



# Joint RL meeting

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Brown University

# Outline

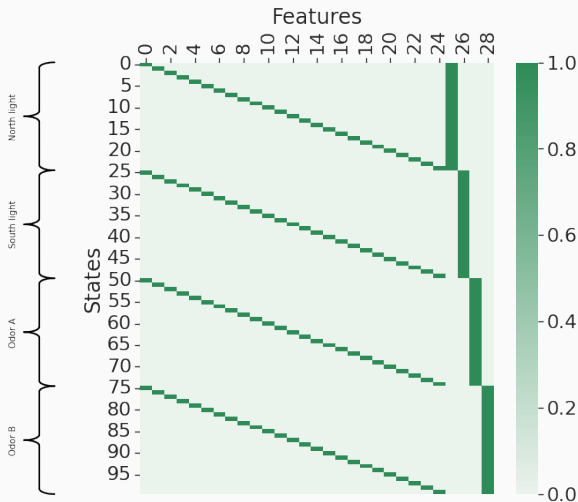
1. Reducing the number of features in function approximation
2. Deep RL – first draft & issues

# Outline

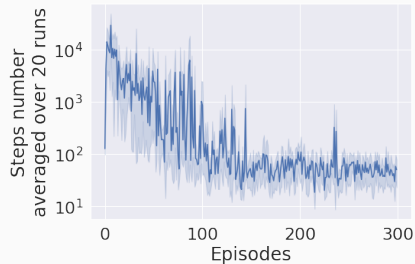
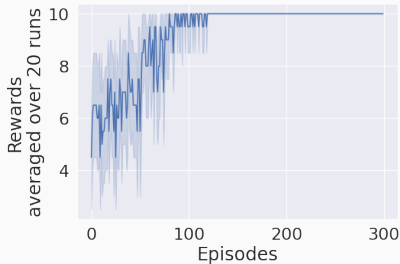
1. Reducing the number of features in function approximation
2. Deep RL – first draft & issues

# Features matrix – allocentric agent

→ Reduced from 100 to 25 locations + 4 cues

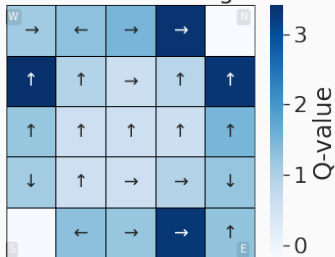


# Rewards and steps – allocentric agent

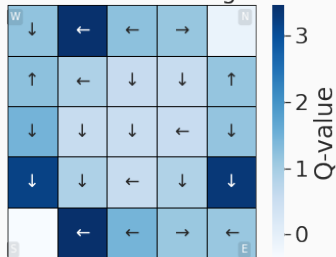


# Q-values learned – allocentric agent

Pre odor - North light



Pre odor - South light



Post odor - Odor A

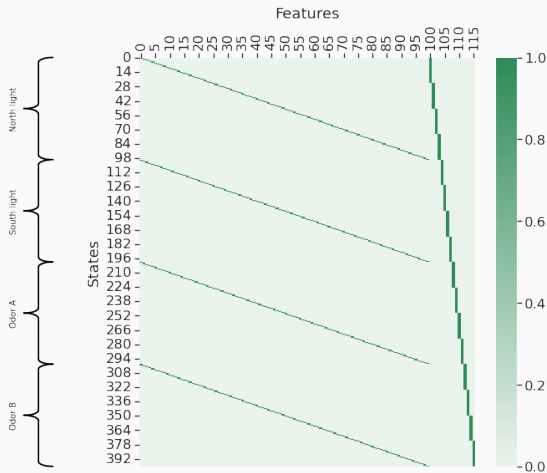


Post odor - Odor B

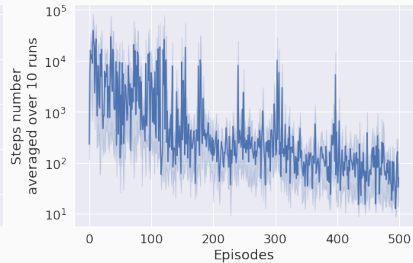
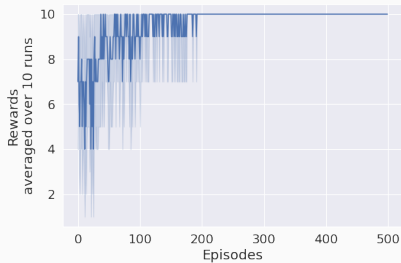


