

Research plan

Fleischmann – Nassar joint meeting

Andrea Pierré

May 17, 2024

Brown University

Outline

1. Conceptual directions & questions ?

2. Experiments & expected results 🌽 📐

3. Roadmap 🕰

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3. Roadmap 🕰

What do we want to know?

- Understand what the network learns → What function does it learns?
- How the constrains of the task affect learning & the representations learned?
- Does the network learn something related to the real neurons? (million \$\$\$ question)

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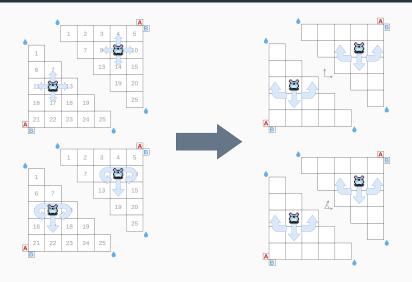
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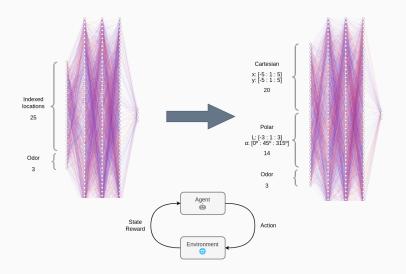
Compositional hypothesis

- From indexed locations (current) to coordinate system → does the network learn a generalizable policy?
- Merged actions space

Compositional hypothesis



Implementation



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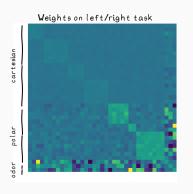
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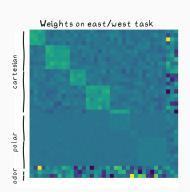
- Feed both coordinates information (Cartesian & polar) to the input layer (+ merge actions spaces in a common one)
- Train on left/right task → we expect the weights are close to zero on Cartesian representation?
- Train on east/west task → we expect the weights are close to zero on polar representation?
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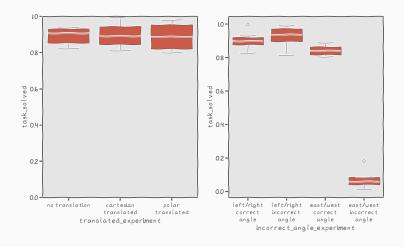


- After training, move the population of agents in a translated coordinate system → we expect the population of agents to be able to solve the task with zero shot learning
- 2. Train with both coordinates information (Cartesian 8 polar), after training feed incorrect polar angles
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3) Conjunctive odor-place coding

- Train a population of agents, then after training, flip odor A and odor B in the task
- In general we expect to find a population of conjunctive neurons that get active with the combination of both odor and specific location
- Do the conjunctive cells get conserved or remapped?
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 - 1.1 Code logic for new environment [~1 week]
 - 1.2 Check everything works as expected (unit testing)[~1 week]
 - 1.3 Bugs? [~1 week]
- 2. Baseline training on new environment (convergence hyperparameter tweaking, etc.)
- 3. Experiments
 - 3.1 Task code 1000 [~1 week]

 - 3.3 Analysis code ★★★ [~2 week]

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