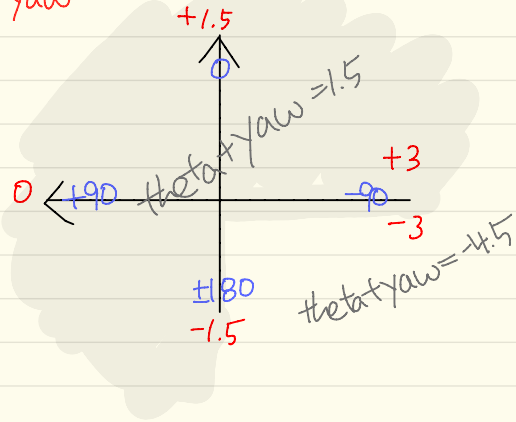


$\theta = \text{drone. yaw}$
 $= \text{"theta"}$



1. 0 +1.5
+1.5 0
 $\text{theta} + \text{yaw} = 1.5$

2. +1.5 +3
0 -1.5
 $\text{theta} + \text{yaw} = 1.5$

3. 0 -1.5
+1.5 +3
 $\text{theta} + \text{yaw} = 1.5$

4. -1.5 -3
-3 -1.5
 $\text{theta} + \text{yaw} = -4.5$