# Features matrix – egocentric agent

→ Reduced from 400 to 100 locations (25 locations x 4 head directions) + 16 cues (4 cues x 4 head directions)

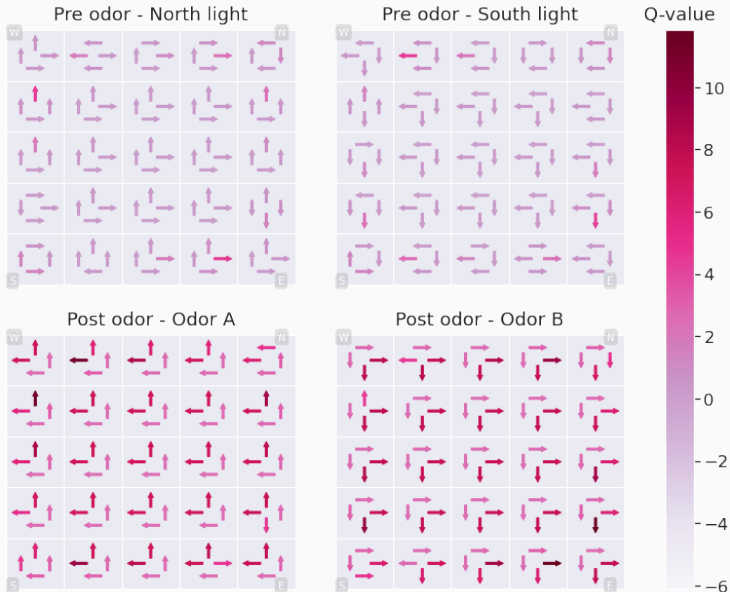


# Rewards and steps – egocentric agent





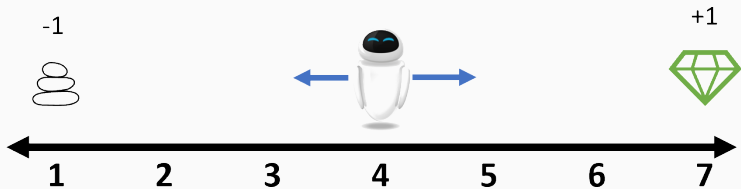
# Q-values learned – egocentric agent



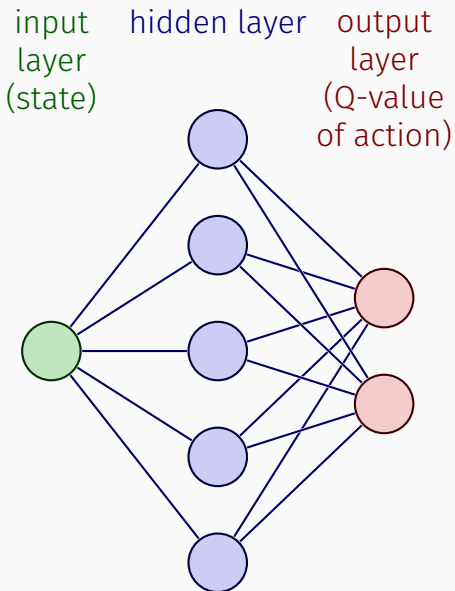
# Outline

1. Reducing the number of features in function approximation
2. Deep RL – first draft & issues

