

Analyse Image Classification Use Encoder Output Images

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Abstract—The method of categorizing and labeling bunches of pixels or vectors inside a picture utilizing particular rules is known as image classification. It is the foremost significant component of advanced image analysis. The objective of this paper is to see into an approach to image classification that's based on an open Hierarchical Temporal Memory (HTM) form algorithm. The HTM Cortical Learning Algorithm (HTM CLA) Spatial Pooler (SP) could be a learning calculation propelled by the neocortical framework. Its objective is to comprehend the spatial design by producing a Sparse Distributed Representation code from the input (SDR). HTM may be a cognitive learning framework and a progressive naturally propelled show of the neocortex's structure that's utilized to maximize basic affecting parameters of the HTM demonstrate in arrange to anticipate more accurately when connected to encoder output pictures. We performed a set of tests in this paper to decide the most excellent parameter combination for accomplishing great and exact likeness between encoder output pictures.

Index Terms—Spatial Pooler, Hierarchical Temporal Memory, Sparse Distributed Representation, neocortex.

I. INTRODUCTION

For decades, image classification and recognition have proven to be difficult tasks in artificial intelligence. Image classification is the process of categorizing images into one of several predefined classes. The system must be able to extract critical feature information that, when combined with training data, allows the system to recognize the item in the image. As a result, picture categorization can employ effective knowledge representation strategies. Hierarchical temporal memory (HTM) is used as a learning technique in this paper.

Hierarchical temporal memory (HTM) [1] is a machine learning algorithm inspired by the neocortex, the human brain's center for higher brain functions, and designed to learn sequences and predict spatiotemporal data. It should be capable of producing generalized representations for similar inputs in its idealized form. HTM can be used in edge computing devices to perform intelligent data processing. HTM semantically encodes input temporal data generated from various data sources as a sparse array known as sparse distributed representation (SDR). This encoded array is subjected to spatial pooling, which normalizes/standardizes the input data from various sources into a sparse output vector or mini-columns (columns of pyramidal neurons) with defined size and sparsity.

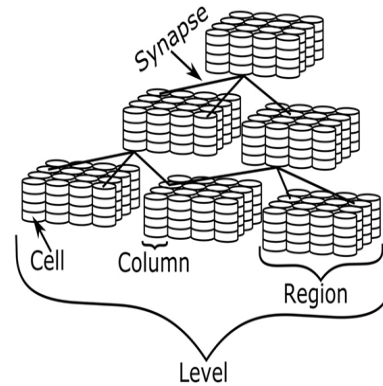


Fig. 1. Depiction of HTM, showing the various levels of detail Source [1]

II. HIERARCHICAL TEMPORAL MEMORY(HTM)

A HTM network is built in the form of a tree-shaped hierarchy. Although uncommon, multiple parents per node are permitted, allowing the parents' receptive fields to overlap. Its structure is similar to that of cortical mini columns in that an HTM region is made up of numerous columns, each of which contains a large number of cells. A level consists of one or more regions. Levels are stacked hierarchically in a tree-like structure to build the entire network. In HTM, synapses are used to make connections, with proximal and distal synapses used to produce feedforward and adjacent connections, respectively, as shown in Figure 1. It is possible to mix and match multiple HTM networks. Hierarchical organization is advantageous in terms of efficiency. Because patterns learned at each level of the hierarchy are reused when combined in interesting ways at higher levels, training time and memory usage are reduced significantly. HTMs automatically learn the best possible representations at each level based on the statistics of the input and the number of resources available. Giving a level more memory results in larger and more sophisticated representations, implying that fewer hierarchical levels are required. When you give a level less memory, it will build smaller and simpler representations, which may necessarily require the use of more hierarchical levels.

As shown in Figure 2, HTM has distinct progression levels. As crude information is entered into the framework at lower levels, it is prepared, and more specific data of the information is exchanged to the higher layers of the HTM. This implies that the higher the layer of the chain of command, the more

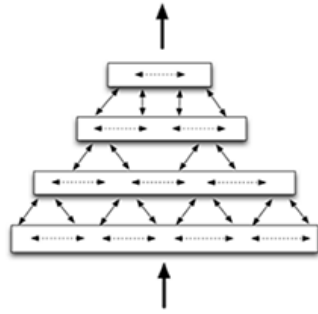


Fig. 2. Simplified diagram of HTM hierarchy [3]

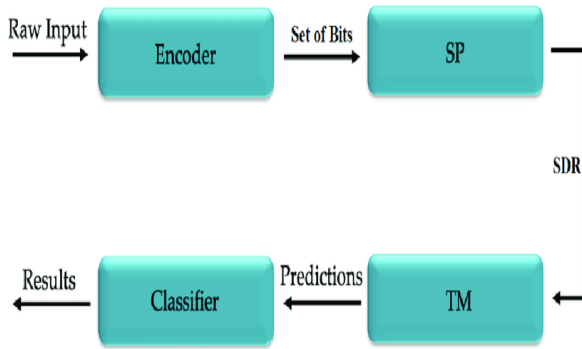


Fig. 3. HTM-network-topology [4]

prepared information and complex highlights are represented. In other words, lower-level hubs deal with straightforward events that change quickly and involve smaller spatial areas, whereas higher-level hubs deal with numerous events that were detected by lower-level hubs and are thus affected by a larger run of information. Higher level hubs, in particular, detect more complex causes, specifically designs of designs, which progress at a slower rate and can be found in larger spatial zones.

