

# Project 1 - Problem 6

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The general expression for  $A\vec{v} = \vec{g}$  with  $\vec{a}$ ,  $\vec{b}$  and  $\vec{c}$  being the sub-, main- and supdiagonal respectively is:

$$\begin{bmatrix} b_1 & c_2 & 0 & 0 \\ a_1 & b_2 & c_3 & 0 \\ 0 & a_2 & b_3 & c_4 \\ 0 & 0 & a_3 & b_4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = \begin{bmatrix} g_1 \\ g_2 \\ g_3 \\ g_4 \end{bmatrix} \quad (1)$$

We can solve this with Gaussian elimination in two general steps: [1] Forward substitution and [2] Backward substitution.

## Forward substitution

The goal here is to get an upper triangular matrix, that is we want to do the following:

$$\begin{bmatrix} \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot \end{bmatrix} \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix} \rightarrow \begin{bmatrix} \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot \\ 0 & 0 & \cdot & \cdot \\ 0 & 0 & 0 & \cdot \end{bmatrix} \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

So we want to get rid of all  $a_i$  entries in the matrix equation (1). We will number and denote the rows with roman numerals.

$$II = II - \frac{a_2}{b_1} I \quad (2)$$

The diagonal new entries will be denoted  $\tilde{b}_i$

$$III = III - \frac{a_3}{\tilde{b}_2} II \quad (3)$$

$$IV = IV - \frac{a_4}{\tilde{b}_3} III \quad (4)$$

$$(5)$$

This gives us the following algorithm for precdure

$$\tilde{b}_1 = b_1 \quad (6)$$

$$\tilde{b}_i = b_i - \frac{a_i}{\tilde{b}_{i-1}} c_{i-1} \quad (7)$$

$$\tilde{g}_1 = g_1 \quad (8)$$

$$\tilde{g}_i = g_i - \frac{a_i}{\tilde{b}_{i-1}} \tilde{g}_{i-1} \quad (9)$$

$$(10)$$

This will be for  $i = 2, 3, \dots, n$  for a general tridiagonal matrix.

### Backward substitution

Now that we have done the forward substitution we want to find the solution to all  $v_i$  from the following equation:

$$\begin{bmatrix} \tilde{b}_1 & c_2 & 0 & 0 \\ 0 & \tilde{b}_2 & c_3 & 0 \\ 0 & 0 & \tilde{b}_3 & c_4 \\ 0 & 0 & 0 & \tilde{b}_4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = \begin{bmatrix} \tilde{g}_1 \\ \tilde{g}_2 \\ \tilde{g}_3 \\ \tilde{g}_4 \end{bmatrix} \quad (11)$$

we quickly see that  $v_4 = \frac{\tilde{g}_4}{\tilde{b}_4}$  and to get the remaining  $v_i$  we move up with the following algorithm (we include the case of  $v_n$  to generalize the algorithm):

$$v_n = \frac{\tilde{g}_n}{\tilde{b}_n} \quad (12)$$

$$v_i = \frac{\tilde{g}_i - c_i v_{i-1}}{\tilde{b}_i} \quad (13)$$

$$(14)$$

for  $i = n - 1, n - 2, \dots, 2, 1$ .

### FLOPs

We can see that algorithm 6 requires  $2(n - 1)$  floating point operations.  $n - 1$  FLOPs for equation (8) and equation (10) each. From equation 12 we can count  $3(n - 1) + 1$  FLOPs. This gives us a total of  $5n - 4$  FLOPs to solve  $A\vec{v} = \vec{g}$  with a tridiagonal matrix of dimention  $n \times n$ .