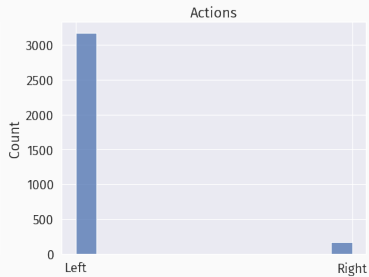
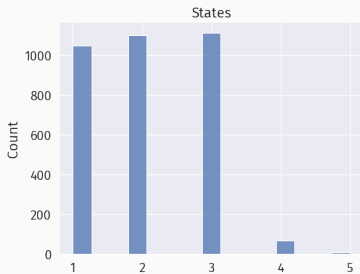
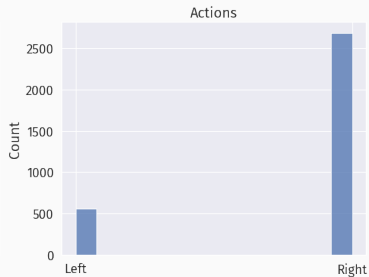
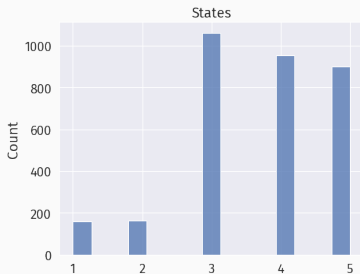
# Toy task : Random Walk 1D



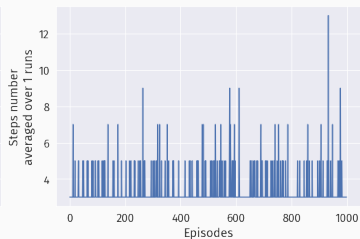
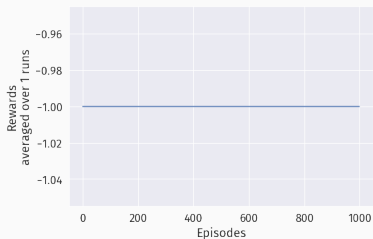
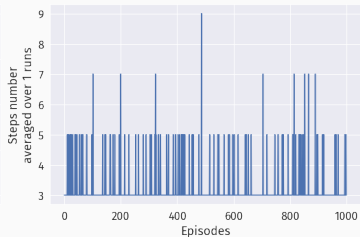
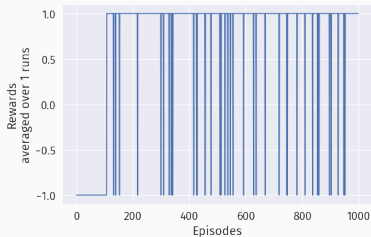
# Network used



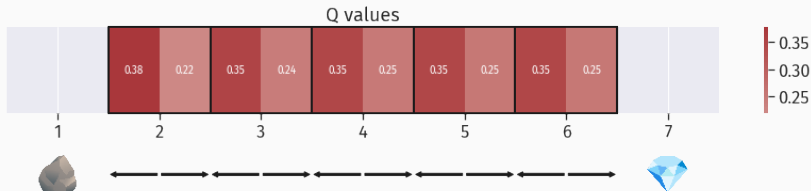
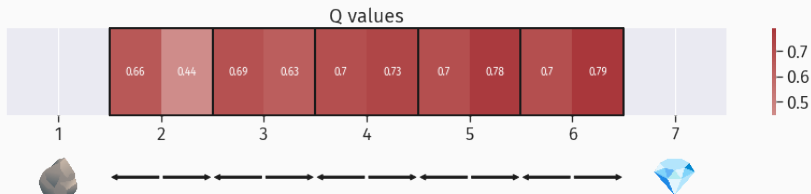
# States and actions