Figure 3 depicts how HTM operates from the beginning to the end of the method. The various components of the framework are depicted one by one as following. In any case, we did not use Transient Memory in this Extraordinary Extend. Input data from a sensor or information source, which can also be continuous and global, is semantically encoded into an inadequate cluster known as inadequate dispersed representation (SDR). This sparse cluster of encoded information enters the framework from the HTM's lowest layer.

III. SPATIAL POOLER MODEL

In an HTM-System, the Spatial Pooler receives data from encoders and sends it to the Transient Memory. The primary goal is to convert the parallel data into a semantically similar SDR with predetermined sparsity. It consists of a series of mini columns arranged in a grid. A mini-column is made up of a collection of HTM Neurons that all have the same open

area. The responsive field specifies which input bits can be used by a scaled down column. After initialization, the SP calculation for each modern input repeats through three stages:

1. Enhancing Coverage Calculation
2. Adaptation through determination as a means of learning.
3. Inhibition.

IV. SPARSE DISTRIBUTED REPRESENTATIONS (SDR)

SDRs correspond to neocortical active neurons. An SDR is a massive array of bits, the vast majority of which are turned off (0s) and only a few are turned on (1s) (1s). The SDR is literally an array of 0's and 1's, and because the HTM concept is attempting to build a system based on the same principles of brain function, the SDRs are a mathematical representation of these sparse signals, which will likely contain around 2

V. ENCODER

Hierarchical Temporal Memory (HTM) provides a versatile and organically precise system for forecasting, classifying, and detecting anomalies in a wide range of information types (Hawkins and Ahmad, 2015). HTM frameworks necessitate data input using Meager Distributed Representations (SDRs) (Ahmad and Hawkins, 2016). SDRs differ from standard computer representations such as ASCII for content in that meaning is encoded directly into the representation. An SDR is made up of a large number of bits, the majority of which are zeros and some of which are ones. Because each bit has a few semantic meanings, if two SDRs have more than a few overlapping one-bits, those two SDRs have similar meanings. Any data that can be converted into an SDR can be used in a wide range of applications that employ HTM systems. Thus, the first step in using an HTM system is to convert a data source into an SDR using a device known as an encoder. The encoder converts the information's native format into an SDR that can be fed into an HTM framework. The encoder is responsible for determining which yield bits should be ones and which should be zeros for a given input value in order to capture the critical semantic properties of the information. Comparable input values should result in highly overlapping SDRs. [5]

A. DateTime Encoder

Before we get to DateTime Encoder, let's go over some important data-usage parameters. [7]

1. Range (R)

It is the difference between the highest and lowest values. In the case of DateTime Encoder, it is always 12 in the case of the month, 31 in the case of the day, 10 in the case of the year, 24 in the case of an hour, 60 in the case of minutes, and 60 in the case of seconds.

2.Width (W)

The width bit is always ON. The width of the output signal is determined by the number of bits used to encode a single value. To avoid centering issues, it should always be an odd number. The algorithm defines it as 'W.' Simply put, width

```
{
  { "W", 21},
  { "N", 1024},
  { "MinVal", now.AddYears(-20)},
  { "MaxVal", now},
  { "Periodic", false},
  { "Name", "DateTimeEncoder"},
  { "ClipInput", false},
  { "Padding", 5},
};
```

Fig. 4. Parameters of DateTime Encoder [7]

refers to the number of ones in a single encoder.

3. Radius (r)

Non-overlapping representations exist for two inputs separated by more than the radius. In general, two inputs separated by less than the radius will overlap in at least some of their bits. It is known as 'Radius.' The radius determines how many bits overlap. $\text{Overlapping} = \text{radius} - 1$.

4. Maximum and Minimum Values

It constrains the input value to fall between the maximum and minimum values. They are denoted by the terms 'MinVal' and 'MaxVal.' Because the date and time are always within the global defined range, it is always fixed in DateTime Encoder.

5. Output bit count (n)

It is the total number of bits required to define an array based on the input data. It is defined by the letter 'n.' $n = \text{width} * (\text{radius} / \text{range})$

DateTime encoders encode a date and time using the encoding parameters specified in their constructor. A DateTime object is used as the input to a date encoder. [6]

VI. METHODOLOGY

ACKNOWLEDGMENT

The preferred spelling of the word "acknowledgment" in America is without an "e" after the "g". Avoid the stilted expression "one of us (R. B. G.) thanks ...". Instead, try "R. B. G. thanks...". Put sponsor acknowledgments in the unnumbered footnote on the first page.

REFERENCES

Please number citations consecutively within brackets [1]. The sentence punctuation follows the bracket [2]. Refer simply to the reference number, as in [3]—do not use "Ref. [3]" or "reference [3]" except at the beginning of a sentence: "Reference [3] was the first ..."

Number footnotes separately in superscripts. Place the actual footnote at the bottom of the column in which it was cited. Do not put footnotes in the abstract or reference list. Use letters for table footnotes.

Unless there are six authors or more give all authors' names; do not use "et al.". Papers that have not been published,

even if they have been submitted for publication, should be cited as "unpublished" [4]. Papers that have been accepted for publication should be cited as "in press" [5]. Capitalize only the first word in a paper title, except for proper nouns and element symbols.

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