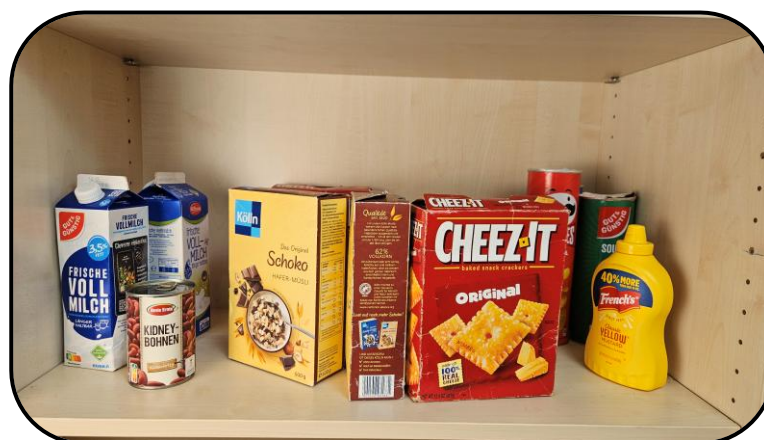


Scene



Scene, no change



Scene after manipulation



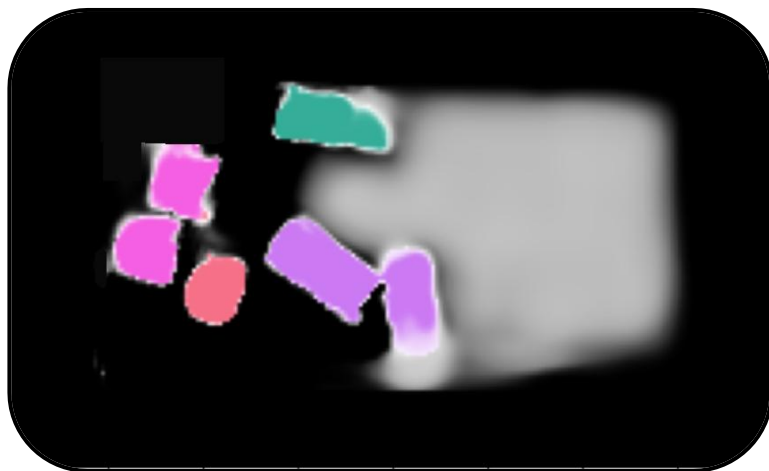
Action: View Change



Action: Move and Push



Robot's Belief

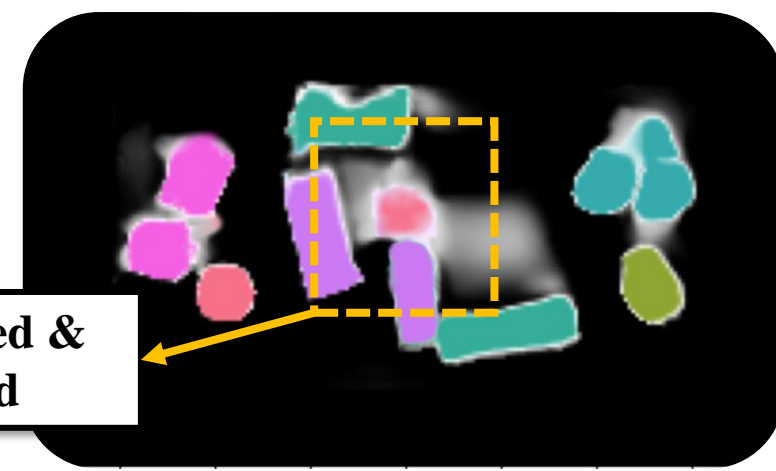


Robot's Belief



New instances discovered & uncertainty reduced

Robot's Belief



New instance uncovered & uncertainty reduced

t

t+1

t+2

Time Step