# Rewards and steps

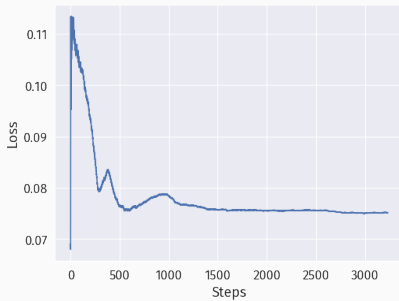


# Q-values learned

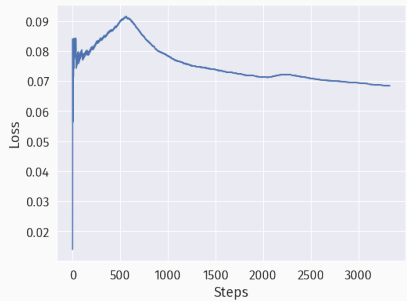


# Network loss

Right leaning



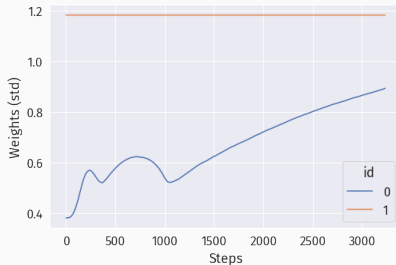
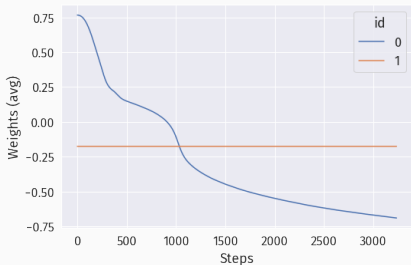
Left leaning



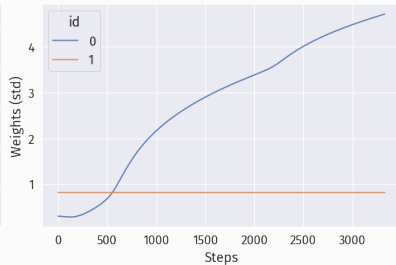
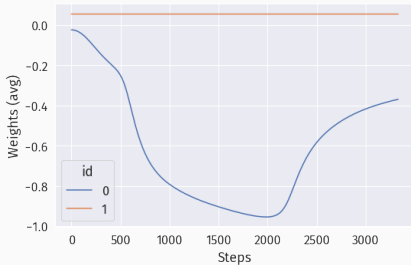


# Network weights

Right leaning

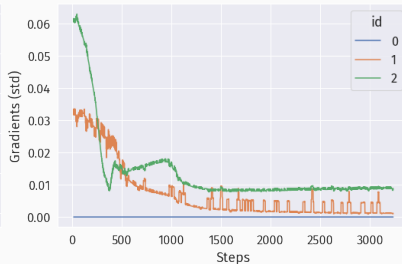
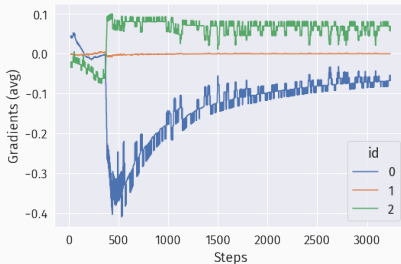


Left leaning

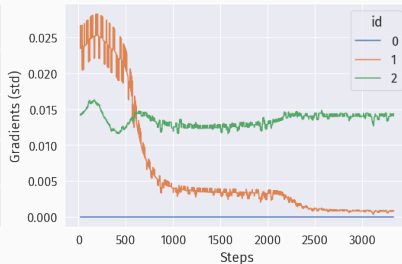
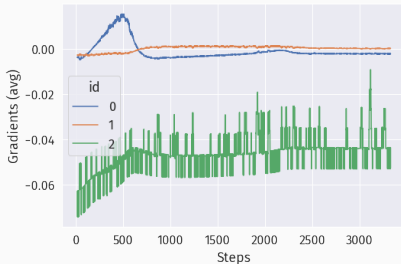


# Network gradients

Right leaning



Left leaning



Questions ?