view_frames Result

Recorded at time: 1666273711.4194844

camera

Broadcaster: /link1_broadcaster
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /apriltag_ros_continuous_node
Average rate: 5.551
Buffer length: 4.864
Most recent transform: 878242.957
Oldest transform: 878238.093

panda_link0

tag_1

Broadcaster: /robot_state_publisher
Average rate: 30.202
Buffer length: 4.967
Most recent transform: 1666273711.355
Oldest transform: 1666273706.389

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link1

panda_link0_sc

Broadcaster: /robot_state_publisher
Average rate: 30.202
Buffer length: 4.967
Most recent transform: 1666273711.355
Oldest transform: 1666273706.389

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link2

panda_link1_sc

Broadcaster: /robot_state_publisher
Average rate: 30.202
Buffer length: 4.967
Most recent transform: 1666273711.355
Oldest transform: 1666273706.389

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link3

panda_link2_sc

Broadcaster: /robot_state_publisher
Average rate: 30.202
Buffer length: 4.967
Most recent transform: 1666273711.355
Oldest transform: 1666273706.389

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link4

panda_link3_sc

Broadcaster: /robot_state_publisher
Average rate: 30.202
Buffer length: 4.967
Most recent transform: 1666273711.355
Oldest transform: 1666273706.389

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link5

panda_link4_sc

Broadcaster: /robot_state_publisher
Average rate: 30.202
Buffer length: 4.967
Most recent transform: 1666273711.355
Oldest transform: 1666273706.389

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link6

panda_link5_sc

Broadcaster: /robot_state_publisher
Average rate: 30.202
Buffer length: 4.967
Most recent transform: 1666273711.355
Oldest transform: 1666273706.389

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link7

panda_link6_sc

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_link8

panda_link7_sc

Broadcaster: /franka_control
Average rate: 29.614
Buffer length: 4.998
Most recent transform: 1666273711.387
Oldest transform: 1666273706.389

Broadcaster: /gripper_broadcaster
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

panda_NE

robotiq_arg2f_base_link

Broadcaster: /franka_control
Average rate: 29.614
Buffer length: 4.998
Most recent transform: 1666273711.387
Oldest transform: 1666273706.389

panda_EE

Broadcaster: /franka_control
Average rate: 29.614
Buffer length: 4.998
Most recent transform: 1666273711.387
Oldest transform: 1666273706.389

panda_K