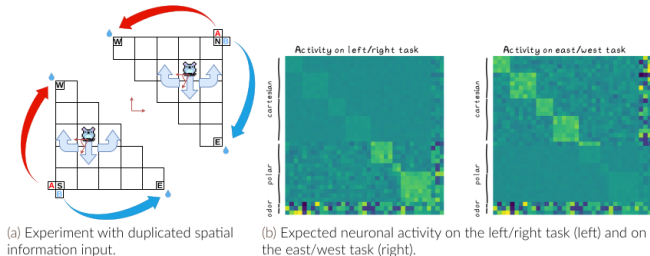


Figure 8. What does the network learn if it gets both Cartesian and polar information as input?  
On the left/right task → we expect the activity to be close to zero on the Cartesian representation.  
On the east/west task → we expect the activity to be close to zero on the polar representation.

- Need for some causal framework?